

Digital Image Processing

Image Enhancement:
Filtering in the Frequency Domain

The Discrete Fourier Transform (DFT)

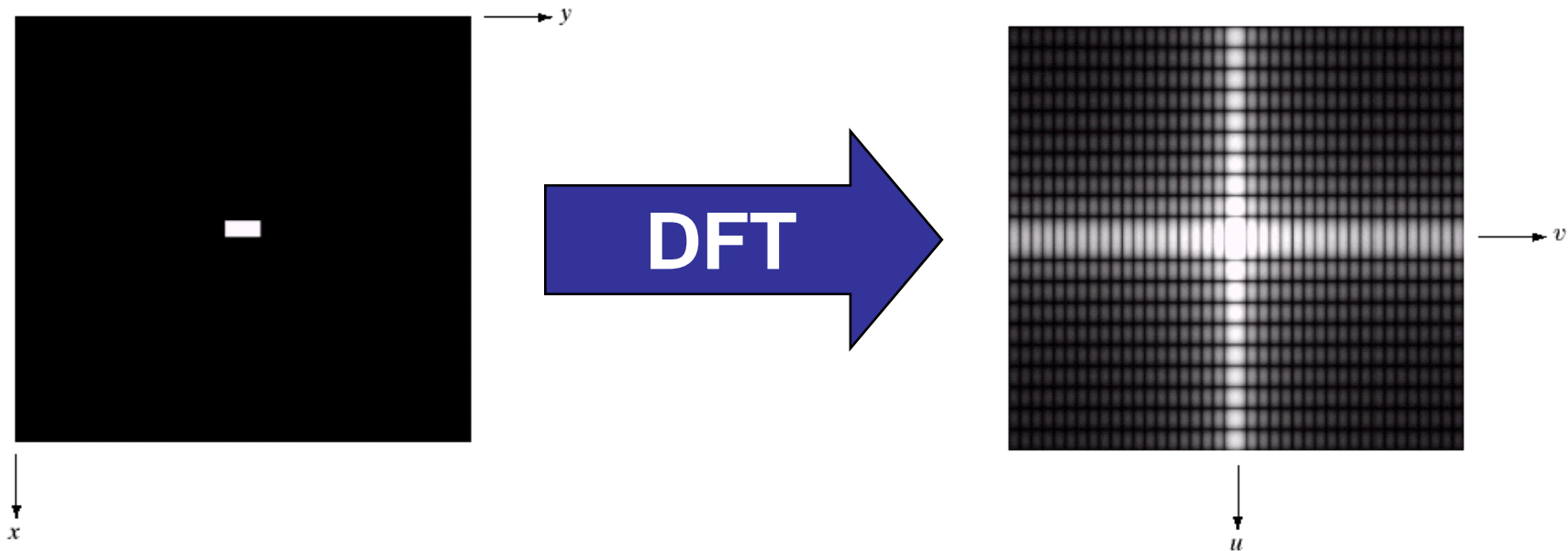
The *Discrete Fourier Transform* of $f(x, y)$, for $x = 0, 1, 2 \dots M-1$ and $y = 0, 1, 2 \dots N-1$, denoted by $F(u, v)$, is given by the equation:

$$F(u, v) = \sum_{x=0}^{M-1} \sum_{y=0}^{N-1} f(x, y) e^{-j2\pi(ux/M + vy/N)}$$

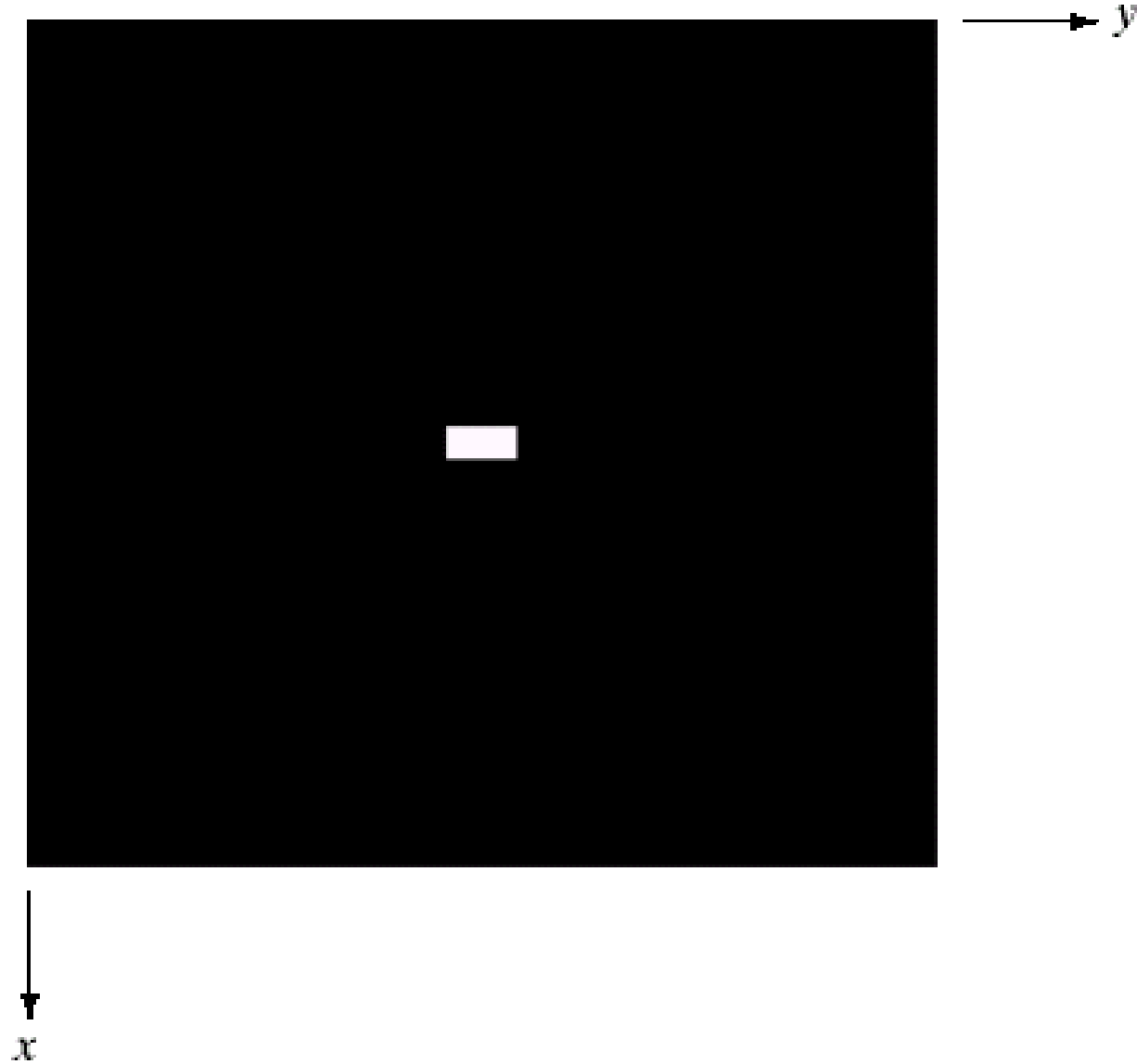
for $u = 0, 1, 2 \dots M-1$ and $v = 0, 1, 2 \dots N-1$.

DFT & Images

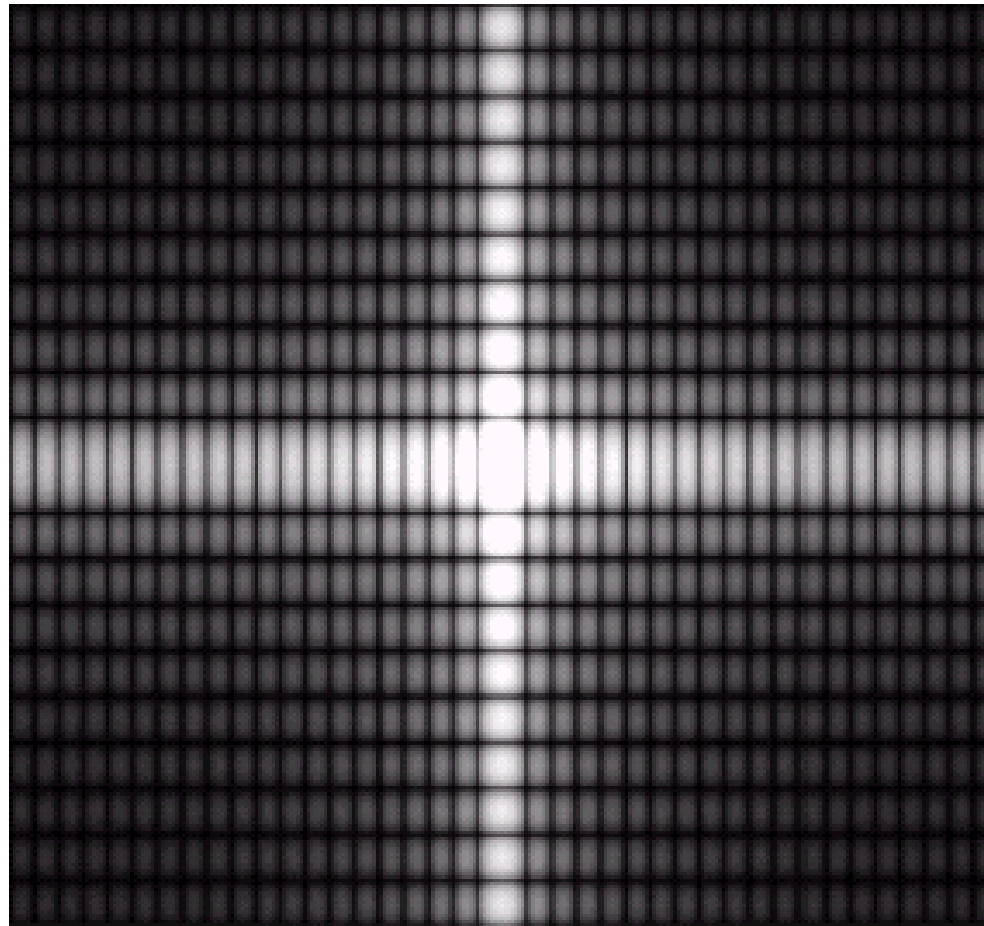
The DFT of a two dimensional image can be visualised by showing the spectrum of the images component frequencies



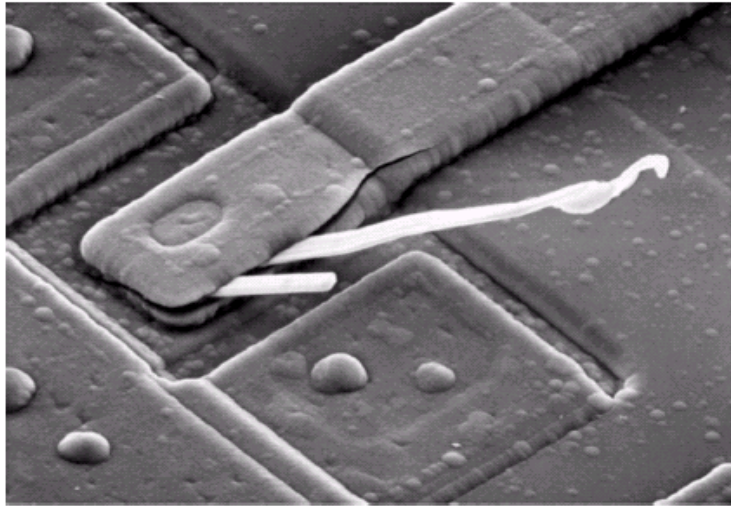
DFT & Images



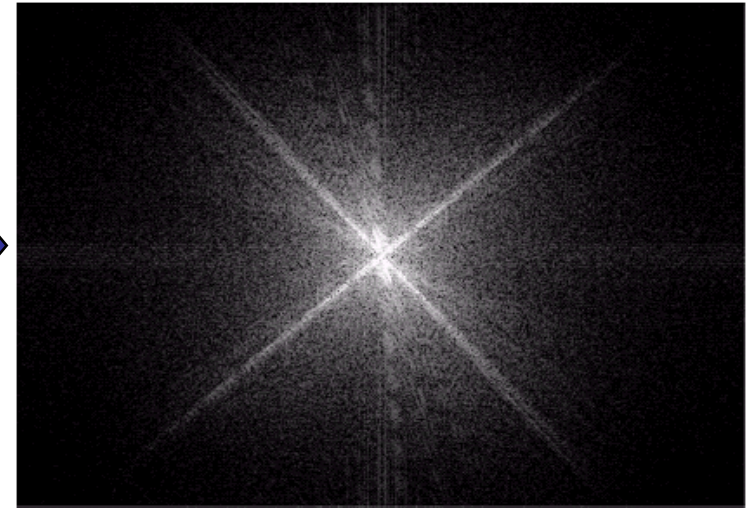
DFT & Images



DFT & Images (cont...)

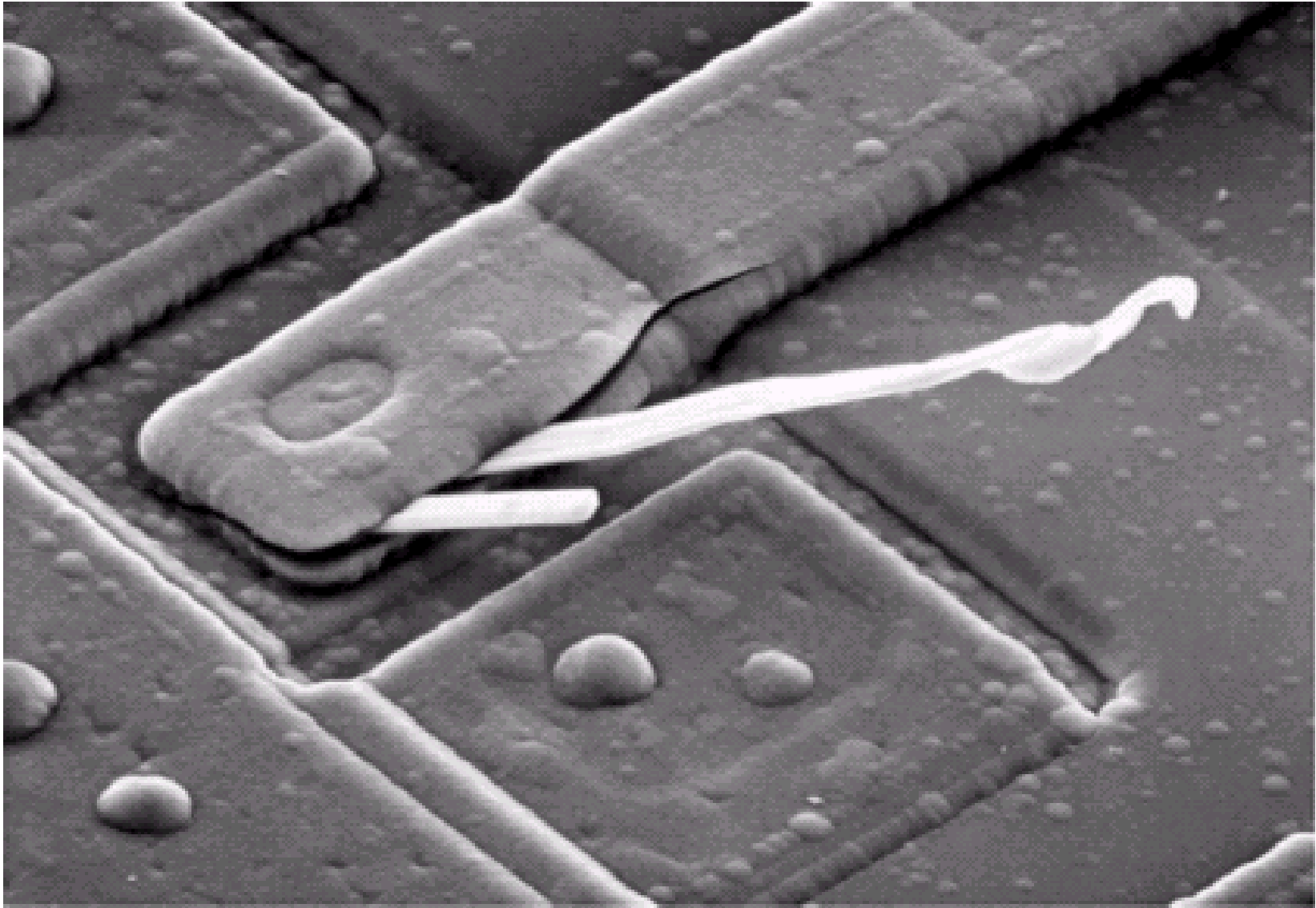


Scanning electron microscope image of an integrated circuit magnified ~2500 times

