

# Bowyer-Watson Algorithm

Delaunay Triangulation

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# Bowyer-Watson Algorithm



- The Bowyer–Watson algorithm is a method for computing the Delaunay triangulation of a finite set of points.
- The algorithm can be also used to obtain a Voronoi diagram of the points.
- The Bowyer–Watson algorithm is an **incremental algorithm**. It works by adding points, one at a time, to a valid Delaunay triangulation of a subset of the desired points.
- **Adrian Bowyer** and **David Watson** devised it independently of each other at the same time, and each published a paper on it in the same issue of **The Computer Journal**.

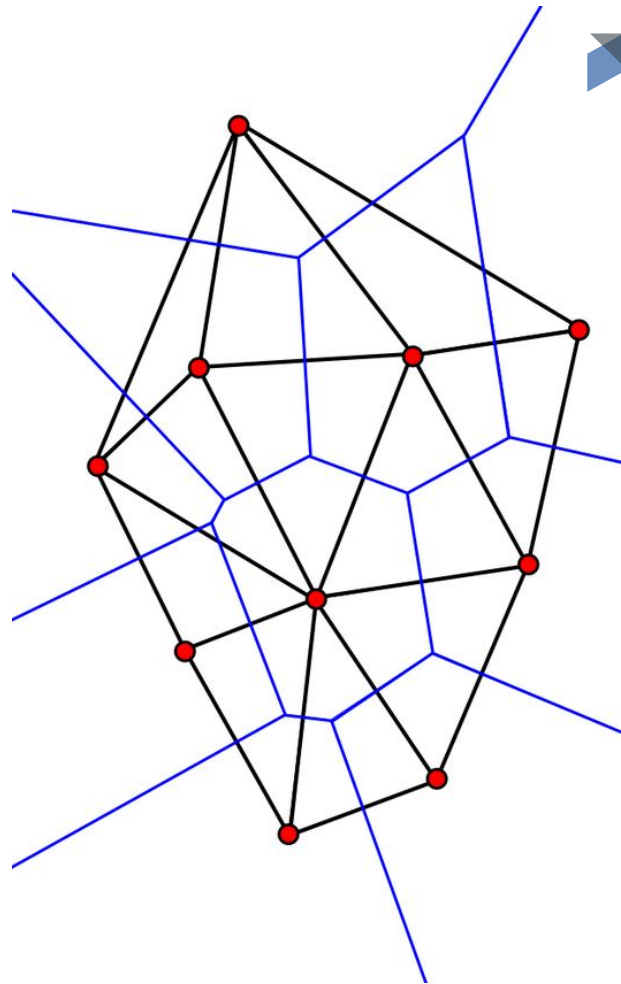
# Bowyer-Watson Algorithm



- Bowyer-Watson algorithm can be used to compute Delaunay Triangulation in  $k$  dimensional Euclidean Space ( $k \geq 2$ ).
- We will mainly focus on its implementation and analysis in 2 dimensional Euclidean Space.
- In  $k$  dimension the algorithm has  $O(n^{1+1/k})$  running time.
- We will also look at how we can obtain the Convex Hull and Voronoi Diagram of a set of points from their Delaunay Triangulation.

# Delaunay Triangulation

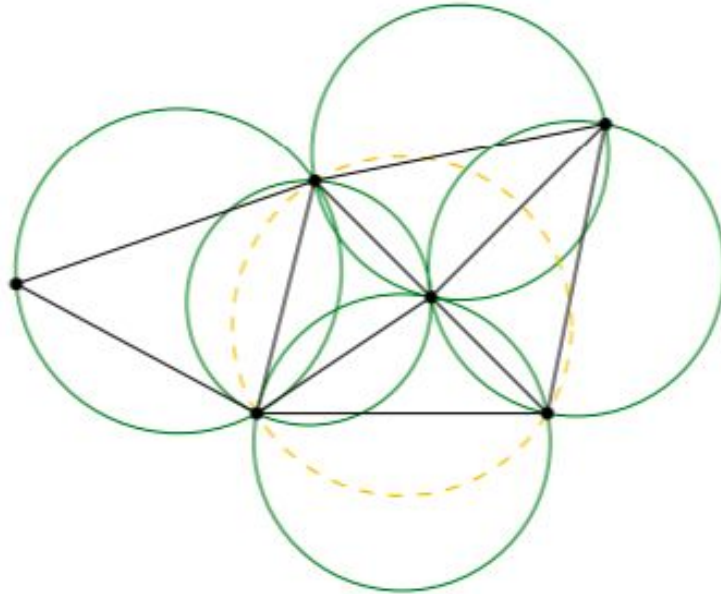
- Delaunay Triangulation is the graph dual of Voronoi Diagram (VoD).
- For each face of the primal graph (VoD), we create a vertex, and then we add an edge between two such vertices if their faces are adjacent in VoD.
- **Uniqueness:** The Delaunay triangulation is unique given no four sites are co-circular.



