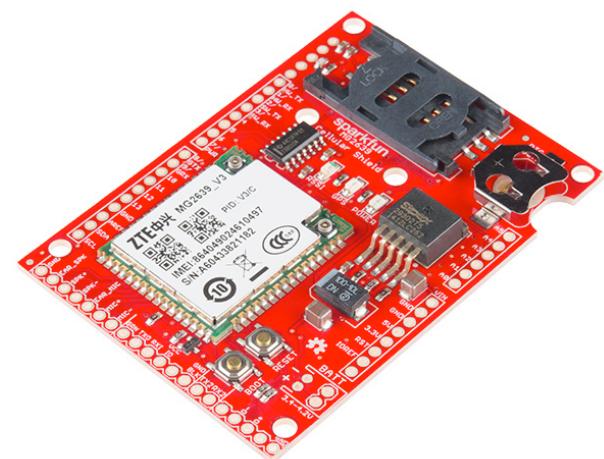
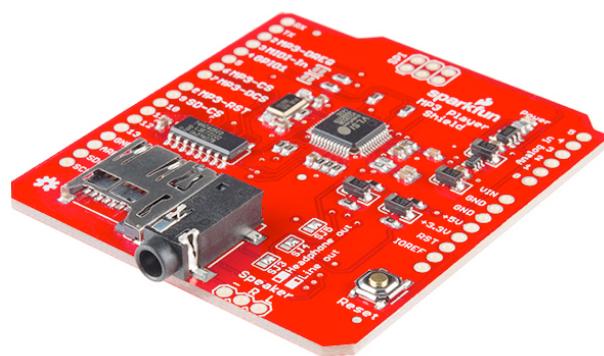
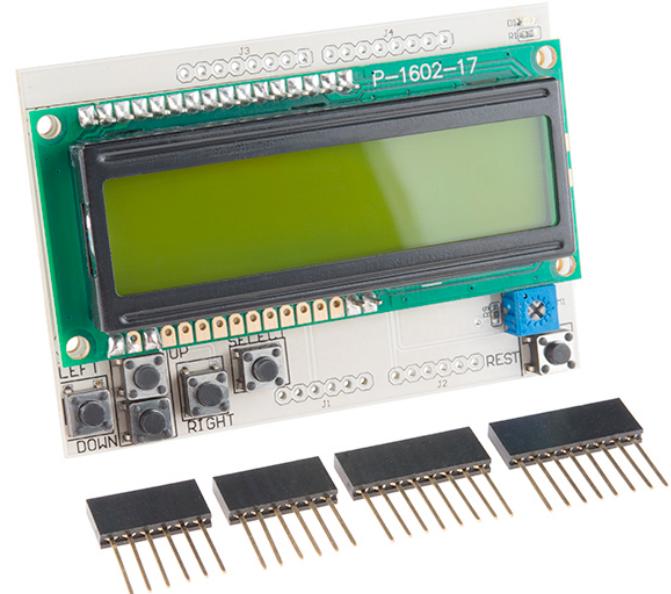
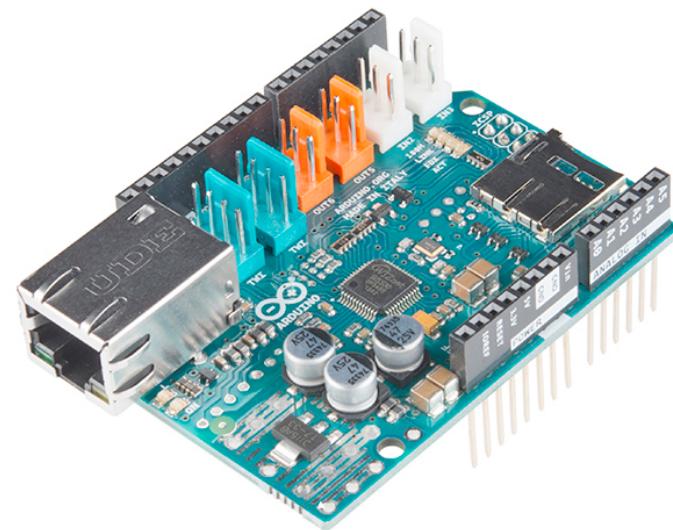
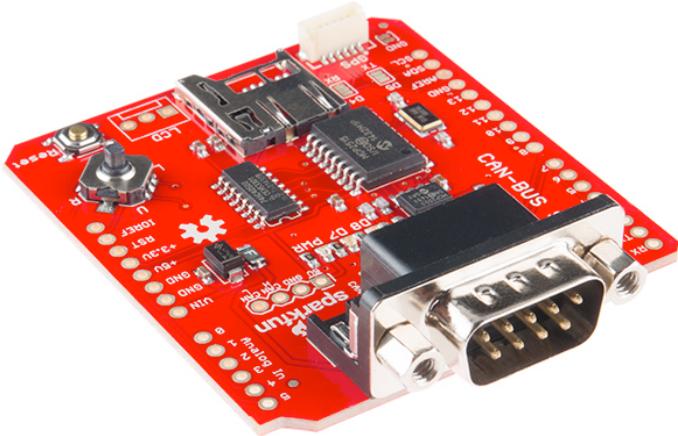
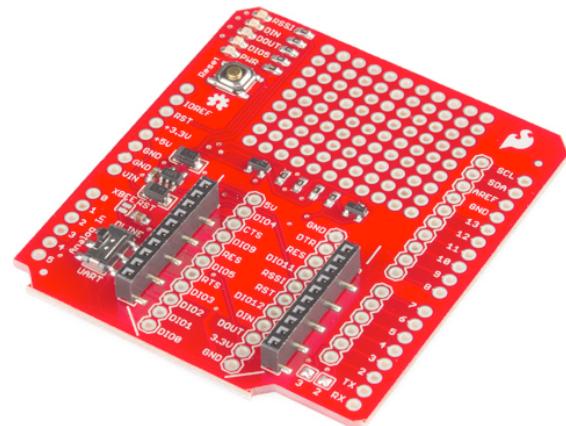
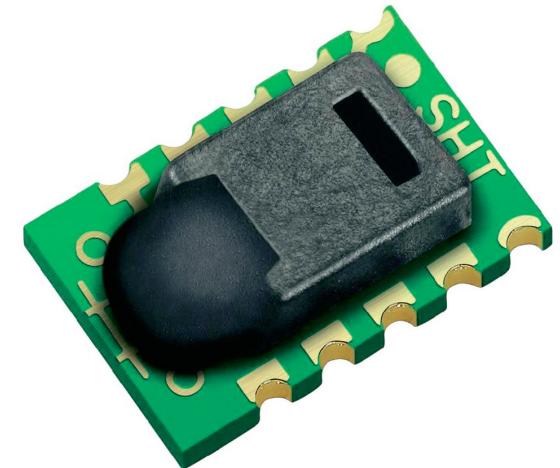
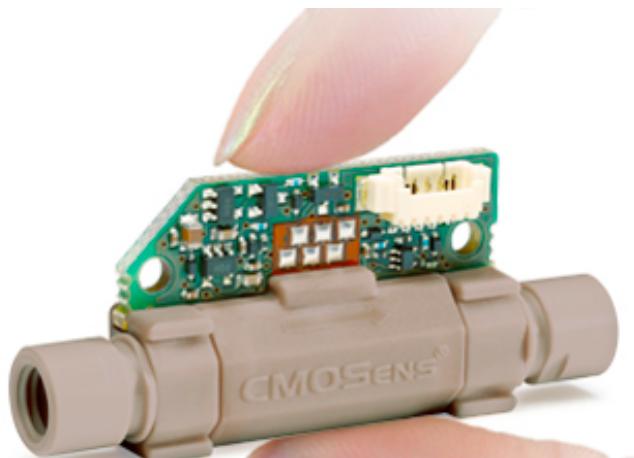
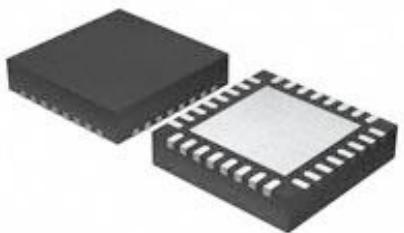