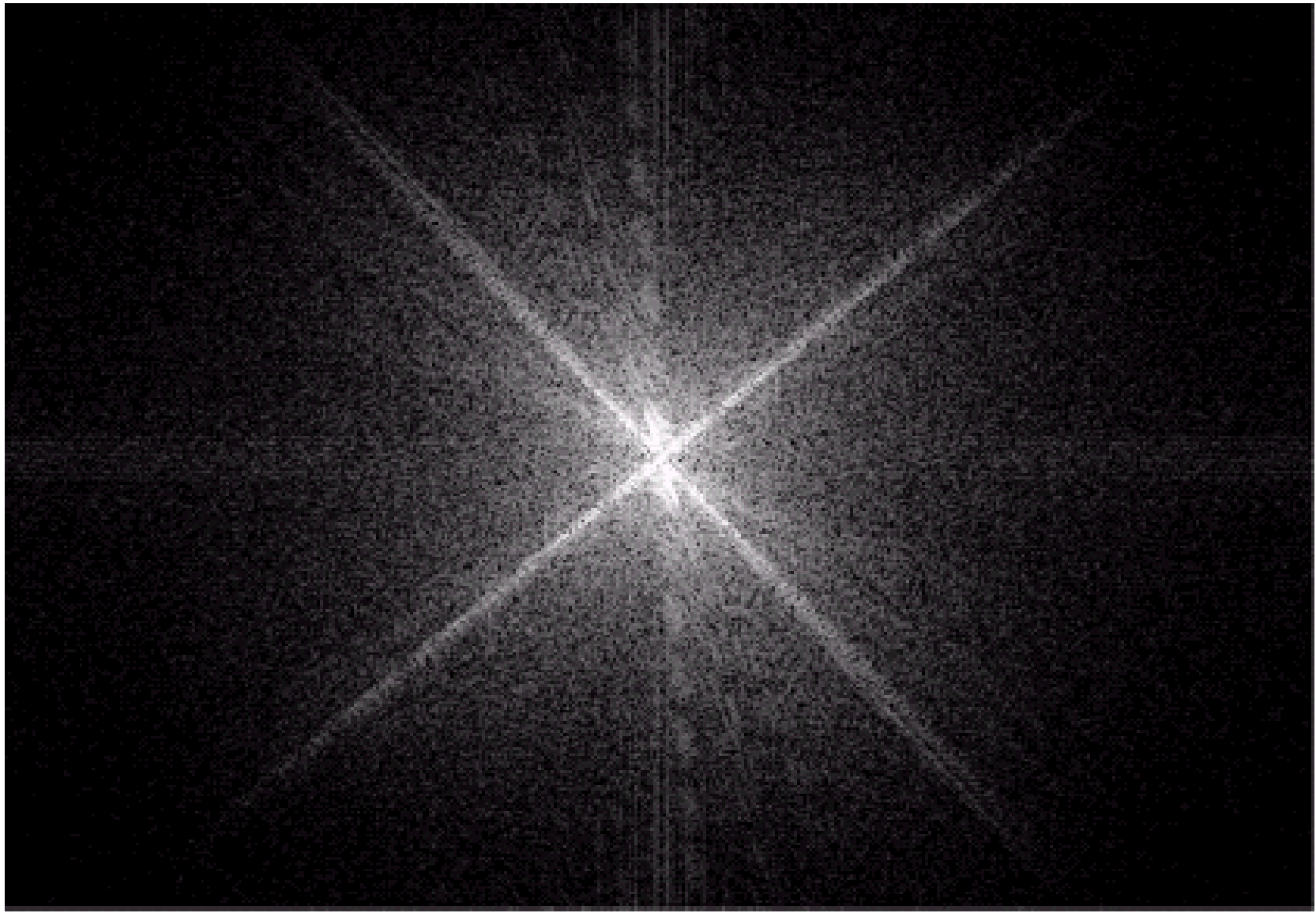


Fourier spectrum of the image

DFT & Images (cont...)



DFT & Images (cont...)



The Inverse DFT

It is really important to note that the Fourier transform is completely **reversible**

The inverse DFT is given by:

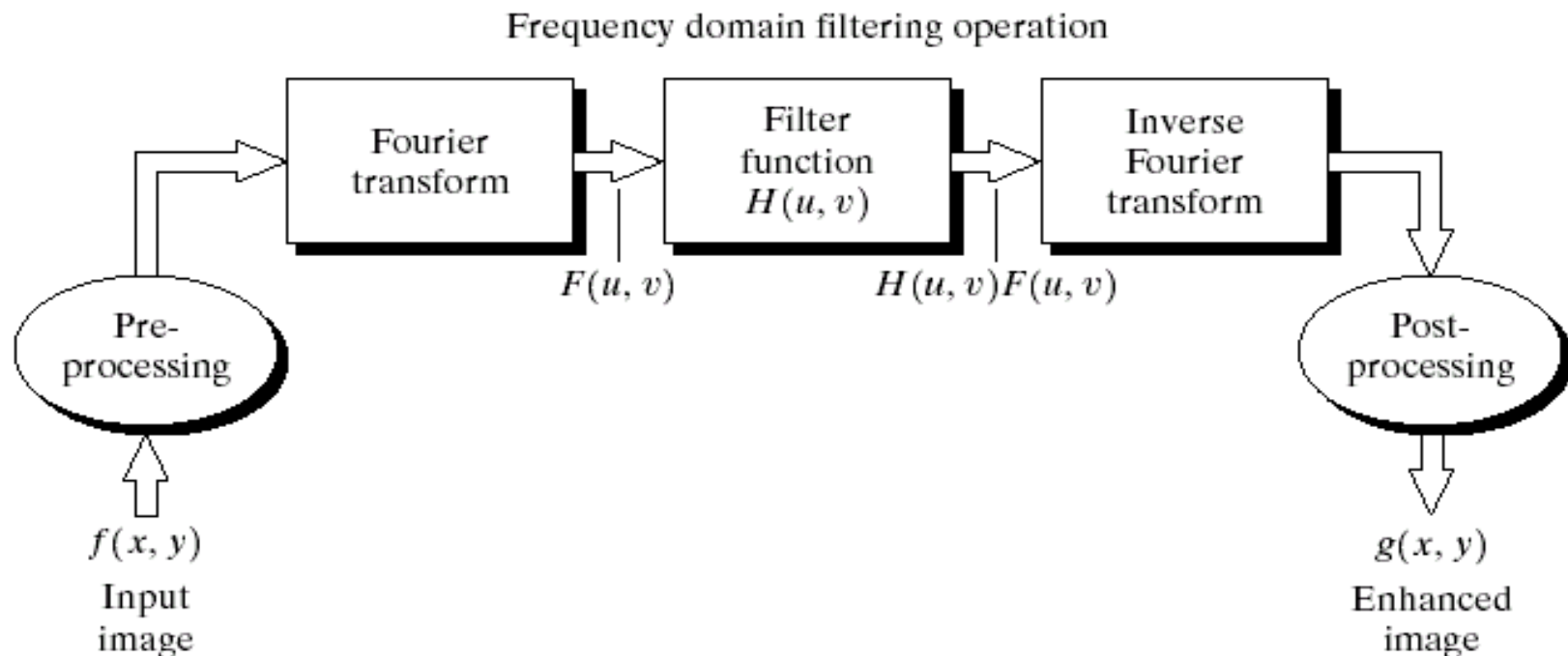
$$f(x, y) = \frac{1}{MN} \sum_{u=0}^{M-1} \sum_{v=0}^{N-1} F(u, v) e^{j2\pi(ux/M + vy/N)}$$

for $x = 0, 1, 2 \dots M-1$ and $y = 0, 1, 2 \dots N-1$

The DFT and Image Processing

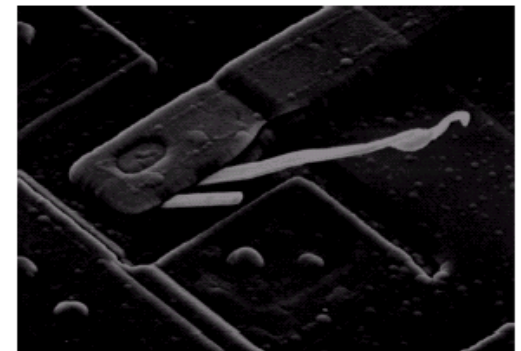
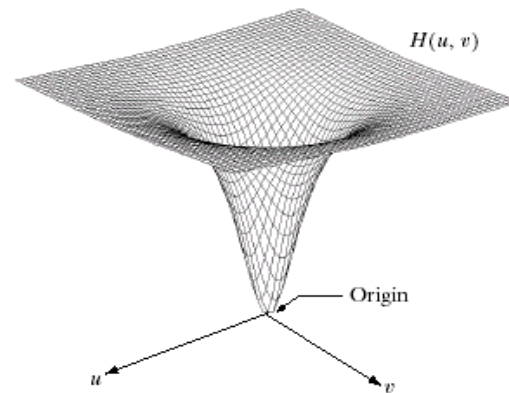
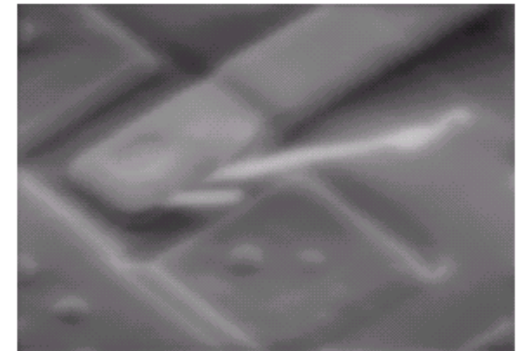
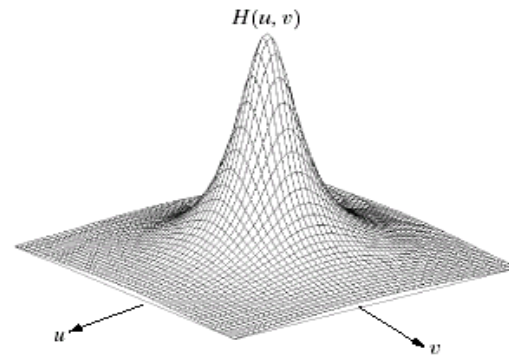
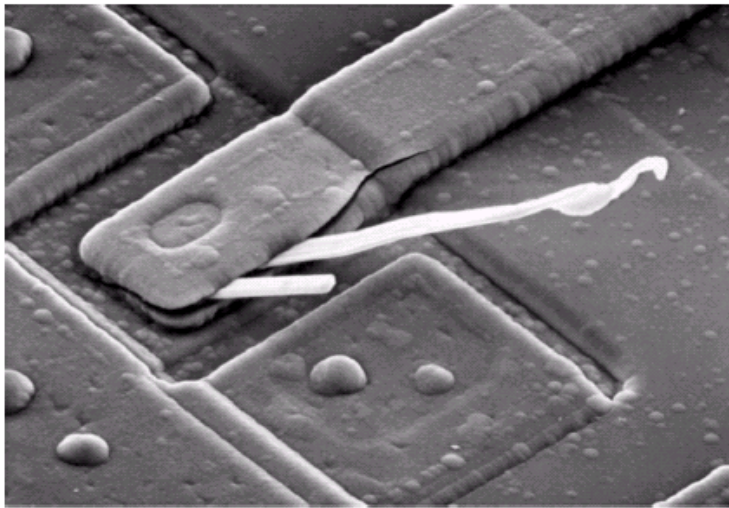
To filter an image in the frequency domain:

1. Compute $F(u, v)$ the DFT of the image
2. Multiply $F(u, v)$ by a filter function $H(u, v)$
3. Compute the inverse DFT of the result



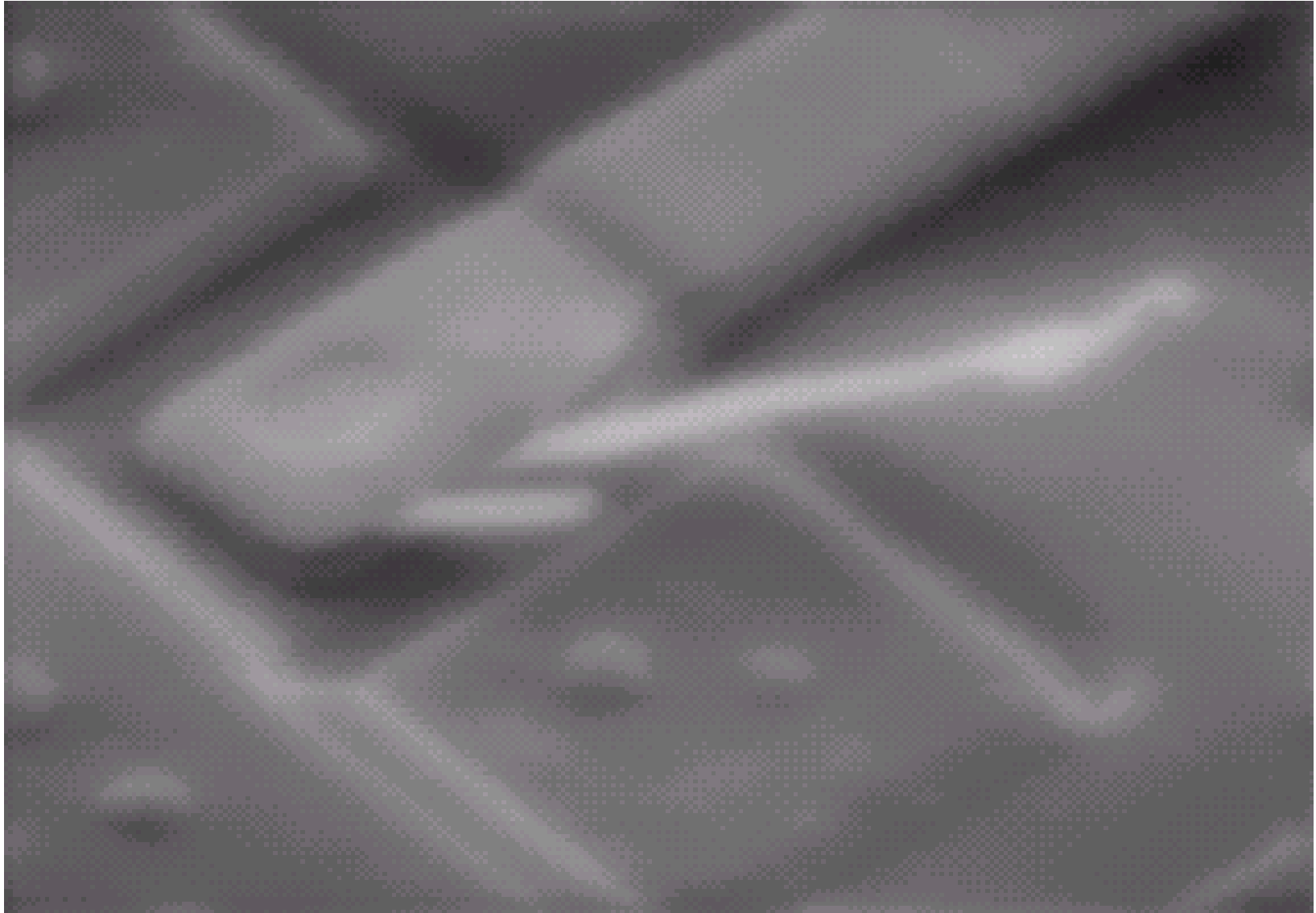
Some Basic Frequency Domain Filters

Low Pass Filter

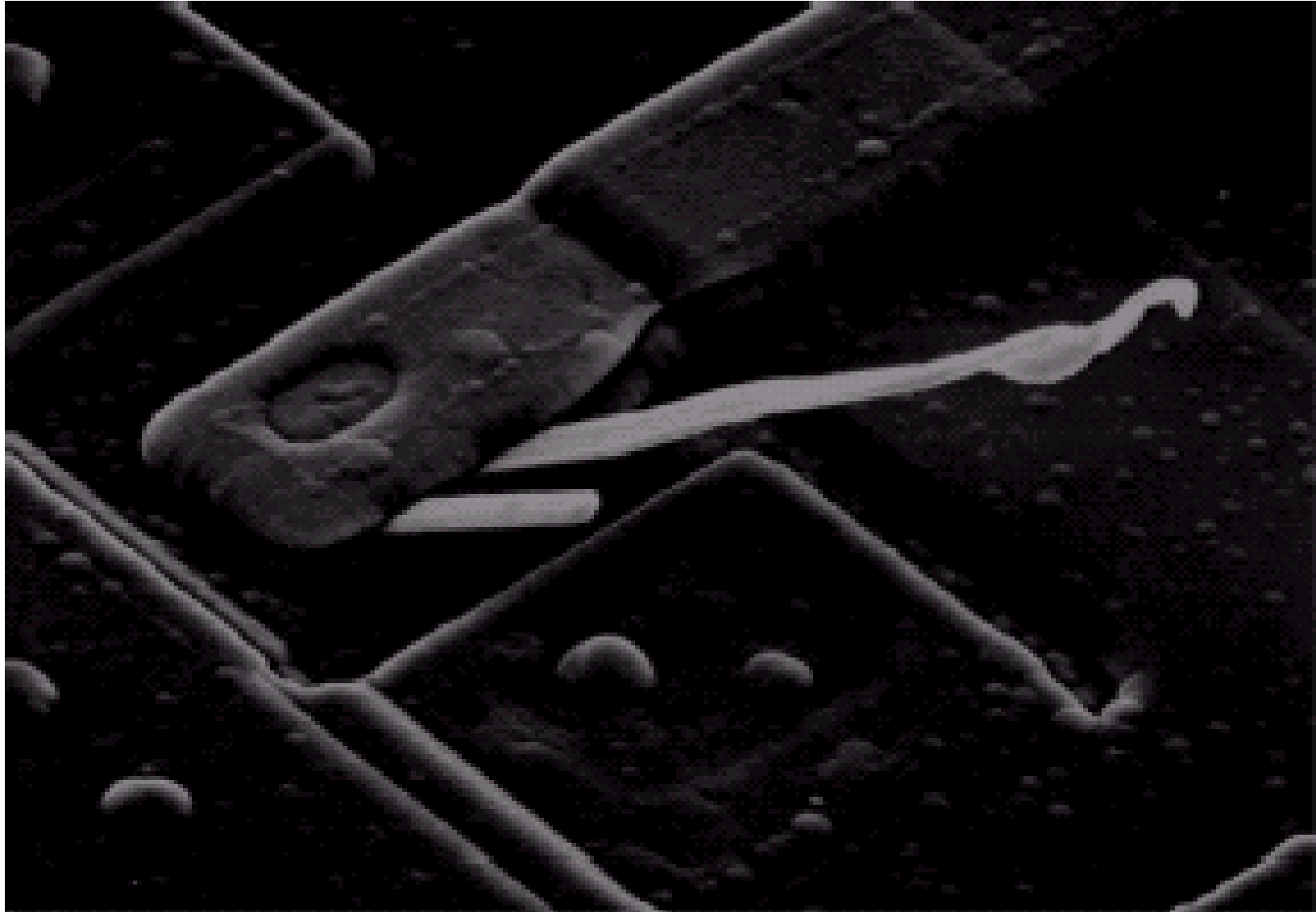


High Pass Filter

Some Basic Frequency Domain Filters



Some Basic Frequency Domain Filters



Smoothing Frequency Domain Filters

Smoothing is achieved in the frequency domain by dropping out the high frequency components

