# Language and Automata, Assignment 1

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### 1.1 Regular expression

We are given following regular expression:

$$a^* + ba^*b + bba^*$$

## 1.2 Examples of accepted strings

- 1.  $\varepsilon$
- 2. a
- 3. bab
- 4. bba
- 5. bb

# $\begin{array}{cc} \textbf{1.3} & \textbf{Building NFA using Thompson construction} \\ & \textbf{algorithm} \end{array}$

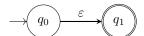


Figure 1.1: Operator 'a'

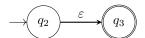


Figure 1.2: Operator 'b'

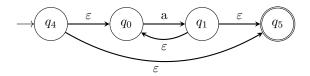


Figure 1.3: Operator  $a^*$ ,

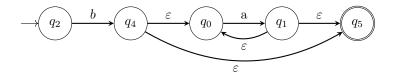


Figure 1.4: Operator  $ba^*$ 

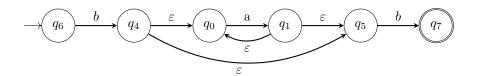


Figure 1.5: Operator ba\*b'

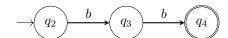


Figure 1.6: Operator 'bb'

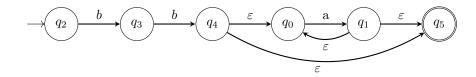


Figure 1.7: Operator ' $bba^*$ '

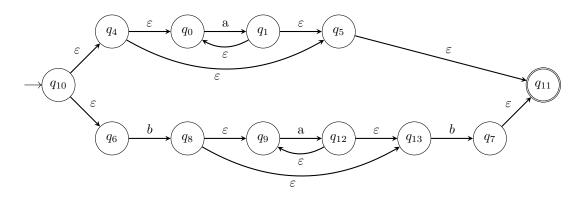


Figure 1.8: Operator  $a^* + ba^*b$ 

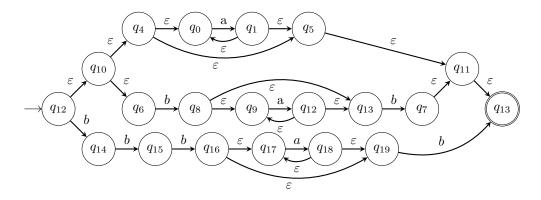


Figure 1.9: Operator  $a^* + ba^*b + bba^*$ 

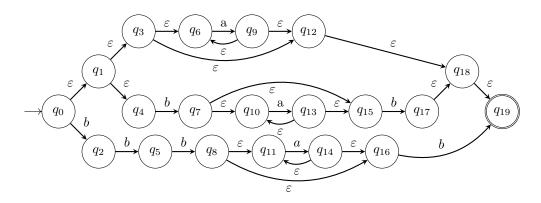


Figure 1.10: Operator ' $a^* + ba^*b + bba^*$ ' - changed names of states

# 1.4 Transforming NFA into DFA using subset algorithm

I will use  $\epsilon_{cl}$  instead of  $\epsilon$ -closure for brevity sake. Final state -  $\underline{q_{19}}$  was marked with an *underline* and so did all the states of DFA that contain it.

$$A = \epsilon_{cl}(q_0) = (q_0, q_1, q_3, q_4, q_6, q_{12}, q_{18}, \underline{q_{19}}) = \underline{A}$$

$$\epsilon_{cl}(move(\underline{A}, a)) = (\epsilon_{cl}(move(q_0, q_1, q_3, q_4, q_6, q_{12}, q_{18}, \underline{q_{19}}, a))) = \epsilon_{cl}(q_9) = (q_6, q_9, q_{12}, q_{18}, \underline{q_{19}}) = \underline{B}$$

$$A = \epsilon_{cl}(move(\underline{A}, b)) = \epsilon_{cl}(move(q_0, q_1, q_3, q_4, q_6, q_{12}, q_{18}, \underline{q_{19}}, b))) = \epsilon_{cl}(q_2, q_7) = (q_2, q_7, q_{10}, q_{15}) = C$$

