

# Artificial Intelligence and Machine Learning Lab

## 1. Write a program to implement BFS and DFS Traversal.

### BFS:-

#### Source Code:-

```
graph={
    '5':['2','3'],
    '2':['4','8'],
    '3':['6'],
    '4':[],
    '8':['7'],
    '6':[],
    '7':[]
}
visited=[]
queue=[]
def bfs(visited,graph,node):
    queue.append(node)
    visited.append(node)
    while queue:
        m=queue.pop(0)
        print(m,end=" ")
        for neighbour in graph[m]:
            if neighbour not in visited:
                visited.append(neighbour)
                queue.append(neighbour)

print("BFS Nodes are:")
bfs(visited,graph,'5')
```

### Out Put:-

BFS Nodes are:  
5 2 3 4 8 6 7

### DFS:-

#### Source Code:-

```
graph={
    '5':['2','3'],
```

```

'2':['4','8'],
'3':['6'],
'4':[],
'8':['7'],
'6':[],
'7':[]
}
visited=[]
stack=[]
def dfs(visited,graph,node):
    if node not in visited:
        visited.append(node)
        stack.append(node)
        n=stack.pop(0)#5
        print(n,end=" ")
        for neighbour in graph[node]:#2,3
            dfs(visited,graph,neighbour)

print("DFS nodes are:")
dfs(visited,graph,'5')

```

### **Out Put:-**

DFS nodes are:  
5 2 4 8 7 3 6

## 2. Write a program to implement A\* Search.

### Source Code:-

```
def aStarAlgo(start_node,stop_node):#A,G
    open_set=set(start_node)# C G
    closed_set=set()#A B E D
    g={}
    parents={}
    g[start_node]=0#g[A]=0
    parents[start_node]=start_node#A->A
    while len(open_set)>0:#2>0
        n=None
        for v in open_set:#G C
            if n==None or g[v]+heuristic(v)<g[n]+heuristic(n):#C
                n=v#G
                #3+99=102<11+0
            if n==stop_node or Graph_nodes[n]==None:
                pass
            else:
                for (m,weight) in get_neighbour(n):#('G',1)
                    if m not in open_set and m not in closed_set:#B
                        open_set.add(m)#A B E C G D
                        parents[m]=n#B->A,E->A,C->B,G->D,D->E
                        g[m]=g[n]+weight#g[B]=0+2=2,g[E]=0+3=3
                        #g[c]=2+1=3,g[g]=2+9=11,g[d]=3+6=9
                    else:
                        if g[m]>g[n]+weight:#11>9+1=10
                            g[m]=g[n]+weight#g[g]=10
                            parents[m]=n#G->D
                            if m in closed_set:
                                closed_set.remove(m)
                                open_set.add(m)
        if n==None:
            print('path does not exist!')
            return None
        if n==stop_node:#A->A,B->A,E->A,C->B,G->D,D->E
            path=[]
            while parents[n]!=n:A!=A
                path.append(n)#G D E
                n=parents[n]#A
            path.append(start_node)#G D E A
```

```

        path.reverse()#A E D G
        print('path found: {}'.format(path))#A E D G
        return path
    open_set.remove(n)# G C
    closed_set.add(n)#A B E D

    print('path does not exit!')
    return None

def get_neighbour(v):#A
    if v in Graph_nodes:
        return Graph_nodes[v]
    else:
        return None

def heuristic(n):
    H_dist={
        'A':11,
        'B':6,
        'C':99,
        'D':1,
        'E':7,
        'G':0
    }
    return H_dist[n]
Graph_nodes={
    'A':[( 'B',2),('E',3)],
    'B':[( 'C',1),('G',9)],
    'C':None,
    'D':[( 'G',1)],
    'E':[( 'D',6)],
}
aStarAlgo('A','G')

```

### Out Put:-

path found: ['A', 'E', 'D', 'G']

['A', 'E', 'D', 'G']

[1]:

### 3. Write a program to implement Travelling Salesman Problem and Graph Coloring Problem

#### Travelling Salesman Problem

##### Source Code:-

```
#Travelling Salesman Problem
from sys import maxsize
from itertools import permutations
v=4
def travellingSalesmanProblem(graph,s):
    vertex=[]#1,2,3
    for i in range(v):#(0,4)0,1,2,3
        if i!=s:#1!=0
            vertex.append(i)#1 2 3
    min_path=maxsize
    next_permutation=permutations(vertex)#[1,2,3][1,3,2][2,1,3][2,3,1]
                                     #[3,1,2][3,2,1]
    for i in next_permutation:#[1,2,3][1,3,2][2,1,3][2,3,1]
                                     #[3,1,2][3,2,1]
        current_pathweight=0
        k=s#00][
        for j in i:#[1,2,3] #3
            current_pathweight+=graph[k][j]#75
            k=j#3
        current_pathweight+=graph[k][s]#75+20=95
        min_path=min(min_path,current_pathweight)#95
    return min_path#80

graph=[[0,10,15,20],[10,0,35,25],
       [15,35,0,30],[20,25,30,0]]
s=0
print(travellingSalesmanProblem(graph,s))#80
```