The basic model for filtering is:

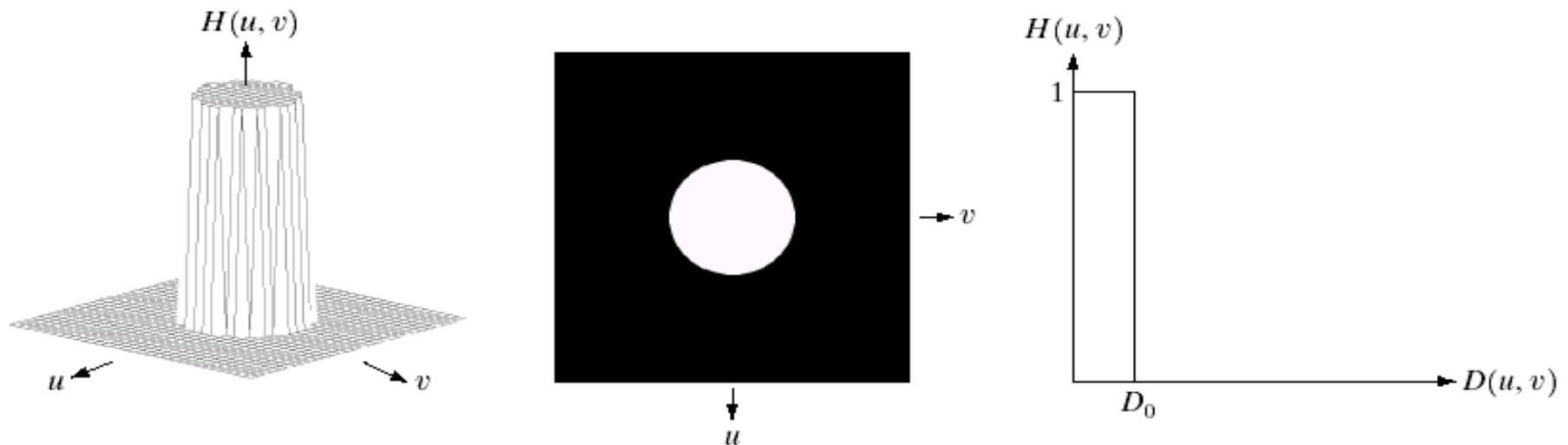
$$G(u,v) = H(u,v)F(u,v)$$

where $F(u,v)$ is the Fourier transform of the image being filtered and $H(u,v)$ is the filter transform function

Low pass filters – only pass the low frequencies, drop the high ones

Ideal Low Pass Filter

Simply cut off all high frequency components that are a specified distance D_0 from the origin of the transform



changing the distance changes the behaviour of the filter

Ideal Low Pass Filter (cont...)

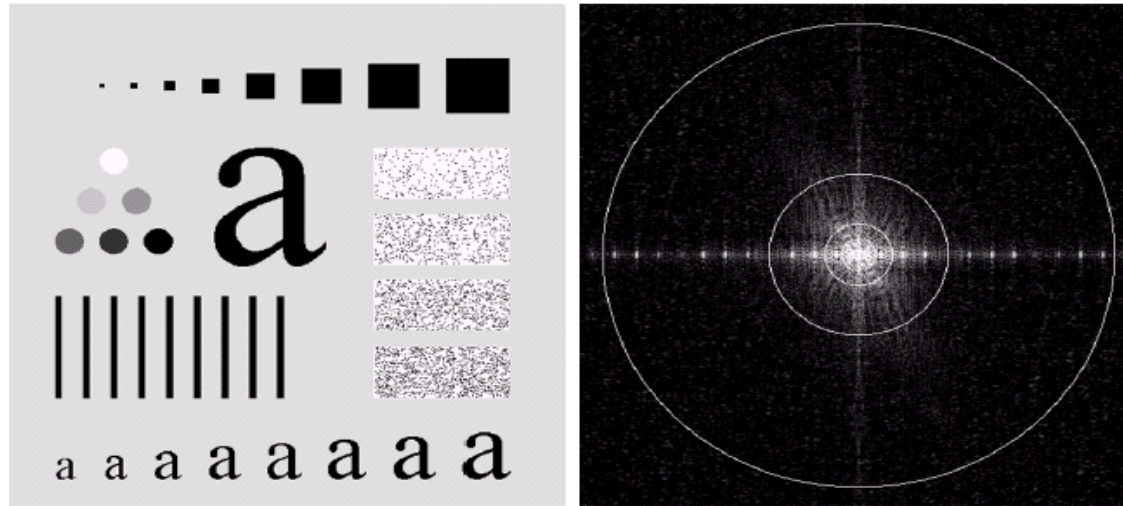
The transfer function for the ideal low pass filter can be given as:

$$H(u, v) = \begin{cases} 1 & \text{if } D(u, v) \leq D_0 \\ 0 & \text{if } D(u, v) > D_0 \end{cases}$$

where $D(u, v)$ is given as:

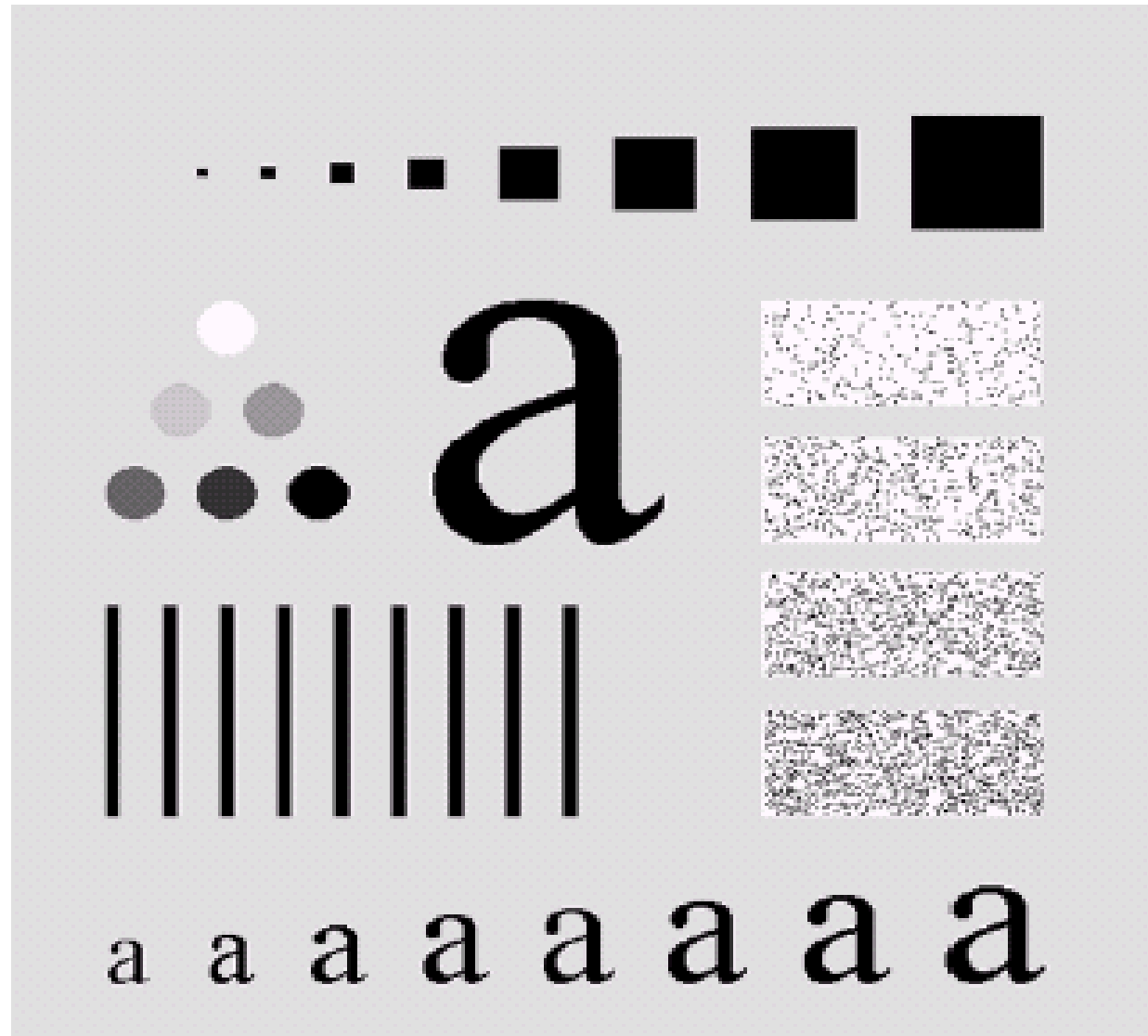
$$D(u, v) = [(u - M / 2)^2 + (v - N / 2)^2]^{1/2}$$

Ideal Low Pass Filter (cont...)

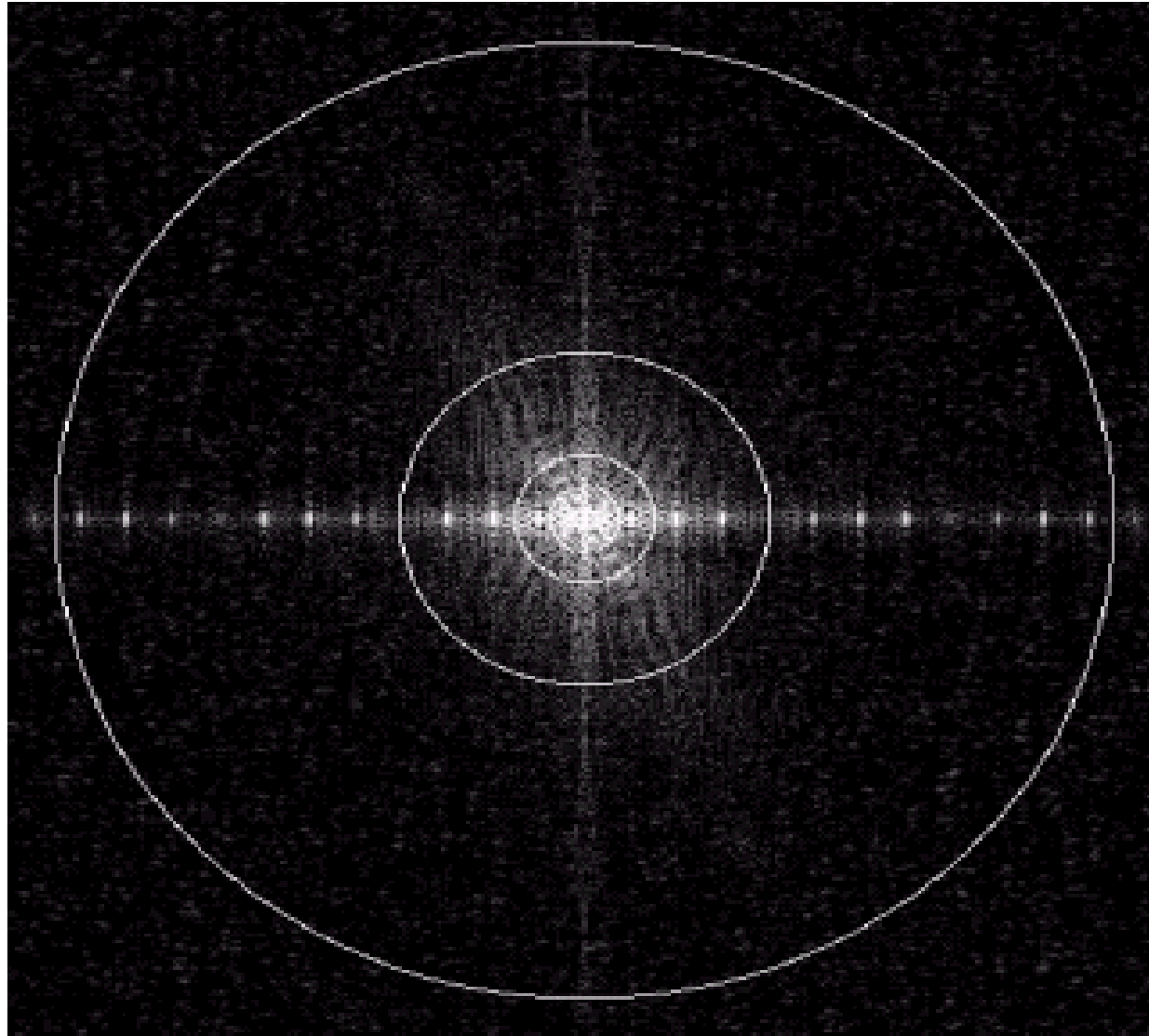


Above we show an image, it's Fourier spectrum and a series of ideal low pass filters of radius 5, 15, 30, 80 and 230 superimposed on top of it

Ideal Low Pass Filter (cont...)

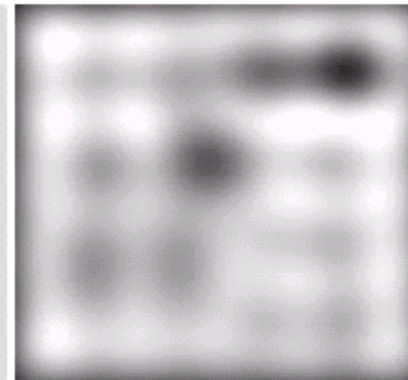
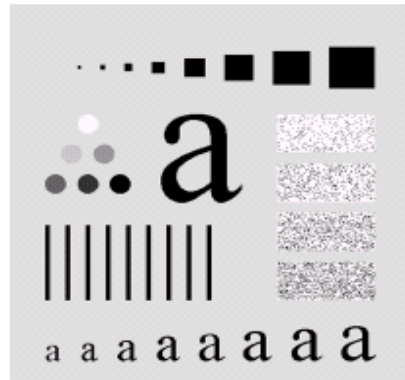


Ideal Low Pass Filter (cont...)



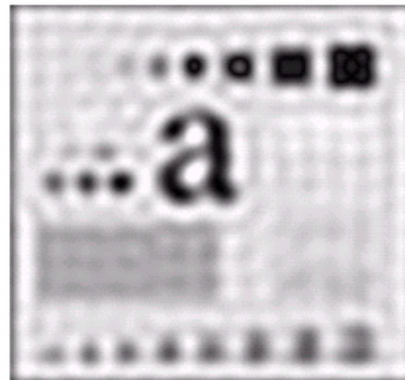
Ideal Low Pass Filter (cont...)

