The University of Texas at Austin
Aerospace Engineering
and Engineering Mechanics
Cockrell School of Engineering

ASE 375 Electromechanical Systems
Section 14115

Monday: 3:00 - 6:00 pm

Report 2:
Temperature Sensor Measurements

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Contents

1 Introduction

This experiment consisted of measuring temperature with three different sensors: a Thermocouple, Thermistor, and an Integrated Circuit Temperature sensor. A Data Acquisition (DAQ) system was used to process the different temperature measurements in LabVIEW, a software workbench used as a graphical interface to model our data.

2 Equipment

The equipment used in this experiment include .....

K-type Thermocouple: connected to NI 9211

Thermistor: connected to NI 9215 via breadboard w/ 1k ohm resistor etc....

IC Temperature Sensor: connected to NI 9215

Breadboard:

Circuitry: various wires, 1k ohm resistor, etc... and 5V power supply

DAQ: Data Aquisition system that digitizes analog information into "bins" for a computer. The specific DAQ had two units, the NI 9215 and NI 9211. Specific Datasheets for each are included in the appendices.

Thermometer: used to measure true temperature w/ 0.5 degrees

Water: Access to water near a boiling temperature, and water in an ice bath.

3 Procedure

4 Data Processing

4.1 Part 1

4.2 Part 2

5 Results and Analysis

6 Conclusion

Appendices

Appendix: t-Distribution Tables

Table A11. *t*-Distribution

Values of z for given values of the distribution function $F(z)$ (cf. p. 754).
Example: For 9 degrees of freedom, $z = 1.83$ when $F(z) = 0.95$.

	Number of Degrees of Freedom									
$F(z)$	1	2	3	4	5	6	7	8	9	10
0.5	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
0.6	0.33	0.29	0.28	0.27	0.27	0.27	0.26	0.26	0.26	0.26
0.7	0.73	0.62	0.58	0.57	0.56	0.55	0.55	0.55	0.54	0.54
0.8	1.38	1.06	0.98	0.94	0.92	0.91	0.90	0.89	0.88	0.88
0.9	3.08	1.89	1.64	1.53	1.48	1.44	1.42	1.40	1.38	1.37
0.95	6.31	2.92	2.35	2.13	2.02	1.94	1.90	1.86	1.83	1.81
0.975	12.7	4.30	3.18	2.78	2.57	2.45	2.37	2.31	2.26	2.23
0.99	31.8	6.97	4.54	3.75	3.37	3.14	3.00	2.90	2.82	2.76
0.995	63.7	9.93	5.84	4.60	4.03	3.71	3.50	3.36	3.25	3.17
0.999	318.3	22.3	10.2	7.17	5.89	5.21	4.79	4.50	4.30	4.14

	Number of Degrees of Freedom									
$F(z)$	11	12	13	14	15	16	17	18	19	20
0.5	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
0.6	0.26	0.26	0.26	0.26	0.26	0.26	0.26	0.26	0.26	0.26
0.7	0.54	0.54	0.54	0.54	0.54	0.54	0.53	0.53	0.53	0.53
0.8	0.88	0.87	0.87	0.87	0.87	0.87	0.86	0.86	0.86	0.86
0.9	1.36	1.36	1.35	1.35	1.34	1.34	1.33	1.33	1.33	1.33
0.95	1.80	1.78	1.77	1.76	1.75	1.75	1.74	1.73	1.73	1.73
0.975	2.20	2.18	2.16	2.15	2.13	2.12	2.11	2.10	2.09	2.09
0.99	2.72	2.68	2.65	2.62	2.60	2.58	2.57	2.55	2.54	2.53
0.995	3.11	3.06	3.01	2.98	2.95	2.92	2.90	2.88	2.86	2.85
0.999	4.03	3.93	3.85	3.79	3.73	3.69	3.65	3.61	3.58	3.55

	Number of Degrees of Freedom									
$F(z)$	22	24	26	28	30	40	50	100	200	∞
0.5	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
0.6	0.26	0.26	0.26	0.26	0.26	0.26	0.26	0.25	0.25	0.25
0.7	0.53	0.53	0.53	0.53	0.53	0.53	0.53	0.53	0.53	0.52
0.8	0.86	0.86	0.86	0.86	0.85	0.85	0.85	0.85	0.84	0.84
0.9	1.32	1.32	1.32	1.31	1.31	1.30	1.30	1.29	1.29	1.28
0.95	1.72	1.71	1.71	1.70	1.70	1.68	1.68	1.66	1.65	1.65
0.975	2.07	2.06	2.06	2.05	2.04	2.02	2.01	1.98	1.97	1.96
0.99	2.51	2.49	2.48	2.47	2.46	2.42	2.40	2.37	2.35	2.33
0.995	2.82	2.80	2.78	2.76	2.75	2.70	2.68	2.63	2.60	2.58
0.999	3.51	3.47	3.44	3.41	3.39	3.31	3.26	3.17	3.13	3.09