

view_frames Result

Recorded at time: 459.233

map

Broadcaster: /rtabmap/rtabmap
Average rate: 20.215 Hz
Most recent transform: 459.312 (-0.079 sec old)
Buffer length: 4.749 sec

odom

Broadcaster: /gazebo
Average rate: 10.213 Hz
Most recent transform: 459.221 (0.012 sec old)
Buffer length: 4.700 sec

robot_footprint

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (459.233 sec old)
Buffer length: 0.000 sec

chassis

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (459.233 sec old)
Buffer length: 0.000 sec

camera

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (459.233 sec old)
Buffer length: 0.000 sec

hokuyo

Broadcaster: /robot_state_publisher
Average rate: 10.215 Hz
Most recent transform: 459.200 (0.033 sec old)
Buffer length: 4.699 sec

left_wheel

Broadcaster: /robot_state_publisher
Average rate: 10.215 Hz
Most recent transform: 459.200 (0.033 sec old)
Buffer length: 4.699 sec

right_wheel