

```

MACHINE
VARIABLES
    phase, operation, prm, stop, R_real, R_est,
    F_real, F_est
INVARIANTS
    inv7:  $(phase = checking \wedge prm = TRUE) \Rightarrow$ 
         $R\_est \leq R\_real$ 
EVENTS
Event Move  $\langle \rangle \triangleq$ 
    any
        m
    where
        grd1:  $phase = move$ 
    then
        act1:  $phase := report$ 
        act2:  $R\_real := R\_real + m$ 
        act3:  $F\_real := F\_real + m$ 
    end
Event Report  $\langle \rangle \triangleq$ 
    when
        grd1:  $phase = report$ 
    then
        act1:  $phase := integrity$ 
    end
Event Integrity  $\langle \rangle \triangleq$ 
    where
        grd5:  $phase = integrity$ 
    then
        act1:  $phase \in \{detection, res\}$ 
    end

```

```

Event Res  $\langle ordinary \rangle \triangleq$ 
    when
        grd1:  $phase = res$ 
    then
        act1:  $phase \in \{detection, est\}$ 
    end
Event Est  $\langle ordinary \rangle \triangleq$ 
    where
        grd1:  $phase = est$ 
        grd4:  $prm = TRUE \Rightarrow r\_est \leq R\_real$ 
    then
        act1:  $phase := checking$ 
        act2:  $R\_est := r\_est$ 
    end
Event Detection  $\langle ordinary \rangle \triangleq$ 
    when
        grd1:  $phase = detection$ 
    then
        act1:  $phase := move$ 
        act2:  $operation := abnormal$ 
    end
Event Checking  $\langle ordinary \rangle \triangleq$ 
    where
        grd1:  $phase = checking$ 
        grd3:  $R\_est > R\_real \Leftrightarrow s = TRUE$ 
    then
        act1:  $phase := move$ 
        act2:  $stop := s$ 
    end
END

```