# Circumcircle Criteria



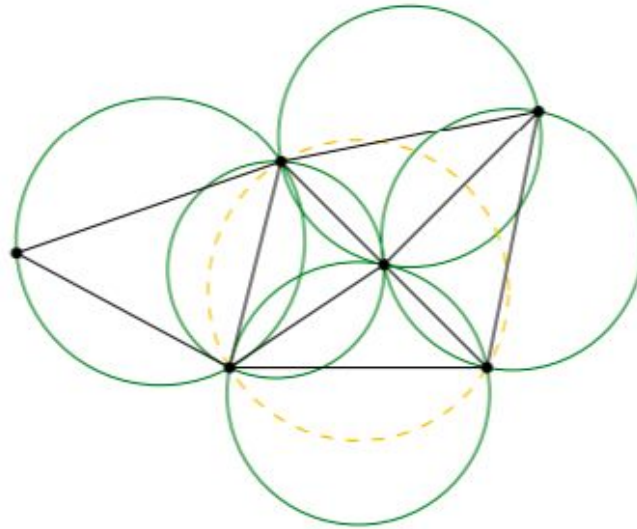
- A triangulation of  $N > 2$  points is Delaunay if and only if the circumcircle of every interior triangle is point free.



# Edge Criteria



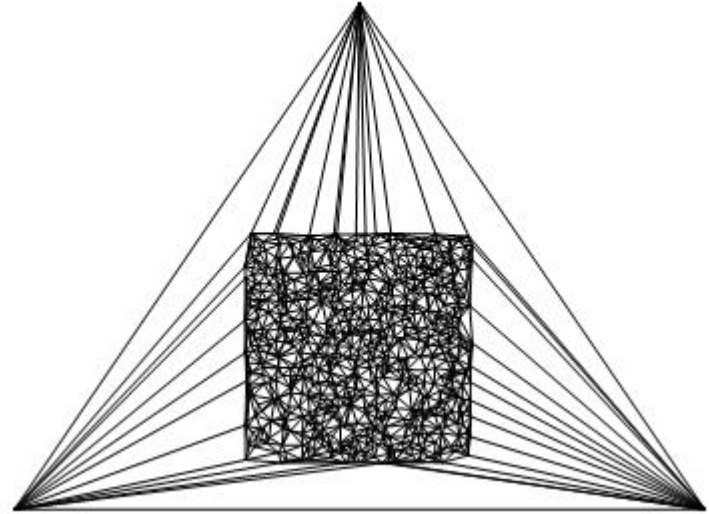
- The edge is in Delaunay Triangulation if and only if there exists an empty circle passing through its endpoints. An edge satisfying this property is said to be Delaunay.



# The Algorithm : Base Case



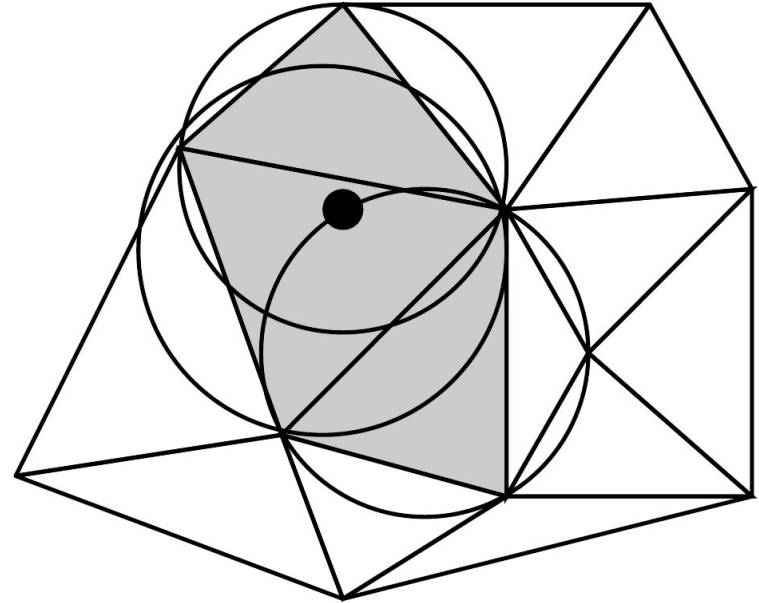
- Start with a Delaunay Triangulation whose convex Hull contains all the given set of points.
- Add a **super triangle** large enough to completely contain all the points.
- Super triangle should not affect the global delaunay triangulation of inner points.



