

# Homework 1

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## 1-2 Ex.2

Let  $\alpha(t)$  be a parametrized curve which does not pass through the origin. If  $\alpha(t_0)$  is a point of the trace of  $\alpha$  closest to the origin and  $\alpha'(t_0) \neq 0$ , show that the position vector  $\alpha(t_0)$  is orthogonal to  $\alpha'(t_0)$ .

### *Solution.*

Let  $s(t) = |\alpha(t)|$ ,  $t_0$  is the minimum point of  $s(t)$  since  $\alpha(t_0)$  is the closest point to the origin on the trace of  $\alpha$ . We know that  $\alpha(t) = (x(t), y(t), z(t))$  is differentiable and doesn't pass through the origin, so

$$s(t) = |\alpha(t)| = \sqrt{x^2(t) + y^2(t) + z^2(t)} > 0$$

is also differentiable. Then we have

$$\begin{aligned} s'(t) &= \frac{d}{dt} \sqrt{x^2(t) + y^2(t) + z^2(t)} \\ &= \frac{x(t)x'(t) + y(t)y'(t) + z(t)z'(t)}{\sqrt{x^2(t) + y^2(t) + z^2(t)}} \\ &= \frac{\alpha(t) \cdot \alpha'(t)}{s(t)} \end{aligned}$$

Noticed that  $t_0$  is the minimum point of  $s(t)$ , It follows

$$s'(t_0) = \frac{\alpha(t_0) \cdot \alpha'(t_0)}{s(t_0)} = 0$$

which implies  $\alpha(t_0) \cdot \alpha'(t_0) = 0$ , i.e.  $\alpha(t_0)$  is orthogonal to  $\alpha'(t_0)$ .  $\square$

## 1-2 Ex.4

Let  $\alpha(t) : I \rightarrow \mathbb{R}^3$  be a parametrized curve and let  $v \in \mathbb{R}^3$  be a fixed vector. Assumed that  $\alpha'(t)$  is orthogonal to  $v$  for all  $t \in I$  and that  $\alpha(0)$  is also orthogonal to  $v$ . Prove that  $\alpha(t)$  is also orthogonal to  $v$  for all  $t \in I$ .

### *Solution.*

Suppose  $I = (a, b)$ ,  $0 \in (a, b)$ , then given  $t \in (a, b)$ ,  $\alpha(t)$  can be written as

$$\alpha(t) = \int_a^t \alpha'(s) ds$$

Thus we have

$$(\alpha(t) - \alpha(0)) \cdot v = \int_0^t \alpha'(s) ds \cdot v = \int_0^t \alpha'(s) \cdot v ds$$

It follows

$$\alpha(t) \cdot v = \alpha(0) \cdot v + \int_0^t \alpha'(s) \cdot v ds = 0 + \int_0^t 0 ds = 0 \quad \square$$

## 1-3 Ex.4

Let  $\alpha : (0, \pi) \rightarrow \mathbb{R}^2$  be given by

$$\alpha(t) = (\sin t, \cos t + \log \tan \frac{t}{2})$$

where  $t$  is the angle that the y axis makes with the vector  $\alpha'(t)$ . The trace of  $\alpha$  is called the tractrix. Show that

**a.**  $\alpha$  is a differentiable parametrized curve, regular except at  $t = \frac{\pi}{2}$ .

**b.** The length of the segment of the tangent of the tractrix between the point of tangency and the y axis is constantly equal to 1.

**Solution.**

**a.** Since  $x(t) = \sin t$  and  $y(t) = \cos t + \log \tan \frac{t}{2}$  are both differentiable in  $(0, \pi)$ ,  $\alpha(t)$  is a differentiable map from  $(0, \pi)$  to  $\mathbb{R}^2$ , so  $\alpha$  is a differentiable parametrized curve. Note that

$$\alpha'(t) = (\cos t, -\sin t + \frac{1}{\sin t})$$

Let  $|\alpha'(t_0)| = 0$ , it follows  $\cos t_0 = 0$ ,  $\sin t_0 = \frac{1}{\sin t_0}$  and we have  $t_0 = \frac{\pi}{2} + k\pi$ ,  $k \in \mathbb{Z}$ .