##### Out Put:-

80

#### Graph Coloring Problem

##### Source Code:-

```
colors=['Red','Blue','Green']
```

```

states=['a','b','c','d']
neighbors={}
neighbors['a']=['b','c','d']
neighbors['b']=['a','d']
neighbors['c']=['a','d']
neighbors['d']=['c','b','a']

colors_of_states={}

def promising(state,color):#d,green
    for neighbor in neighbors.get(state):#c,b,a
        color_of_neighbor=colors_of_states.get(neighbor)#blue
        if color_of_neighbor==color:#b==b
            return False
    return True

def get_color_for_state(state):#d
    for color in colors:#Red,Blue,Green
        if promising(state,color):#d,Red
            return color

def main():
    for state in states:#c,d
        colors_of_states[state]=get_color_for_state(state)#a:Red,b:blue,c:blue,d:green

    print(colors_of_states)

main()

```

### **Out Put:-**

```
{'a': 'Red', 'b': 'Blue', 'c': 'Blue', 'd': 'Green'}
```

#### 4. Write a program to implement Knowledge Representation.

##### Source Code:-

```
from sympy import symbols, Not, Implies, Xor, And

# Define propositional variables
rained = symbols('rained')
visited_hagrid = symbols('visited_hagrid')
visited_dumbledore = symbols('visited_dumbledore')

# Define the logical expressions based on the given statements
statement1 = Implies(Not(rained), visited_hagrid) # If it didn't rain, then Harry visited
Hagrid today
statement2 = Xor(visited_hagrid, visited_dumbledore) # Harry visited either Hagrid or
Dumbledore, but not both
statement3 = visited_dumbledore # Harry visited Dumbledore today

# Combine the statements into a single formula
combined_formula = And(statement1, statement2, statement3)

# Function to check consistency of the combined formula and print evaluations
def check_combined_consistency():
    # Evaluate all possible scenarios for rained and visited_hagrid
    possible_values = [True, False]
    consistent_scenarios = []

    for rained_value in possible_values:#true,false
        for visited_hagrid_value in possible_values:#true,false
            # Substitute the variable values into the combined formula
            results = {
                rained: rained_value,#t
                visited_hagrid: visited_hagrid_value,#f
                visited_dumbledore: True # We know that Harry visited Dumbledore today
            }

            # Evaluate the logical statements individually
            eval_statement1 = statement1.subs(results)#t
            eval_statement2 = statement2.subs(results)#t
            eval_statement3 = statement3.subs(results)#t
```

```

# Evaluate the combined formula
eval_combined_formula = combined_formula.subs(results)#t

# Print the evaluation of each statement and the combined formula
print(f"rained={rained_value}, visited_hagrid={visited_hagrid_value},
visited_dumbledore=True")
print(f" Statement 1 ( $\neg R \rightarrow H$ ) evaluates to: {eval_statement1}")
print(f" Statement 2 ( $H \oplus D$ ) evaluates to: {eval_statement2}")
print(f" Statement 3 (D) evaluates to: {eval_statement3}")
print(f" Combined Formula evaluates to: {eval_combined_formula}\n")

# Append to consistent scenarios if the combined formula is true
if eval_combined_formula:
    consistent_scenarios.append((rained_value, visited_hagrid_value))#t,f

return consistent_scenarios

# Find consistent scenarios
consistent_scenarios = check_combined_consistency()#t,f

# Output consistent scenarios
print("Consistent scenarios based on the combined formula:")
if consistent_scenarios:#t,f
    for scenario in consistent_scenarios:
        rained_value, visited_hagrid_value = scenario#t,f
        print(f"rained={rained_value}, visited_hagrid={visited_hagrid_value},
visited_dumbledore=True")
    else:
        print("No consistent scenarios found.")

# Output the combined formula for reference
print("\nCombined logical formula:")
print(combined_formula)

```

## Out Put:-

```

rained=True, visited_hagrid=True, visited_dumbledore=True
Statement 1 ( $\neg R \rightarrow H$ ) evaluates to: True
Statement 2 ( $H \oplus D$ ) evaluates to: False
Statement 3 (D) evaluates to: True
Combined Formula evaluates to: False

```



rained=True, visited\_hagrid=False, visited\_dumbledore=True

Statement 1 ( $\neg R \rightarrow H$ ) evaluates to: True

Statement 2 ( $H \oplus D$ ) evaluates to: True

Statement 3 (D) evaluates to: True

Combined Formula evaluates to: True

rained=False, visited\_hagrid=True, visited\_dumbledore=True

Statement 1 ( $\neg R \rightarrow H$ ) evaluates to: True

Statement 2 ( $H \oplus D$ ) evaluates to: False

Statement 3 (D) evaluates to: True

Combined Formula evaluates to: False

rained=False, visited\_hagrid=False, visited\_dumbledore=True

Statement 1 ( $\neg R \rightarrow H$ ) evaluates to: False

Statement 2 ( $H \oplus D$ ) evaluates to: True

Statement 3 (D) evaluates to: True

Combined Formula evaluates to: False

Consistent scenarios based on the combined formula:

rained=True, visited\_hagrid=False, visited\_dumbledore=True

Combined logical formula:

$\text{visited\_dumbledore} \ \& \ (\text{visited\_dumbledore} \wedge \text{visited\_hagrid}) \ \& \ (\text{Implies}(\sim\text{rained}, \text{visited\_hagrid}))$

