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Using PS/2 Keyboards in Embedded Systems

Reasons to use a PS/2 Keyboard



The keyboards have always been the most favorite units for data input to the computers. The PC AT keyboard has not changed electronically and protocol-wise since the announcement of the first IBM PC AT in 1984. It has evolved into its current layout and connector with IBM PS/2 series in 1987, and thus has been started to be called as the **PS/2 Keyboard**.

The fact that this de-facto standard has not changed for almost 20 years has created two very positive results:

- Low Prices (< 4 USD !),
- Alternative Input Units using PS/2 compatible interface. Most of Laser / CCD Scanners and barcode / magnetic slot readers utilize PS/2 interface.



If one takes a close look at PS/2 keyboards; it will be seen that they consist of matrix keypads (whose size has grown up to 8 rows by 16 columns) and a controller (such as Intel 8048) which encodes the row-column information. Our PCs have a complimentary controller (such as Intel 8042), which acts as a 'host' and decodes this information. An embedded system targeted for PS/2 connectivity should realize the functions of this decoder.

The specifics of 'Host' – Keyboard (encoder) protocol are given in the articles provided by Adam Chapweske in (1) & (2).

Two properties of this protocol are important for the embedded systems:

1. The communication is binary, synchronous and **serial based**: Only two channels (**CLOCK** and **DATA**) are sufficient.

It is a very common practice to connect matrix keypads directly to the input/output channels of the embedded systems used for automation. For example, JKmicro provides a 4x4 (16 keys) matrix keypad solution complete with the hardware and software driver for the FlashLite186 single board computer that is used in this article. Although being very easy to implement, the downside of the matrix keypads is their requirement for channels equal to the number of rows plus columns. Thus, FlashLite186's 4x4 keypad solution requires 8, a 101 keys unit (similar to PS/2 keyboard) would require a minimum of 21 input/output channels. This is a very demanding requirement when you think that a FlashLite186 has only 44 such I/Os.

In short, the fact that PS/2 keyboard's hardware protocol is serial and thus needs only two pins is an important advantage. Designing a tailored encoder circuit for matrix keypads is a widely used solution, but I am sure that they cost a lot more than 4 US Dollars.

2. Communication is **two-sided**: In addition to the expected data flow from keyboard's encoder to the 'host' (PC), the host can send commands to it for adjusting certain functions.

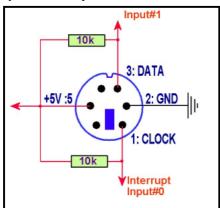
When we take a look at the commands that can be sent; it will be seen that they are used to control LEDs (Num/Caps/Scroll Lock) and to setup the typematic rates. We can assume that we will not need these adjustments in embedded systems and make provisions for only **one-sided communication** from keyboard to the host.

This is exactly what has been tested in this article to reduce the development work and CPU load.

Connections and the Protocol

Due to above summarized advantages; there are a lot of PS/2 keyboard related solutions for various platforms in the Internet. Craig Peacock presents an application developed for 68HC705 in (3). This article also contains lots of detailed info about PS/2 keyboards. Atmel has a sample solution developed for its AVR processor, written in 'C' (4).

There are two important preparations that need to be completed before connecting a PS/2 keyboard to any controller:

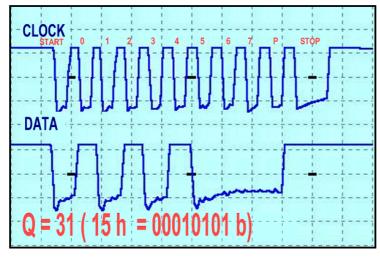


- A regulated, +5VDC power needs to be supplied to the keyboard. The power requirement can go up to 100mA and one needs to ensure that the GNDs of the power supply and the controller are common.
- 2) DATA and CLOCK signals are "open collector" type: they need to be "pulled-up" to 5VDC via 10kOhm resistors. Remember that a logical "0" generates a 5V signal, while a logical "1" is observed as 0V!

Each key pressed causes a packet of data to be output by the encoder. Each data packet is output during 11 cycles of CLOCK, therefore can be interpreted to be containing **11 bits**: 1 start bit (= 0), 8 data bits (one byte), 1 parity (= 0 or =1) and 1 stop (=1) bit.

The signals that will be observed on CLOCK and DATA pins, when 'Q' is pressed are shown below. This diagram is taken from Adam Chapweske's article (1). 'Q' key is encoded with an ASCII value of 31 ("15" as hexadecimal and "00010101" as binary).

The conclusions to be derived from the wave representations of the communications protocol are given below:



CLOCK signal is generated only during the data transmission period: In other words, this signal is suitable for an interrupt-based application.