So  $t_0 = \frac{\pi}{2}$  is the unique solution in  $(0, \pi)$ . Therefore,  $\alpha$  is regular in  $(0, \pi)$  except at  $t = \frac{\pi}{2}$ .  $\square$

**b.** Let  $(x(t), y(t))$  denote the point of tangency. Since we know that  $t$  is the angle that the y axis makes with the vector  $\alpha'(t)$ , the segment length  $l(t)$  can be calculated by

$$l(t) = \frac{x(t)}{\sin t} = \frac{\sin t}{\sin t} = 1 \quad \square$$

### 1-3 Ex.10

(Straight Lines as Shortest) Let  $\alpha : I \rightarrow \mathbb{R}^3$  be a parametrized curve. Let  $[a, b] \subset I$  and set  $\alpha(a) = p$ ,  $\alpha(b) = q$ .

**a.** Show that, for any constant vector  $v$ ,  $|v| = 1$ ,

$$(q - p) \cdot v = \int_a^b \alpha'(t) \cdot v dt \leq \int_a^b |\alpha'(t)| dt$$

**b.** Set

$$v = \frac{q - p}{|q - p|}$$

and show that

$$|\alpha(b) - \alpha(a)| \leq \int_a^b |\alpha'(t)| dt$$

That is, the curve of shortest length from  $\alpha(a)$  to  $\alpha(b)$  is the straight line joining these points.

**Solution.**

**a.** Since  $\alpha$  is differentiable,

$$q - p = \alpha(b) - \alpha(a) = \int_a^b \alpha'(t) dt$$

Thus,

$$(q - p) \cdot v = \int_a^b \alpha'(t) dt \cdot v = \int_a^b \alpha'(t) \cdot v dt$$

For each  $t \in (a, b)$ ,  $\alpha'(t) \cdot v \leq |\alpha'(t)| |v| = |\alpha'(t)|$ , so

$$\int_a^b \alpha'(t) \cdot v dt \leq \int_a^b |\alpha'(t)| dt \quad \square$$

**b.** According to the conclusion above, take  $v = \frac{q-p}{|q-p|}$  and it follows immediately that

$$|\alpha(b) - \alpha(a)| = |q - p| = (q - p) \cdot v \leq \int_a^b |\alpha'(t)| dt \quad \square$$

### 1-4 Ex.2

A plane  $P$  contained in  $\mathbb{R}^3$  is given by the equation  $ax + by + cz + d = 0$ . Show that the vector  $v = (a, b, c)$  is perpendicular to the plane and that  $\frac{|d|}{\sqrt{a^2 + b^2 + c^2}}$  measures the distance from the plane to the origin  $(0, 0, 0)$ .

**Solution.**

For each point  $(x, y, z)$  in plane  $P$ , the equation  $ax + by + cz + d = 0$  holds. Hence for each vector  $u$  contained in  $P$ , it can be denoted by  $u = (x_2 - x_1, y_2 - y_1, z_2 - z_1)$  where  $(x_1, y_1, z_1)$  and  $(x_2, y_2, z_2)$  are points in  $P$ . Therefore,

$$a(x_2 - x_1) + b(y_2 - y_1) + c(z_2 - z_1) = 0$$

That is,

$$u \cdot v = (x_2 - x_1, y_2 - y_1, z_2 - z_1) \cdot (a, b, c) = 0$$

Suppose  $v_0$  is the shortest vector from the origin to  $P$ , it's easy to see that  $v_0$  and  $v$  are linear dependent, so  $v_0$  can be written as  $\lambda v$ , where  $\lambda \in \mathbb{R}$ , therefore, for each point  $(x, y, z) \in P$ ,

$$((x, y, z) - v_0) \cdot v_0 = (x - \lambda a, y - \lambda b, z - \lambda c) \cdot \lambda(a, b, c) = 0$$

i.e.