## 5. Write a program to implement Bayesian Network.

### Source Code:-

```
# Define conditional probability tables (CPTs)
P_burglary = 0.002#t
P_earthquake = 0.001#t

# Probability of alarm given burglary and earthquake
P_alarm_given_burglary_and_earthquake = 0.94
P_alarm_given_burglary_and_no_earthquake = 0.95
P_alarm_given_no_burglary_and_earthquake = 0.31
P_alarm_given_no_burglary_and_no_earthquake = 0.001

# Probability of David calling given alarm
P_david_calls_given_alarm = 0.91#t
P_david_does_not_call_given_alarm = 0.09
P_david_calls_given_no_alarm = 0.05#t
P_david_does_not_call_given_no_alarm = 0.95

# Probability of Sophia calling given alarm
P_sophia_calls_given_alarm = 0.75
P_sophia_does_not_call_given_alarm = 0.25
P_sophia_calls_given_no_alarm = 0.02
P_sophia_does_not_call_given_no_alarm = 0.98

# Calculate joint probability
def joint_probability(alarm, burglary, earthquake, david_calls, sophia_calls):#(t,f,f,t,t)
    if alarm:
        if burglary and earthquake:
            P_alarm = P_alarm_given_burglary_and_earthquake
        elif burglary:
            P_alarm = P_alarm_given_burglary_and_no_earthquake
        elif earthquake:
            P_alarm = P_alarm_given_no_burglary_and_earthquake
        else:
            P_alarm = P_alarm_given_no_burglary_and_no_earthquake#0.001
    else:
        if burglary and earthquake:
            P_alarm = 1 - P_alarm_given_burglary_and_earthquake
        elif burglary:
```

```

    P_alarm = 1 - P_alarm_given_burglary_and_no_earthquake
elif earthquake:
    P_alarm = 1 - P_alarm_given_no_burglary_and_earthquake
else:
    P_alarm = 1 - P_alarm_given_no_burglary_and_no_earthquake

P_david = (P_david_calls_given_alarm if david_calls else
P_david_does_not_call_given_alarm) if alarm else (P_david_calls_given_no_alarm if
david_calls else P_david_does_not_call_given_no_alarm)#0.91

P_sophia = (P_sophia_calls_given_alarm if sophia_calls else
P_sophia_does_not_call_given_alarm) if alarm else (P_sophia_calls_given_no_alarm if
sophia_calls else P_sophia_does_not_call_given_no_alarm)#0.75

return (P_burglary if burglary else 1 - P_burglary) * (P_earthquake if earthquake else 1
- P_earthquake) * P_alarm * P_david * P_sophia#0.75*0.91*0.001*0.998*0.999

# Calculate the probability for the given scenario
result = joint_probability(
    alarm=True,
    burglary=False,
    earthquake=False,
    david_calls=True,
    sophia_calls=True
)

# Print the result
print(f'The probability that the alarm has sounded, there is neither a burglary nor an
earthquake, and both David and Sophia called Harry is: {result:.8f}')
```

## Out Put:-

The probability that the alarm has sounded, there is neither a burglary nor an earthquake, and both David and Sophia called Harry is: 0.00068045

## 6. Write a program to implement Hidden Markov Model.

### Source Code:-

```
import numpy as np

class HMM:

    def __init__(self, states, observations):#['Sunny', 'Cloudy', 'Rainy'],['Umbrella', 'Normal',
'Raincoat']

        self.states = states#['Sunny', 'Cloudy', 'Rainy']

        self.n_states = len(states)#3

        self.n_obs = len(observations)#3

        self.state_index = {state: i for i, state in enumerate(states)}#{'Sunny': 0, 'Cloudy': 1,
'Rainy': 2}

        self.obs_index = {obs: i for i, obs in enumerate(observations)}#{'Umbrella': 0, 'Normal': 1,
'Raincoat': 2}


    # Transition probability matrix (A)

    self.A = np.array([

        [0.6, 0.3, 0.1], # Sunny -> Sunny, Cloudy, Rainy

        [0.2, 0.5, 0.3], # Cloudy -> Sunny, Cloudy, Rainy

        [0.1, 0.4, 0.5] # Rainy -> Sunny, Cloudy, Rainy

    ])


    # Emission probability matrix (B)

    self.B = np.array([

        [0.8, 0.15, 0.05], # Sunny: Umbrella, Normal, Raincoat

        [0.3, 0.4, 0.3], # Cloudy: Umbrella, Normal, Raincoat

        [0.1, 0.2, 0.7] # Rainy: Umbrella, Normal, Raincoat

    ])
```

```

# Initial state probabilities (pi)
self.pi = np.array([0.5, 0.3, 0.2]) # Sunny, Cloudy, Rainy

def forward(self, obs_seq):#[0,1,0,2]
    n = len(obs_seq)#4
    alpha = np.zeros((n, self.n_states))#(4,3)
    '''
    [[0. 0. 0.]
    [0. 0. 0.]
    [0. 0. 0.]
    [0. 0. 0.]]
    '''

    # Initialize alpha
    alpha[0] = self.pi * self.B[:, obs_seq[0]]#[0.5 0.3 0.2]*[0.8 0.3 0.1]=[0.4 0.09 0.02]
    # Recursion
    for t in range(1, n):#1,2,3
        for j in range(self.n_states):#0,1,2
            alpha[t, j] = (alpha[t-1] @ self.A[:, j]) * self.B[j, obs_seq[t]]#alpha[1]
            #alpha[0]*A[:,0]*b[0,1]
            #([0.4 0.09 0.02]*[0.6 0.2 0.1])*0.15
#[0.039,0.0692,0.0154]
#[0.031024,0.015738,0.003236]
#[0.00110428,0.00554118,0.00660926]
    # Probability of the observation sequence
    return alpha.sum(axis=1)[-1]#0.0133.

