

MHM Approximations of discrete fracture networks

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Outline

1 MHM Formulation

- Simulating multiscale problems with MHM

2 Apply MHM to Fracture Networks

- Problem Statement
- Add fractures to MHM-HDiv
- Substructuring MHM-H(Div) + Fractures

3 Implementation

- Fracture Preprocessor
- Gmsh programming
- Finite element simulation

4 Numerical Results

- One fracture
- A two fracture simulation

• Verify the influence of the layout of the MHM domain

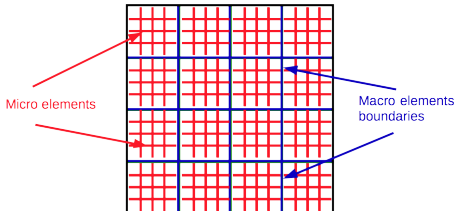
The Multiscale Hybrid Method (MHM)

- MHM was conceived by Christopher Harder, F. Valentin and D. Paredes
- MHM is a numerical approximation technique conceived for simulating problems involving multiple scales
- It is a general concept that can be applied to different problems in computational mechanics
 - Flow through porous media
 - Elasticity
 - Maxwell equations



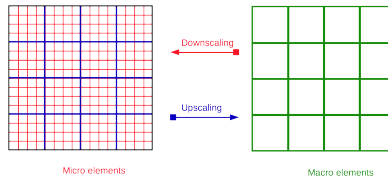
General concept of MHM

- MHM approximations are divided in two parts:
 - Approximation of the dual (flux) variable at the interface between *macro* elements
 - Approximation of the conservation law (flux and pressure) at the interior of each macro element



General concept of MHM

- MHM approximations contain two scaling operators:
- **Downscaling** (Coarse scale \rightarrow Fine scale)
 - The fine scale behaviour is captured by the numerical simulation at the interior of the *macro* elements.
- **Upscaling** (Fine scale \rightarrow Coarse scale)
 - The fine scale properties of the solution are transferred to the global problem associated with the fluxes.



Mixed approximation of Darcy's law

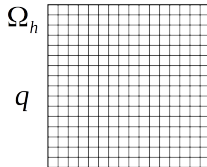
Find $(\mathbf{q}, p) \in H(\text{div})(\Omega) \times L^2(\Omega)$ such that

$$\begin{aligned} \int_{\Omega} K^{-1} \mathbf{q} \cdot \boldsymbol{\tau} dV + \int_{\Omega} p \operatorname{div}(\boldsymbol{\tau}) dV &= \int_{\partial\Omega_D} p_D(\boldsymbol{\tau} \cdot \mathbf{n}) ds \\ \int_{\Omega} \operatorname{div}(\mathbf{q}) z dV &= \int_{\Omega} z f dV \end{aligned}$$

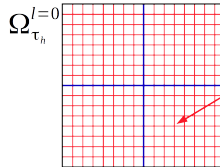
for all $(\boldsymbol{\tau}, z) \in H(\text{div})(\Omega) \times L^2(\Omega)$ (+ b.c.)

MHM with Mixed approximation

The flux functions into σ internal functions and functions associated with λ fluxes between *macro* elements, $\mathbf{q} = \sigma + \lambda$

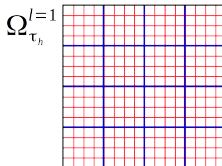


Global mixed partition

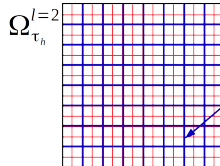


MHM-HDiv partition with skeleton at $l=0$

σ
 Micro elements



MHM-HDiv partition with skeleton at $l=1$



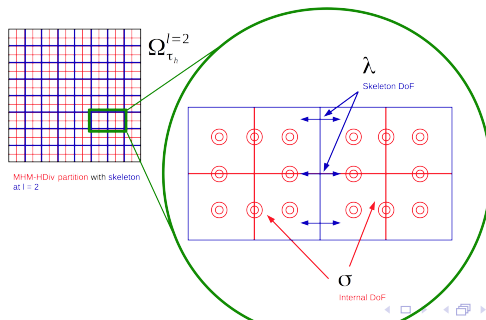
MHM-HDiv partition with skeleton at $l=2$

λ
 Skeleton elements

MHM with Mixed Approximation - shape function restraints

?