$$\begin{aligned} \lambda a(x - \lambda a) + \lambda b(y - \lambda b) + \lambda c(z - \lambda c) &= -(a^2 + b^2 + c^2)\lambda^2 + (ax + by + cz)\lambda = 0 \\ (a^2 + b^2 + c^2)\lambda^2 + d\lambda &= 0 \end{aligned}$$

this implies  $\lambda = -\frac{d}{a^2 + b^2 + c^2}$  (when  $\lambda = 0$ ,  $d = 0$ ), so  $|v_0| = |\lambda||v| = \frac{|d|}{\sqrt{a^2 + b^2 + c^2}}$ , which is exactly the distance from the plane to the origin  $(0, 0, 0)$ .

**1-4 Ex.11**

**a.** Show that the volume  $V$  of a parallelepiped generated by three linearly independent vectors  $u, v, w \in \mathbb{R}^3$  is given by  $V = |(u \wedge v) \cdot w|$ , and introduce an oriented volume in  $\mathbb{R}^3$ .

**b.** Prove that

$$V^2 = \begin{vmatrix} u \cdot u & u \cdot v & u \cdot w \\ v \cdot u & v \cdot v & v \cdot w \\ w \cdot u & w \cdot v & w \cdot w \end{vmatrix}$$

**Solution.**

**a.** Let  $S$  and  $h$  denote the basal area and height of the parallelepiped, then

$$V = S \cdot h = |u||v|\sin\langle u, v \rangle h = |u \wedge v| \frac{|(u \wedge v) \cdot w|}{|u \wedge v|} = |(u \wedge v) \cdot w| \quad \square$$

**b.** Let

$$G = \begin{bmatrix} u \cdot u & u \cdot v & u \cdot w \\ v \cdot u & v \cdot v & v \cdot w \\ w \cdot u & w \cdot v & w \cdot w \end{bmatrix}$$

If any two vectors of  $u, v, w$  are linearly dependent, then it's easy to see both sides will equal to 0. Thus it only remains to verify the cases that  $\{u, v, w\}$  are linearly independent.

In these cases,  $\{u, v, w\}$  is a basis of  $\mathbb{R}^3$ . By Gram-Schmidt process, we can find an orthonormal basis  $\{\epsilon_i\}$  based on  $u, v, w$ , and there exists an upper triangular matrix  $P$  such that

$$(u, v, w) = (\epsilon_1, \epsilon_2, \epsilon_3)P = (\epsilon_1, \epsilon_2, \epsilon_3) \begin{bmatrix} p_{11} & p_{12} & p_{13} \\ & p_{22} & p_{23} \\ & & p_{33} \end{bmatrix}$$

Hence,

$$\begin{aligned} G &= \begin{bmatrix} u \cdot u & u \cdot v & u \cdot w \\ v \cdot u & v \cdot v & v \cdot w \\ w \cdot u & w \cdot v & w \cdot w \end{bmatrix} = \begin{bmatrix} u \\ v \\ w \end{bmatrix} \cdot \begin{bmatrix} u & v & w \end{bmatrix} \\ &= P^T \cdot \begin{bmatrix} \epsilon_1 \\ \epsilon_2 \\ \epsilon_3 \end{bmatrix} \cdot \begin{bmatrix} \epsilon_1 & \epsilon_2 & \epsilon_3 \end{bmatrix} \cdot P \\ &= P^T \cdot I \cdot P = P^T P \end{aligned}$$

Therefore,  $|G| = |P|^2 = p_{11}^2 \cdot p_{22}^2 \cdot p_{33}^2$ .  
On the other hand,

$$\begin{aligned} V(u, v, w) &= |(u \wedge v) \cdot w| \\ &= |(p_{11}\epsilon_1 \wedge (p_{12}\epsilon_1 + p_{22}\epsilon_2)) \cdot (p_{13}\epsilon_1 + p_{23}\epsilon_2 + p_{33}\epsilon_3)| \\ &= |p_{11}p_{22}(\epsilon_1 \wedge \epsilon_2) \cdot (p_{13}\epsilon_1 + p_{23}\epsilon_2 + p_{33}\epsilon_3)| \\ &= |p_{11}p_{22}\epsilon_3 \cdot (p_{13}\epsilon_1 + p_{23}\epsilon_2 + p_{33}\epsilon_3)| \\ &= |p_{11}p_{22}p_{33}| \end{aligned}$$

