

- Things to pack
- M3, M2 Screws
- Backup prints (especially steering column)
- 3x TFLunas + Cables
- 2x IMUs + Cables
- Spare Servo
- Spare Motor
- 2x Lego Wheels
- Mounting Tape
- 4x Lipos (Total)
- Spare (soldered) PCB
- Spare OpenMV
- Hot glue gun
- Soldering Iron + Solder

Integrate block detection

Print backup parts

Completed

- Pack the yellow measuring tape at the end of the day

Overdue, Wed, September 6
- START DOCUMENTING EVERYTHING
- Figure out how to mount a compass (away from the ferromagnetic stuff)

ZA
- Try to get OpenMV working?
- CAD pivoting mount for camera

ZA
- Test and set lidar I²C addresses
- Test steering servo and generate look up table for steering angles
- Get materials for gamemat
- CAD lidar mounts and start testing?