# I/O: External Peripherals

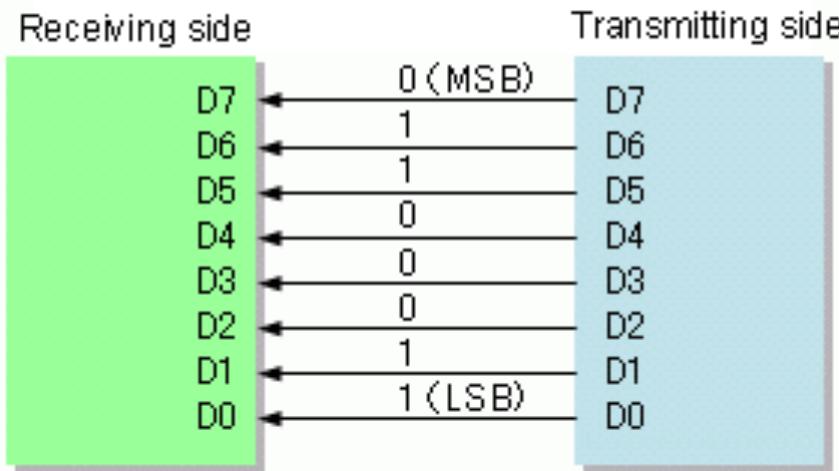
## SPI, PS/2, and PWM



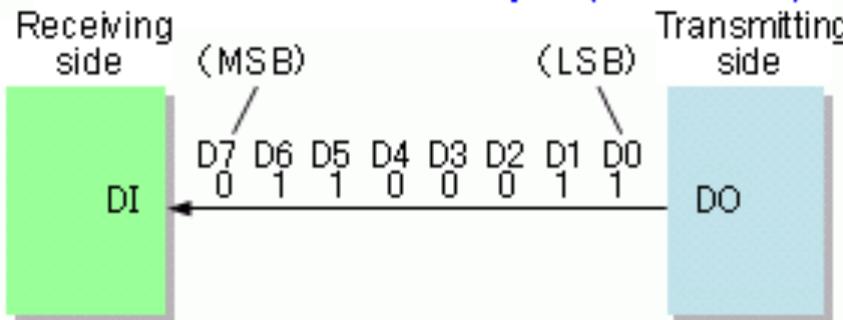


# Serial vs. Parallel

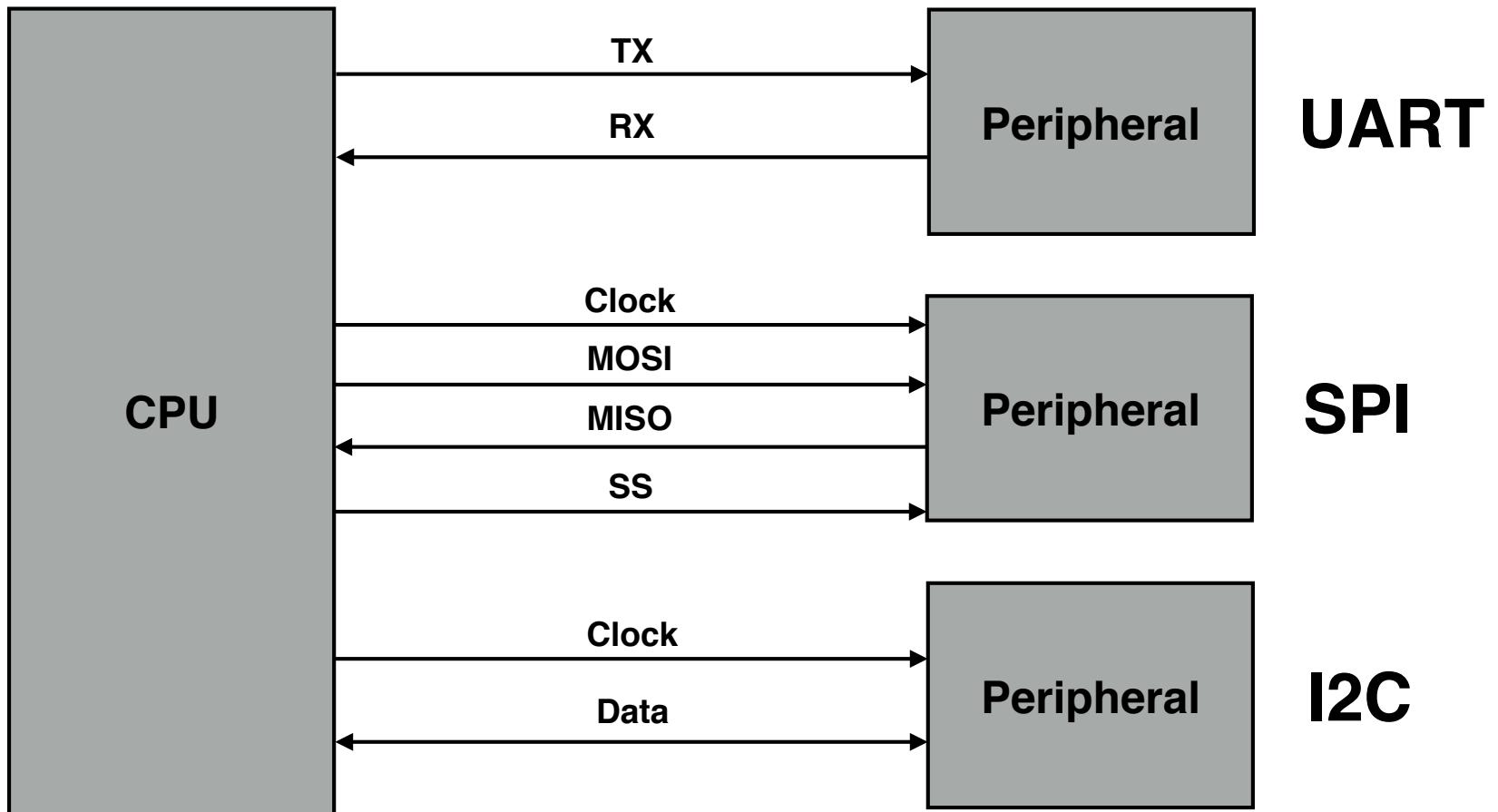
## Parallel interface example



## Serial interface example (MSB first)



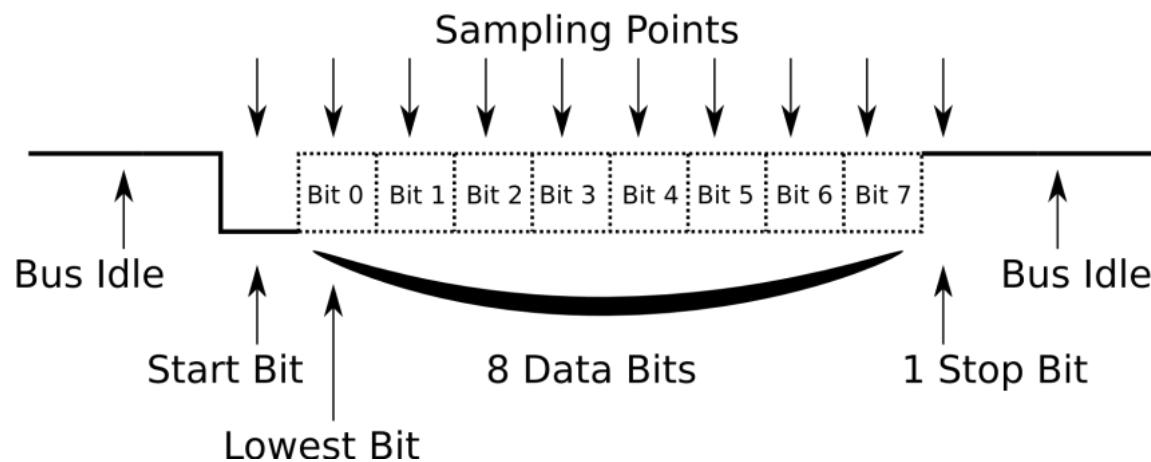
# Bus Protocols



# UART

- Used in your printf & the bootloader
- Asynchronous — no clock line
- Start bit, (5 to 9) data bits, (0 or 1) parity bit, (1 or 2) stop bits

UART with 8 Databits, 1 Stopbit and no Parity (8-N-1)



# UART timing demo

# Parity Bits

- Error detection — discard if parity bit wrong
- Even parity: parity = XOR of data bits, ensures an even number of 1s (w/ parity bit)
- Odd parity: !even parity, ensures an odd number of 1s