# The Algorithm : Adding New Point



- Find set of all the triangles whose circumcircle encloses the new vertex (say  $T_{bad}$ ).
- The triangles in  $T_{bad}$  no longer satisfy the **Circumcircle Criteria** hence are no longer Delaunay.
- All other triangles (not in  $T_{bad}$ ) remain Delaunay triangles, and are left undisturbed.

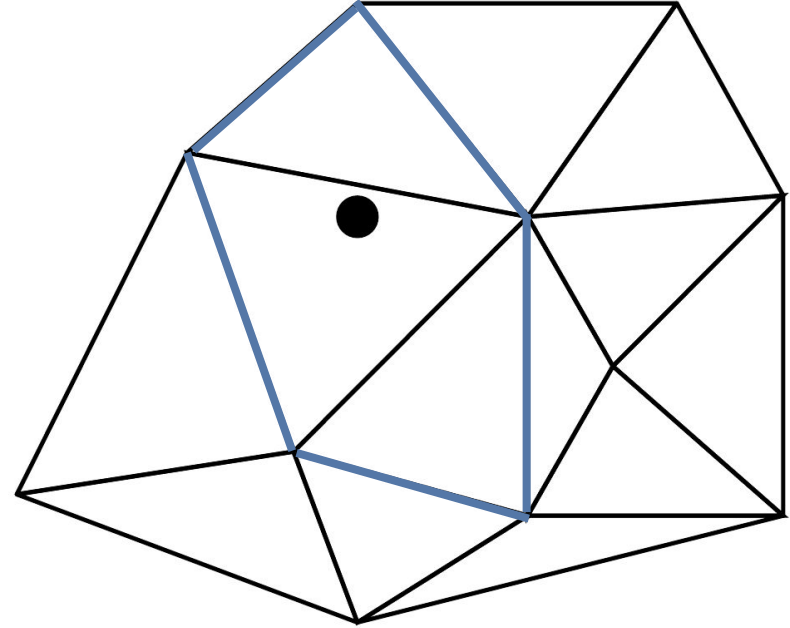




# The Algorithm : Adding New Point



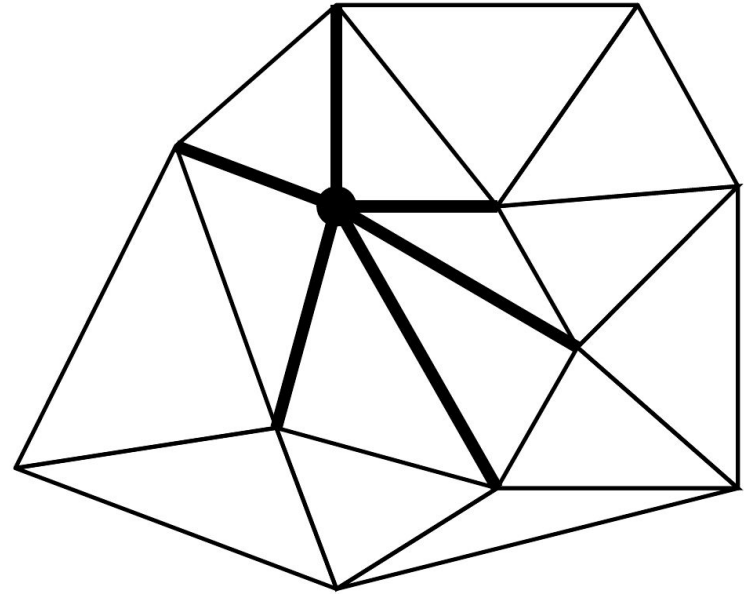
- The set of deleted triangles collectively form an insertion polygon, which is left vacant by the deletion of these triangles.
- Insertion polygon is shown in the figure.