```

```
# Define states and observations
states = ['Sunny', 'Cloudy', 'Rainy']
observations = ['Umbrella', 'Normal', 'Raincoat']#0,1,2

# Initialize the HMM
hmm = HMM(states, observations)

# Define an observation sequence
obs_seq = ['Umbrella', 'Normal', 'Umbrella', 'Raincoat'] # Convert this to indices for
computation
obs_seq_indices = [hmm.obs_index[obs] for obs in obs_seq]#[0,1,0,2]

# Evaluate the probability of the observation sequence
prob = hmm.forward(obs_seq_indices)
print(f"Probability of the observation sequence '{obs_seq}': {prob:.4f}")#0.0133.
```

### **Out Put:-**

Probability of the observation sequence ['Umbrella', 'Normal', 'Umbrella', 'Raincoat']': 0.0133

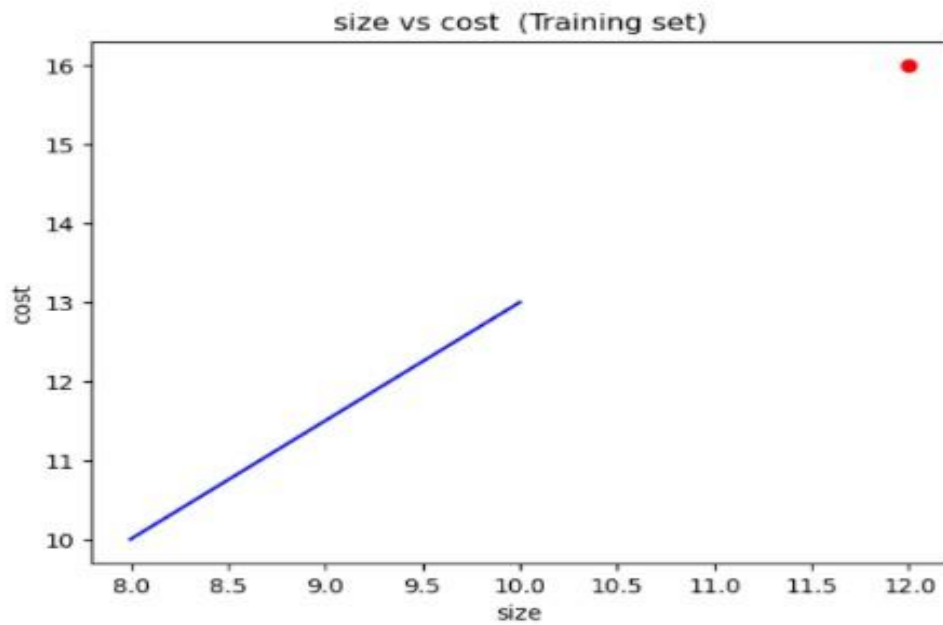
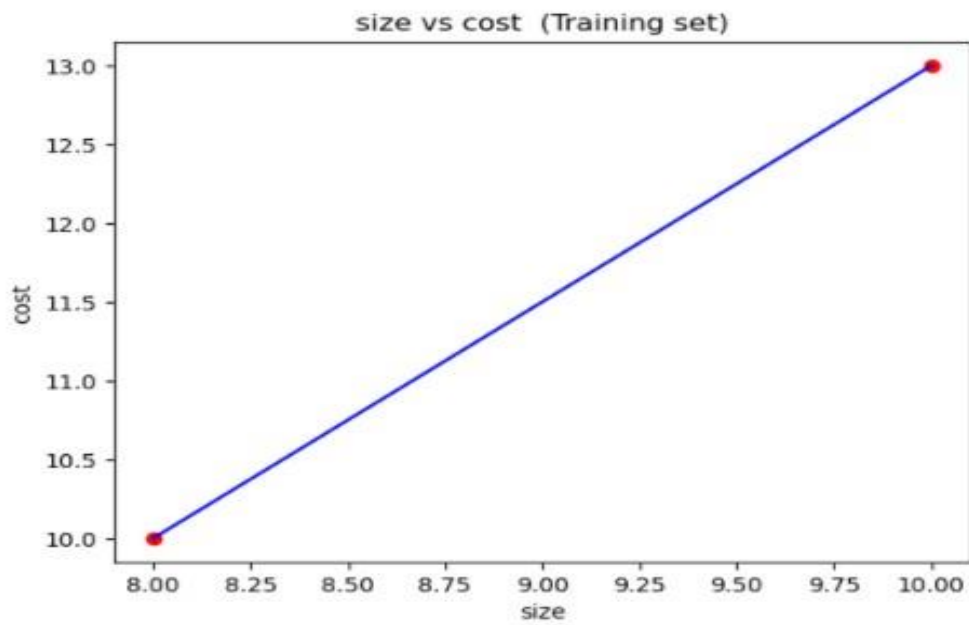
## 7. Write a program to implement Regression algorithm.