- MHM with mixed approximation is equivalent to apply shape function restraints to the boundary fluxes.
- The multiplying coefficients of the fluxes (σ) are dependent on the multiplying coefficients of the boundary flux λ .
- The restraints ensure the strong continuity between the micro fluxes associated with two macro elements.



Problem statement

Consider a fluid flow through porous media with a superposed fracture network:

$$\int_{T_2} \vec{\psi}_2 \cdot K_2^{-1} \vec{\sigma}_2 d\Omega - \int_{T_2} \operatorname{div}(\vec{\psi}_d) p_2 d\Omega + \int_{T_1} \Sigma(\vec{\psi}_2 \cdot n) p_{\Gamma_2} d\omega = - \int_{\partial\Omega_D} p_D \vec{\nu} \cdot \vec{\nu} d\omega$$

$$- \int_T \operatorname{div}(\vec{\sigma}_2) \varphi_2 d\Omega = \int f \varphi_d d\Omega$$

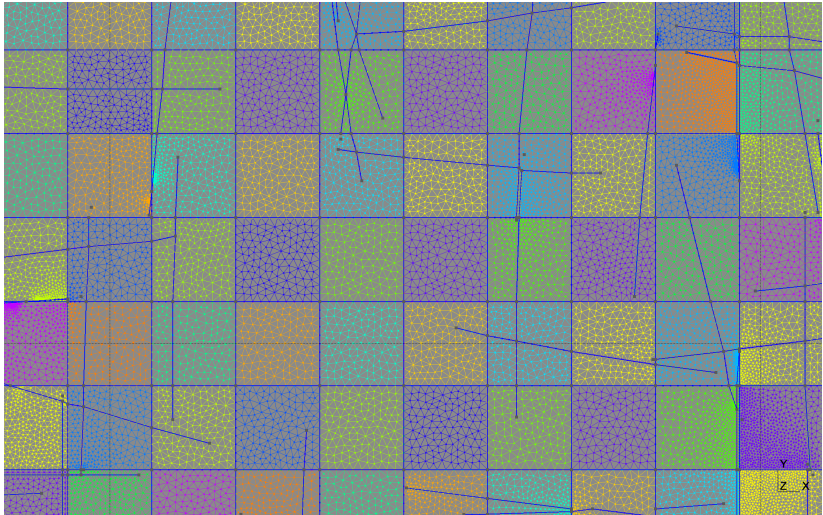
$$\int_{T_1} \vec{\psi}_1 \cdot K_1^{-1} \vec{\sigma}_1 dT_1 - \int_{T_1} \operatorname{div}(\vec{\psi}_1) p_1 dT_1 + \int_{T_0} \Sigma(\vec{\psi}_1 \cdot n) p_0 dT_0 = 0$$

$$- \int_{T_1} \operatorname{div}(\vec{\sigma}_1) \varphi_1 + \int_{\Gamma_2} \varphi_1 \Sigma \vec{\sigma}_2 \cdot n = 0$$

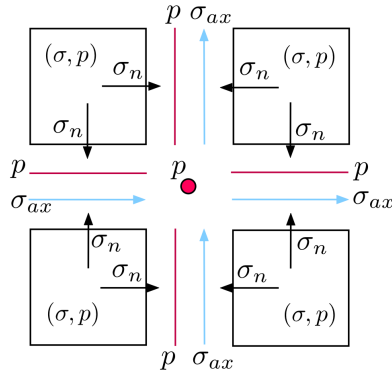
$$\int_{T_0} \varphi_0 \Sigma(\vec{\sigma}_1 \cdot n) dT_0 = 0$$

?

Problem statement

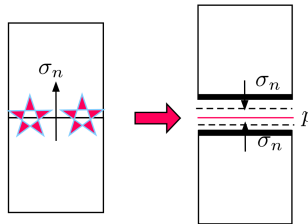


H(div) Configuration with fracture flow



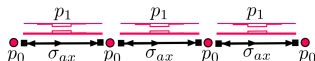
How to incorporate fractures in MHM-HDiv

- Starting from a $H(\text{div})$ approximation
- Split the continuous $H(\text{div})$ flux function - add a pressure Lagrange multiplier



Adding a one dimensional flux/pressure pair

- After creating the pressure Lagrange element
- Superpose a pressure flux pair
- Add an H(Div) wrapper
- Add a zero dimensional pressure Lagrange Multiplier