# The Algorithm : Adding New Point



- The Bowyer-Watson algorithm connects each vertex of the insertion polyhedron to the new vertex with a new edge.

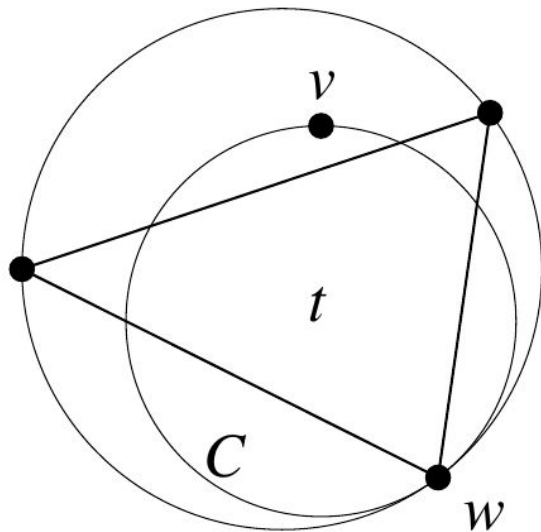


# Correctness



**Theorem:** Let  $\mathbf{v}$  be a newly inserted vertex, let  $\mathbf{t}$  be a triangle that is deleted because its circumcircle encloses  $\mathbf{v}$ , and let  $\mathbf{w}$  be a vertex of  $\mathbf{t}$ . Then  $\mathbf{vw}$  is Delaunay.

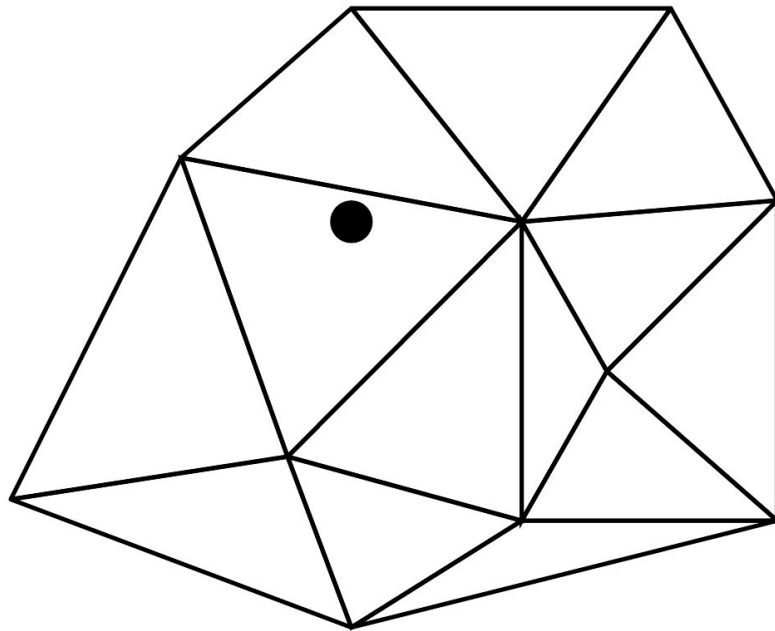
**Proof:** The circumcircle of  $\mathbf{t}$  encloses no vertex but  $\mathbf{v}$ . Let  $\mathbf{C}$  be the circle that passes through  $\mathbf{v}$  and  $\mathbf{w}$ , and is tangent to the circumcircle of  $\mathbf{t}$  at  $\mathbf{w}$ .  $\mathbf{C}$  is empty, so  $\mathbf{vw}$  is Delaunay.