**even**

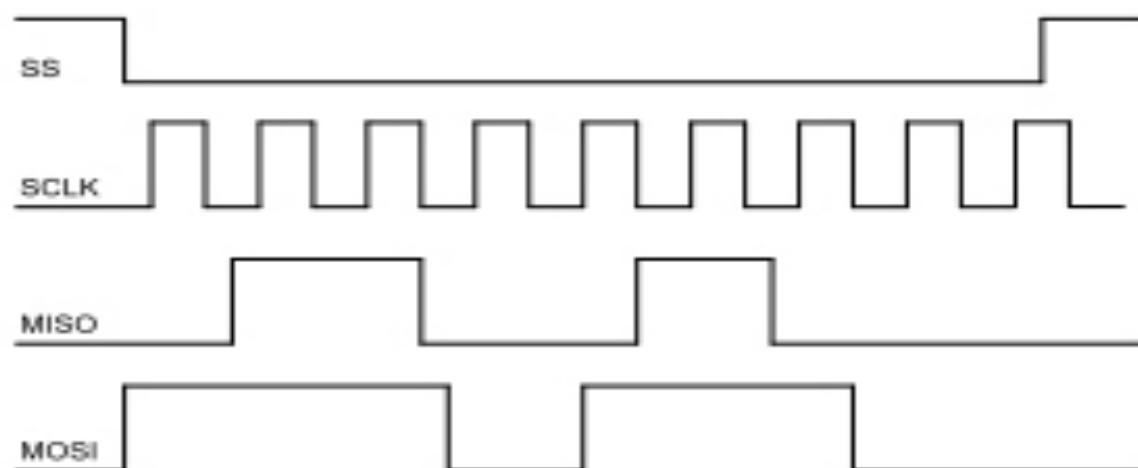
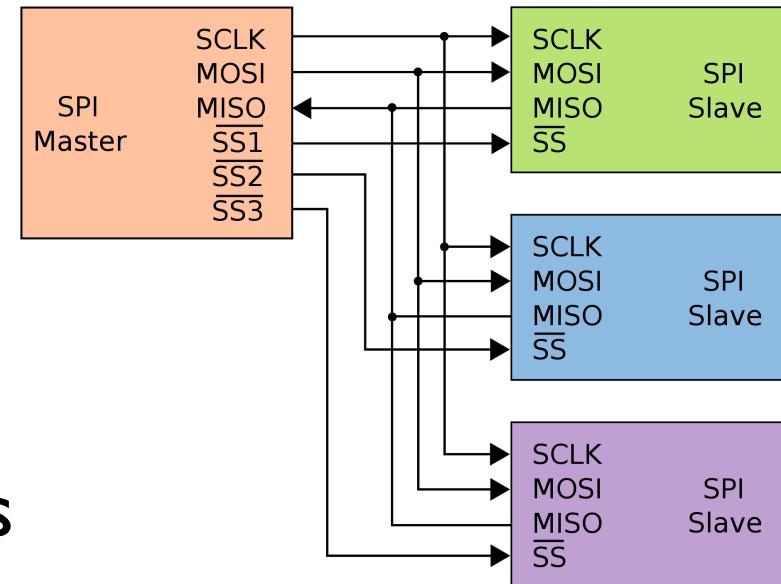
data	parity							
1	1	0	1	0	1	1	0	1

**odd**

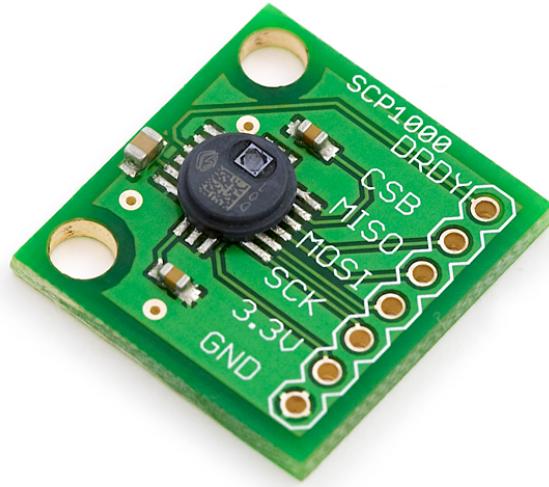
data	parity							
1	1	0	1	0	1	1	0	0

# SPI

- Clocked by master
- Shared CLK, MOSI, MISO lines
- Active low chip select (slave select) lines to specify which peripheral is active

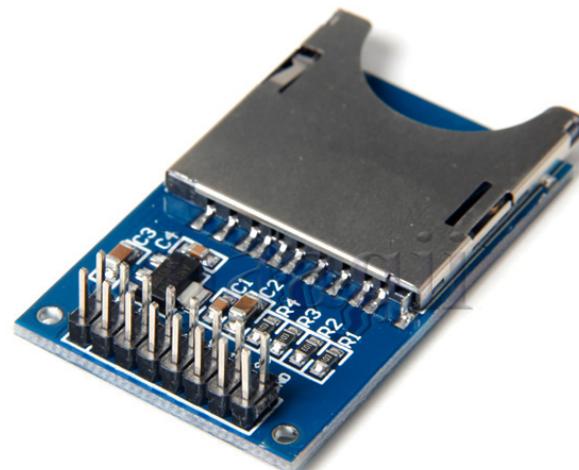


Figures from [https://upload.wikimedia.org/wikipedia/commons/thumb/f/fc/SPI\\_three\\_slaves.svg/2000px-SPI\\_three\\_slaves.svg.png](https://upload.wikimedia.org/wikipedia/commons/thumb/f/fc/SPI_three_slaves.svg/2000px-SPI_three_slaves.svg.png) (top), <http://www.tequipment.net/RigolSD-SPI-DS4.html> (bottom)



