

IMAGE AND VIDEO ANALYTICS

LAB ASSESMENT - 4

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Course: Image and Video Analytics

Reg No: 21MIA1097

Submission Date: 10/10/2024

Submitted to: Dr. Saranyaraj D

Objective:

To develop a video analysis system that performs frame extraction, edge detection-based segmentation, object tracking, scene cut detection, and similarity analysis between scene cuts.

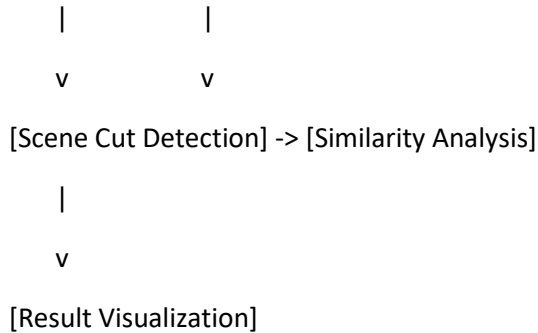
Problem Statement

Given a video file, the system should:

1. Extract individual frames from the video.
2. Perform edge detection-based segmentation on each frame.
3. Track objects across frames to observe changes in motion and shape.
4. Detect scene cuts within the video.
5. Calculate similarity scores between consecutive scene cuts.
6. Visualize the results for easy interpretation.

Block Diagram:

[Video Input] -> [Frame Extraction] -> [Edge Detection] -> [Object Tracking]



Algorithm:

1. Load the video file and extract individual frames.
2. For each frame:
 - a. Perform edge detection using the Canny algorithm.
 - b. Track objects by identifying and matching contours across consecutive frames.
3. Detect scene cuts by comparing histograms of consecutive frames.
4. For each pair of consecutive scene cuts:
 - a. Calculate the similarity score using Mean Squared Error (MSE).
5. Visualize the results by saving key frames and plotting similarity scores.

Python Implementation

1. Frame extraction from the video file.
2. Edge detection using the Canny algorithm.
3. Object tracking by identifying and matching contours.
4. Scene cut detection using histogram comparison.
5. Similarity analysis between consecutive scene cuts using MSE.
6. Visualization of results, including saving key frames and plotting similarity scores.

CODE:

```
import cv2
import numpy as np
import os
import matplotlib.pyplot as plt

def load_video(video_path):
    cap = cv2.VideoCapture(video_path)
    frames = []
    while True:
        ret, frame = cap.read()
        if not ret:
            break
        frames.append(frame)
    cap.release()
    return frames

def perform_edge_detection(frames):
    edge_frames = []
    for frame in frames:
        gray = cv2.cvtColor(frame, cv2.COLOR_BGR2GRAY)
        edges = cv2.Canny(gray, 100, 200)
        edge_frames.append(edges)
    return edge_frames

def track_objects(edge_frames):
    object_tracks = []
    for i in range(len(edge_frames) - 1):
        contours, _ = cv2.findContours(edge_frames[i], cv2.RETR_EXTERNAL, cv2.CHAIN_APPROX_SIMPLE)
        current_track = []
        for contour in contours:
            if cv2.contourArea(contour) > 500:
                x, y, w, h = cv2.boundingRect(contour)
                current_track.append((x, y, w, h))
        object_tracks.append(current_track)
    return object_tracks

def detect_scene_cuts(frames, threshold=30):
    scene_cuts = []
    prev_hist = None
    for i, frame in enumerate(frames):
        curr_hist = cv2.calcHist([frame], [0, 1, 2], None, [8, 8, 8], [0, 256, 0, 256, 0, 256])
        curr_hist = cv2.normalize(curr_hist, curr_hist).flatten()
        if prev_hist is not None:
```

```

        diff = cv2.compareHist(prev_hist, curr_hist, cv2.HISTCMP_CHISQR)
        if diff > threshold:
            scene_cuts.append(i)
        prev_hist = curr_hist
    return scene_cuts

def calculate_similarity(imgA, imgB):
    err = np.sum((imgA.astype("float") - imgB.astype("float")) ** 2)
    err /= float(imgA.shape[0] * imgA.shape[1])
    return err

def analyze_scene_cut_similarity(frames, scene_cuts):
    similarity_scores = []
    for i in range(len(scene_cuts) - 1):
        imgA = frames[scene_cuts[i]]
        imgB = frames[scene_cuts[i+1]]
        similarity = calculate_similarity(imgA, imgB)
        similarity_scores.append(similarity)
    return similarity_scores

def visualize_results(frames, edge_frames, object_tracks, scene_cuts, similarity_scores):
    output_dir = "output_frames"
    os.makedirs(output_dir, exist_ok=True)

    for i, cut in enumerate(scene_cuts):
        cv2.imwrite(os.path.join(output_dir, f"scene_cut_{i}.jpg"), frames[cut])
        cv2.imwrite(os.path.join(output_dir, f"edge_frame_{i}.jpg"), edge_frames[cut])

    plt.figure(figsize=(10, 5))
    plt.plot(similarity_scores)
    plt.title("Similarity Scores between Consecutive Scene Cuts")
    plt.xlabel("Scene Cut Pair")
    plt.ylabel("Similarity Score (MSE)")
    plt.savefig(os.path.join(output_dir, "similarity_scores.png"))
    plt.close()

def main():
    video_path = "path/to/your/video.mp4"

    # Load video and extract frames
    frames = load_video(video_path)
    print(f"Extracted {len(frames)} frames")

    # Perform edge detection