# Data Structures



- List of Triangles
- Triangle
  - List of **vertices**
  - List of **edges**
  - List of **neighbours** - pair(triangle, edge)
  - **Circumcircle** (radius, center)
  - Boolean value **isDeleted**



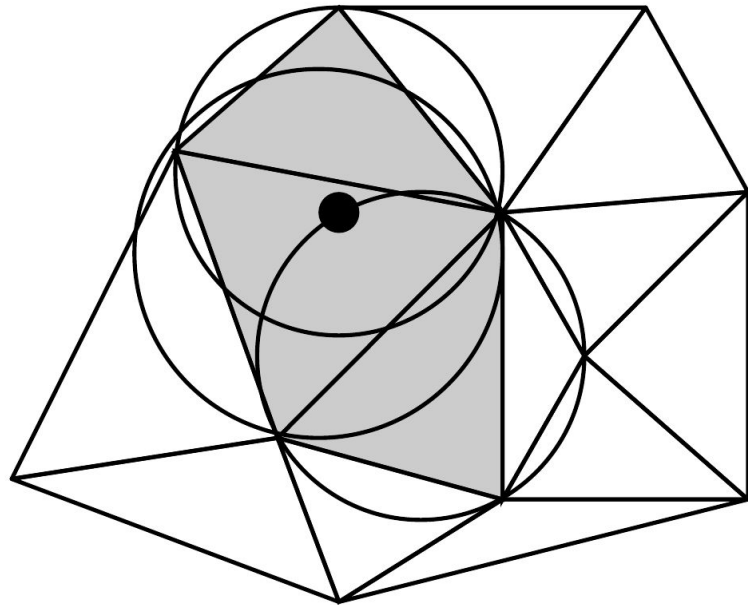
# Finding $T_{\text{bad}}$



- **Brute Force:** Check all triangles  $O(n)$ .

OR

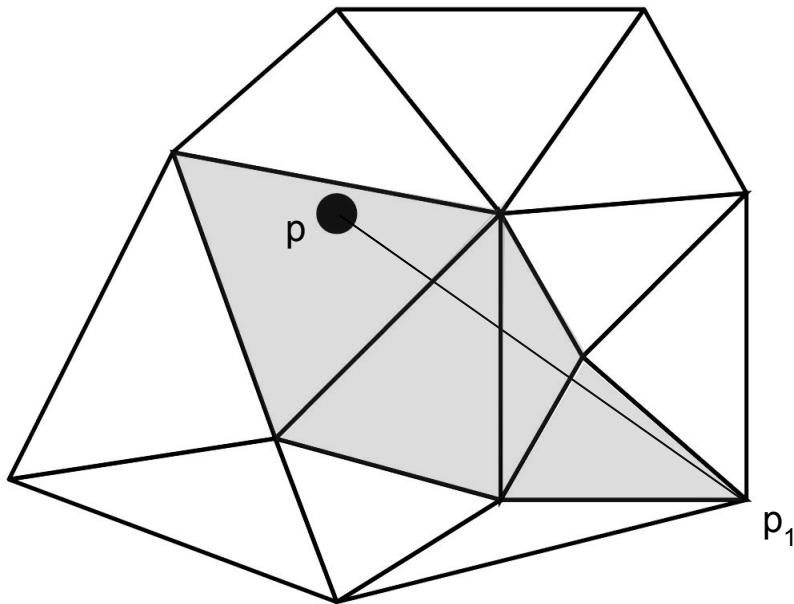
- Find the triangle in which the new vertex lies using **Green-Sibson Method**.
- Perform **tree search** through the triangles looking for other triangles to be deleted.



# Green-Sibson Method



- Green and Sibson propose taking a random point, say  $p_1$ , and performing a walk to the query point  $p$ .