# SPI Devices

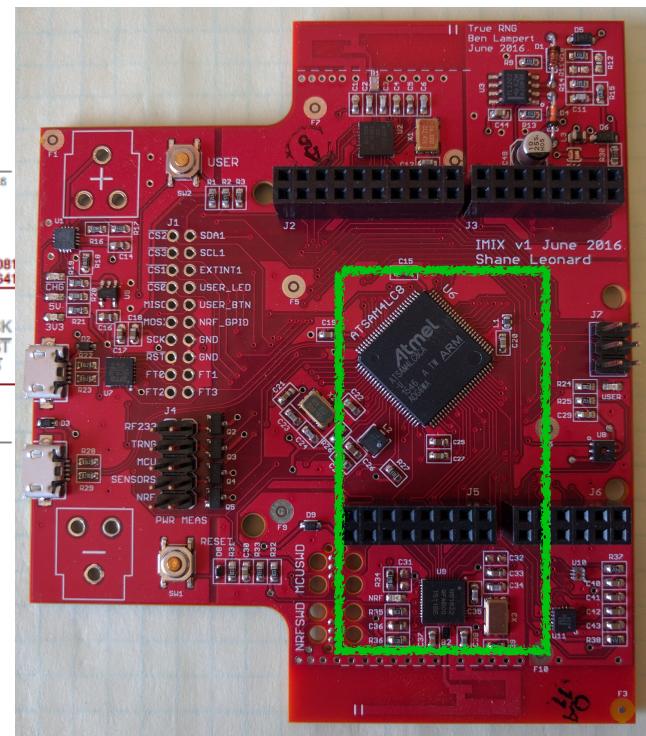
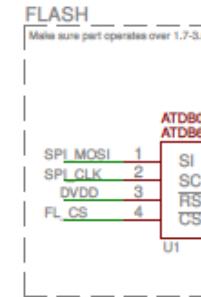
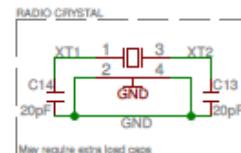
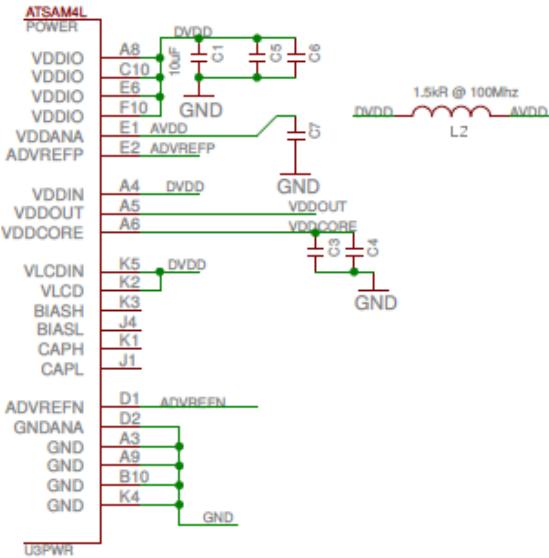
- Sensors (pressure, temperature, Hall effect)
- Control/Configure (ethernet switch, digital potentiometer, OLED display)
- SD Card
- Radios!



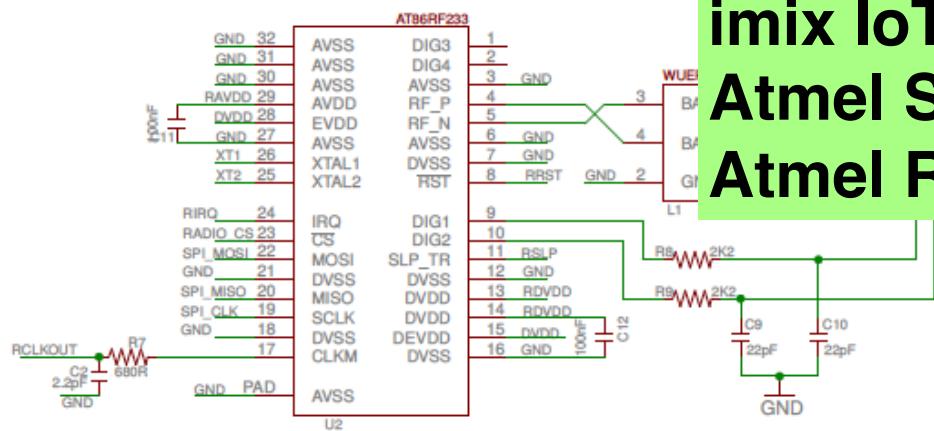
Figures from <https://developer.mbed.org/media/uploads/MichaelW/scp1000d01.jpg> (top)

<http://raspberrypi.stackexchange.com/questions/28648/how-can-i-wire-this-sd-card-reader-to-raspberrypi> (bottom)

# SPI Demo



Errata:  
C11 + C12 should be 100nF

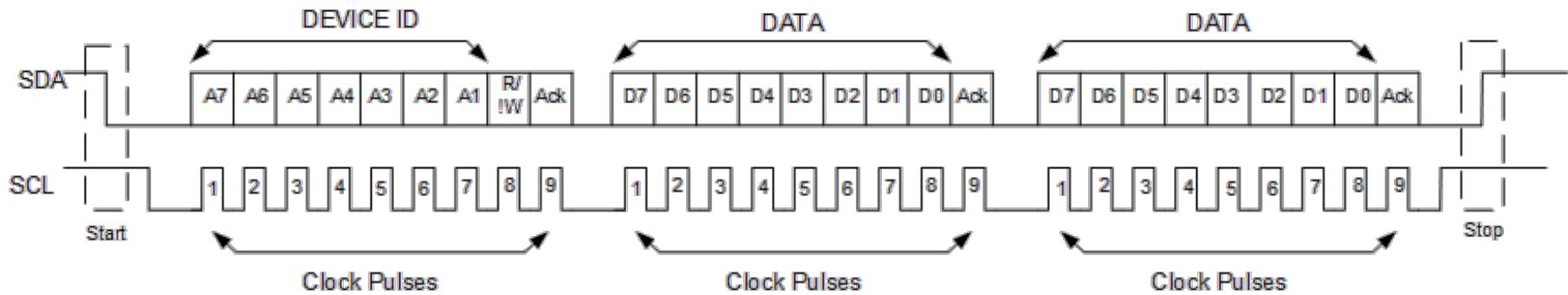
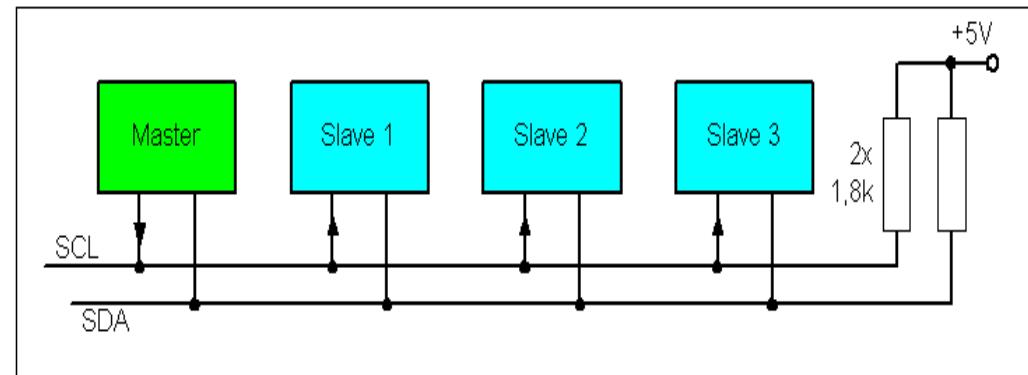


imix IoT research platform  
Atmel SAM4L master (ARM Cortex M)  
Atmel RF233 slave (802.15.4 radio)