### Source Code:-

- `import numpy as np`
- `import pandas as pd`
- `import matplotlib.pyplot as plt`
- `#from google.colab import files`
- `#uploaded = files.upload()`
- `dataset = pd.read_csv('pizza.csv')`
- `X = dataset.iloc[:, 0:-1].values #independent variable array`
- `y = dataset.iloc[:,1].values #dependent variable vector`
- `# splitting the dataset`
- `from sklearn.model_selection import train_test_split`
- `X_train, X_test, y_train, y_test = train_test_split(X,y,test_size=1/3,random_state=0)`
- `# fitting the regression model`
- `from sklearn.linear_model import LinearRegression`
- `regressor = LinearRegression()`
- `regressor.fit(X_train,y_train) #actually produces the linear eqn for the data`
- `regressor`
- `# predicting the test set results`
- `y_pred = regressor.predict(X_test)`
- `#comparing both y_test and y_pred`
- `df1=pd.DataFrame({'Actual':y_test,'Prediction':y_pred})`
- `df1`
- `# visualizing the results`
- `#plot for the TRAIN`
- `plt.scatter(X_train, y_train, color='red') # plotting the observation line`
- `plt.plot(X_train, regressor.predict(X_train), color='blue') # plotting the regression line`
- `plt.title("size vs cost (Training set)") # stating the title of the graph`
- `plt.xlabel("size") # adding the name of x-axis`
- `plt.ylabel("cost") # adding the name of y-axis`
- `plt.show() # specifies end of graph`
- `#plot for the TEST`
- `plt.scatter(X_test, y_test, color='red')`
- `plt.plot(X_train, regressor.predict(X_train), color='blue') # plotting the regression line`
- `plt.title("size vs cost (Training set)") # stating the title of the graph`
- `plt.xlabel("size") # adding the name of x-axis`
- `plt.ylabel("cost") # adding the name of y-axis`

- plt.show()
- dataset.head()

## Out Put:-



```
[4]:
```

	size	cost
0	8	10
1	10	13
2	12	16



## 8. Write a program to implement decision tree based ID3 algorithm.

### Source Code:-

```
import pandas as pd
from collections import Counter
import math
from pprint import pprint

# Entropy calculation function
def entropy(probs):
    return sum(-prob * math.log(prob, 2) for prob in probs if prob > 0)

# Calculate entropy of a list
def entropy_of_list(a_list):
    cnt = Counter(a_list)
    num_instances = len(a_list)
    probs = [x / num_instances for x in cnt.values()]
    return entropy(probs)

# Information gain function
def information_gain(df, split_attribute_name, target_attribute_name):
    df_split = df.groupby(split_attribute_name)
    print(df_split)
    nobs = len(df.index) * 1.0

    df_agg_ent = df_split[target_attribute_name].agg(
        [entropy_of_list, lambda x: len(x) / nobs]
    )
```

```

avg_info = sum(df_agg_ent['entropy_of_list'] * df_agg_ent['<lambda_0>'])
old_entropy = entropy_of_list(df[target_attribute_name])
return old_entropy - avg_info

```

# ID3 Decision Tree algorithm

```

def id3DT(df, target_attribute_name, attribute_names, default_class=None):
    cnt = Counter(df[target_attribute_name])
    if len(cnt) == 1:
        return next(iter(cnt))
    elif df.empty or not attribute_names:
        return default_class
    else:
        default_class = max(cnt, key=cnt.get)
        gainz = [information_gain(df, attr, target_attribute_name) for attr in attribute_names]

        index_of_max = gainz.index(max(gainz))
        best_attr = attribute_names[index_of_max]
        tree = {best_attr: {}}
        remaining_attributes = [i for i in attribute_names if i != best_attr]
        for attr_val, data_subset in df.groupby(best_attr):
            subtree = id3DT(data_subset, target_attribute_name, remaining_attributes,
default_class)
            tree[best_attr][attr_val] = subtree

        return tree

```

# Simulate the dataset from the image provided earlier

```

data = {

```

'Outlook': ['Sunny', 'Sunny', 'Overcast', 'Rain', 'Rain', 'Rain', 'Overcast', 'Sunny', 'Sunny', 'Rain', 'Sunny', 'Overcast', 'Overcast', 'Rain'],

'Temperature': ['Hot', 'Hot', 'Hot', 'Mild', 'Cool', 'Cool', 'Cool', 'Mild', 'Cool', 'Mild', 'Mild', 'Mild', 'Hot', 'Mild'],

'Humidity': ['High', 'High', 'High', 'High', 'Normal', 'Normal', 'Normal', 'High', 'Normal', 'Normal', 'Normal', 'High', 'Normal', 'High'],

'Wind': ['Weak', 'Strong', 'Weak', 'Weak', 'Weak', 'Strong', 'Strong', 'Weak', 'Weak', 'Weak', 'Strong', 'Strong', 'Weak', 'Strong'],

'PlayTennis': ['No', 'No', 'Yes', 'Yes', 'Yes', 'No', 'Yes', 'No', 'Yes', 'Yes', 'Yes', 'Yes', 'Yes', 'No']