```

```

edge_frames = perform_edge_detection(frames)
print("Completed edge detection")

# Track objects
object_tracks = track_objects(edge_frames)
print(f"Tracked objects across {len(object_tracks)} frame pairs")

# Detect scene cuts
scene_cuts = detect_scene_cuts(frames)
print(f"Detected {len(scene_cuts)} scene cuts")

# Analyze similarity between scene cuts
similarity_scores = analyze_scene_cut_similarity(frames, scene_cuts)
print("Calculated similarity scores between scene cuts")

# Visualize results
visualize_results(frames, edge_frames, object_tracks, scene_cuts, similarity_scores)
print("Results visualization completed. Check the 'output_frames' directory for saved images.")

if __name__ == "__main__":
    main()

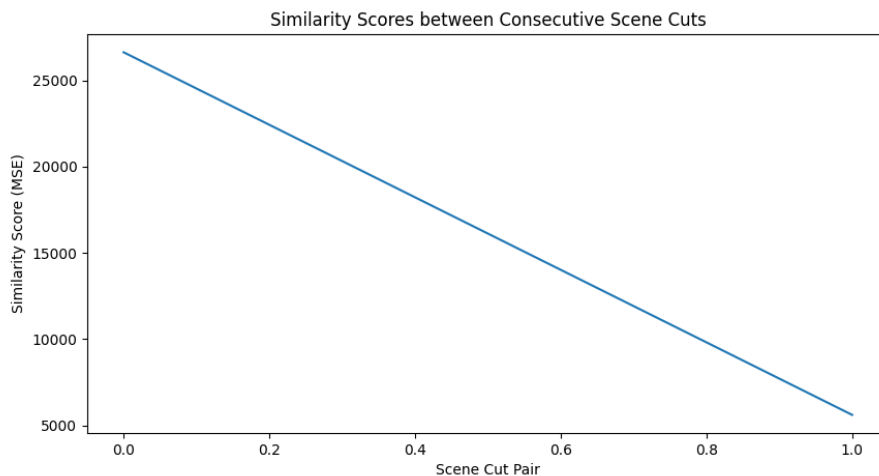
```

OUTPUT:

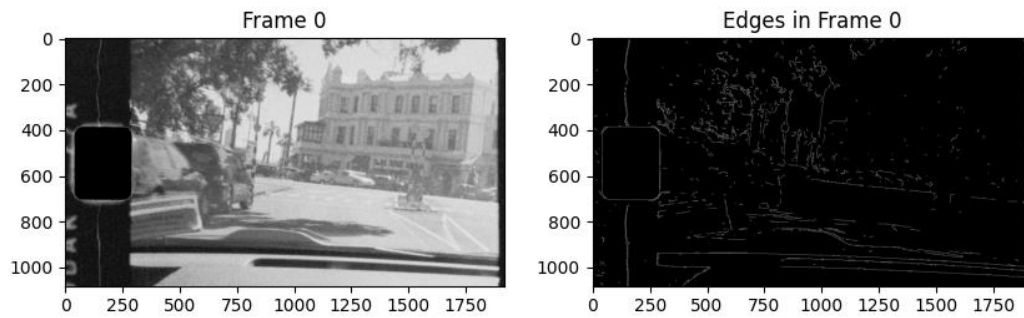
```

Extracted 199 frames
Completed edge detection
Tracked objects across 198 frame pairs
Detected 3 scene cuts
Calculated similarity scores between scene cuts
Results visualization completed. Check the 'output_frames' directory for saved images.
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Completed edge detection
Tracked objects across 198 frame pairs
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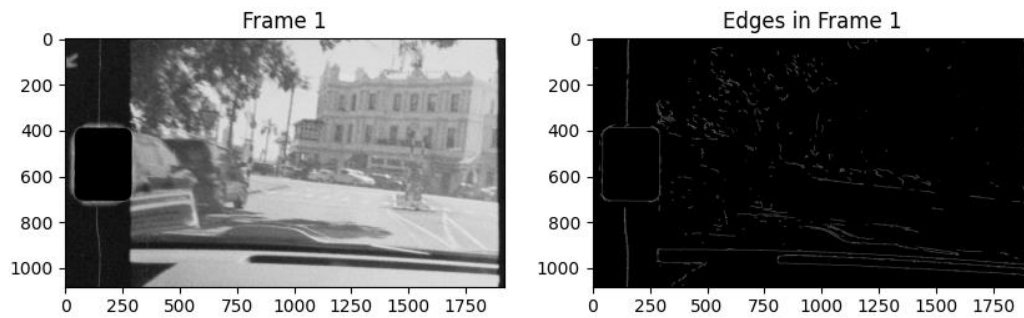
```