BEARLOGO

# I<sup>2</sup>C

- Only CLK & DATA lines
- Clocked by master, sides alternate who sends data
- Shared bus, slave identified by 7 (or 10) bit address



Figures from <http://www.cs.fsu.edu/~baker/devices/notes/graphics/i2cbus3.gif> (top)  
[https://learn.digilentinc.com/Documents/chipKIT/chipKITPro/P08/Fig\\_1\\_Waveform.png](https://learn.digilentinc.com/Documents/chipKIT/chipKITPro/P08/Fig_1_Waveform.png) (bottom)

# I2C Devices

- Sensors (pressure, temperature, colorimeter)
- Control/Configure (HDMI display)
- ADC & DAC

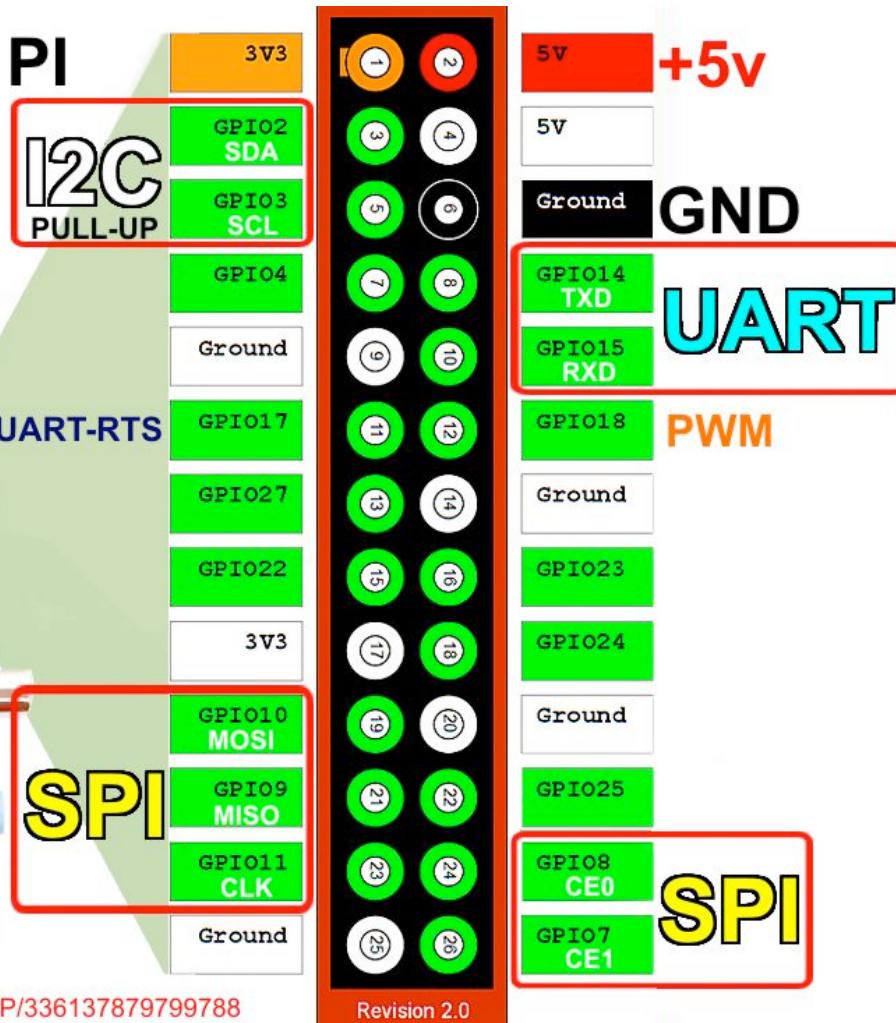


Figure from [http://www.seeedstudio.com/wiki/Grove - I2C\\_Color\\_Sensor](http://www.seeedstudio.com/wiki/Grove - I2C_Color_Sensor)

# Raspberry Pi Header Pins

## RASPBERRY PI Revision 2 Pinout

<http://www.pinballsp.com>



<https://www.facebook.com/pages/PinballSP/336137879799788>

# PS/2 Keyboard

- PS/2 is an old serial protocol for keyboards
- Synchronous: CLK and DATA lines



# PS/2 Protocol

- 8-Odd-1 (8 data bits, odd parity, 1 stop bit)
- Data changes when clock line goes high
- Read data when clock is low
- Open-collector CLK & DATA
  - High is an open circuit
  - Low is connected to ground
  - Need a pull-up resistor to make high actually high

