

# MHM Approximations of discrete fracture networks

Philippe R B Devloo<sup>1</sup>   Chensong Zhang<sup>2</sup>

<sup>1</sup>Faculdade de Engenharia Civil, Arquitetura e Urbanismo  
UNICAMP

<sup>2</sup>CAS-China

BISEC, Beijing

# Outline

## 1 MHM Formulation

- Simulating multiscale problems with MHM

## 2 Apply MHM to Fracture Networks

- Problem Statement
- Add fractures to MHM-HDiv
- Substructuring MHM-H(Div) + Fractures

## 3 Implementation

- Fracture Preprocessor
- Gmsh programming
- Finite element simulation

## 4 Numerical Results

- One fracture
- A two fracture simulation

• Verify the influence of the layout of the MHM domain



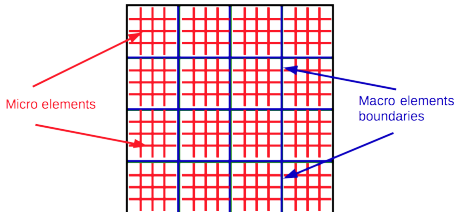
# The Multiscale Hybrid Method (MHM)

- MHM was conceived by Christopher Harder, F. Valentin and D. Paredes
- MHM is a numerical approximation technique conceived for simulating problems involving multiple scales
- It is a general concept that can be applied to different problems in computational mechanics
  - Flow through porous media
  - Elasticity
  - Maxwell equations



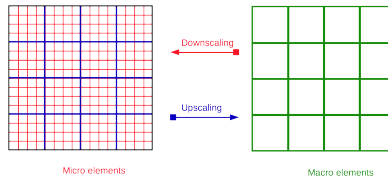
# General concept of MHM

- MHM approximations are divided in two parts:
  - Approximation of the dual (flux) variable at the interface between *macro* elements
  - Approximation of the conservation law (flux and pressure) at the interior of each macro element



# General concept of MHM

- MHM approximations contain two scaling operators:
- **Downscaling** (Coarse scale  $\rightarrow$  Fine scale)
  - The fine scale behaviour is captured by the numerical simulation at the interior of the *macro* elements.
- **Upscaling** (Fine scale  $\rightarrow$  Coarse scale)
  - The fine scale properties of the solution are transferred to the global problem associated with the fluxes.



## Mixed approximation of Darcy's law

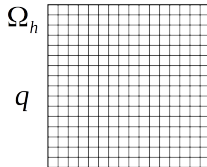
Find  $(\mathbf{q}, p) \in H(\text{div})(\Omega) \times L^2(\Omega)$  such that

$$\begin{aligned} \int_{\Omega} K^{-1} \mathbf{q} \cdot \boldsymbol{\tau} dV + \int_{\Omega} p \operatorname{div}(\boldsymbol{\tau}) dV &= \int_{\partial\Omega_D} p_D(\boldsymbol{\tau} \cdot \mathbf{n}) ds \\ \int_{\Omega} \operatorname{div}(\mathbf{q}) z dV &= \int_{\Omega} z f dV \end{aligned}$$

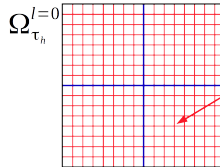
for all  $(\boldsymbol{\tau}, z) \in H(\text{div})(\Omega) \times L^2(\Omega)$  (+ b.c.)

# MHM with Mixed approximation

The flux functions into  $\sigma$  internal functions and functions associated with  $\lambda$  fluxes between *macro* elements,  $\mathbf{q} = \sigma + \lambda$

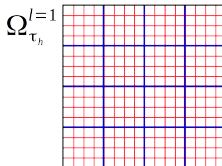


Global mixed partition

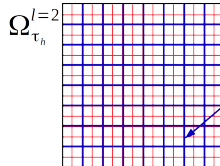


MHM-HDiv partition with skeleton at  $l = 0$

$\sigma$   
 Micro elements



MHM-HDiv partition with skeleton at  $l = 1$

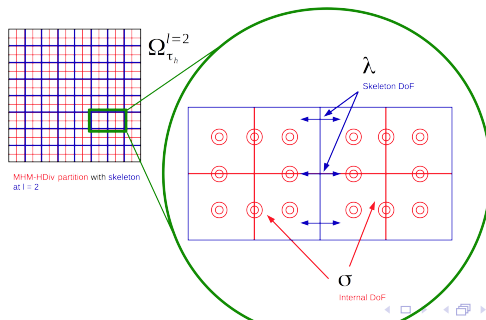


MHM-HDiv partition with skeleton at  $l = 2$

$\lambda$   
 Skeleton elements

# MHM with Mixed Approximation - shape function restraints

- MHM with mixed approximation is equivalent to apply shape function restraints to the boundary fluxes.
- The multiplying coefficients of the fluxes ( $\sigma$ ) are dependent on the multiplying coefficients of the boundary flux  $\lambda$ .
- The restraints ensure the strong continuity between the micro fluxes associated with two macro elements.



