Left side

	position				
orientation	very left	left	center	right	very right
very left	middle forward	middle forward	slow forward	normal forward	normal forward
left	slow forward	slow forward	middle forward	slow forward	middle forward
center	normal forward	normal forward	normal forward	middle forward	slow forward
right	middle forward	slow forward	slow forward	slow backward	slow backward
very right	middle forward	slow forward	slow backward	middle backward	middle backward

Right side

	position				
orientation	very left	left	center	right	very right
very left	middle backward	middle backward	slow backward	slow forward	middle forward
left	slow backward	slow backward	slow forward	slow forward	middle forward
center	slow forward	middle forward	normal forward	normal forward	normal forward
right	middle forward	slow forward	middle forward	slow forward	slow forward
very right	normal forward	normal forward	slow forward	middle forward	middle forward

speed

- normal forward
- slow forward
- middle forward
- stop
- slow backward
- middle backward
- normal backmard

position

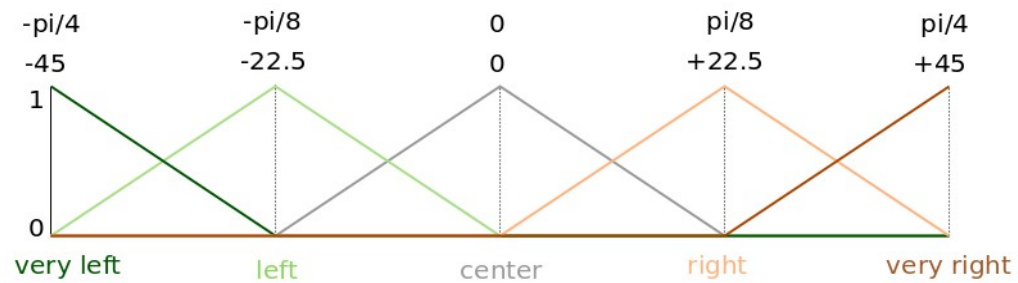bl=0　　bl=br/2　　bl=br　　br=bl/2　　br=0

1

0

very left　　left　　center　　right　　very right
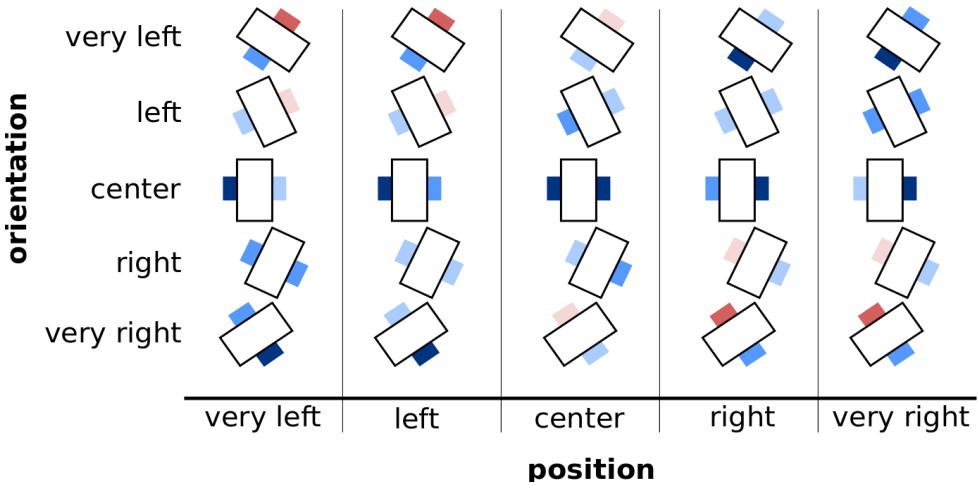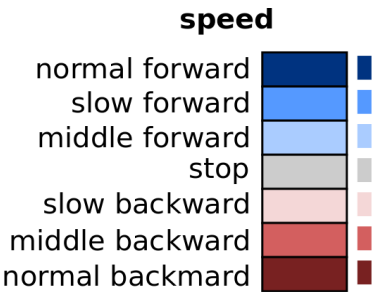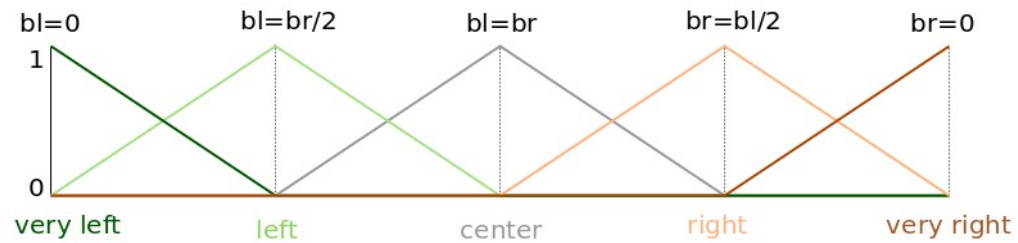
bl : |b| value of the left model
br : |b| value of the right model

orientation

-pi/4　　-pi/8　　0　　pi/8　　pi/4
-45　　-22.5　　0　　+22.5　　+45

1

0

very left　　left　　center　　right　　very right

speed

-max　　-2*max/3　　-max/3　　0　　max/3　　2*max/3　　max

1

0

normal
backward　　middle
backward　　slow
backward　　stop　　slow
forward　　middle
forward　　normal
forward