Statically condense internal equations

- order the equations with the internal degrees of freedom first

$$\begin{bmatrix} K_{11} & K_{12} \\ K_{21} & K_{22} \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} = \begin{bmatrix} F_1 \\ F_2 \end{bmatrix}$$

- reduce the equations

$$[K_{22} - K_{21}K_{11}^{-1}K_{12}] [u_2] = [F_2 - K_{21}K_{11}^{-1}F_1]$$

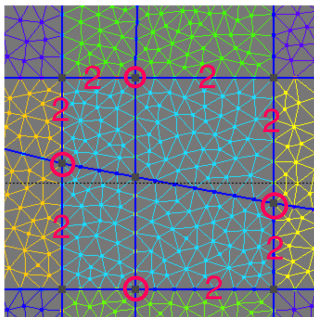
- Compute the internal degrees of freedom

$$[u_1] = [K_{11}^{-1}] [F_1] - [K_{12}] [u_2]$$



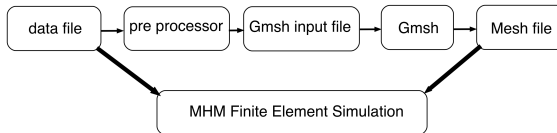
Reducing the equation of an MHM subdomain

- There are 20 external equations



Generating an MHM+fracture approximation

- MHM+frac simulations are generated by the interaction of three computational tools
- Input data
 - is a unique file which defines the fracture configuration



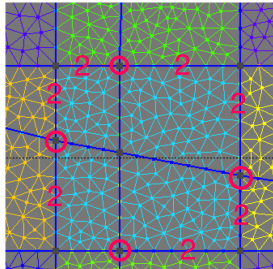
Fracture pre processor

- Transforms a fracture definition file into a Gmsh input file

```
0 0 9 9 - Domain Size
13 - Number of MHM domains
0.33 0.003 - Element size and Singular Element size
#
1 1 - simulation type (0 = Steady State, 1 = time evolution) initial_pressure
#
5 - number of materials
"Darcy" 2 1 flow 1 1 - name dimension material_id material_type rho Perm
"BCIN" 1 -1 boundary 0 1 - name dimension material_id bc_type value
"BCOUT" 1 -2 boundary 0 0 - name dimension material_id bc_type value
"BCNOFLOW" 1 -3 boundary 1 0 - name dimension material_id bc_type value
"BC" 1 -4 boundary 1 0 - name dimension material_id bc_type value
#
2 - number of timestep series
0.1 20 - delt nsteps
1. 20 - delt nsteps
..
```

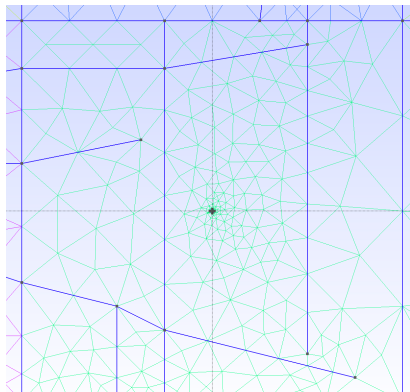
Gmsh programming

- Gmsh allow to associate *physical groups* to points, lines, surfaces and volumes
- The fracture preprocessor generates commands associating physical groups with sections of fractures, MHM boundaries and MHM subdomains
- Internal fractures are *embedded* in MHM domains



Gmsh programming

- The input file to Gmsh can be modified
 - to incorporate well
 - to modify boundary conditions

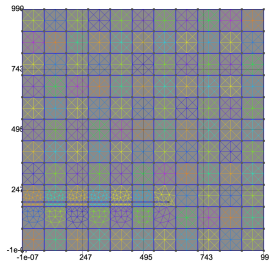


Gmsh will crash

- when fracture lines overlap
- when a point of a fracture is too close to another fracture
- when a fracture line coincides with the boundary of an MHM domain

Putting it all together

- the fracture definition file and Gmsh output file are used to construct an MHM simulation
- Elements and MHM boundaries are grouped using TPZRefPattern objects



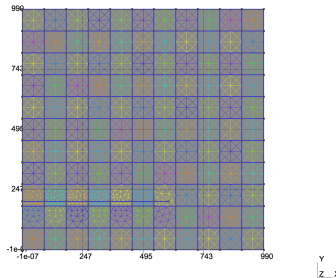
Numerical Results

- Some simulations are qualitative
- Some are comparative
- Some verify the robustness of the approximation technique