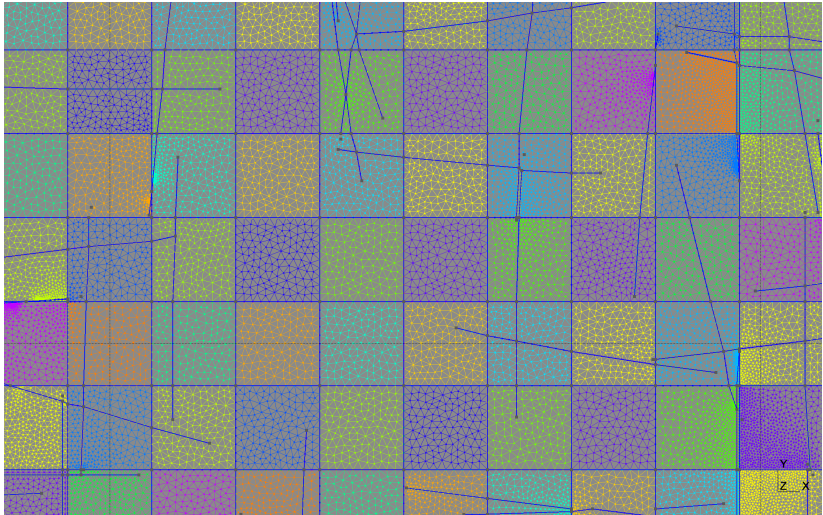


## Problem statement

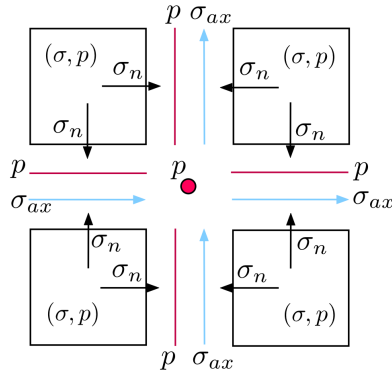
Consider a fluid flow through porous media with a superposed fracture network:

$$\begin{aligned}
 \int_{T_2} \vec{\psi}_2 \cdot K_2^{-1} \vec{\sigma}_2 d\Omega - \int_{T_2} \operatorname{div}(\vec{\psi}_d) p_2 d\Omega + \int_{T_1} \Sigma(\vec{\psi}_2 \cdot n) p_{\Gamma_2} d\omega &= - \int_{\partial\Omega_D} p_D \vec{\psi}_2 \cdot n d\omega \\
 - \int_T \operatorname{div}(\vec{\sigma}_2) \varphi_2 d\Omega &= \int f \varphi_d d\Omega \\
 \int_{T_1} \vec{\psi}_1 \cdot K_1^{-1} \vec{\sigma}_1 dT_1 - \int_{T_1} \operatorname{div}(\vec{\psi}_1) p_1 dT_1 + \int_{T_0} \Sigma(\vec{\psi}_1 \cdot n) p_0 dT_0 &= 0 \\
 - \int_{T_1} \operatorname{div}(\vec{\sigma}_1) \varphi_1 + \int_{\Gamma_2} \varphi_1 \Sigma \vec{\sigma}_2 \cdot n &= 0 \\
 \int_{T_0} \varphi_0 \Sigma(\vec{\sigma}_1 \cdot n) dT_0 &= 0
 \end{aligned}$$

# Problem statement

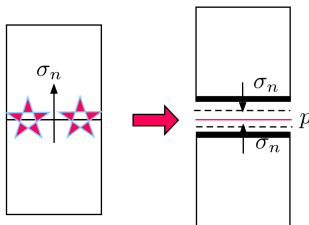


# H(div) Configuration with fracture flow



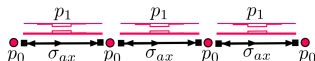
# How to incorporate fractures in MHM-HDiv

- Starting from a  $H(\text{div})$  approximation
- Split the continuous  $H(\text{div})$  flux function - add a pressure Lagrange multiplier