Correct DATA values are generated only after CLOCK signal level has gone down to 0V: Interrupt routine should read the DATA bit only during this stage.

Key Codes

If we take a close look on our keyboard usage; we will notice that it consists of several steps. Even if we press a single key; key pressing is the obvious event. Key-up is the second one which triggers its own stream of data. Repeating the generated key codes (after a certain delay), generating different code combinations when a key is pressed with secondary keys such as [SHIFT], [ALT], [ALTGR], and [CTRL] are the other functions the encoder fulfills.

Craig Peacock's article (3) gives a very useful diagram for the codes generated by a keyboard in US English layout :

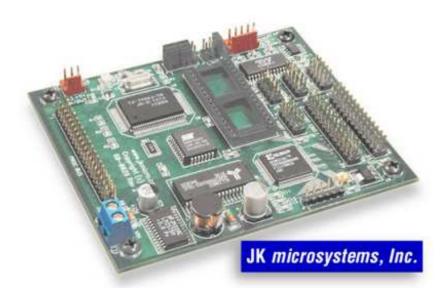


This diagram should warn a developer about two issues:

- Some keys generate two, a few such as [PRT SCR] and [PAUSE] generate more characters.
- The codes need to be decoded (interpreted) as per the layout: For example the 'Q' key (15h) should be decoded as 'F' when using a "Turkish F Keyboard".

A Test Application for JKmicro's FlashLite186

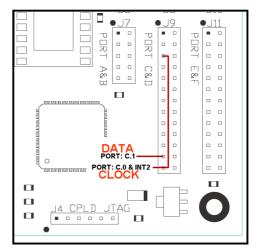
In this test study, **FlashLite186** has been used. It is an industrial, single board computer manufactured by JKmicro (www.jkmicro.com), has a 33Mhz 80186 compatible RDC8822 processor and comes with a preloaded DOS compatible OS. It is very compact in size and has an extended working temperature range of -20 to +85 °C. An unregulated power supply with 2W, 7 to 34 VDC can be used if needed. Its detailed specification can be accessed from: http://www.jkmicro.com/products/flashlite186.html



Since the operating system is DOS (compatible); one can use many of the conventional (old) development environments. In this study, Borland C/C++ V.4.52 has been used. The application has been installed and then launched in a FlashLite186 with HyperTerminal using

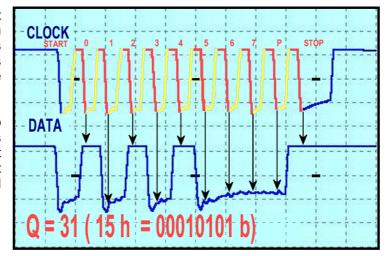
its serial port named "console". This name has been chosen deliberately because all "console" interactions such as keyboard inputs ('getch') and screen outputs ('printf') are diverted to this port at BIOS level.

FlashLite186 has 44 channels of digital I/0. In the test application, two of the I/Os grouped under PORTC (located within J9 connector) have been used. J9 connector also has a pin to accept a signal to trigger interrupt INT2. CLOCK signal has been connected to this INT2 in addition to pin 0 of PORTC, to facilitate a simpler and cleaner programming algorithm by using this interrupt.



The application's interrupt routine is triggered when CLOCK signal's level is changing from 0 to 5V. This phase has been shown with the yellow portion of clock waves.

The DATA bit's value needs to be read only when CLOCK is 0V. Therefore, the interrupt routine needs to wait until that stage, as shown with the red portions of the waves.



Two 'C' functions collecting the data bits as per this diagram and decoding them are given below:

```
/* ps2 int: INT driven service routine that collects 10
                                                      */
/* bits that make up a scan code sent by a PS2 encoder.
/* It does not check the validity of parity or stop bits
/*******************************
void interrupt ps2 int(void)
    unsigned char retry = 0, binp;
    unsigned static char bkey = 0, bcount = 0;
    if (bcount < 10)
              // Wait until CLOCK signal is down (0V)
             while ( ((binp = inportb(0x602)) & 1) && (retry++ < PS2 WAIT) );
             if ( retry < PS2 WAIT )
                   if ( (bcount < 8) && (binp & 2)) bkey = bkey + bits[bcount];</pre>
                   bcount++;
             } else {
              // CLOCK signal did not go down - ERROR
                    bcount = 0;
                    bkey
    } else {
                   // 10. bit is received - Decode the key
                   ps2 decode(bkey);
                   bcount = 0;
                         = 0;
                   bkey
    // Selective End of Interrupt for INT2
    outport(EOI, 0x000E);
```