So we have  $V^2 = p_{11}^2 \cdot p_{22}^2 \cdot p_{33}^2 = |G| = \begin{vmatrix} u \cdot u & u \cdot v & u \cdot w \\ v \cdot u & v \cdot v & v \cdot w \\ w \cdot u & w \cdot v & w \cdot w \end{vmatrix}$ .  $\square$

### 1-5 Ex.1

Given the parametrized curve (helix)

$$\alpha(s) = (a \cos \frac{s}{c}, a \sin \frac{s}{c}, b \frac{s}{c}), s \in \mathbb{R}$$

where  $c^2 = a^2 + b^2$ ,

- Show that the parameter  $s$  is the arc length.
- Determine the curvature and the torsion of  $\alpha$ .
- Determine the osculating plane of  $\alpha$ .
- Show that the lines containing  $n(s)$  and passing through  $\alpha(s)$  meet the  $z$  axis under a constant angle equal to  $\frac{\pi}{2}$ .
- Show that the tangent line of  $\alpha$  make a constant angle with the  $z$  axis.

**Solution.**

- We only need to verify that  $|\alpha'(s)| \equiv 1$ .

$$\begin{aligned} \alpha'(s) &= (-\frac{a}{c} \sin \frac{s}{c}, \frac{a}{c} \cos \frac{s}{c}, \frac{b}{c}) \\ |\alpha'(s)| &= \sqrt{(-\frac{a}{c} \sin \frac{s}{c})^2 + (\frac{a}{c} \cos \frac{s}{c})^2 + (\frac{b}{c})^2} = \sqrt{\frac{a^2 + b^2}{c^2}} = 1 \quad \square \end{aligned}$$

**b.**

$$\begin{aligned} \alpha''(s) &= (-\frac{a}{c^2} \cos \frac{s}{c}, -\frac{a}{c^2} \sin \frac{s}{c}, 0) \\ k(s) &= |\alpha''(s)| = \frac{|a|}{c^2} \\ n(s) &= (-\operatorname{sgn}(a) \cdot \cos \frac{s}{c}, -\operatorname{sgn}(a) \cdot \sin \frac{s}{c}, 0) \\ b(s) &= \alpha'(s) \wedge n(s) = (\operatorname{sgn}(a) \cdot \frac{b}{c} \sin \frac{s}{c}, -\operatorname{sgn}(a) \cdot \frac{b}{c} \cos \frac{s}{c}, \frac{a}{c}) \\ b'(s) &= (\operatorname{sgn}(a) \cdot \frac{b}{c^2} \cos \frac{s}{c}, \operatorname{sgn}(a) \cdot \frac{b}{c^2} \sin \frac{s}{c}, 0) \end{aligned}$$

Hence we have  $\tau(s) = \frac{b}{c^2}$ .  $\square$

- The osculating plane of  $\alpha$  is the plane spanned by  $t(s)$  and  $n(s)$ . So the normal vector of the osculating plane is  $b(s)$ . Given  $s \in \mathbb{R}$ , the osculating plane at  $s$  is defined by the equation

$$\operatorname{sgn}(a) \cdot \frac{b}{c} \sin \frac{s}{c} (x - a \cos \frac{s}{c}) - \operatorname{sgn}(a) \cdot \frac{b}{c} \cos \frac{s}{c} (y - a \sin \frac{s}{c}) + \frac{a}{c} (z - b \frac{s}{c}) = 0$$

$\square$

d. Note that  $n(s) \cdot (0, 0, 1) = 0$ .  $\square$

e. Note that  $t(s) \cdot (0, 0, 1) = \frac{b}{c}$  for all  $s \in \mathbb{R}$ .  $\square$