## Adding a one dimensional flux/pressure pair

- After creating the pressure Lagrange element
- Superpose a pressure flux pair
- Add an H(Div) wrapper
- Add a zero dimensional pressure Lagrange Multiplier



## Statically condense internal equations

- order the equations with the internal degrees of freedom first

$$\begin{bmatrix} K_{11} & K_{12} \\ K_{21} & K_{22} \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} = \begin{bmatrix} F_1 \\ F_2 \end{bmatrix}$$

- reduce the equations

$$[K_{22} - K_{21}K_{11}^{-1}K_{12}] [u_2] = [F_2 - K_{21}K_{11}^{-1}F_1]$$

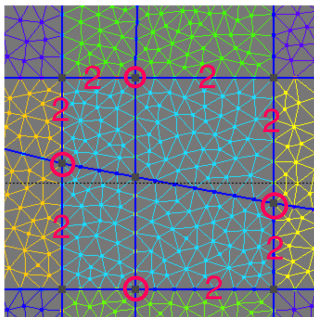
- Compute the internal degrees of freedom

$$[u_1] = [K_{11}^{-1}] [F_1] - [K_{12}] [u_2]$$



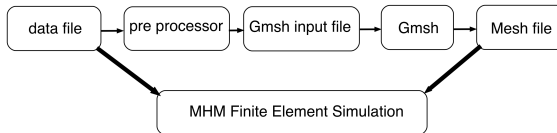
## Reducing the equation of an MHM subdomain

- There are 20 external equations



# Generating an MHM+fracture approximation

- MHM+frac simulations are generated by the interaction of three computational tools
- Input data
  - is a unique file which defines the fracture configuration





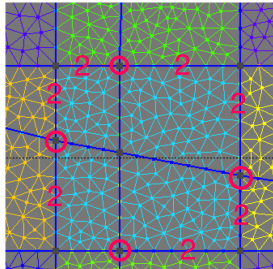
# Fracture pre processor

- Transforms a fracture definition file into a Gmsh input file

```
0 0 9 9 - Domain Size
13 - Number of MHM domains
0.33 0.003 - Element size and Singular Element size
#
1 1 - simulation type (0 = Steady State, 1 = time evolution) initial_pressure
#
5 - number of materials
"Darcy" 2 1 flow 1 1 - name dimension material_id material_type rho Perm
"BCIN" 1 -1 boundary 0 1 - name dimension material_id bc_type value
"BCOUT" 1 -2 boundary 0 0 - name dimension material_id bc_type value
"BCNOFLOW" 1 -3 boundary 1 0 - name dimension material_id bc_type value
"BC" 1 -4 boundary 1 0 - name dimension material_id bc_type value
#
2 - number of timestep series
0.1 20 - delt nsteps
1. 20 - delt nsteps
..
```

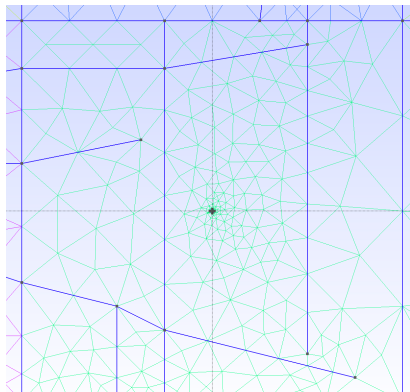
# Gmsh programming

- Gmsh allow to associate *physical groups* to points, lines, surfaces and volumes
- The fracture preprocessor generates commands associating physical groups with sections of fractures, MHM boundaries and MHM subdomains
- Internal fractures are *embedded* in MHM domains



# Gmsh programming

- The input file to Gmsh can be modified
  - to incorporate well
  - to modify boundary conditions

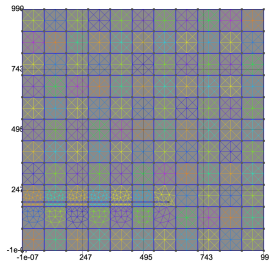


## Gmsh will crash

- when fracture lines overlap
- when a point of a fracture is too close to another fracture
- when a fracture line coincides with the boundary of an MHM domain

## Putting it all together

- the fracture definition file and Gmsh output file are used to construct an MHM simulation
- Elements and MHM boundaries are grouped using TPZRefPattern objects



