

HEURISTIC ANALYSIS

Problems Definition & Result Matrix:

- *Air Cargo Action Schema:*

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Action(Load(c, p, a),

PRECOND: $At(c, a) \wedge At(p, a) \wedge Cargo(c) \wedge Plane(p) \wedge Airport(a)$

EFFECT: $\neg At(c, a) \wedge In(c, p)$

Action(Unload(c, p, a),

PRECOND: $In(c, p) \wedge At(p, a) \wedge Cargo(c) \wedge Plane(p) \wedge Airport(a)$

EFFECT: $At(c, a) \wedge \neg In(c, p)$

Action(Fly(p, from, to),

PRECOND: $At(p, from) \wedge Plane(p) \wedge Airport(from) \wedge Airport(to)$

EFFECT: $\neg At(p, from) \wedge At(p, to)$

...

- *Problem 1 initial state and goal:*

...

Init($At(C1, SFO) \wedge At(C2, JFK)$

$\wedge At(P1, SFO) \wedge At(P2, JFK)$

$\wedge Cargo(C1) \wedge Cargo(C2)$

$\wedge Plane(P1) \wedge Plane(P2)$

$\wedge Airport(JFK) \wedge Airport(SFO))$

Goal($At(C1, JFK) \wedge At(C2, SFO)$)

...

Optimal Plan:

Load(C1, P1, SFO)

Load(C2, P2, JFK)

Fly(P2, JFK, SFO)

Unload(C2, P2, SFO)

Fly(P1, SFO, JFK)

Unload(C1, P1, JFK)

Search Method	Optimality	Plane Length	Time Elapsed	New nodes	# Node Expand	Goal Tests
breadth_first_search	Yes	6	0.052	180	43	56
depth_first_graph_search	No	6	1.36	5960	1458	1459
greedy_best_first_graph_search h_1	Yes	6	0.01	28	7	9

- Problem 2 initial state and goal:

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$Init(At(C1, SFO) \wedge At(C2, JFK) \wedge At(C3, ATL)$
 $\wedge At(P1, SFO) \wedge At(P2, JFK) \wedge At(P3, ATL)$
 $\wedge Cargo(C1) \wedge Cargo(C2) \wedge Cargo(C3)$
 $\wedge Plane(P1) \wedge Plane(P2) \wedge Plane(P3)$
 $\wedge Airport(JFK) \wedge Airport(SFO) \wedge Airport(ATL))$
 $Goal(At(C1, JFK) \wedge At(C2, SFO) \wedge At(C3, SFO))$

Search Method	Optimality	Plane Length	Time Elapsed	# Node Expand

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- Problem 3 initial state and goal:

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$Init(At(C1, SFO) \wedge At(C2, JFK) \wedge At(C3, ATL) \wedge At(C4, ORD)$
 $\wedge At(P1, SFO) \wedge At(P2, JFK)$
 $\wedge Cargo(C1) \wedge Cargo(C2) \wedge Cargo(C3) \wedge Cargo(C4)$
 $\wedge Plane(P1) \wedge Plane(P2)$
 $\wedge Airport(JFK) \wedge Airport(SFO) \wedge Airport(ATL) \wedge Airport(ORD))$
 $Goal(At(C1, JFK) \wedge At(C3, JFK) \wedge At(C2, SFO) \wedge At(C4, SFO))$

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Search Method	Optimality	Plane Length	Time Elapsed	# Node Expand