Original image



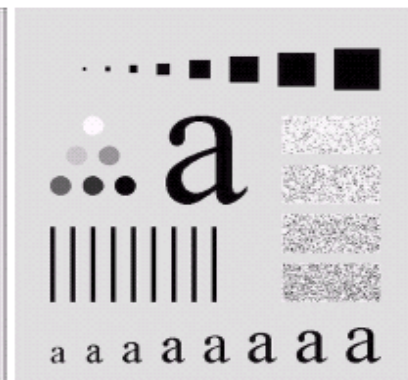
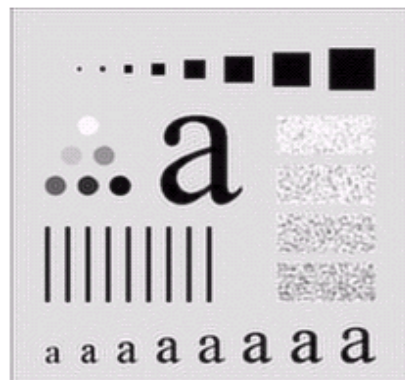
Result of filtering with ideal low pass filter of radius 5

Result of filtering with ideal low pass filter of radius 15



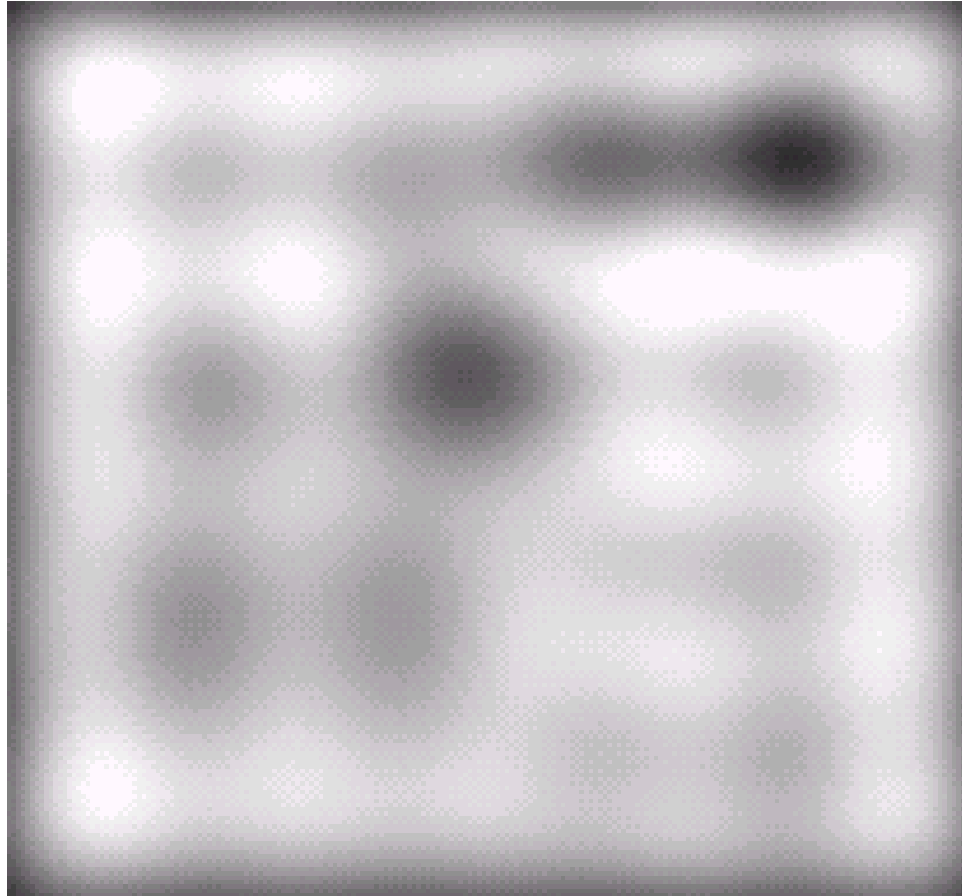
Result of filtering with ideal low pass filter of radius 30

Result of filtering with ideal low pass filter of radius 80



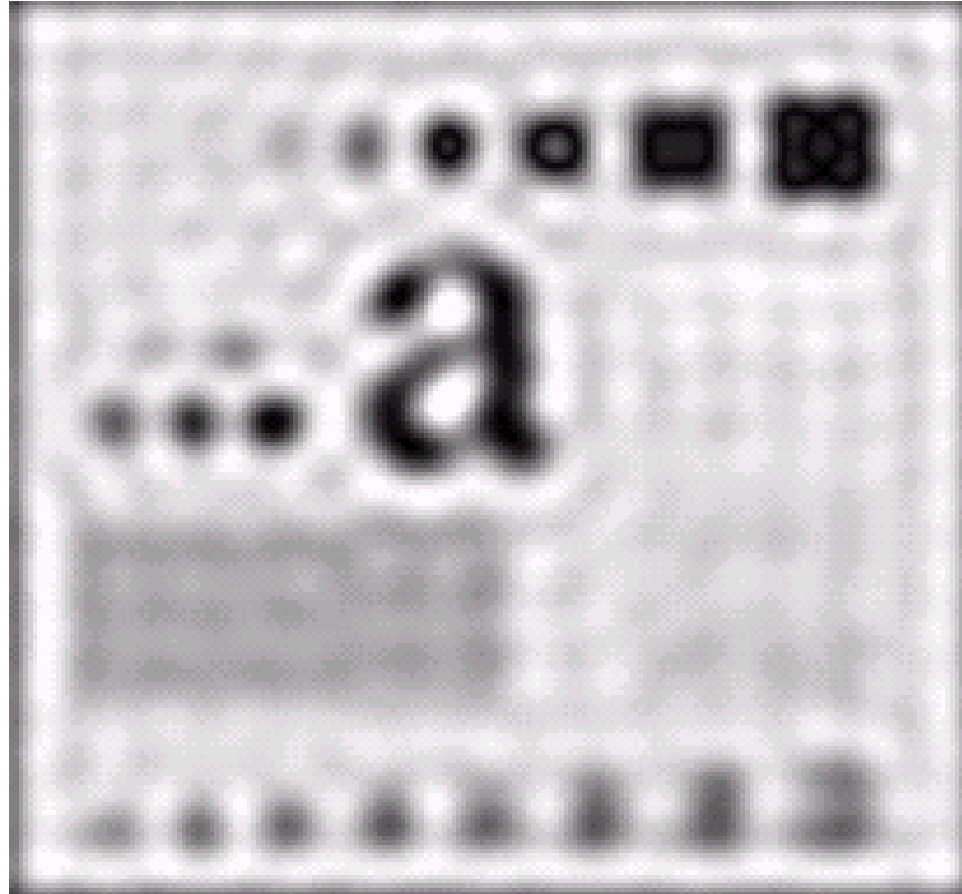
Result of filtering with ideal low pass filter of radius 230

Ideal Low Pass Filter (cont...)



Result of filtering
with ideal low pass
filter of radius 5

Ideal Low Pass Filter (cont...)

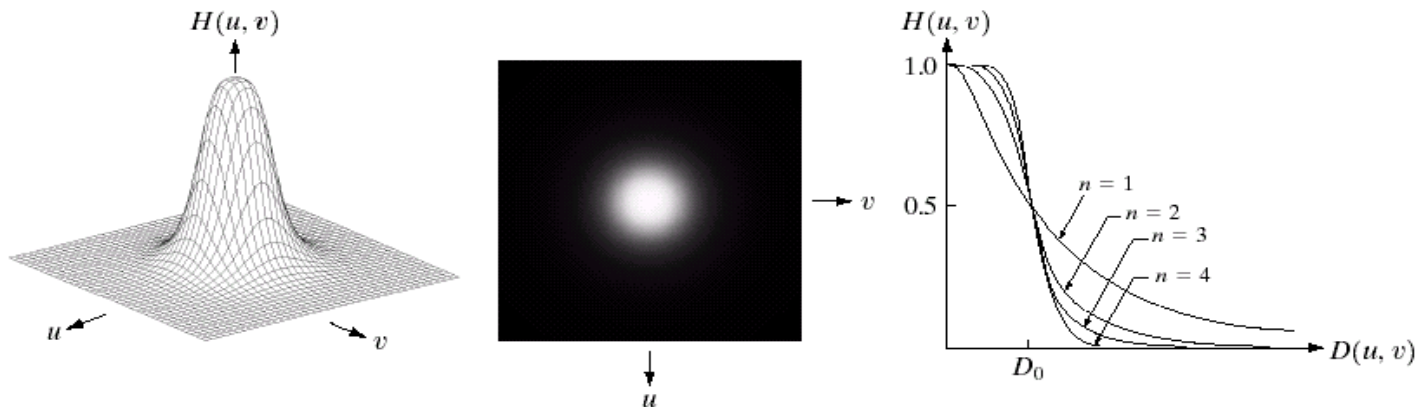


Result of filtering
with ideal low pass
filter of radius 15

Butterworth Lowpass Filters

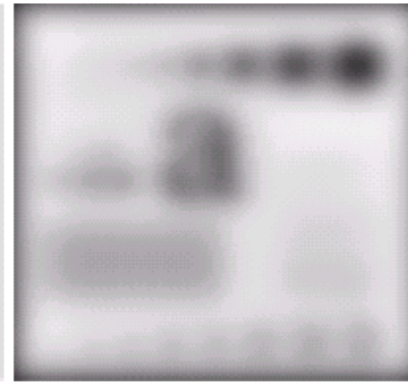
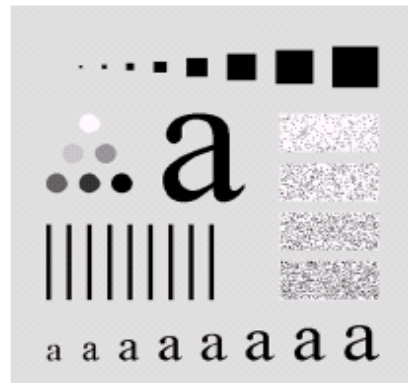
The transfer function of a Butterworth lowpass filter of order n with cutoff frequency at distance D_0 from the origin is defined as:

$$H(u, v) = \frac{1}{1 + [D(u, v) / D_0]^{2n}}$$



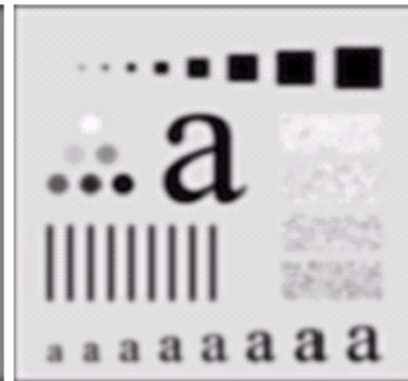
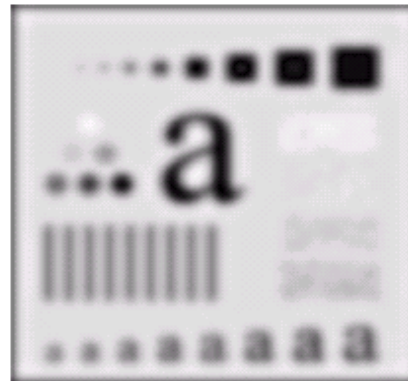
Butterworth Lowpass Filter (cont...)

Original image



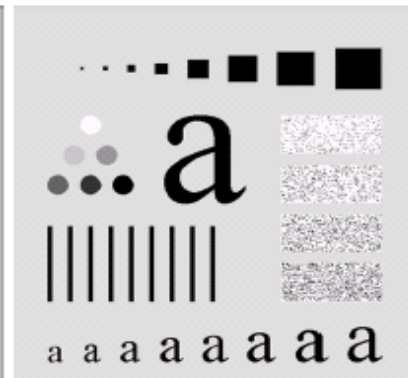
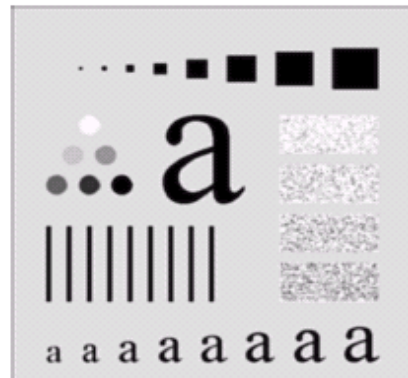
Result of filtering with Butterworth filter of order 2 and cutoff radius 5

Result of filtering with Butterworth filter of order 2 and cutoff radius 15



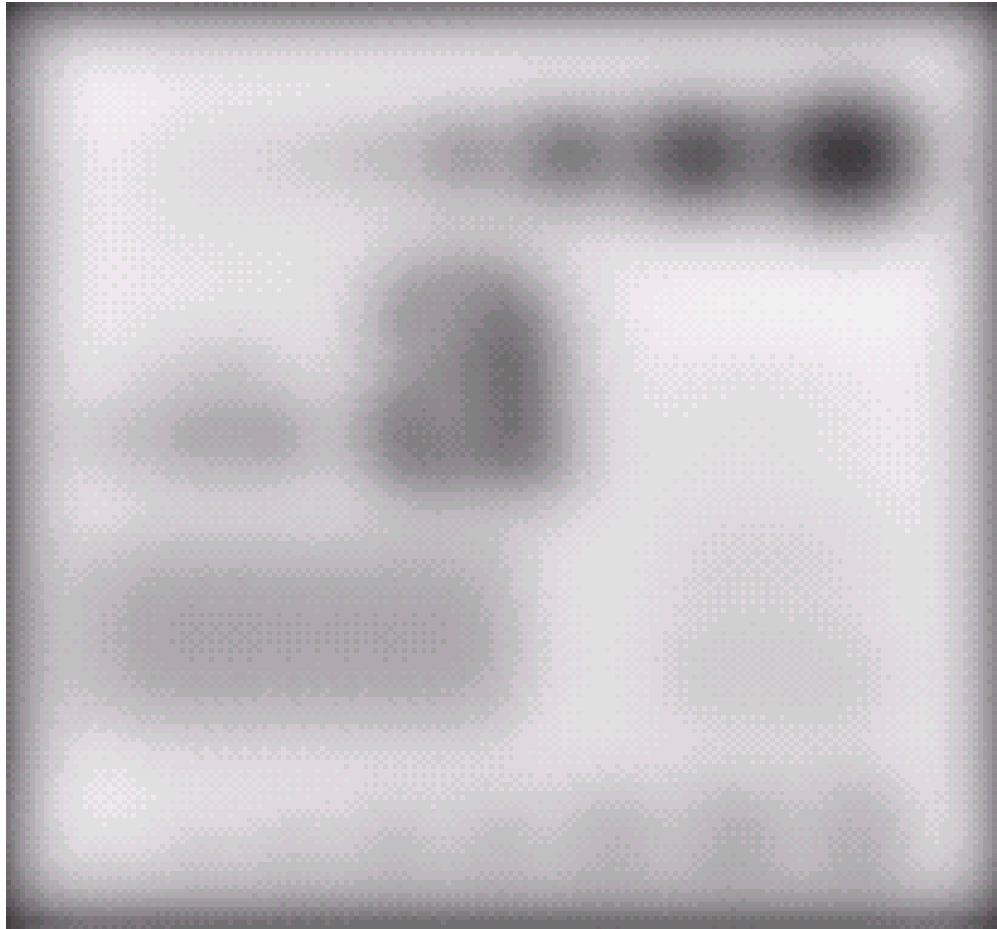
Result of filtering with Butterworth filter of order 2 and cutoff radius 30

Result of filtering with Butterworth filter of order 2 and cutoff radius 80



Result of filtering with Butterworth filter of order 2 and cutoff radius 230

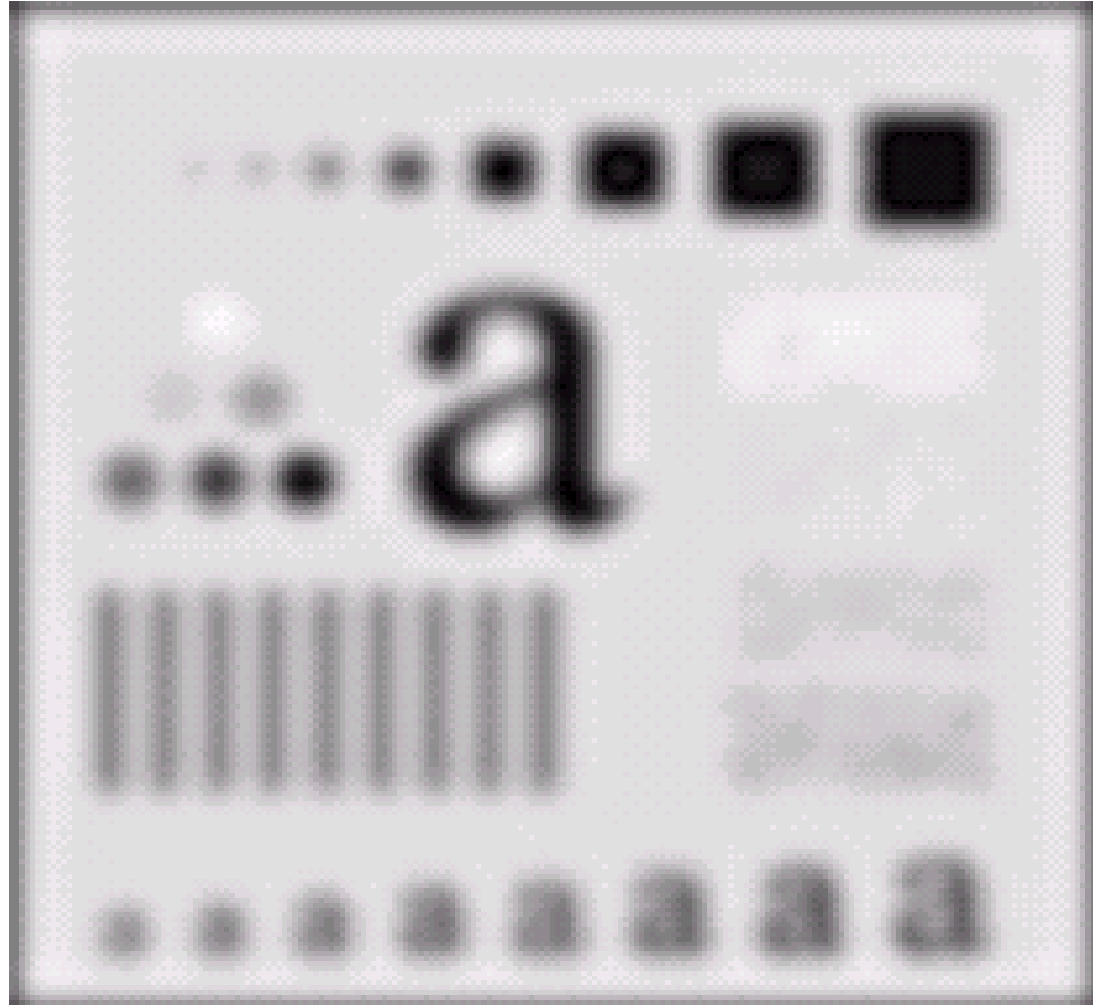
Butterworth Lowpass Filter (cont...)