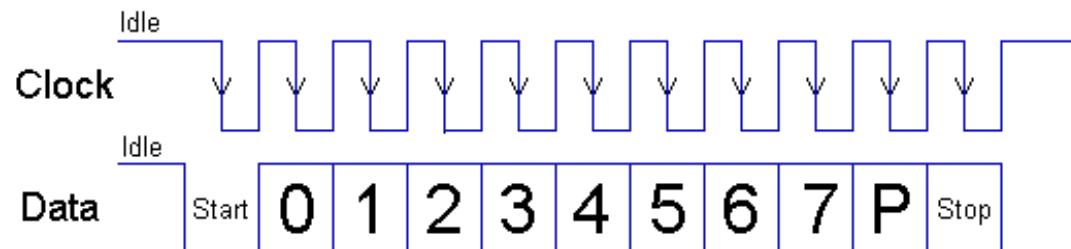
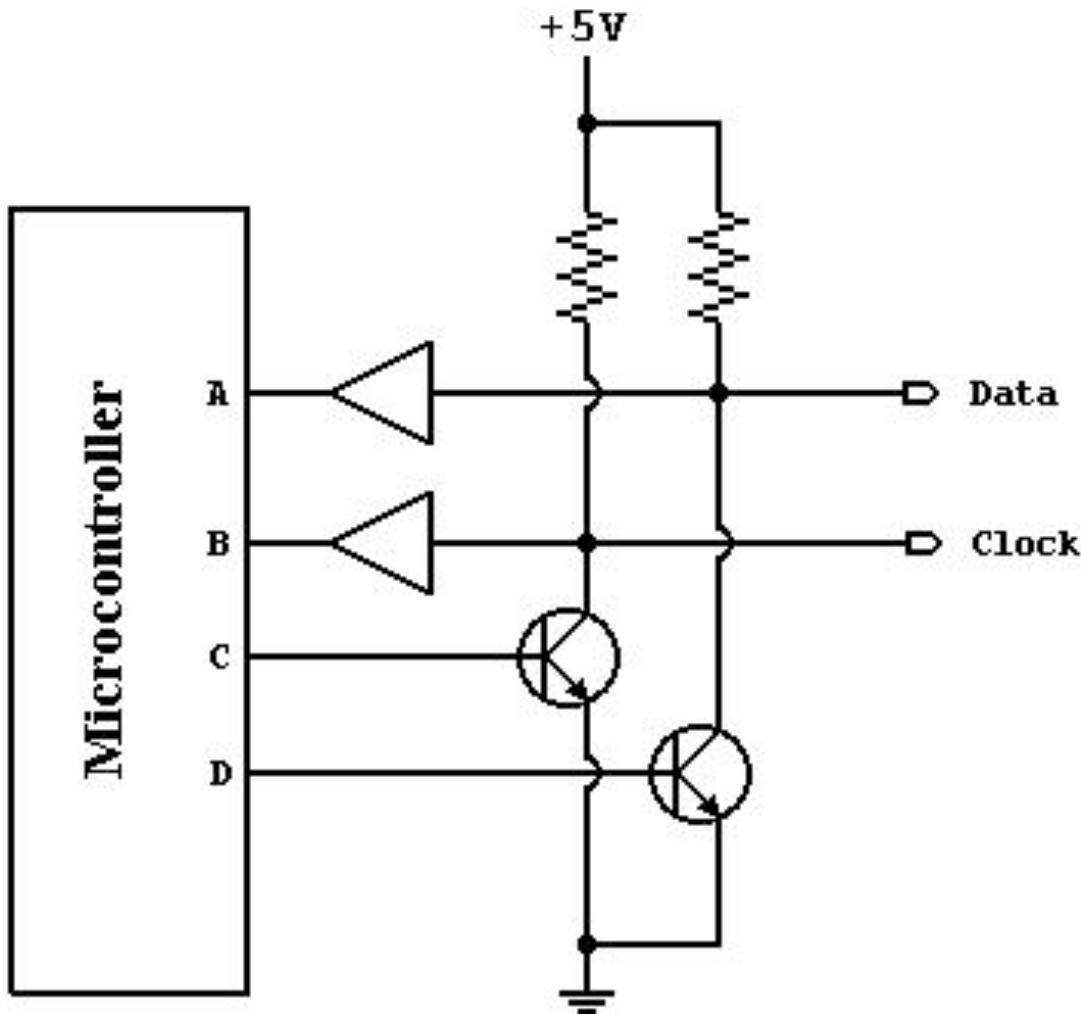


Figure from <http://retired.beyondlogic.org/keyboard/keyboar1.gif>

# Open Collector



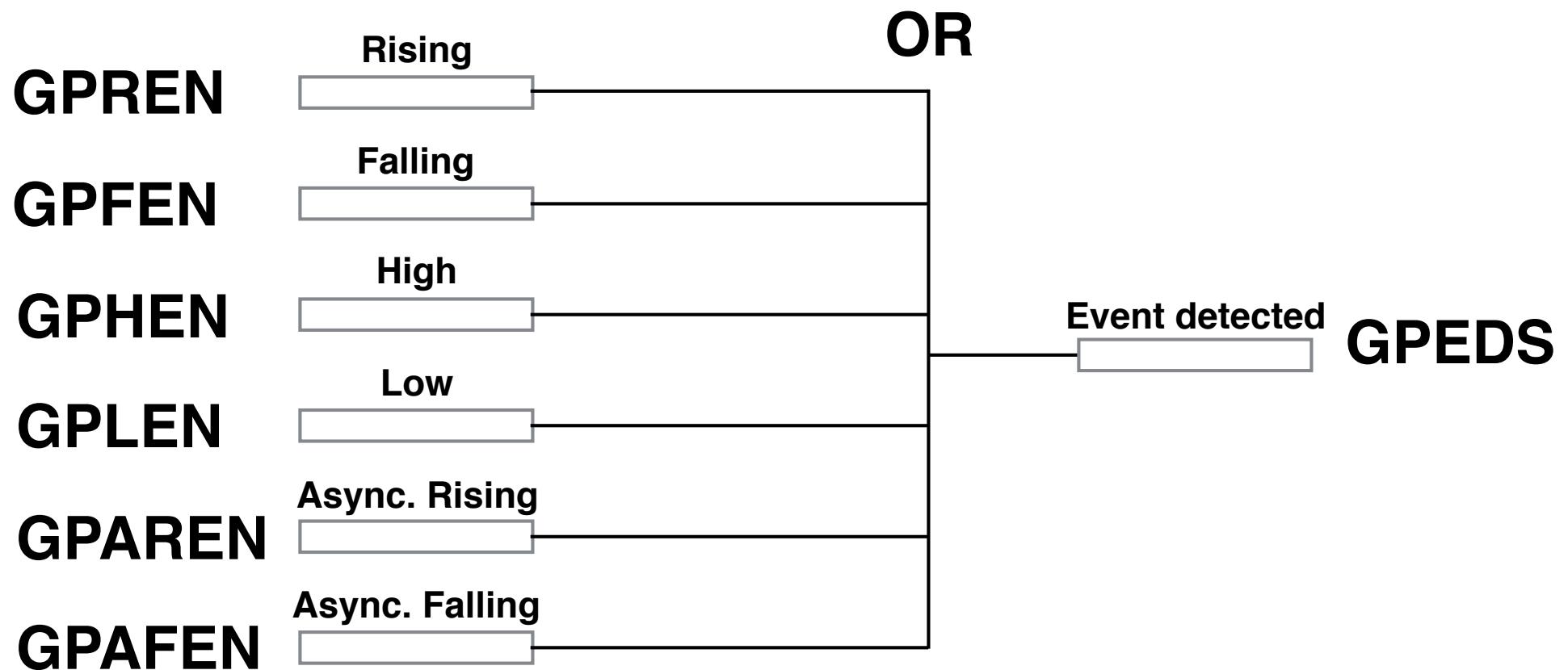
- Asserting C will bring clock low
  - Otherwise goes high from pull-up resistor
- Asserting D will bring data low
  - Otherwise goes high from pull-up resistor

