

Asst.Prof.Akrapong Patchararungruang, Ph.D.
Department of Computer Engineering
Faculty of Engineering
Kasetsart University

Sheet: /
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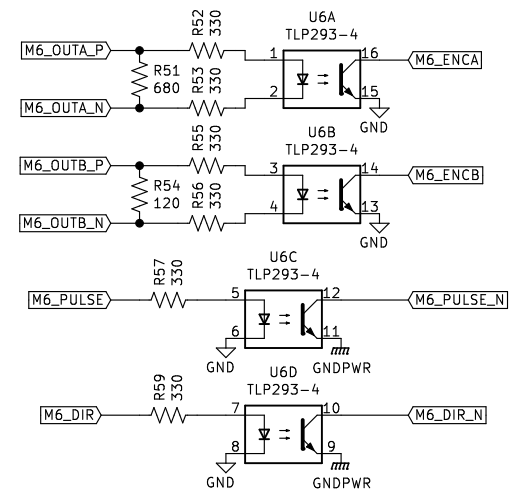
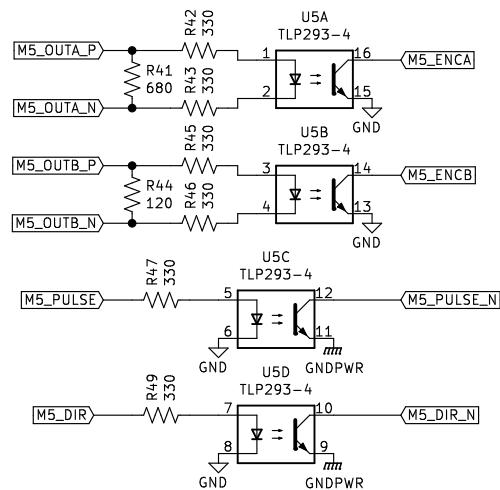
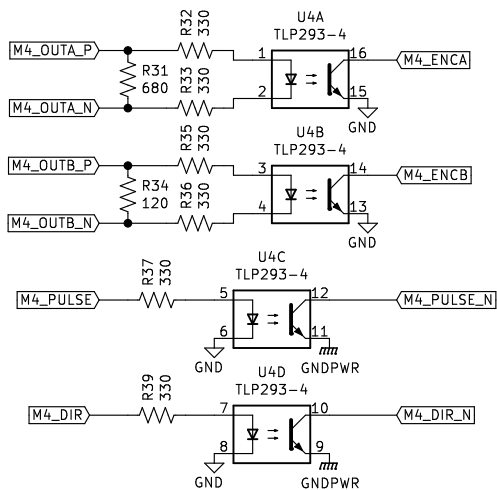
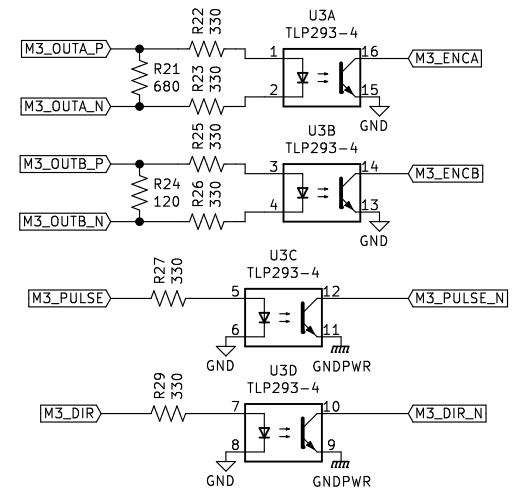
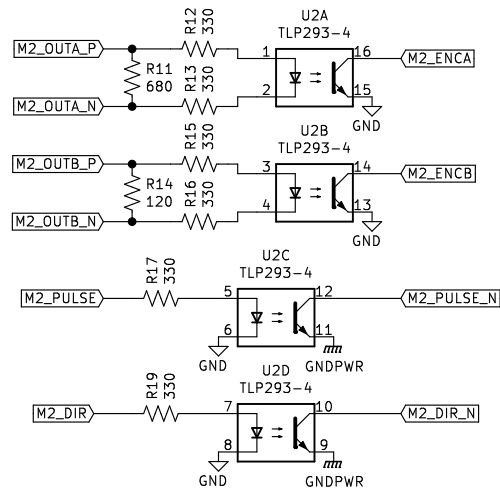
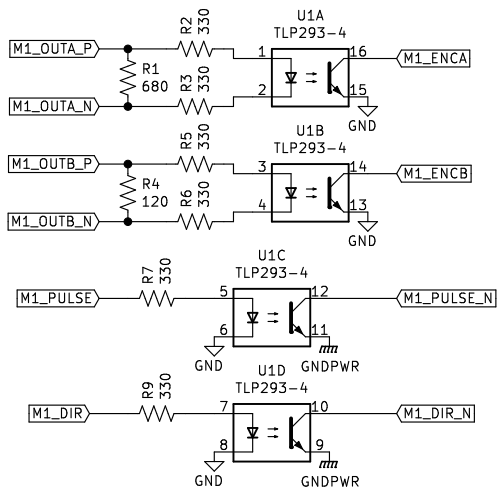
Title: 6DOF Parallel Robot