Result of filtering
with Butterworth filter
of order 2 and cutoff
radius 5

Butterworth Lowpass Filter (cont...)

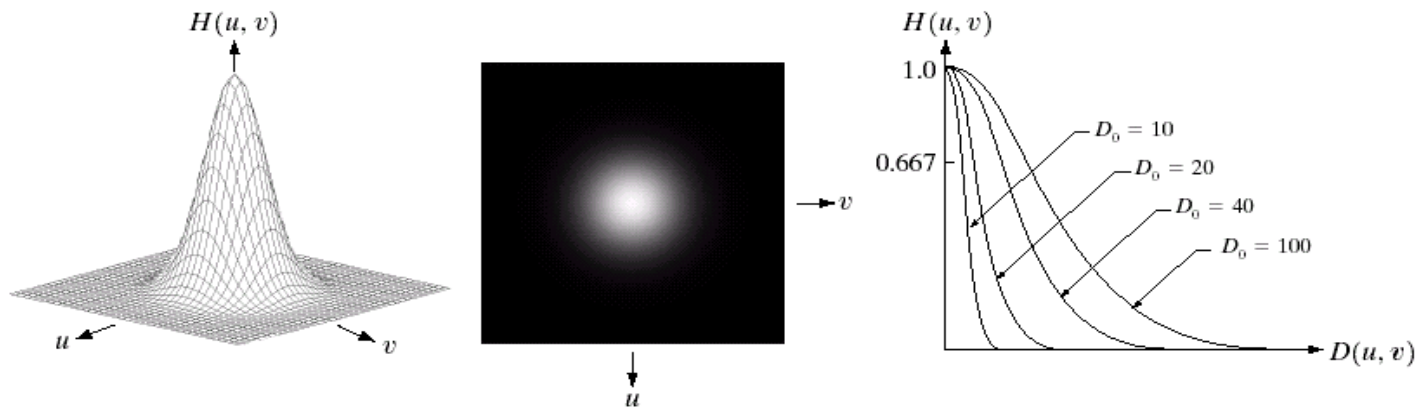
Result of filtering with
Butterworth filter of
order 2 and cutoff
radius 15



Gaussian Lowpass Filters

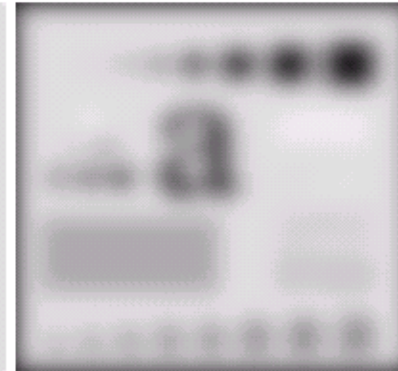
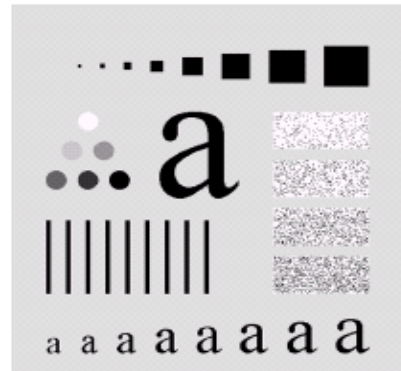
The transfer function of a Gaussian lowpass filter is defined as:

$$H(u, v) = e^{-D^2(u, v) / 2D_0^2}$$



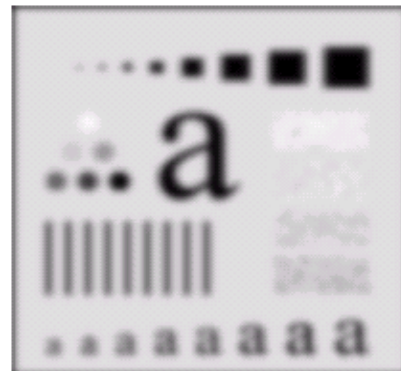
Gaussian Lowpass Filters (cont...)

Original image



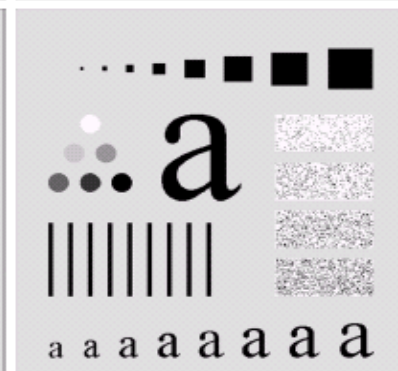
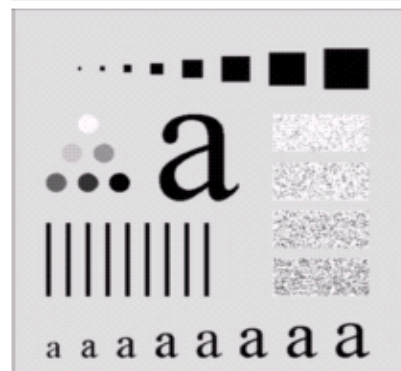
Result of filtering with Gaussian filter with cutoff radius 5

Result of filtering with Gaussian filter with cutoff radius 15



Result of filtering with Gaussian filter with cutoff radius 30

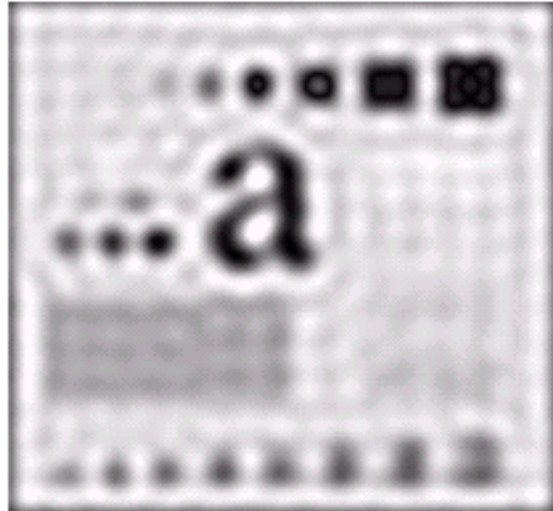
Result of filtering with Gaussian filter with cutoff radius 85



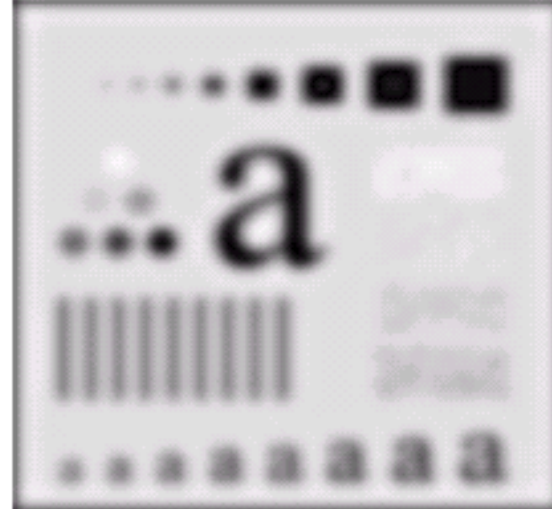
Result of filtering with Gaussian filter with cutoff radius 230

Lowpass Filters Compared

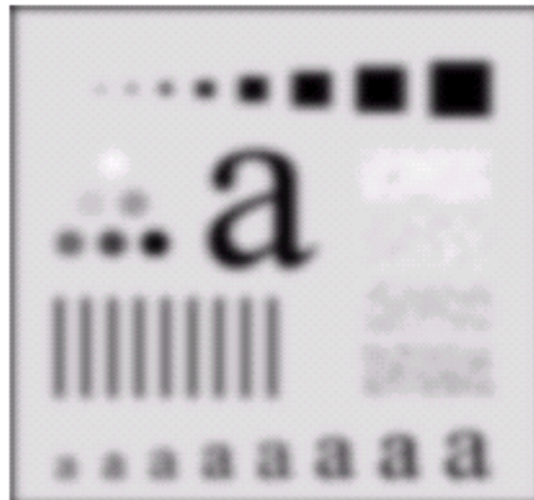
Result of filtering
with ideal low pass
filter of radius 15



Result of filtering
with Butterworth
filter of order 2
and cutoff radius
15

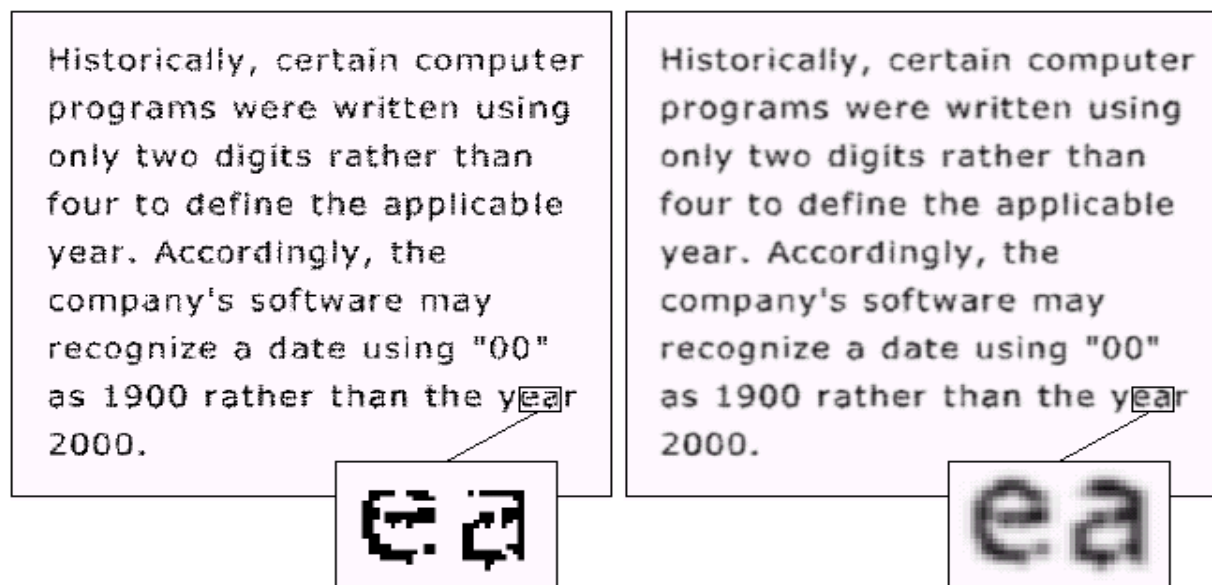


Result of filtering
with Gaussian
filter with cutoff
radius 15



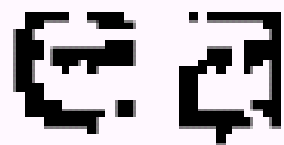
Lowpass Filtering Examples

A low pass Gaussian filter is used to connect broken text

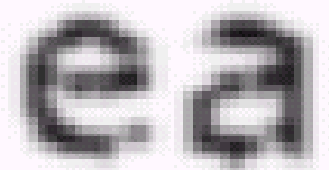


Lowpass Filtering Examples

Historically, certain computer programs were written using only two digits rather than four to define the applicable year. Accordingly, the company's software may recognize a date using "00" as 1900 rather than the year 2000.



Historically, certain computer programs were written using only two digits rather than four to define the applicable year. Accordingly, the company's software may recognize a date using "00" as 1900 rather than the year 2000.



Lowpass Filtering Examples (cont...)

Different lowpass Gaussian filters used to remove blemishes in a photograph

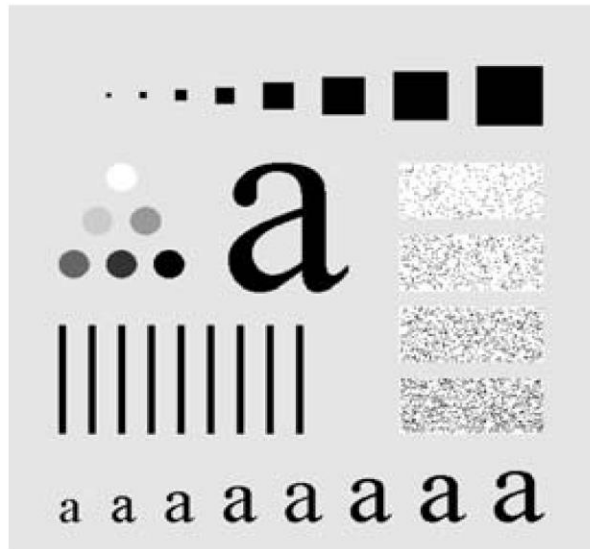


Lowpass Filtering Examples (cont...)

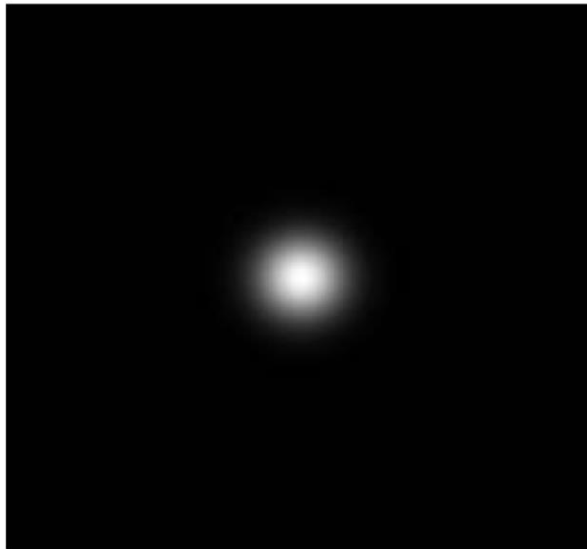


Lowpass Filtering Examples (cont...)

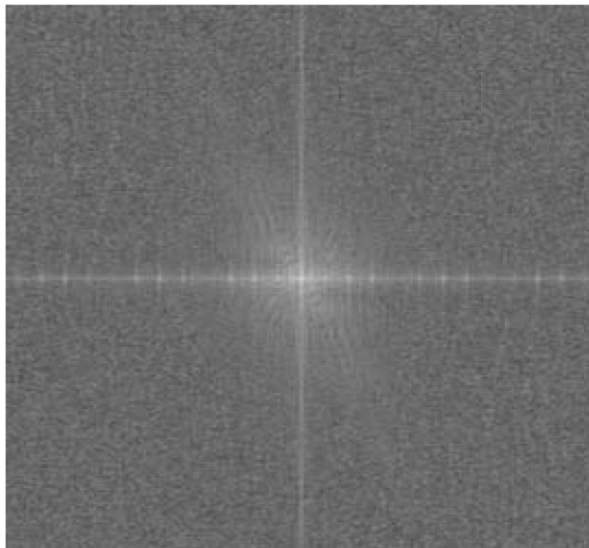
Original image



Gaussian lowpass filter



Spectrum of original image



Processed image



Sharpening in the Frequency Domain

Edges and fine detail in images are associated with high frequency components

High pass filters – only pass the high frequencies, drop the low ones

High pass frequencies are precisely the reverse of low pass filters, so:

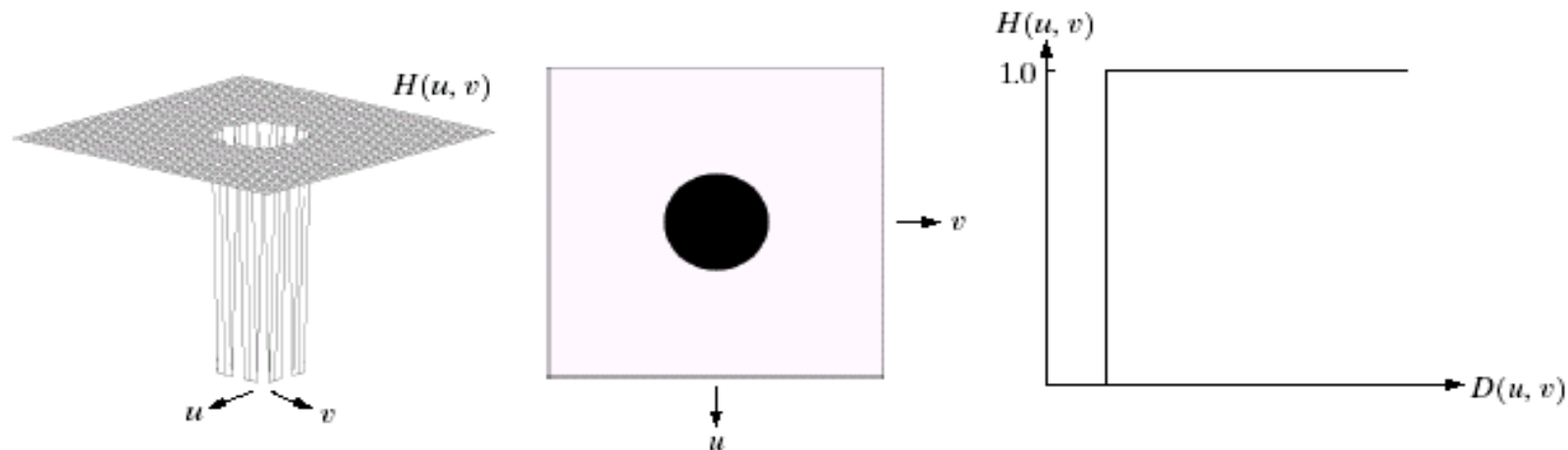
$$H_{hp}(u, v) = 1 - H_{lp}(u, v)$$

Ideal High Pass Filters

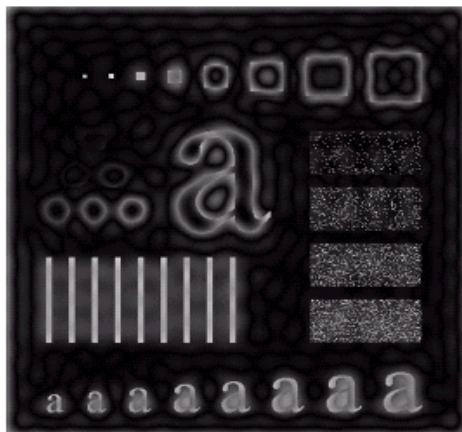
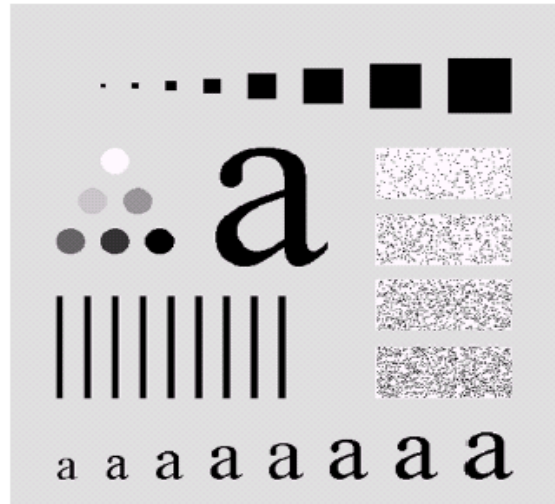
The ideal high pass filter is given as:

$$H(u, v) = \begin{cases} 0 & \text{if } D(u, v) \leq D_0 \\ 1 & \text{if } D(u, v) > D_0 \end{cases}$$

where D_0 is the cut off distance as before



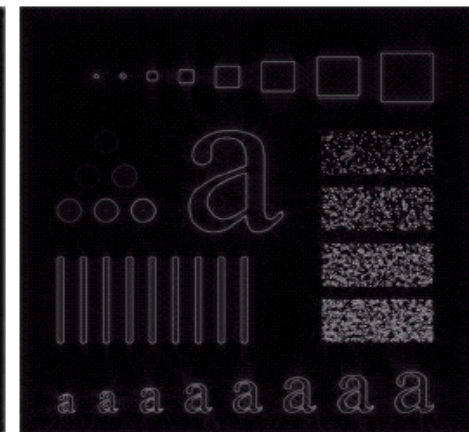
Ideal High Pass Filters (cont...)



Results of ideal
high pass filtering
with $D_0 = 15$



Results of ideal
high pass filtering
with $D_0 = 30$



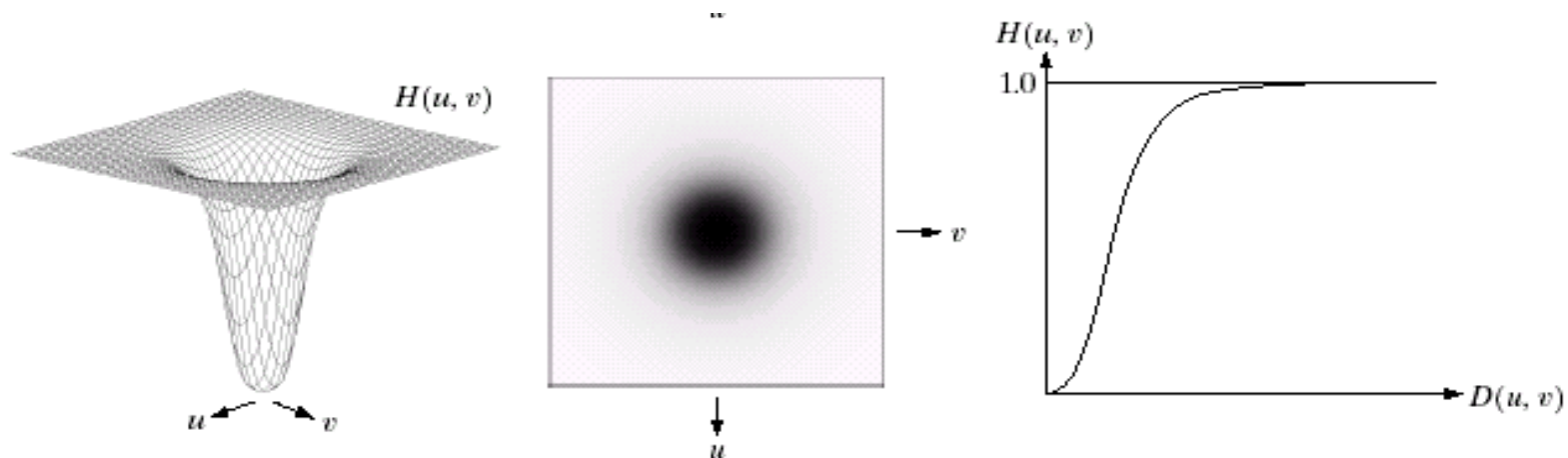
Results of ideal
high pass filtering
with $D_0 = 80$

Butterworth High Pass Filters

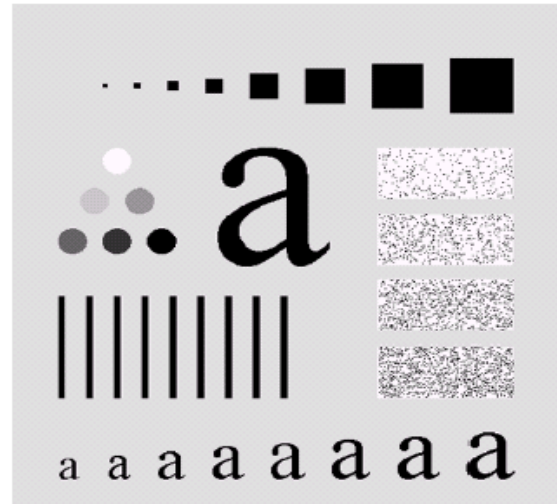
The Butterworth high pass filter is given as:

$$H(u, v) = \frac{1}{1 + [D_0 / D(u, v)]^{2n}}$$

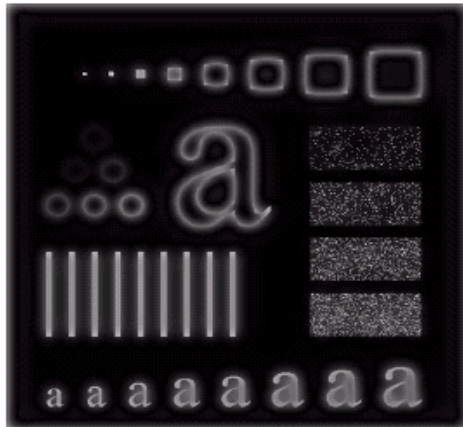
where n is the order and D_0 is the cut off distance as before



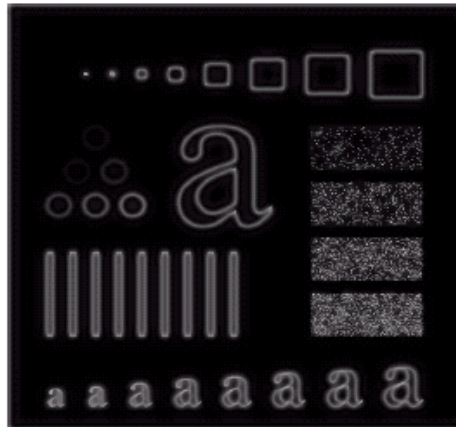
Butterworth High Pass Filters (cont...)



Results of
Butterworth
high pass
filtering of
order 2 with
 $D_0 = 15$



Results of Butterworth high pass
filtering of order 2 with $D_0 = 30$



Results of
Butterworth
high pass
filtering of
order 2 with
 $D_0 = 80$

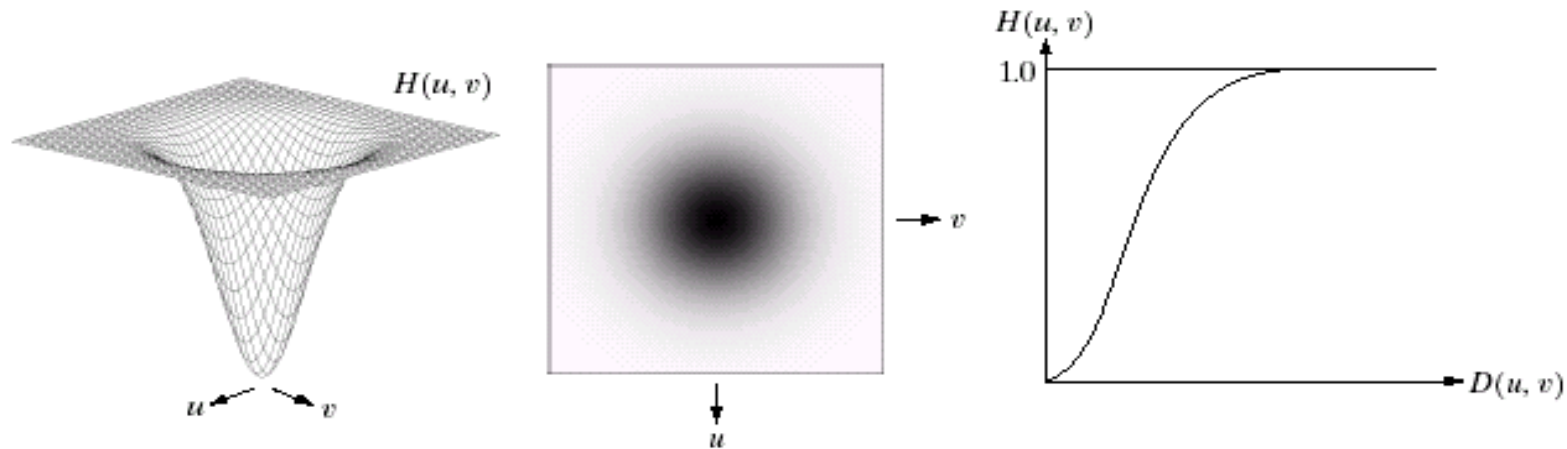


Gaussian High Pass Filters

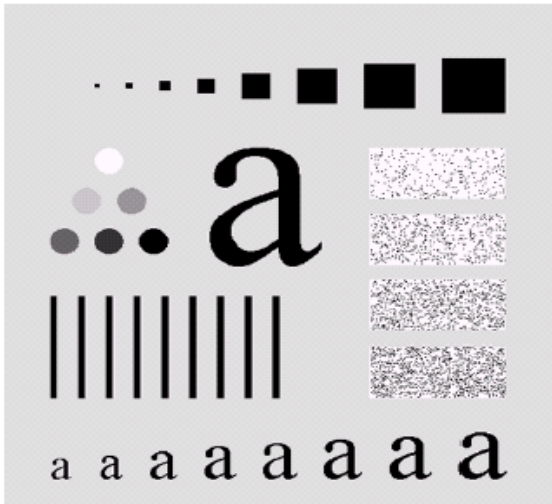
The Gaussian high pass filter is given as:

$$H(u, v) = 1 - e^{-D^2(u, v) / 2D_0^2}$$

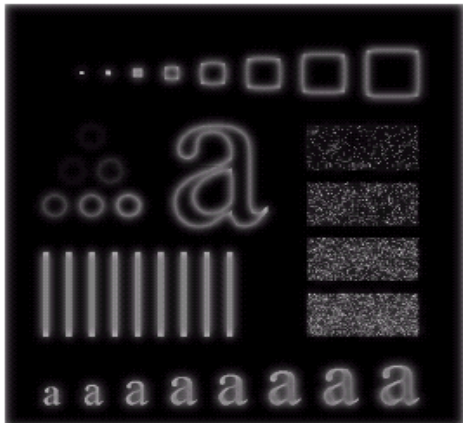
where D_0 is the cut off distance as before



Gaussian High Pass Filters (cont...)



Results of
Gaussian
high pass
filtering with
 $D_0 = 15$



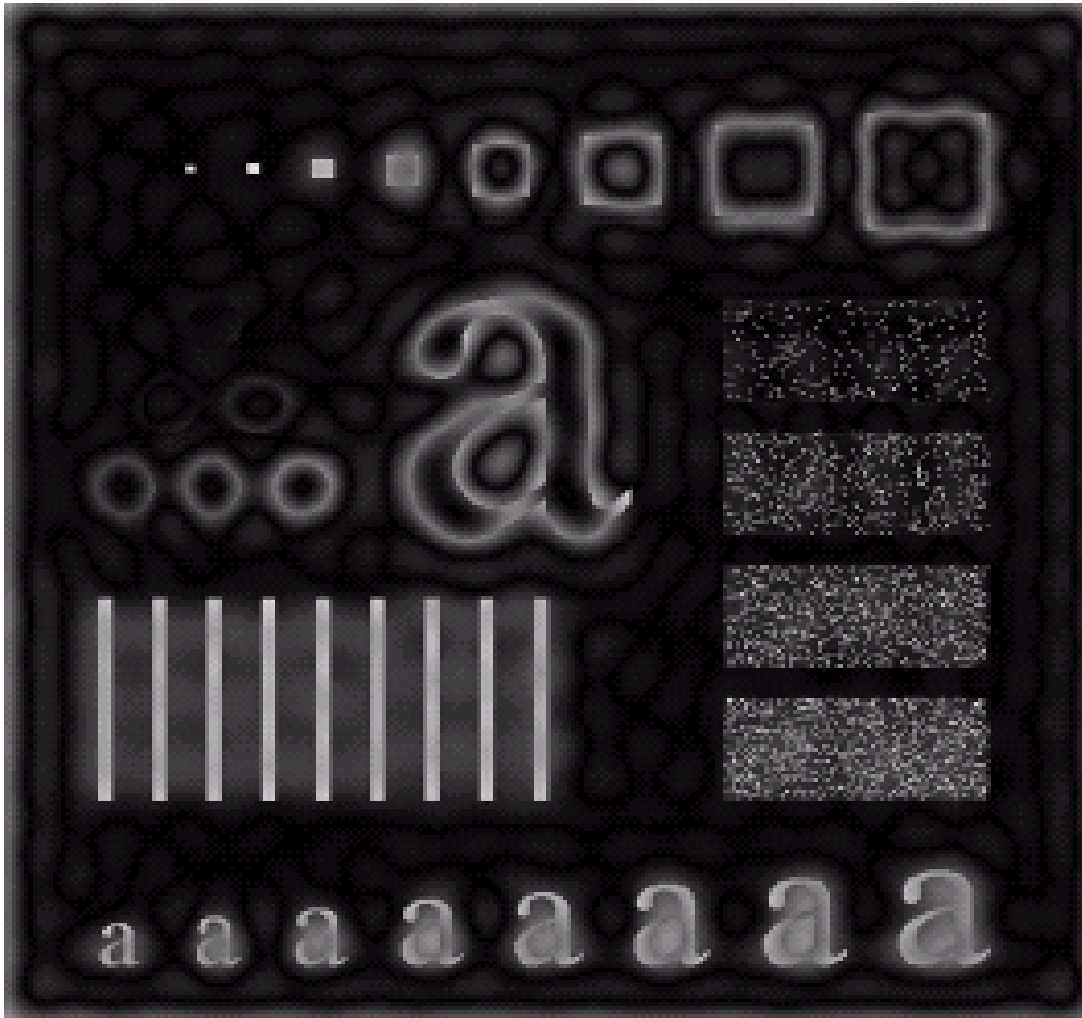
Results of Gaussian high pass
filtering with $D_0 = 30$