**1-5 Ex.2**

Show that the torsion  $\tau$  of  $\alpha$  is given by

$$\tau(s) = -\frac{\alpha'(s) \wedge \alpha''(s) \cdot \alpha'''(s)}{|k(s)|^2}$$

**Solution.**

Since  $b'(s) = \tau(s)n(s)$ ,

$$\begin{aligned}\tau(s) &= b'(s) \cdot n(s) = (t(s) \wedge n(s))' \cdot n(s) \\ &= (t'(s) \wedge n(s) + t(s) \wedge n'(s)) \cdot n(s) \\ &= (t(s) \wedge n'(s)) \cdot n(s) \\ &= (t(s) \wedge \left(\frac{\alpha''(s)}{k(s)}\right)') \cdot \frac{\alpha''(s)}{k(s)} \\ &= \frac{(\alpha'(s) \wedge \alpha'''(s)) \cdot \alpha''(s)}{|k(s)|^2} \\ &= -\frac{\alpha'(s) \wedge \alpha''(s) \cdot \alpha'''(s)}{|k(s)|^2} \quad \square\end{aligned}$$

**1-5 Ex.4**

Assume that all normals of a parametrized curve pass through a fixed point. Prove that the trace of the curve is contained in a circle.

**Solution.**

Suppose the fixed point is denoted by  $p_0$ . Then given any  $s \in I$ ,  $p_0 - \alpha(s) = \lambda(s) \cdot n(s)$ , where  $0 \leq \lambda(s) \leq 1$ . Take derivatives of both sides of the equation, we have

$$-t(s) = \lambda(s)n'(s) = \lambda(s)(-k(s)t(s) - \tau(s)b(s)) + \lambda'(s)n(s)$$

Since  $t(s)$  is always perpendicular to  $b(s)$  and  $n(s)$ , it follows that  $\tau(s) = 0$  and  $\lambda'(s) = 0$ , so  $t(s) = \lambda(s)k(s)t(s)$ ,  $\lambda(s) = \frac{1}{k(s)} = r$  where  $r$  is a constant. Therefore,

$$|p_0 - \alpha(s)| = |\lambda(s)n(s)| = r$$

That is, the trace of  $\alpha(s)$  is contained in a circle centered at the point  $p_0$  with radius  $r$ .

**1-5 Ex.9**

Given a differentiable function  $k(s)$ ,  $s \in I$ , show that the parametrized plane curve having  $k(s) = k$  as curvature is given by

$$\alpha(s) = \left( \int \cos \theta(s) ds + a, \int \sin \theta(s) ds + b \right),$$

where

$$\theta(s) = \int k(s) ds + \phi$$

**Solution.**

Note that

$$\begin{aligned}\alpha''(s) &= (-\sin(\theta(s))\theta'(s), \cos(\theta(s))\theta'(s)) \\ |\alpha''(s)| &= |\theta'(s)| = |k(s)| \quad \square\end{aligned}$$

**1-5 Ex.12**

Let  $\alpha : I \rightarrow \mathbb{R}^3$  be a regular parametrized curve (not necessarily by arc length) and let  $\beta : J \rightarrow \mathbb{R}^3$  be a

reparametrization of  $\alpha(I)$  by the arc length  $s = s(t)$ , measured from  $t_0 \in I$ . Let  $t = t(s)$  be the inverse function of  $s$  and set  $\frac{d\alpha}{dt} = \alpha'$ ,  $\frac{d^2\alpha}{dt^2} = \alpha''$ , etc. Prove that

**a.**

$$\frac{dt}{ds} = \frac{1}{|\alpha'|}, \quad \frac{d^2t}{ds^2} = -\frac{\alpha' \cdot \alpha''}{|\alpha'|^4}$$