Size: A4 Date: 2019-September-26

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Id: 1/6



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Sheet: /rs422_interface/

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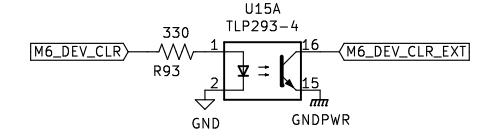
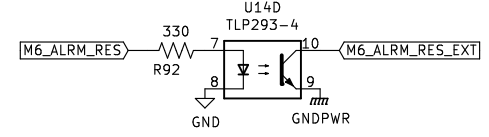
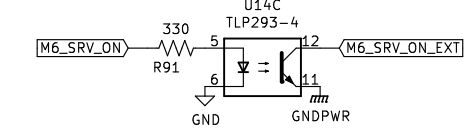
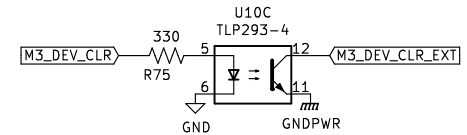
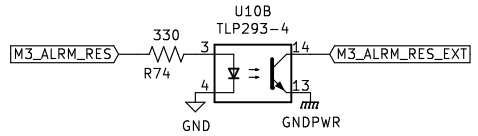
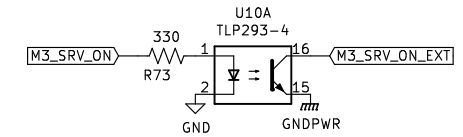
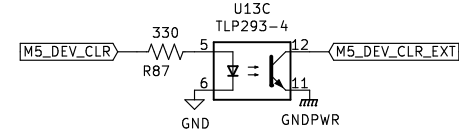
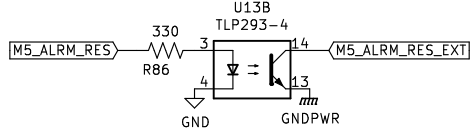
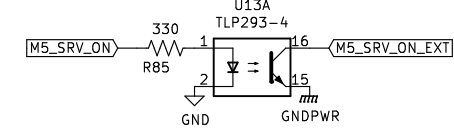
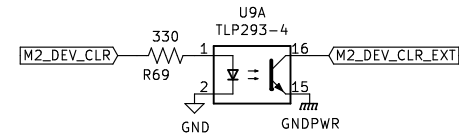
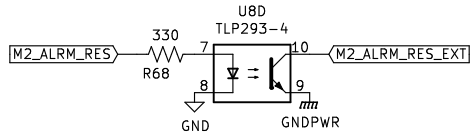
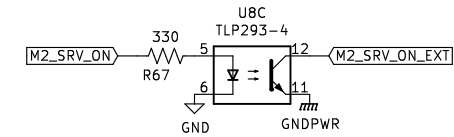
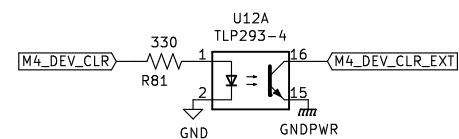
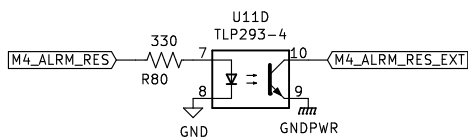
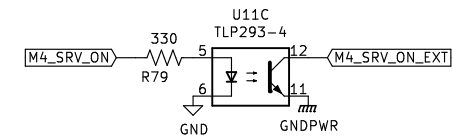
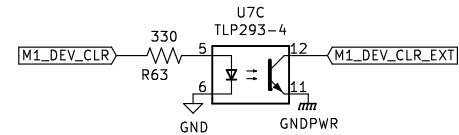
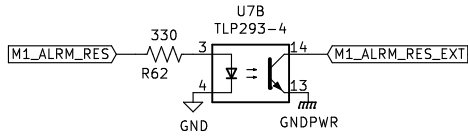
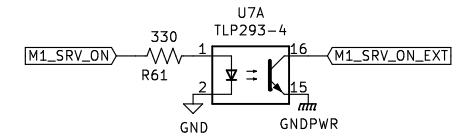
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Id: 2/6