Results of
Gaussian
high pass
filtering with
 $D_0 = 80$

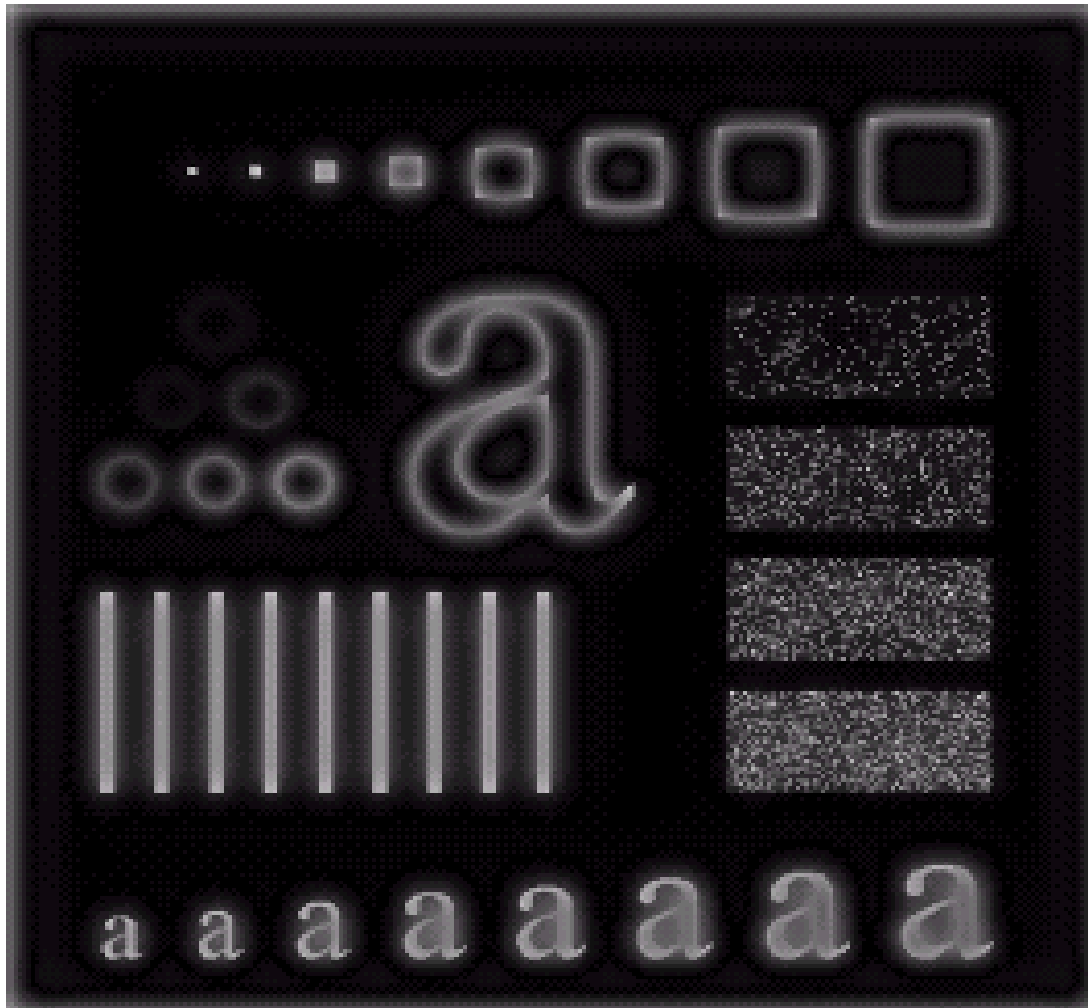


Highpass Filter Comparison



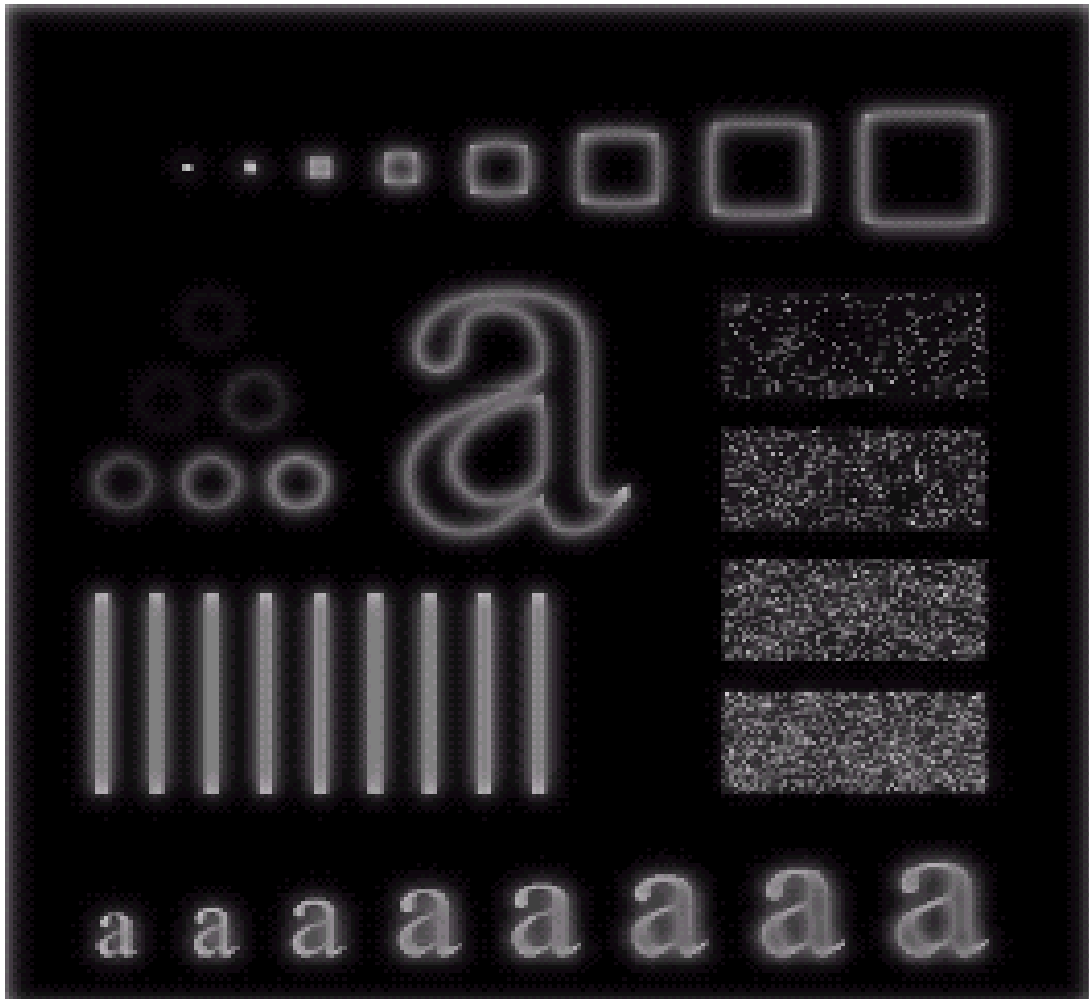
Results of ideal
high pass filtering
with $D_0 = 15$

Highpass Filter Comparison



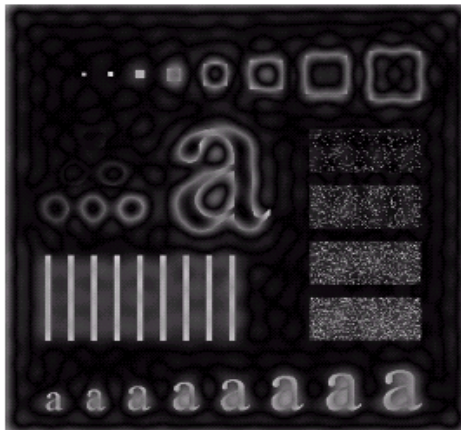
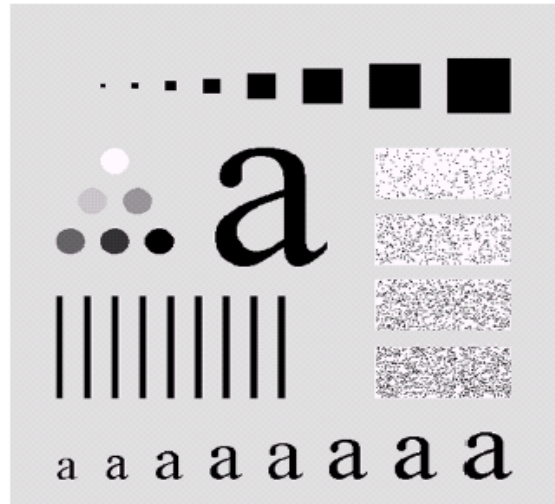
Results of Butterworth
high pass filtering of order
2 with $D_0 = 15$

Highpass Filter Comparison

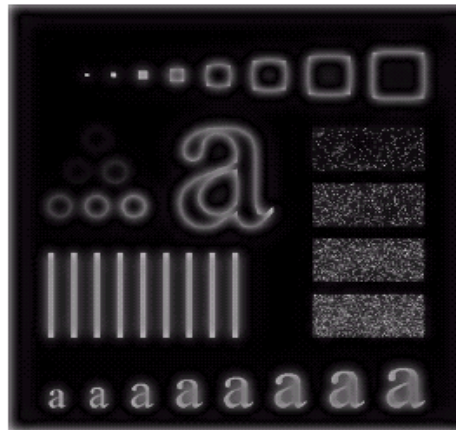


Results of Gaussian
high pass filtering with
 $D_0 = 15$

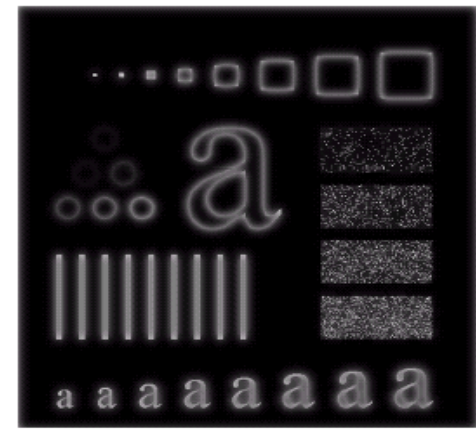
Highpass Filter Comparison



Results of ideal
high pass filtering
with $D_0 = 15$

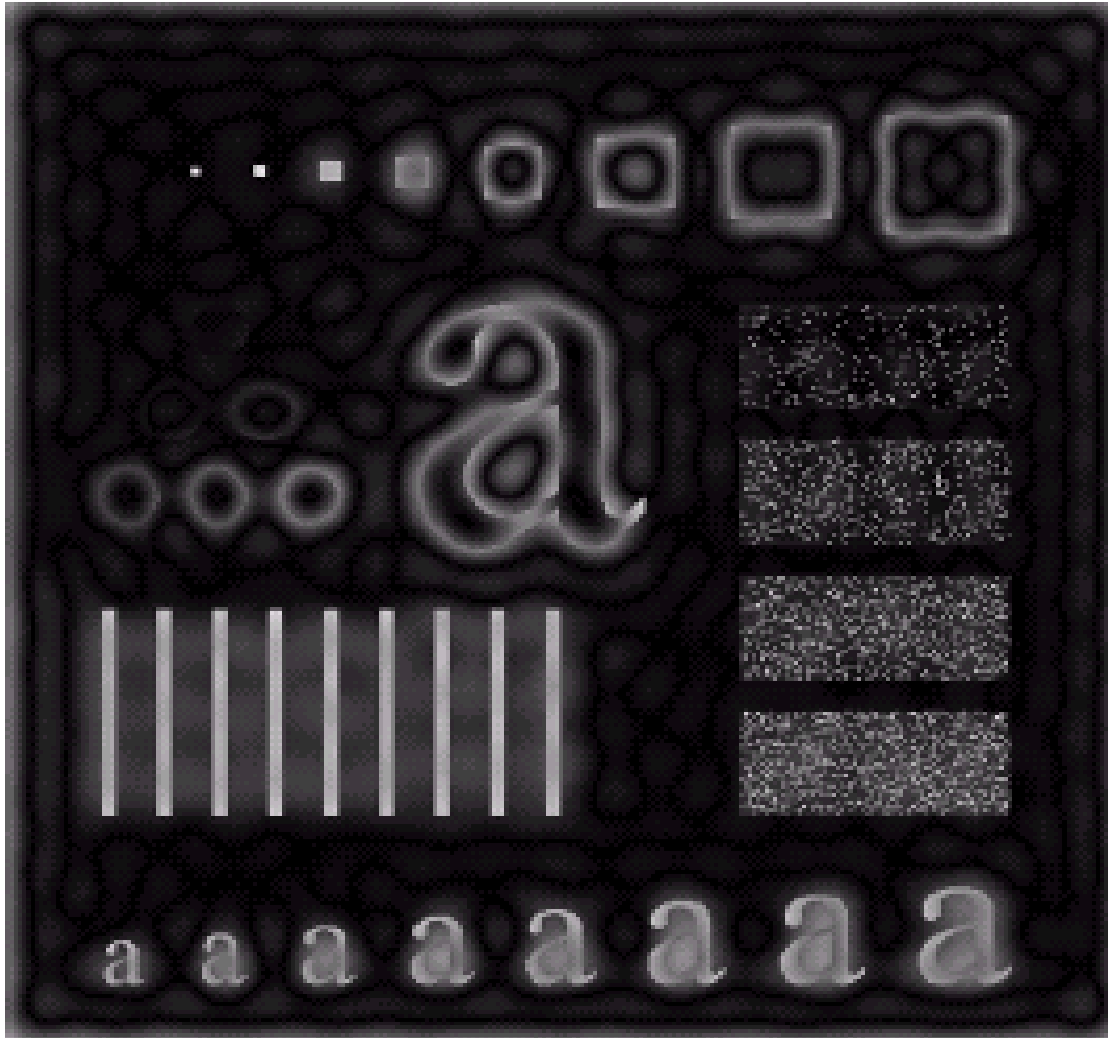


Results of Butterworth
high pass filtering of order
2 with $D_0 = 15$



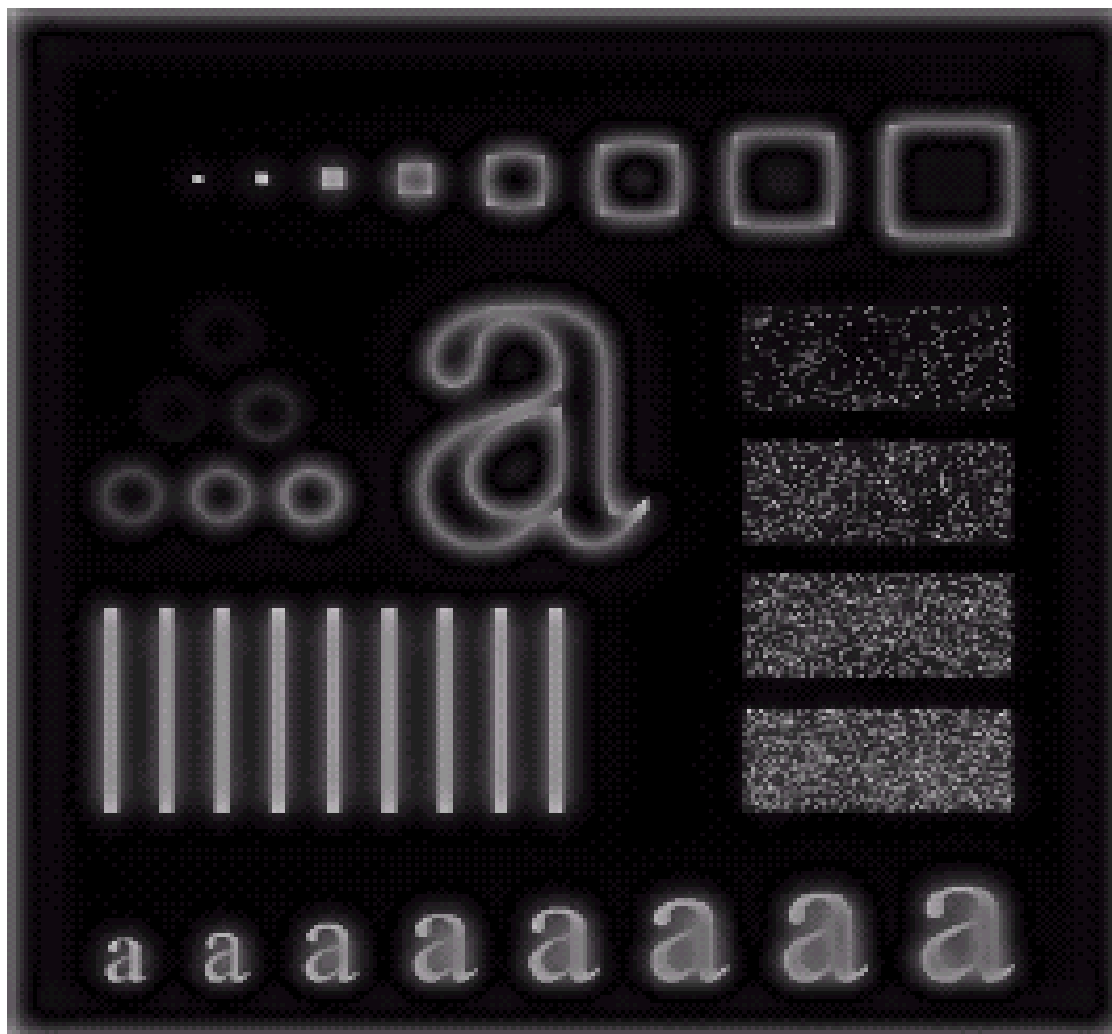
Results of Gaussian
high pass filtering with
 $D_0 = 15$