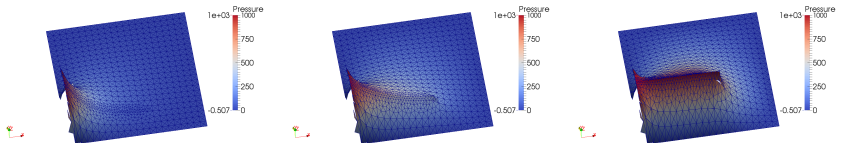
A single fracture in a reservoir

- Study the effect of the permeability of the fracture
- Domain 900×900 , permeability $K=1$



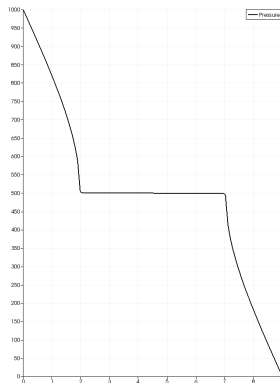
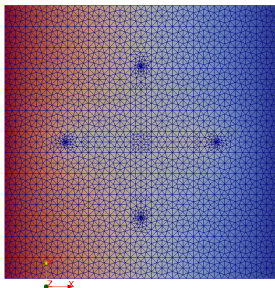
Pressure profile as function of fracture permeability

- Fracture permeability $K=1$, $K=1000$, $K=100000$



A two fracture simulation

- 9 × 9 reservoir. A vertical and horizontal fracture from 2 to 7, permeability $K=1$, total fracture permeability $K=100$



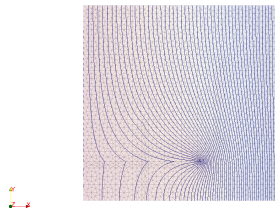
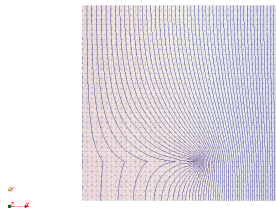
A two fracture simulation

- Comparative results with a finite volume simulator.
- MHM linear resulted in 841 equations

Author	Fluid Flux
Wenchao	1.2892
MHM quadratic	1.285
MHM linear	1.284

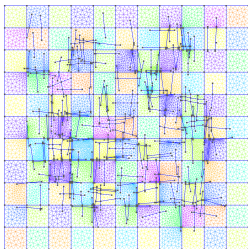
A fracture on the skeleton mesh

- Depending on the MHM layout a fracture may coincide with a MHM boundary
- Boundary flux integrated was 1452 versus 1461



A complex fracture network

- Around 250 fracture in random patterns



y
x

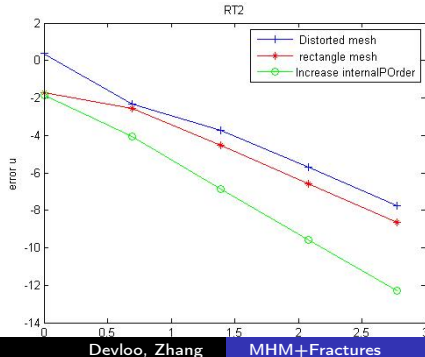
Objectives

- Verify if the $H(\text{Div})$ approximation spaces can be used for the construction of robust and convergent tensor space approximations
- Verify if enhanced convergence rates for the primal variable are applicable to tensor space approximations
- Work developed with
 - Prof Jun Hu and Shudan Tian
 - Prof Sonia M Gomes and Pablo Carvalho



Results obtained

- The tensor space approximations in standard configuration yield optimal convergence rates, even for distorted meshes
- Increasing the internal order of approximation improves the convergence rate, but optimal rates are not obtained



Summary

- Discrete fracture networks in conjunction with MHM were developed and implemented
- The combination of a general data file with Gmsh resulted in a very general approach
- MHM can also be very efficient for the simulation of time dependent problems
- Tensor spaces have been implemented and certified



Future Work

- Can $\text{MHM-}H(\text{div})$ be used as a preconditioner for the full scale solution?
- Can the approach for fracture networks be extended to three dimensional configurations?
- Can the convergence rates of the tensor spaces be justified by theoretical analysis?



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