# Green-Sibson Method

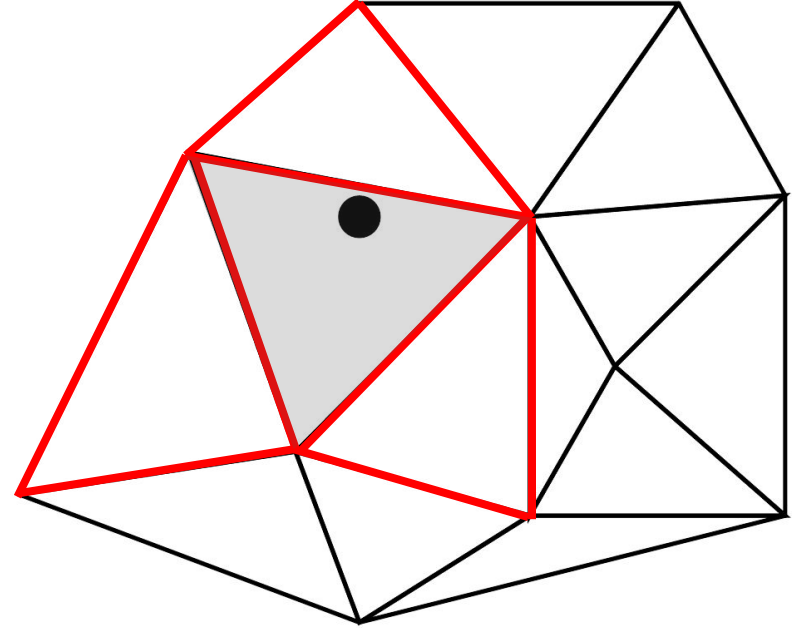


- The complexity of Green–Sibson method is bounded by  $\text{degree}(p_1, DT_n)$ , the degree of  $p_1$  in the Delaunay triangulation  $DT_n$  for  $p_1, \dots, p_n$  (to find the starting triangle in the Delaunay triangulation) plus  $N^*$ , the number of triangles visited by  $(p, p_1)$  in  $DT_n$ .
- **Theorem:** The expected complexity of the Green–Sibson method for a random Delaunay triangulation and an independent and uniformly distributed query point on  $[0, 1]^2$  is  $\Theta(\sqrt{n})$ .

# Tree Search



- Each triangle in Delaunay Triangulation except the ones on the boundary share their edges with other triangles (neighbours).
- A breadth first search like algorithm is used to find the triangles belonging to  $T_{\text{bad}}$ .
- Runtime is proportional to number of triangles in  $T_{\text{bad}}$  as the number of neighbours of a triangle is at most 3.

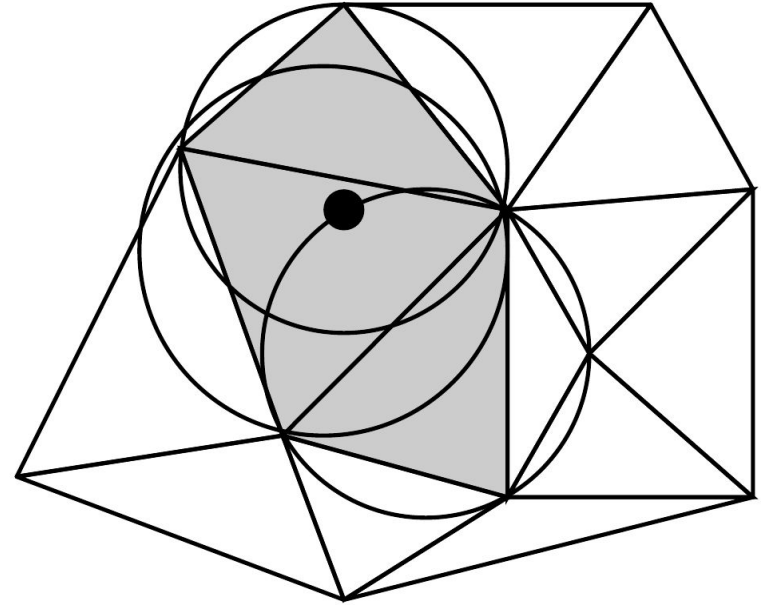




# Size of $T_{\text{bad}}$



- $|T_{\text{bad}}| \propto \text{degree}(p_i, DT_i)$ .
- Given  $k$  (dimension), expected degree of a vertex in Delaunay Triangulation is constant.
- In 2 dimensions the Euler-Poincare formula ( $V - E + F = 2$ ) can be used to prove that,  
 $E[\text{degree}(p, DT)] = 6$



# Runtime of Algorithm



1. Add Super Triangle ( $p_{-1}, p_{-2}, p_{-3}$ ) -----  $O(1)$
2. For each  $i$  in 0 to  $n-1$  -----  $O(n) *$ 
  - a. Find the triangle in which  $p_i$  -----  $O(\sqrt{(i+3)})$   
lies
  - b. Find  $T_{\text{bad}}$  -----  $O(1)$
  - c. Find boundary vertices of -----  $O(1)$   
 $T_{\text{bad}}$
  - d. Delete  $T_{\text{bad}}$  -----  $O(1)$
  - e. Add edges from  $p_i$  to -----  $O(1)$   
boundary vertices.
3. Delete all the edges connected to -----  $O(n)$   
Super Triangle ( $p_{-1}, p_{-2}, p_{-3}$ ).