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Sheet: /motor_ctrl_signal/
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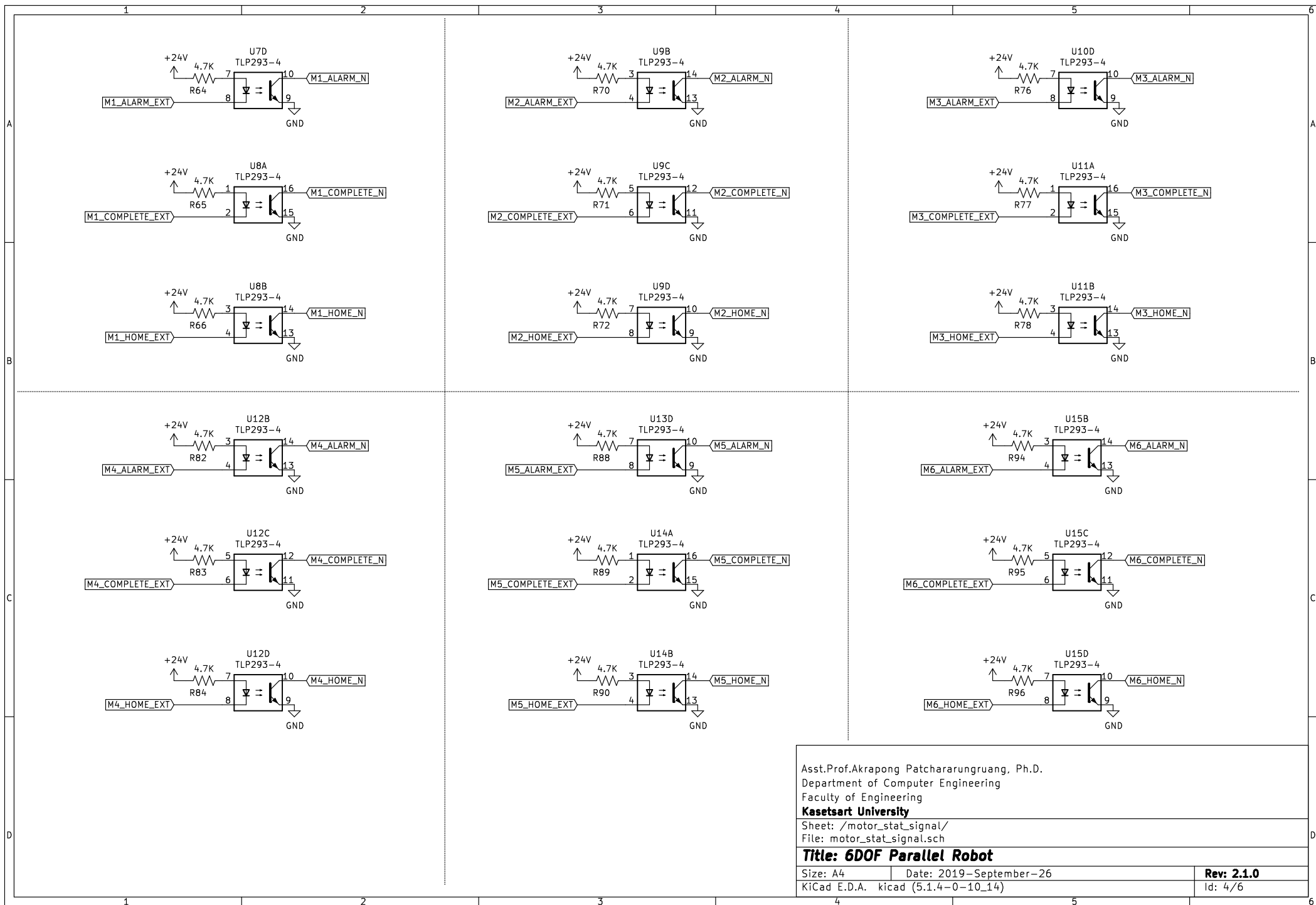
Title: 6DOF Parallel Robot