}

```
df = pd.DataFrame(data)
```

```
df
```

**Output:-**

	Outlook	Temperature	Humidity	Wind	PlayTennis
0	Sunny	Hot	High	Weak	No
1	Sunny	Hot	High	Strong	No
2	Overcast	Hot	High	Weak	Yes
3	Rain	Mild	High	Weak	Yes
4	Rain	Cool	Normal	Weak	Yes
5	Rain	Cool	Normal	Strong	No
6	Overcast	Cool	Normal	Strong	Yes
7	Sunny	Mild	High	Weak	No
8	Sunny	Cool	Normal	Weak	Yes
9	Rain	Mild	Normal	Weak	Yes
10	Sunny	Mild	Normal	Strong	Yes
11	Overcast	Mild	High	Strong	Yes
12	Overcast	Hot	Normal	Weak	Yes
13	Rain	Mild	High	Strong	No

### Code Continue:-

# Define attribute names and target column name

```
attribute_names = list(df.columns)
```

```
attribute_names.remove('PlayTennis')
```

# Build the decision tree

```
tree = id3DT(df, 'PlayTennis', attribute_names)
```

```
print("The Resultant Decision Tree is:")
```

```
pprint(tree)
```

### Output:-

The Resultant Decision Tree is:

```
{'Outlook': {'Overcast': 'Yes',
             'Rain': {'Wind': {'Strong': 'No', 'Weak': 'Yes'}},
             'Sunny': {'Humidity': {'High': 'No', 'Normal': 'Yes'}}}}
```

## 9. Write a program to implement K-Means Clustering algorithm.

### Source Code:-

```
import matplotlib.pyplot as plt
from sklearn import datasets
from sklearn.cluster import KMeans
import sklearn.metrics as sm
import pandas as pd
import numpy as np

iris =datasets.load_iris()
X=pd.DataFrame(iris.data)
X.columns=['Sepal_Length','Sepal_Width', 'Petal_length', 'Petal_Width']
y=pd.DataFrame(iris.target)
y.columns=['target']
plt.figure(figsize=(14,7))
colormap=np.array(['red','lime','black'])
plt.subplot(1,2,1)
plt.scatter(X.Sepal_Length,X.Sepal_Width,c=colormap[y.target],s=40)
plt.title('Sepal')
plt.subplot(1,2,2)
plt.scatter(X.Petal_length,X.Petal_Width,c=colormap[y.target],s=40)
plt.title('Petal')
model=KMeans(n_clusters=3)
model.fit(X)
print(model.labels_)
plt.subplot(1,2,1)
plt.scatter(X.Petal_length,X.Petal_Width,c=colormap[y.target],s=40)
```

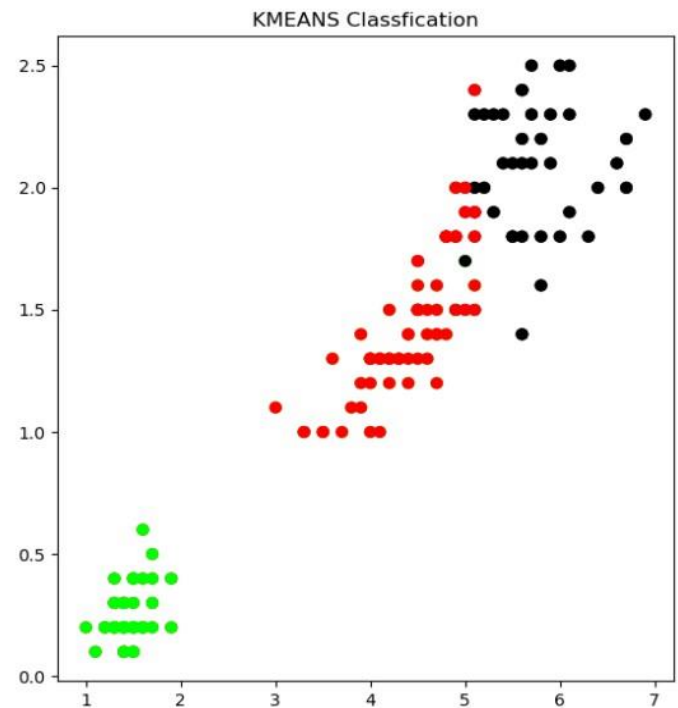
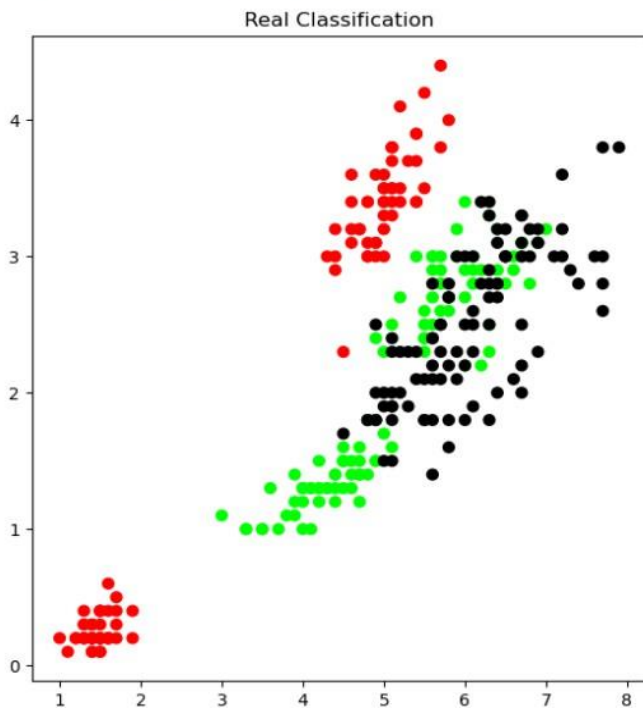
```
plt.title( 'KMEANS Classfication')
```