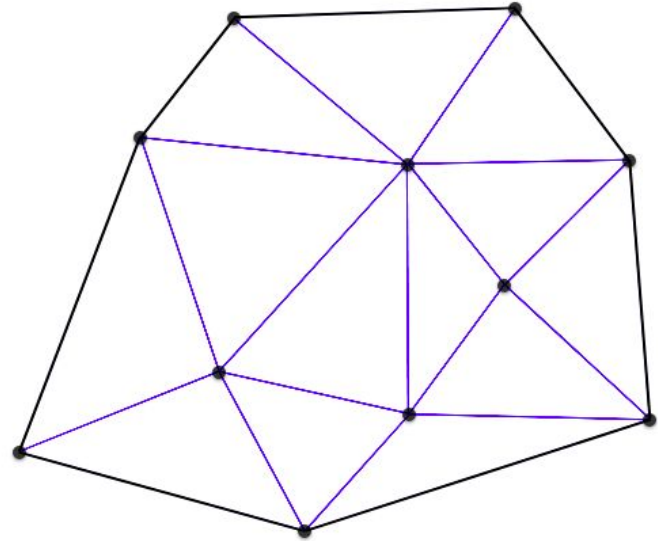
# Analysis



- In 2 dimension,
  - Expected Runtime:  $O(n \sqrt{n})$
  - Space Complexity:  $O(n)$ 
    - As addition of each new vertex creates  $O(1)$  new triangles.
- The algorithm can also be extended to  $k$ -dimensions, with expected runtime of  $O(n^{(1+1/k)})$ .

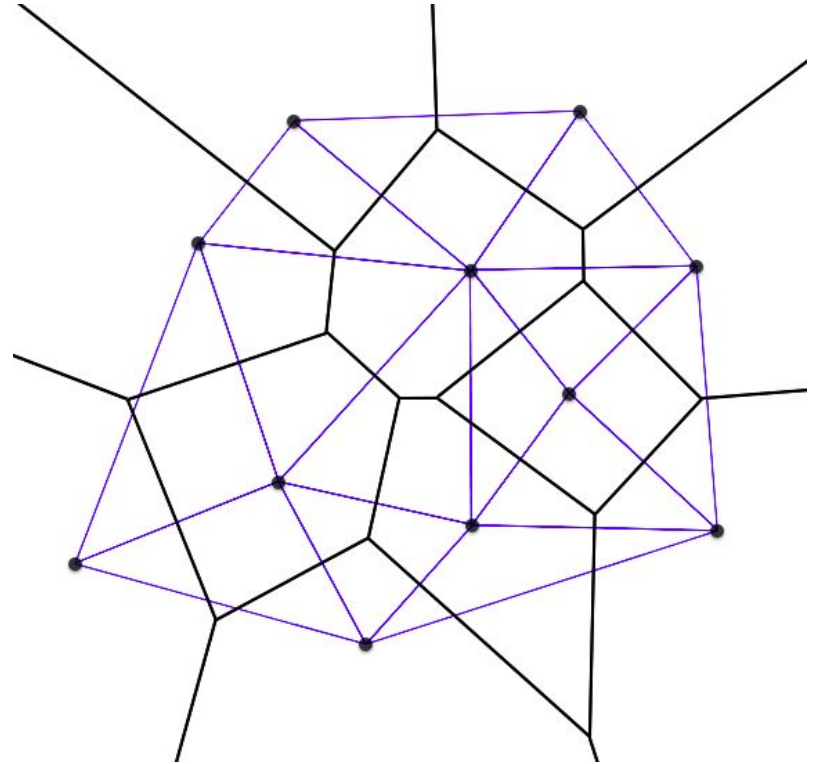
# Convex Hull

Every edge that lies on the boundary of the convex hull of a vertex set and has no vertex in its interior is Delaunay.



# Voronoi Diagram

- Vertices in Voronoi Diagram are the circumcenters of the triangles in Delaunay Triangulation.
- If we join the circumcenters of neighbouring triangles in Delaunay Triangulation, we get the Voronoi Diagram.



# Demo

<https://poojab01.github.io/DelaunayViz/>