# GPIO Event Detection

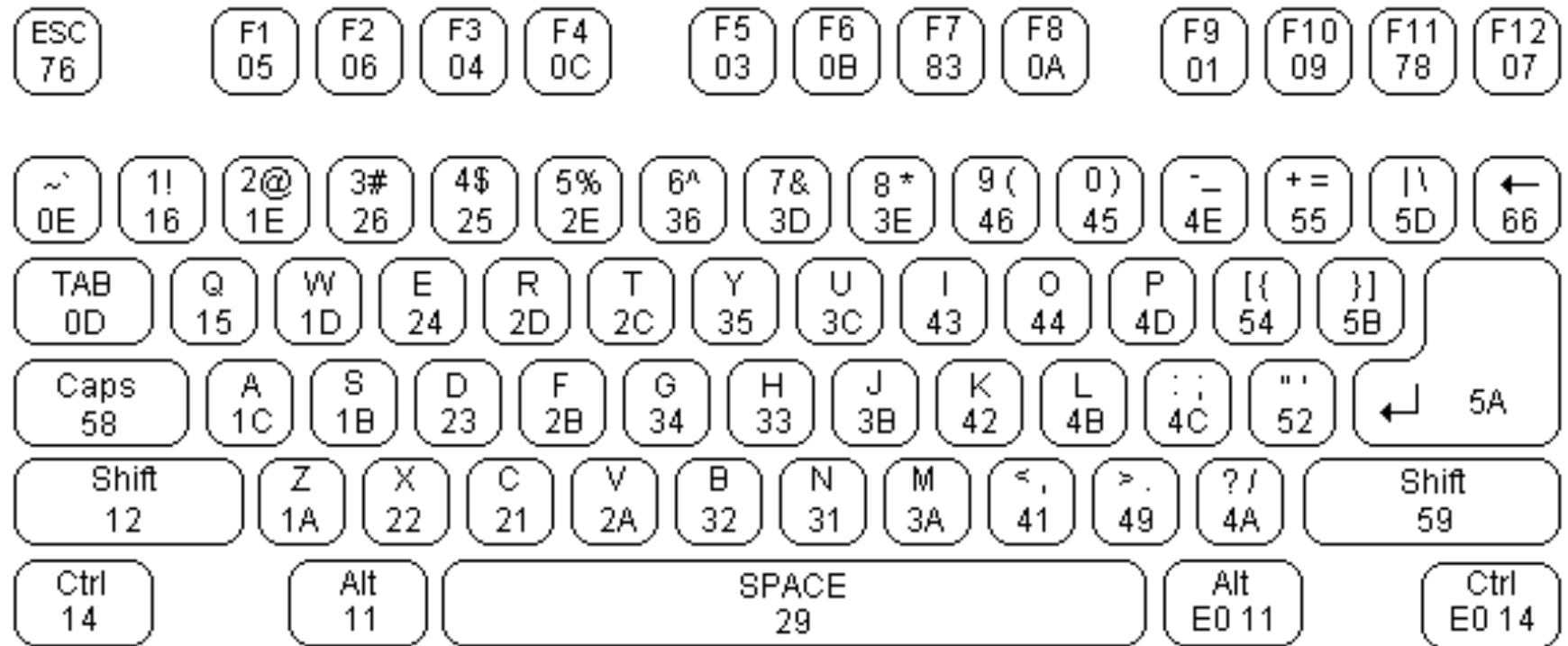
- Can detect falling / rising edge, low / high level
- Set bit for pin in appropriate GPIO event detect enable register (e.g. GPFEN)
- Once enabled, events on that pin will set a bit in the GPIO event detect status register (GPEDS)
- Check GPEDS register for event
- Clear event by writing 1 to bit in GPEDS

See BCM2835-ARM-Peripherals manual pages 96-100

# GPIO Event Detection



# Keyboard Data



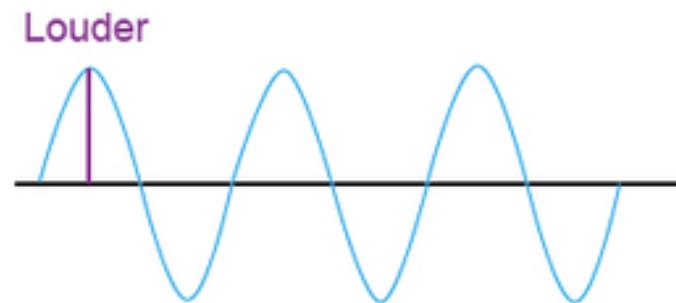
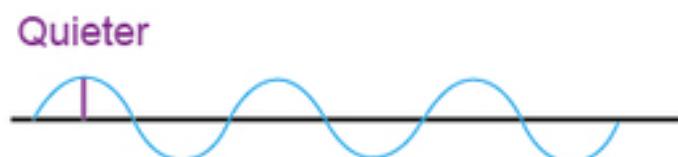
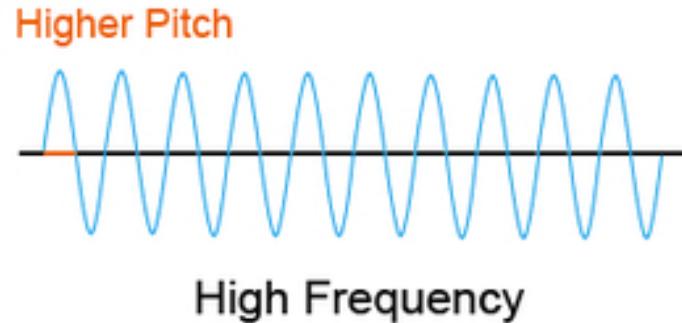
Key	Action	Scan Code
A	Make (down)	0x1C
A	Break (up)	0xF0 0x1C
Shift L	Make (down)	0x12
Shift L	Break (up)	0xF0 0x12

# Keys != Characters

- Keyboard scancodes usually converted to ASCII bit stream
- Conversion throws away some info (left-shift vs. right-shift, multiple keys pressed, alt/cmd + key, etc.)
- Sometimes want the extra info (e.g. games) so interface directly with scancodes