**b.** The curvature of  $\alpha$  at  $t \in I$  is

$$k(t) = \frac{|\alpha' \wedge \alpha''|}{|\alpha'|^3}.$$

**c.** The torsion of  $\alpha$  at  $t \in I$  is

$$\tau(t) = -\frac{(\alpha' \wedge \alpha'') \cdot \alpha'''}{|\alpha' \wedge \alpha''|^2}.$$

**d.** If  $\alpha : I \rightarrow \mathbb{R}^2$  is a plane curve  $\alpha(t) = (x(t), y(t))$ , the signed curvature of  $\alpha$  at  $t$  is

$$k(t) = \frac{x'y'' - x''y'}{(x'^2 + y'^2)^{\frac{3}{2}}}.$$

**Solution.**

**a.**

$$\begin{aligned} \frac{dt}{ds} &= \left(\frac{ds}{dt}\right)^{-1} = \frac{1}{|\alpha'|} \\ \frac{d^2t}{ds^2} &= \frac{d}{ds} \frac{1}{|\alpha'(t)|} = -\frac{1}{|\alpha'(t)|^2} \frac{d}{ds} |\alpha'(t)| = -\frac{1}{|\alpha'(t)|^2} \cdot \frac{\alpha'(t) \cdot \alpha''(t)}{|\alpha'(t)|} \frac{dt}{ds} = -\frac{\alpha' \cdot \alpha''}{|\alpha'|^4} \quad \square \end{aligned}$$

**b.** Note that

$$\begin{aligned} \alpha'(t) &= \frac{d\beta(s)}{dt} = \frac{d\beta(s)}{ds} \cdot \frac{ds}{dt} = \beta'(s) \frac{ds}{dt} \\ \alpha''(t) &= \frac{d\alpha'(t)}{dt} = \beta'(s) \frac{d^2s}{dt^2} + \beta''(s) \left(\frac{ds}{dt}\right)^2 \end{aligned}$$

Thus

$$\begin{aligned} |\alpha'(t) \wedge \alpha''(t)| &= |(\beta'(s) \frac{ds}{dt} \wedge (\beta''(s) \frac{ds}{dt})^2)| \\ &= \left(\frac{ds}{dt}\right)^3 \cdot |\beta'(s) \wedge \beta''(s)| \\ &= (|\alpha'(t)|)^3 \cdot k_\beta(s(t)) \\ &= (|\alpha'(t)|)^3 \cdot k_\alpha(t) \end{aligned}$$

So we have

$$k(t) = k_\alpha(t) = \frac{|\alpha' \wedge \alpha''|}{|\alpha'|^3} \quad \square$$

**c.**

$$\begin{aligned} \tau_\alpha(t) &= \tau_\beta(s(t)) = -\frac{\beta'(s) \wedge \beta''(s) \cdot \beta'''(s)}{|k_\beta(s)|^2} \\ &= -\frac{|\beta'(s)|^6 \cdot (\beta'(s) \wedge \beta''(s)) \cdot \beta'''(s)}{|\beta'(s) \wedge \beta''(s)|^2} \\ &= -\frac{\left(\frac{\alpha'}{|\alpha'|} \wedge \frac{\alpha''}{|\alpha'|^2}\right) \cdot \frac{\alpha'''}{|\alpha'|^3}}{\left|\frac{\alpha'}{|\alpha'|} \wedge \frac{\alpha''}{|\alpha'|^2}\right|^2} \\ &= -\frac{(\alpha' \wedge \alpha'') \cdot \alpha'''}{|\alpha' \wedge \alpha''|^2} \quad \square \end{aligned}$$

**d.** By the conclusion of **b**, we have

$$|k(t)| = \frac{|\alpha' \wedge \alpha''|}{|\alpha'|^3} = \frac{|(x', y') \wedge (x'', y'')|}{(x'^2 + y'^2)^{\frac{3}{2}}} = \frac{|x'y'' - x''y'|}{(x'^2 + y'^2)^{\frac{3}{2}}}$$