$$\epsilon_{cl}(move(\underline{B}, a)) = \epsilon_{cl}(move(q_6, q_9, q_{12}, q_{18}, \underline{q_{19}}), a) = \epsilon_{cl}(q_9) = (q_6, q_9, q_{12}, q_{18}, \underline{q_{19}}) = \underline{B}$$

$$\epsilon_{cl}(move(\underline{B}, b)) = \epsilon_{cl}(move(q_6, q_9, q_{12}, q_{18}, \underline{q_{19}}), b) = \emptyset$$

$$\epsilon_{cl}(move(C, a)) = \epsilon_{cl}(move(q_2, q_7, q_{10}, q_{15}), a) = \epsilon_{cl}(q_{13}) = (q_{10}, q_{13}, q_{15}) = D$$

$$\epsilon_{cl}(move(D, a)) = \epsilon_{cl}(move((q_{10}, q_{13}, q_{15}), a) = \epsilon_{cl}(q_{13}) = (q_{10}, q_{13}, q_{15}) = D$$

$$\epsilon_{cl}(move(\underline{B}, b)) = \epsilon_{cl}(move(q_{10}, q_{13}, q_{15}), a) = \epsilon_{cl}(q_{17}) = (q_{17}, q_{18}, \underline{q_{19}}) = \underline{E}$$

$$\epsilon_{cl}(move(\underline{B}, b)) = \epsilon_{cl}(move(q_{10}, q_{13}, q_{15}, b) = \epsilon_{cl}(q_{17}) = (q_{17}, q_{18}, \underline{q_{19}}) = \underline{E}$$

$$\epsilon_{cl}(move(\underline{E}, a)) = \epsilon_{cl}(move(q_{17}, q_{18}, \underline{q_{19}}), a) = \epsilon_{cl}(\emptyset) = \emptyset$$

$$\epsilon_{cl}(move(\underline{E}, b)) = \epsilon_{cl}(move(q_{17}, q_{18}, \underline{q_{19}}), b) = \epsilon_{cl}(\emptyset) = \emptyset$$

#### 1.4.1 State table

State	a	b
<u>A</u>	<u>B</u>	С
<u>B</u>	<u>B</u>	Ø
С	D	$\underline{E}$
D	D	$\underline{E}$
<u>E</u>	Ø	Ø
Ø	Ø	Ø

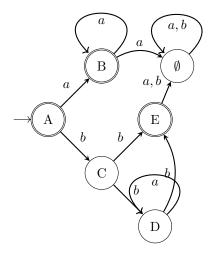


Figure 1.11: DFA graph before minimalization

#### 1.5 Constructing minimal state DFA

$\underline{A}$						
<u>B</u>	$x_1$					
С	$x_1$	$x_1$				
D	$x_1$	$x_1$	$x_2$			
<u>E</u>	$x_1$	$x_1$	$x_1$	$x_1$		
Ø	$x_1$	$x_1$	$x_2$	$x_2$	$x_1$	
	$\underline{\underline{A}}$	<u>B</u>	С	D	<u>E</u>	Ø

1. First I marked (with  $x_1$ ) all the pairs in which at least one of them were final state:

$$\begin{split} ([\underline{A},\emptyset],[\underline{A},\underline{E}],[\underline{A},D],[\underline{A},C],[\underline{A},\underline{B}]) \\ ([\underline{B},\emptyset],([\underline{B},\underline{E}],([\underline{B},D],([\underline{B},C]) \\ ([\underline{E},\emptyset],[\underline{E},C],[\underline{E},D]) \end{split}$$

2. We are left with the pairs:

$$([\emptyset, C], [\emptyset, D], [D, C])$$

For pair:  $[\emptyset, C]$  C goes to final state  $\underline{E}$  on transition 'b' therefore we mark it with  $x_2$  For pair:  $[\emptyset, D]$  D goes to final state  $\underline{E}$  on transition 'b' therefore we mark it with  $x_2$  For pair: [D, C] both C and D go to final state  $\underline{E}$  on transition 'b' therefore we mark it with  $x_2$ 

No states could be minimized! Therefore our final minimal state DFA looks like this:

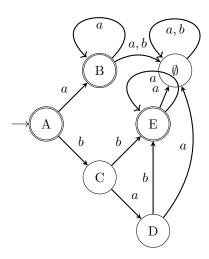


Figure 1.12: DFA graph after minimalization