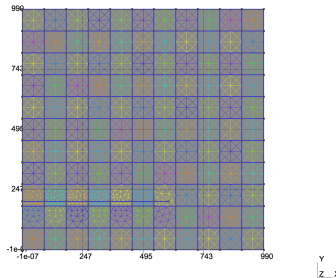
# Numerical Results

- Some simulations are qualitative
- Some are comparative
- Some verify the robustness of the approximation technique



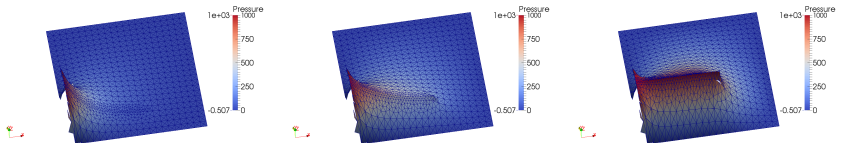
# A single fracture in a reservoir

- Study the effect of the permeability of the fracture
- Domain  $900 \times 900$ , permeability  $K=1$



# Pressure profile as function of fracture permeability

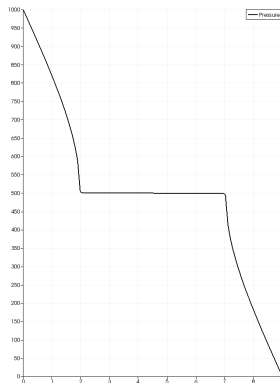
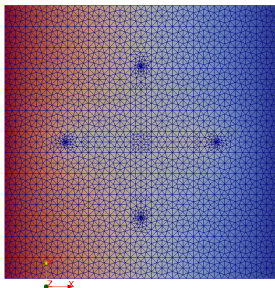
- Fracture permeability  $K=1$ ,  $K=1000$ ,  $K=100000$





## A two fracture simulation

- $9 \times 9$  reservoir. A vertical and horizontal fracture from 2 to 7, permeability  $K=1$ , total fracture permeability  $K=100$



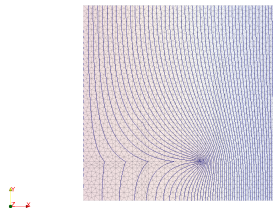
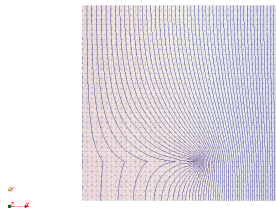
## A two fracture simulation

- Comparative results with a finite volume simulator.
- MHM linear resulted in 841 equations

Author	Fluid Flux
Wenchao	1.2892
MHM quadratic	1.285
MHM linear	1.284

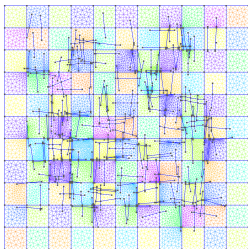
## A fracture on the skeleton mesh

- Depending on the MHM layout a fracture may coincide with a MHM boundary
- Boundary flux integrated was 1452 versus 1461



# A complex fracture network

- Around 250 fracture in random patterns



y  
x

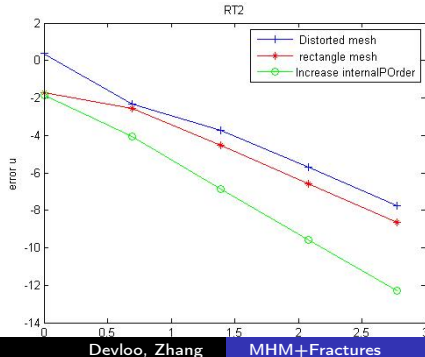
# Objectives

- Verify if the  $H(\text{Div})$  approximation spaces can be used for the construction of robust and convergent tensor space approximations
- Verify if enhanced convergence rates for the primal variable are applicable to tensor space approximations
- Work developed with
  - Prof Jun Hu and Shudan Tian
  - Prof Sonia M Gomes and Pablo Carvalho



## Results obtained

- The tensor space approximations in standard configuration yield optimal convergence rates, even for distorted meshes
- Increasing the internal order of approximation improves the convergence rate, but optimal rates are not obtained



# Summary

- Discrete fracture networks in conjunction with MHM were developed and implemented
- The combination of a general data file with Gmsh resulted in a very general approach
- MHM can also be very efficient for the simulation of time dependent problems
- Tensor spaces have been implemented and certified



## Future Work

- Can  $\text{MHM-}H(\text{div})$  be used as a preconditioner for the full scale solution?
- Can the approach for fracture networks be extended to three dimensional configurations?
- Can the convergence rates of the tensor spaces be justified by theoretical analysis?





## Acknowledgements

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