### Out Put:-

```
[1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1  
1 1 1 1 1 1 1 1 1 1 1 1 0 0 2 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0  
2 0 0 2 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 2 0 2 2 2 0 2 2 2 2  
0 0 0 2 2 2 2 0 2 0 2 0 2 2 0 0 2 2 2 2 0 2 2 2 2 0 2 2 2 0 2  
2 0]
```

```
C:\ProgramData\anaconda3\Lib\site-packages\sklearn\cluster\_kmeans.py:1446: UserWarning: KMeans is known to have a memory leak on Windows with MKL, when there are less chunks than available threads. You can avoid it by setting the environment variable OMP_NUM_THREADS=1.
  warnings.warn(
```

```
[9]: Text(0.5, 1.0, 'KMEANS Classification')
```



## 10. Write a program to implement K-Nearest Neighbor algorithm (K-NN).

### Source Code:-

```
# Import necessary libraries
import pandas as pd
from sklearn.datasets import load_iris
from sklearn.model_selection import train_test_split
from sklearn.neighbors import KNeighborsClassifier
from sklearn.metrics import confusion_matrix, accuracy_score

# Load the Iris dataset
iris = load_iris()

# Print dataset keys for reference
print("Dataset keys:", iris.keys())

# Convert data to DataFrame for better visualization
df = pd.DataFrame(iris['data'], columns=iris['feature_names'])
print("Feature Data:\n", df.head()) # Display first few rows of feature data

# Target names and feature names for reference
print("Target names:", iris['target_names'])
print("Feature names:", iris['feature_names'])

# Display target values (species labels)
print("Target array:\n", iris['target'])

# Define features (X) and target labels (y)
X = df
y = iris['target']

# Split the dataset into training and testing sets (67% train, 33% test)
X_train, X_test, y_train, y_test = train_test_split(X, y, test_size=0.33, random_state=42)

# Initialize and train the k-NN classifier with k=3
knn = KNeighborsClassifier(n_neighbors=3)
knn.fit(X_train, y_train)

# Predict on the test set
y_pred = knn.predict(X_test)
```





[ 0 2 32]]

## 11. Write a program to implement Back Propagation Algorithm.

### Source Code:-

```
import numpy as np

# Sigmoid activation function
def sigmoid(x):
    return 1 / (1 + np.exp(-x))

# Derivative of sigmoid function
def sigmoid_derivative(x):
    return x * (1 - x)

# Initialize dataset (input features and corresponding labels)
X = np.array([[0, 0], [0, 1], [1, 0], [1, 1]]) # XOR problem
y = np.array([[0], [1], [1], [0]]) # XOR output

# Set the hyperparameters
input_layer_neurons = 2 # 2 features
hidden_layer_neurons = 4 # Number of neurons in hidden layer
output_layer_neurons = 1 # Single output neuron
epochs = 10000 # Number of iterations
learning_rate = 0.1 # Learning rate

# Initialize weights and biases with random values
np.random.seed(42) # For reproducibility
```

```
# Weights between input and hidden layer
```

```
wh = np.random.uniform(size=(input_layer_neurons, hidden_layer_neurons))
```

```
bh = np.random.uniform(size=(1, hidden_layer_neurons))
```

```
# Weights between hidden and output layer
```

```
wout = np.random.uniform(size=(hidden_layer_neurons, output_layer_neurons))
```

```
bout = np.random.uniform(size=(1, output_layer_neurons))
```

```
# Training the neural network
```

```
for epoch in range(epochs):
```

```
    # Forward pass
```

```
    # Hidden layer input
```

```
    hidden_layer_input = np.dot(X, wh) + bh
```

```
    # Hidden layer activation (sigmoid)
```

```
    hidden_layer_output = sigmoid(hidden_layer_input)
```

```
    # Output layer input
```

```
    output_layer_input = np.dot(hidden_layer_output, wout) + bout
```

```
    # Output layer activation (sigmoid)
```

```
    output = sigmoid(output_layer_input)
```

```
    # Calculate the error (difference between actual and predicted)
```

```
    error = y - output
```

```
    # Backpropagation
```

```
    # Output layer gradients
```

```
    output_layer_gradient = sigmoid_derivative(output)
```

```

d_output = error * output_layer_gradient # Derivative of loss with respect to output

# Hidden layer gradients
hidden_layer_gradient = sigmoid_derivative(hidden_layer_output)
d_hidden_layer = d_output.dot(wout.T) * hidden_layer_gradient
# Derivative of loss w.r.t. hidden layer

# Update weights and biases using gradient descent
wout += hidden_layer_output.T.dot(d_output) * learning_rate # Update weights between
hidden and output layer
bout += np.sum(d_output, axis=0, keepdims=True) * learning_rate # Update biases for
output layer

wh += X.T.dot(d_hidden_layer) * learning_rate # Update weights between input and hidden
layer
bh += np.sum(d_hidden_layer, axis=0, keepdims=True) * learning_rate
# Update biases for hidden layer

# Optionally print the error for every 1000 epochs
if epoch % 1000 == 0:
    print(f"Epoch {epoch}, Error: {np.mean(np.abs(error))}")

# Final predictions
print("Final predictions after training:")
print(output)