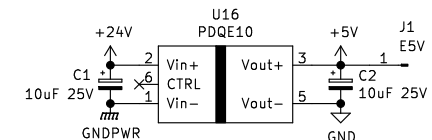
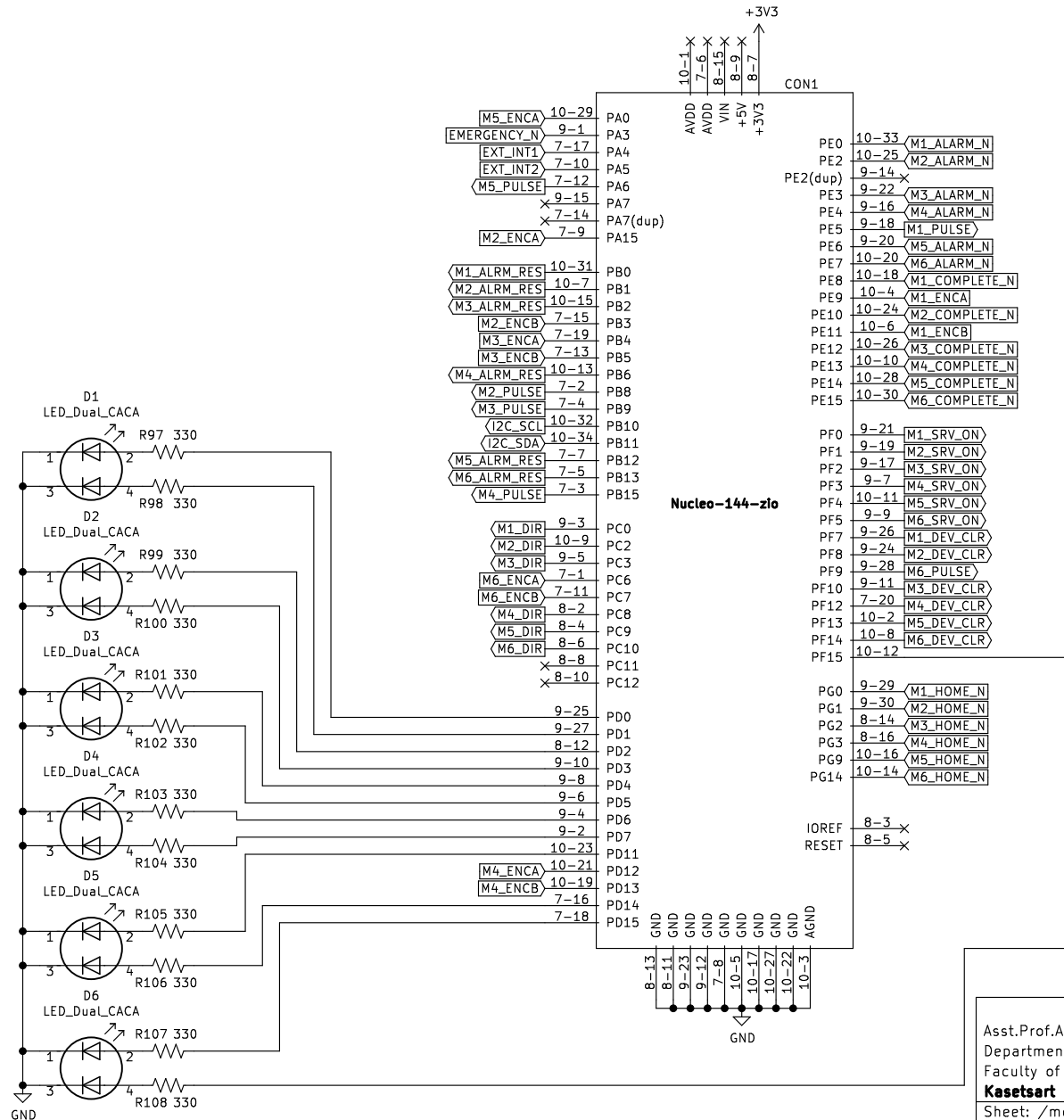
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Rev: 2.1.0

Id: 3/6





Extra connection to Morpho pin CN11-6

Extra connection to Morpho pin CN11-30

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Sheet: /mcu/
File: mcu.sch

Title: 6DOF Parallel Robot

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Rev: 2.1.0

Id: 5/6