Highpass Filter Comparison



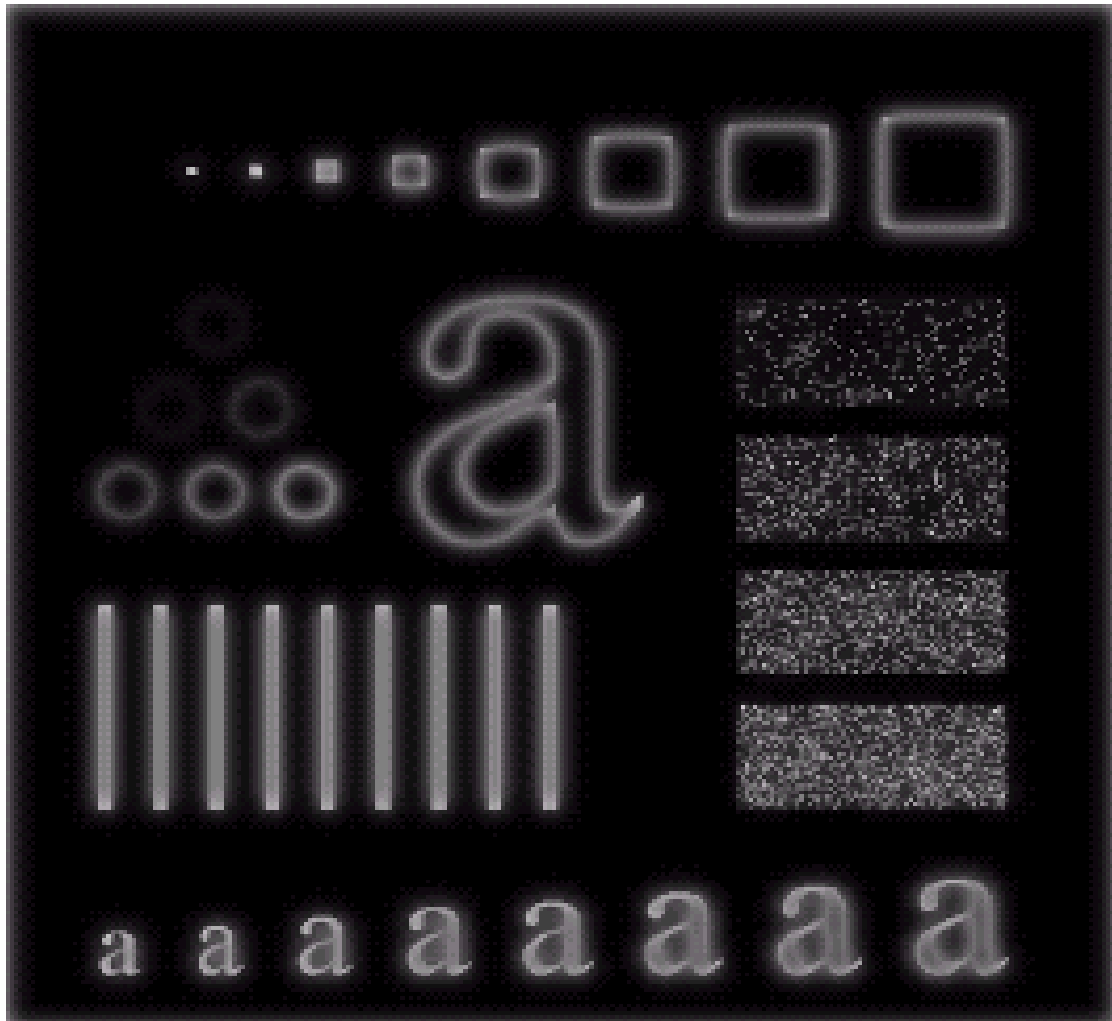
Results of ideal
high pass filtering
with $D_0 = 15$

Highpass Filter Comparison



Results of Butterworth
high pass filtering of order
2 with $D_0 = 15$

Highpass Filter Comparison



Results of Gaussian
high pass filtering with
 $D_0 = 15$

Highpass Filtering Example

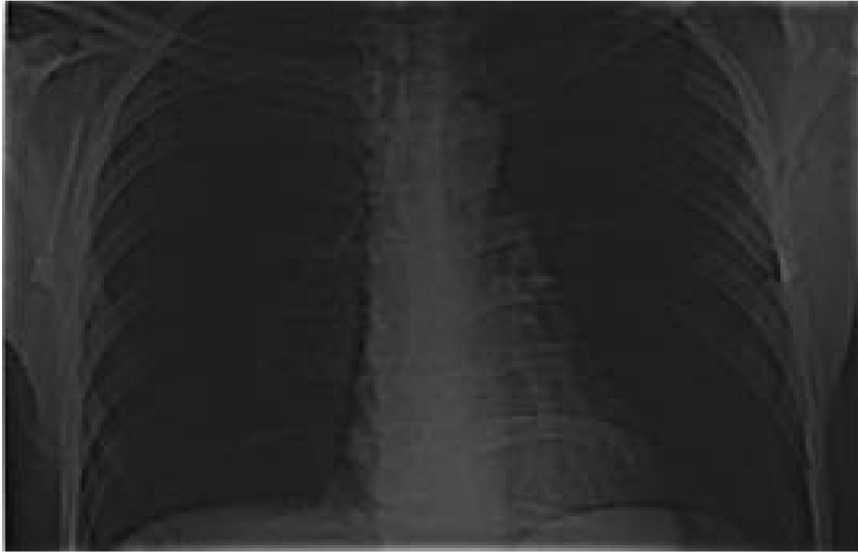
Original image



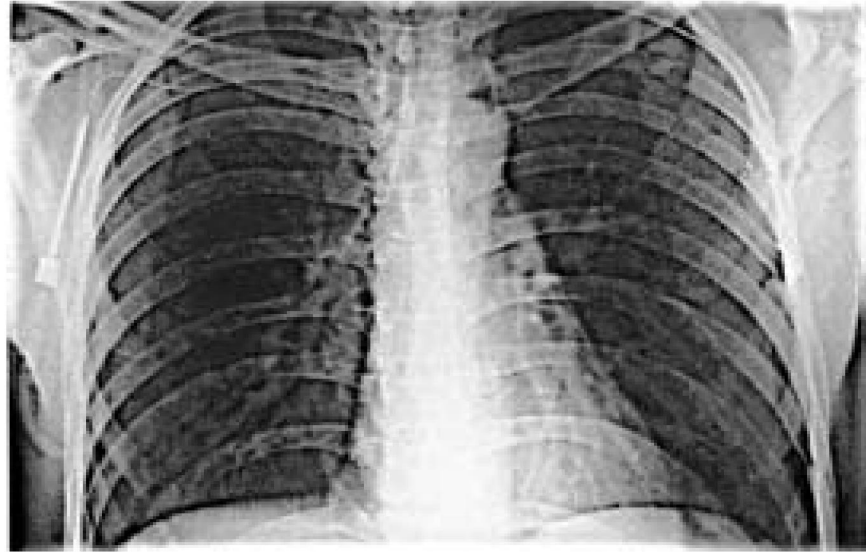
Highpass filtering result



High frequency
emphasis result

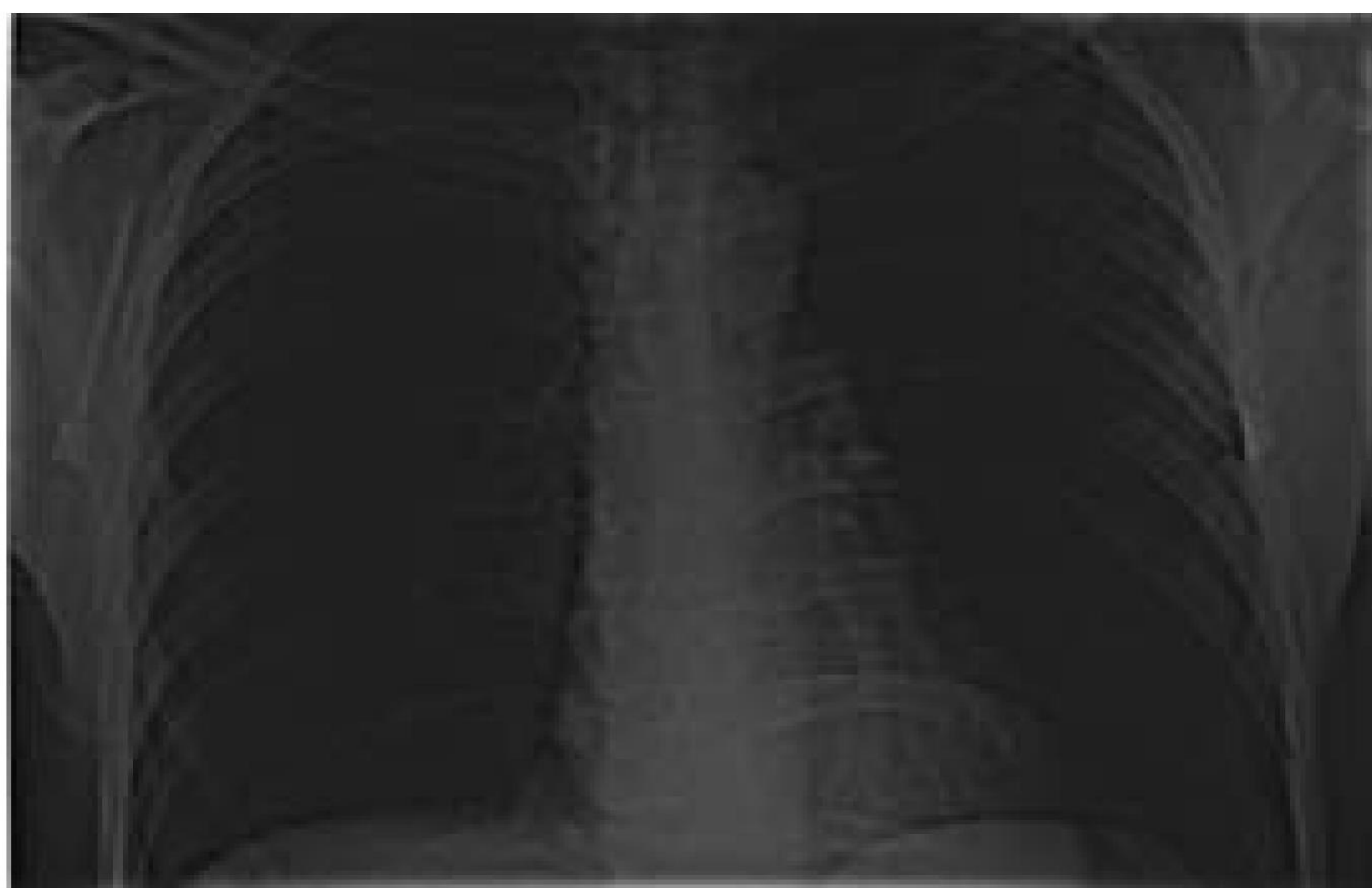


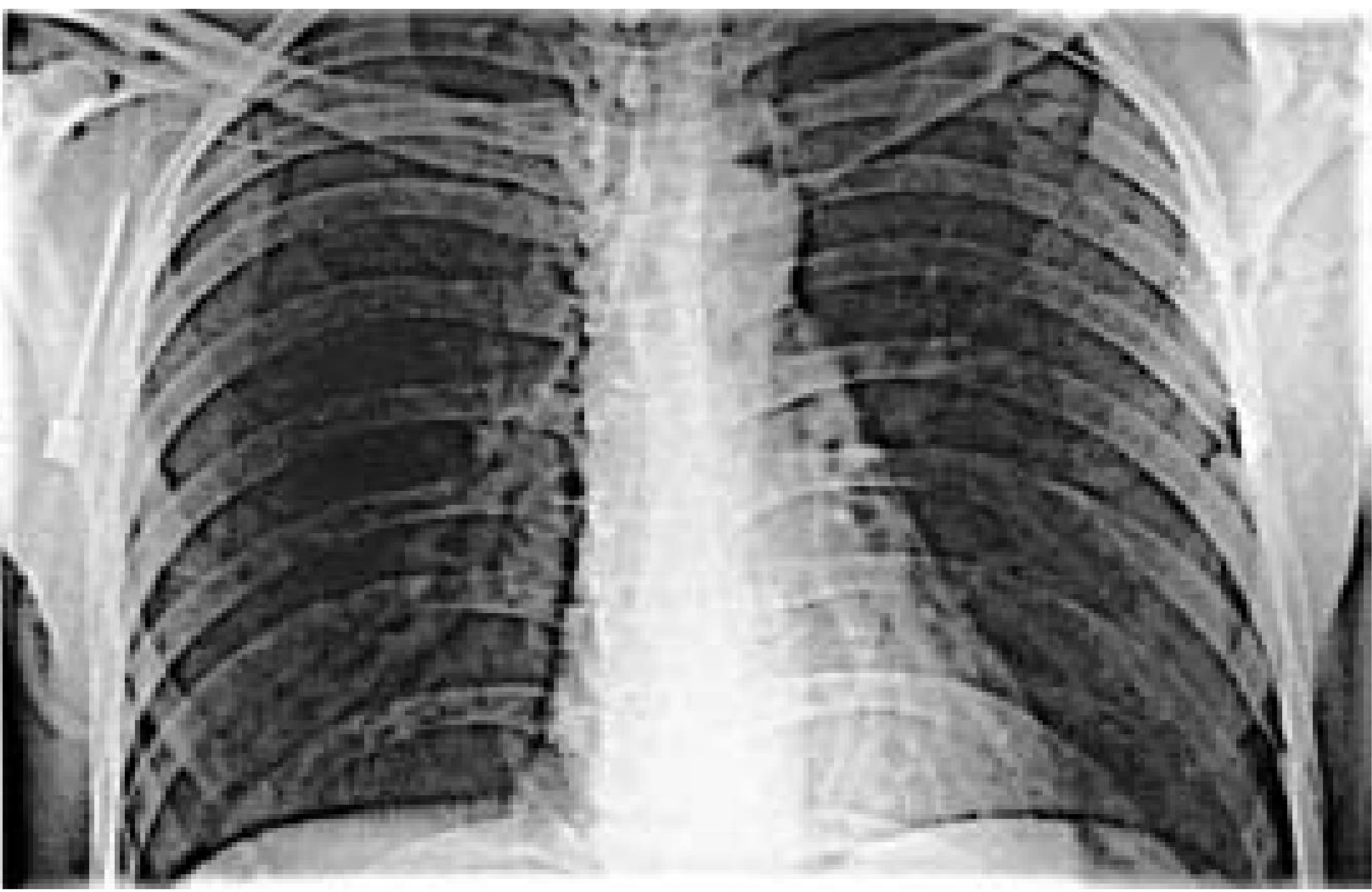
After histogram
equalisation





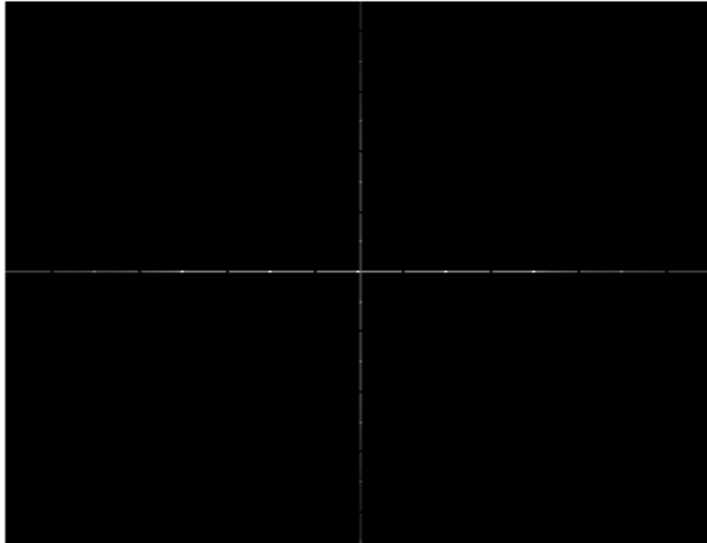




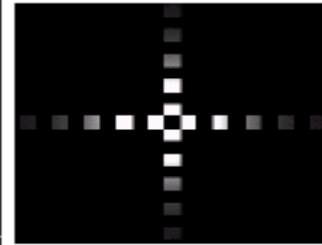
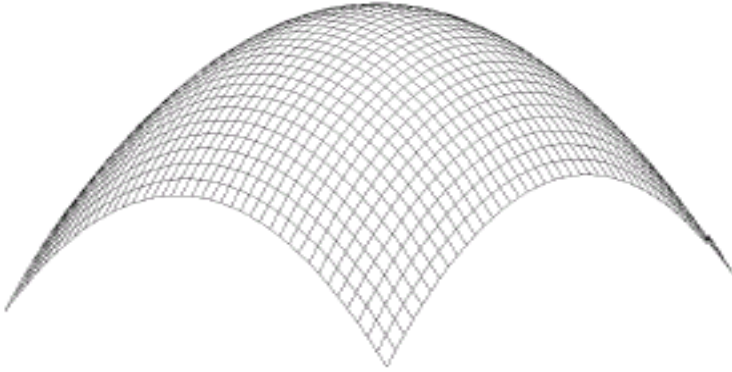


Laplacian In The Frequency Domain

Inverse DFT of
Laplacian in the
frequency domain



Laplacian in the
frequency domain




0	1	0
1	-4	1
0	1	0

Zoomed section of
the image on the
left compared to
spatial filter

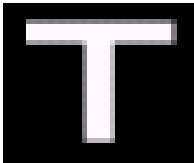
2-D image of Laplacian
in the frequency
domain



Interesting Application Of Frequency Domain Filtering



UTK



T

Interesting Application Of Frequency Domain Filtering