```

## Out Put:-

```

Epoch 0, Error: 0.49914791405546904
Epoch 1000, Error: 0.4989908274224632
Epoch 2000, Error: 0.49392112204426847
Epoch 3000, Error: 0.46086324847622695
Epoch 4000, Error: 0.37081148754970494

```

Epoch 5000, Error: 0.2293685934150816  
Epoch 6000, Error: 0.1411700792664044  
Epoch 7000, Error: 0.10187019467760619  
Epoch 8000, Error: 0.08085064924133495  
Epoch 9000, Error: 0.06790718296112089  
Final predictions after training:  
[[0.04690963]  
[0.95663392]  
[0.92548675]  
[0.07177571]]

## 12. Write a program to implement Support Vector Machine.

### Source Code:-

```
import numpy as np
import matplotlib.pyplot as plt
from sklearn.svm import SVC
from sklearn.metrics import classification_report, accuracy_score

# Step 1: Create a small dataset with 2 numeric features
# Example data points where each point has 2 features and a sentiment label
# Feature 1 could represent "positivity score" and Feature 2 "intensity score"
data = np.array([
    [1.5, 2.0, 1], # Positive sentiment
    [1.0, 1.0, 1], # Positive sentiment
    [2.0, 2.5, 1], # Positive sentiment
    [2.5, 1.5, 1], # Positive sentiment
    [3.0, 1.0, 0], # Negative sentiment
    [3.5, 0.5, 0], # Negative sentiment
    [4.0, 1.0, 0], # Negative sentiment
    [4.5, 1.5, 0] # Negative sentiment
])

# Separate features and labels
X = data[:, :2] # First two columns are features
y = data[:, 2] # Last column is the label (1 for positive, 0 for negative)

# Step 2: Train the SVM model
svm_model = SVC(kernel='linear')
svm_model.fit(X, y)
```

```

# Step 3: Evaluate the model
y_pred = svm_model.predict(X)
print("Accuracy:", accuracy_score(y, y_pred))
print("\nClassification Report:\n", classification_report(y, y_pred))

# Step 4: Visualize the Decision Boundary
# Create a mesh to plot the decision boundary
x_min, x_max = X[:, 0].min() - 1, X[:, 0].max() + 1
y_min, y_max = X[:, 1].min() - 1, X[:, 1].max() + 1
xx, yy = np.meshgrid(np.arange(x_min, x_max, 0.01),
                     np.arange(y_min, y_max, 0.01))
print("xx=",xx)
print("yy=",yy)

# Predict on each point of the mesh to determine decision boundaries
Z = svm_model.predict(np.c_[xx.ravel(), yy.ravel()])
Z = Z.reshape(xx.shape)
print ("Z=",Z)

# Plot the decision boundary and data points
plt.figure(figsize=(10, 6))
plt.contourf(xx, yy, Z, alpha=0.2, cmap='coolwarm')
plt.scatter(X[:, 0], X[:, 1], c=y, cmap='coolwarm', edgecolor='k', s=100)
plt.xlabel("Feature 1 (e.g., Positivity Score)")
plt.ylabel("Feature 2 (e.g., Intensity Score)")
plt.title("SVM Decision Boundary on 2-Feature Sentiment Data")
plt.show()

```

## Out Put:-

Accuracy: 1.0

Classification Report:

	precision	recall	f1-score	support
0.0	1.00	1.00	1.00	4
1.0	1.00	1.00	1.00	4
accuracy			1.00	8
macro avg	1.00	1.00	1.00	8

weighted avg      1.00      1.00      1.00      8

```
xx= [[0. 0.01 0.02 ... 5.47 5.48 5.49]
[0. 0.01 0.02 .... 5.47 5.48 5.49]
[0. 0.01 0.02 .... 5.47 5.48 5.49]
...
[0. 0.01 0.02 .... 5.47 5.48 5.49]
[0. 0.01 0.02 .... 5.47 5.48 5.49]
[0. 0.01 0.02 .... 5.47 5.48 5.49]]
yy= [[-0.5 -0.5 -0.5 ... -0.5 -0.5 -0.5 ]
[-0.49 -0.49 -0.49 ... -0.49 -0.49 -0.49]
[-0.48 -0.48 -0.48 ... -0.48 -0.48 -0.48]
...
[ 3.47  3.47  3.47 ...  3.47  3.47  3.47]
[ 3.48  3.48  3.48 ...  3.48  3.48  3.48]
[ 3.49  3.49  3.49 ...  3.49  3.49  3.49]]
Z= [[1. 1. 1. ... 0. 0. 0.]
[1. 1. 1. ... 0. 0. 0.]
[1. 1. 1. ... 0. 0. 0.]
...
[1. 1. 1. ... 0. 0. 0.]
[1. 1. 1. ... 0. 0. 0.]
[1. 1. 1. ... 0. 0. 0.]]
```