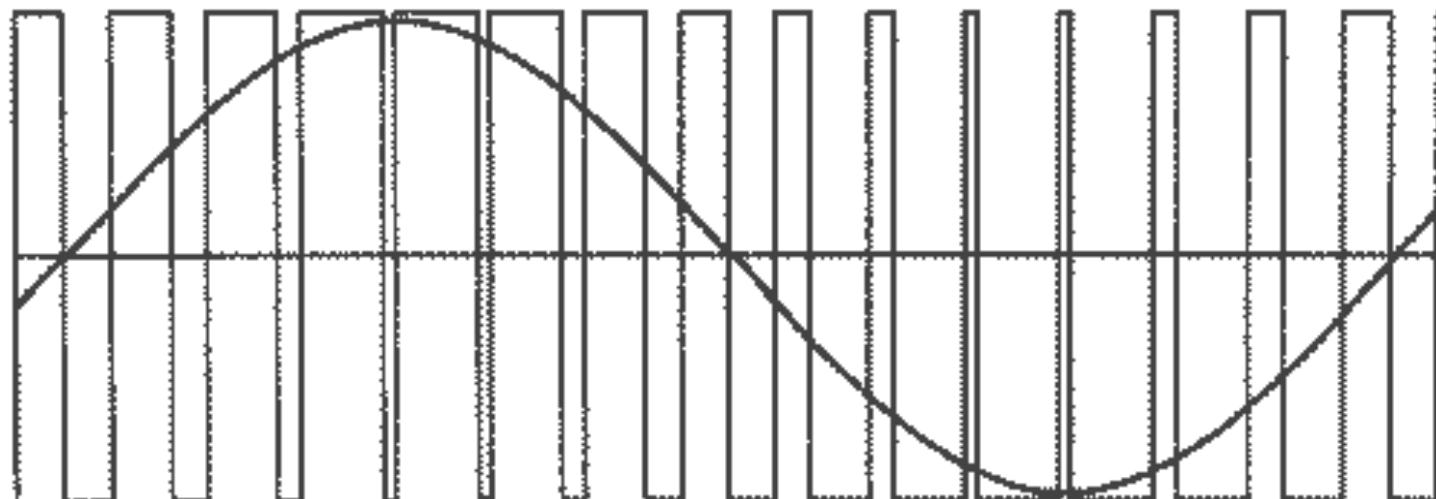
# PWM & Sound

# Sound Waves



# Pulse Width Modulation

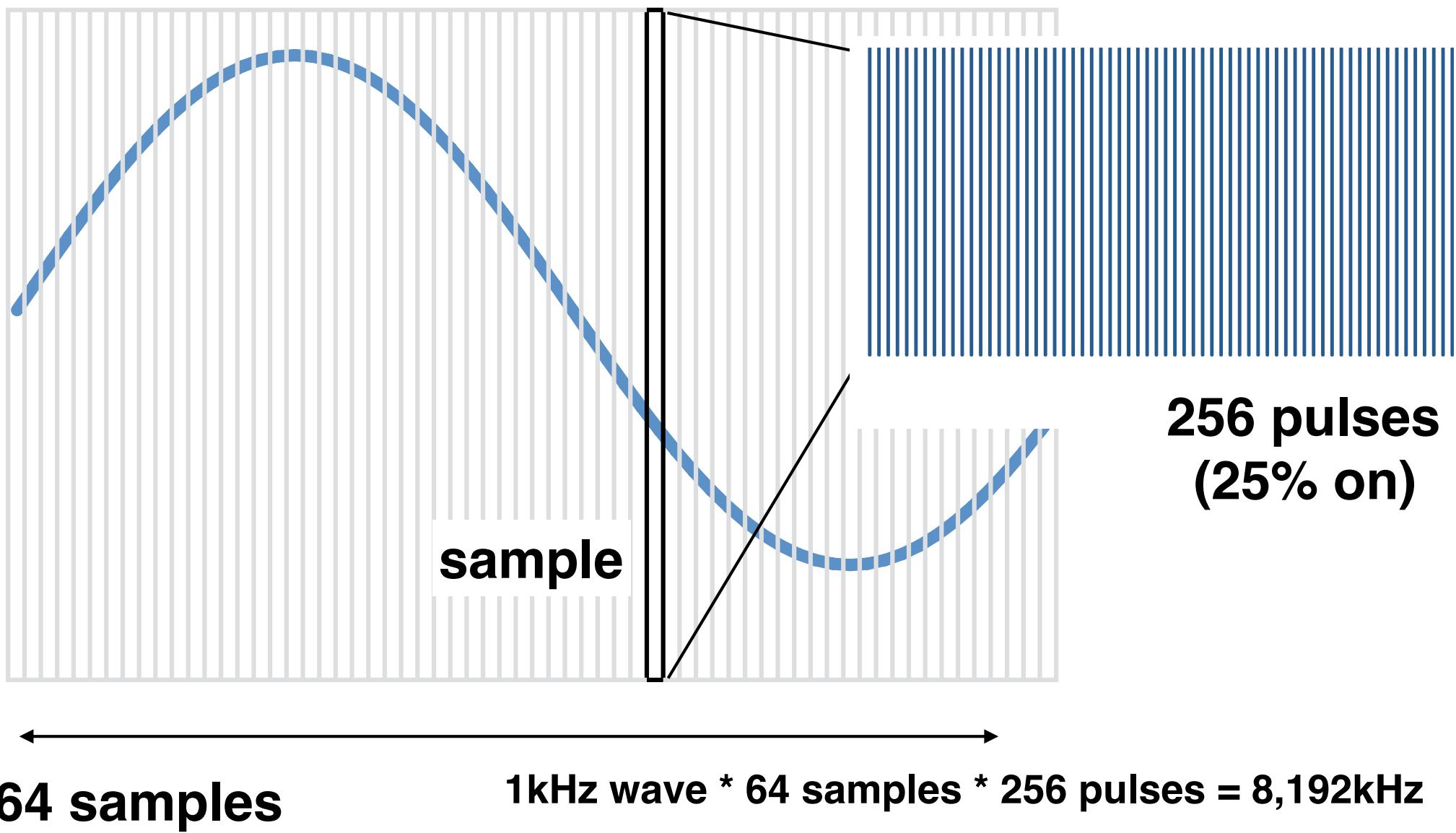
Can simulate continuous values with fast enough PWM clocking



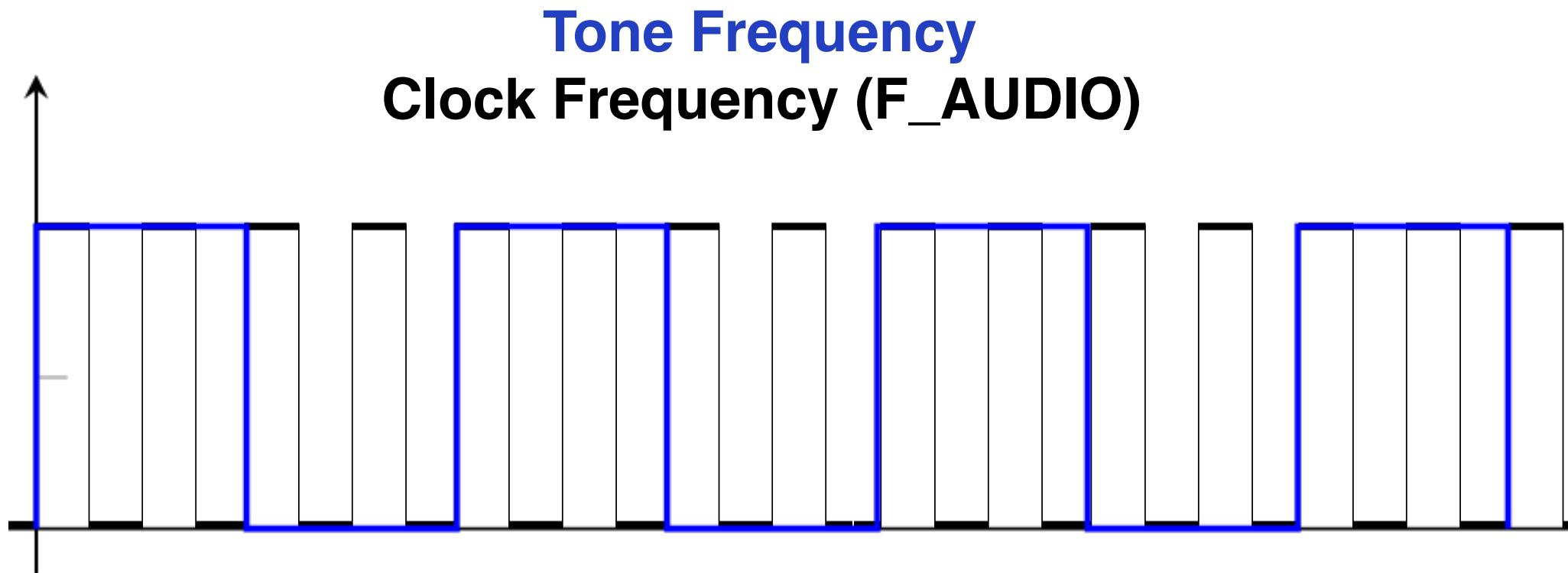
# Hardware PWM Support

- Start with a 19.2MHz clock, divide it to specify the time slots of on/off (e.g., divider of 2.375 = 8,192kHz)
- Divide wave into steps (e.g., 64)
- Divide each step into train of (e.g., 256) pulses
- Tell hardware how many pulses should be high

# Example: Sine



# Square Wave



**Range = 4, Width = 2**

# Waveforms

