# Anil Celik Maral

Education

Technical University of Munich

April 2022 – March 2025

Master of Science - MS, Informatics: Games Engineering

2.065 / 5

University of California, Santa Cruz

Bachelor of Science - BS, Robotics Engineering

June 2015 – June 2019 1.3 / 5

Experience

C++ Developer

April 2024 - Present

Dassault Systemes Munich, Germany - Hybrid

• Working in the 3D Preparation Operators team that develops the xOptimizePro / DataPrep operations for the **3DEXPERIENCE** app.

Game Developer

May 2022 - Jan 2024

Peanut Entertainment

Ankara, Turkey - Remote

 $\bullet$  Developing games using  ${\bf Unity},\,{\bf Unreal\ Engine}$  and  ${\bf Blender}.$ 

Robotics Engineer

Jan 2020 – Apr 2022

ERISIM A.S.

Ankara, Turkey - On Site

• Drew and designed the **P** & **ID** / flow diagrams for gypsum based construction material production plants and wrote programs for the **PLC** automation systems used in these plants.

Embedded Systems Engineer Intern

Sep 2019 - Dec 2019

Archer Components

San Francisco Bay Area - On Site

• Developed automation solutions using **IoT** by utilizing **AWS**, **Arduino**, **ZigBee**, **C** and various other microcontrollers and programming languages.

Undergraduate Researcher

Nov 2015 - Jul 2017

University of California, Santa Cruz

Santa Cruz, California - On Site

• Modeled tensegrity robots and sketched them in AutoCAD Inventor and also did stress analysis/simulation of the tensegrity robots using NASA Tensegrity Robotics Toolkit (NTRT). Afterwards, built the prototypes by 3D printing/prototyping for testing.

**Projects** 

#### Differentiable Finite Volume Method

• In my master's thesis, I worked on computational fluid dynamics (CFD) simulations using the finite volume method (FVM). I developed and coded the finite volume method (FVM) solutions for  $\Phi_{Flow}$ , a differentiable PDE solving framework for machine learning, and then published my results.

#### Chaos Coaster Video Game

• Developed an 3D FPS in **Unity**. Models were designed in **Blender**. The enemies were trained using machine learning using **Unity**'s **ML-Agents**.

### Stellaris Mod - The Veiled Cluster

• Developed a mod to play in an extra-galactic cluster. The mod comes with story driven events and an additional species trait.

## Implementation of the KinectFusion 2011 by Richard A. Newcombe et al Research Paper

• Implemented the 2011 research paper titled KinectFusion: Real-Time Dense Surface Mapping and Tracking by Richard A. Newcombe et al. using C++, OpenCV and CUDA. Additionally, utilized Eigen3 and FreeImage 3 C++ libraries.

Skills

Unity, Unreal Engine, Blender, C++, C#, C, Python, Java, MIPS Assembly, Verilog, PLC Ladder Logic, Matlab, AutoCAD, Autodesk Inventor, SolidWorks, Robot Operating System (ROS), Gazebo ROS, OpenCV, CUDA

Languages

English: Native or Bilingual Proficiency Turkish: Native or Bilingual Proficiency German: Elementary proficiency

**Organizations** 

Tau Beta Pi, The Engineering Honor Society

Member May 2018 - Present