According to the definition of signed curvature,  $k(t) > 0$  when  $\det(\alpha', \alpha'') > 0$ ,  $k(t) < 0$  when  $\det(\alpha', \alpha'') < 0$ . Hence

$$k(t) = \frac{x'y'' - x''y'}{(x'^2 + y'^2)^{\frac{3}{2}}} \quad \square$$

### 1-5 Ex.13

Assume that  $\tau(s) \neq 0$  and  $k'(s) \neq 0$  for all  $s \in I$ . Show that a necessary and sufficient condition for  $\alpha(I)$  to lie on a sphere is that

$$R^2 + (R')^2 T^2 = \text{const.}$$

where  $R = \frac{1}{k}$ ,  $T = \frac{1}{\tau}$ , and  $R'$  is the derivative of  $R$  relative to  $s$ .

#### **Solution.**

Without loss of generality, we can assume that the sphere is centered at the origin.  
 $\Rightarrow$ :"

Suppose  $\alpha(I)$  lies on a sphere, then there exists some constant  $C$  such that

$$|\alpha(s)|^2 = C^2$$

Take derivatives on both sides of the equation, we have

$$\alpha(s) \cdot \alpha'(s) = \alpha(s) \cdot t(s) = 0$$

$$\alpha(s) \cdot \alpha''(s) + |\alpha'(s)|^2 = k(s)\alpha(s) \cdot n(s) + 1 = 0$$

$$\alpha(s) \cdot \alpha'''(s) + 3\alpha'(s) \cdot \alpha''(s) = \alpha(s) \cdot \alpha'''(s) = 0$$

For each  $s \in I$ , we can write  $\alpha(s)$  in the form of

$$\alpha(s) = c_1 t(s) + c_2 n(s) + c_3 b(s)$$

The first equation above implies that  $c_1 = 0$ , the second equation implies that  $c_2 = -\frac{1}{k(s)}$ .  
 Also note that,

$$\begin{aligned} \alpha'''(s) &= (k(s)n(s))' = k'(s)n(s) + k(s)n'(s) = k'(s)n(s) - k^2(s)t(s) - k(s)\tau(s)b(s) \\ &= -k^2(s) \cdot t(s) + k'(s) \cdot n(s) - k(s)\tau(s) \cdot b(s) \end{aligned}$$

Thus the third equation implies that

$$c_2 \cdot k'(s) - k(s)\tau(s)c_3 = -\frac{k'(s)}{k(s)} - k(s)\tau(s)c_3 = 0$$

It follows

$$c_3 = -\frac{k'(s)}{k^2(s)\tau(s)}$$

Thus we have

$$\alpha(s) = -\frac{1}{k(s)}n(s) - \frac{k'(s)}{k^2(s)\tau(s)}b(s) = -Rn + R'Tb$$

And

$$|\alpha(s)|^2 = R^2 + (R'T)^2 = C^2 \quad \square$$

$\Leftarrow$ :"

Let  $\beta(s) = \alpha(s) + Rn - R'Tb$ .

First take derivatives on  $R^2 + (R'T)^2 = C^2$ , we get

$$RR' + (R'T)(R'T)' = 0$$

Then, note that

$$\begin{aligned}
\beta'(s) &= t(s) + R'n + Rn' - (R'T)'b - (R'T)b' \\
&= t + R'n + R(-kt - \tau b) - (R'T)'b - (R'T)\tau n \\
&= t + R'n - R\left(\frac{t}{R} + \frac{b}{T}\right) - (R'T)'b - (R'T)\frac{n}{T} \\
&= t + R'n - t - \frac{R}{T}b - (R'T)'b - R'n \\
&= -\frac{R}{T}b - (R'T)'b = -b\left(\frac{R}{T} + (R'T)'\right)
\end{aligned}$$

Hence

$$\beta'(s) \cdot R'T = -b(RR' + (R'T)(R'T)') = 0$$

Since  $k' \neq 0$ ,  $\tau \neq 0$ , it implies  $\beta'(s) = 0$  and thus  $\beta(s)$  is a constant  $p_0 \in \mathbb{R}^3$ . So we have

$$|\alpha - p_0| = |\alpha - \beta| = C \quad \square$$