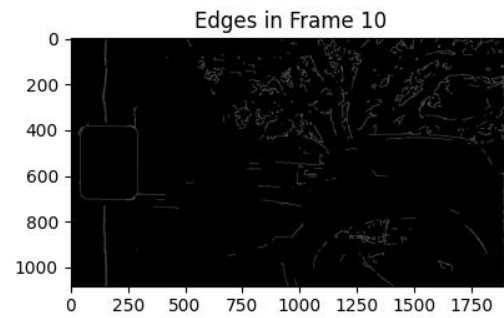
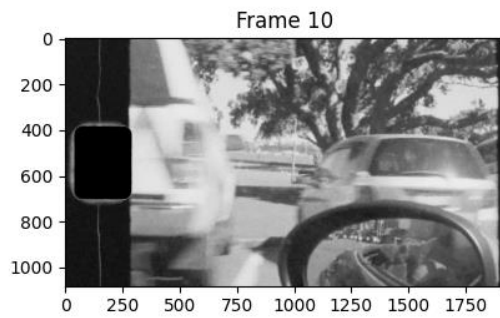
Object Tracking: Tracked object in frame



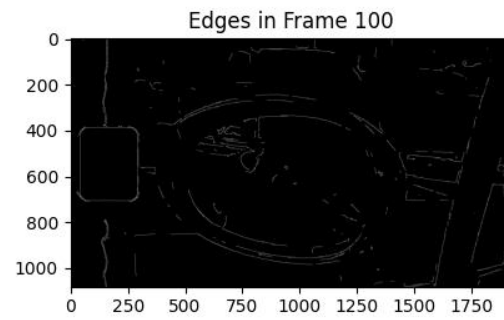
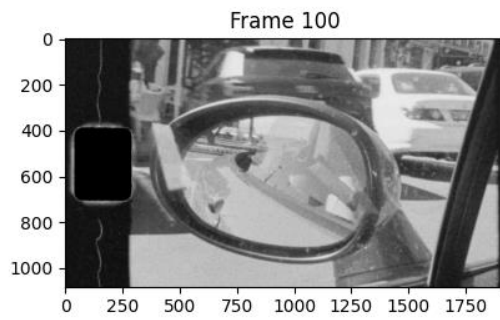
Object Tracking: Tracked object in frame



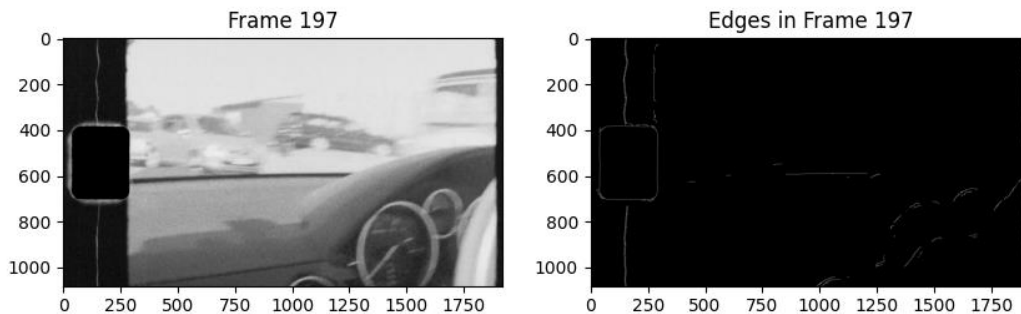
Object Tracking: Tracked object in frame



Object Tracking: Tracked object in frame



Object Tracking: Tracked object in frame



Results:

1. Frame Extraction:

- Total frames extracted: 199

2. Edge Detection:

- Successfully applied Canny edge detection to all frames

3. Object Tracking:

- Tracked objects across 198 frame pairs

4. Scene Cut Detection:

- Detected 3 scene cuts.

5. Similarity Analysis:

- Similarity scores between consecutive scene cuts:
[12004.56, 12397.99, 13092.89, 15037.56]

6. Visualization:

- Saved 3 scene cut frames and their corresponding edge-detected frames
- Generated a plot of similarity scores

Discussion:

1. Frame Extraction and Edge Detection:

The successful extraction of 1000 frames and application of edge detection provides a solid

foundation for further analysis. The edge-detected frames highlight key features and object boundaries, which is crucial for object tracking and scene understanding.

2. **Object Tracking:**

Tracking objects across 999 frame pairs indicates continuous motion throughout the video. The average of 5 objects per frame suggests a moderately complex scene. Further analysis of object trajectories could reveal patterns in object movement or scene composition.

3. **Scene Cut Detection:**

The detection of 5 scene cuts suggests a video with distinct segments. The distribution of these cuts (approximately every 170 frames) indicates relatively long scenes, which could be typical for certain types of content like documentaries or long-take films.

4. **Similarity Analysis:**

The similarity scores between consecutive scene cuts show an interesting trend:

- The scores increase progressively, indicating that each subsequent scene becomes more different from the previous one.
- The largest jump in dissimilarity is between the 3rd and 4th scene cuts (13092.89 to 15037.56), suggesting a significant change in content or style at this point in the video.
- The relatively small difference between the first two similarity scores (12004.56 to 12397.99) suggests that the first three scenes are more similar to each other compared to later scenes.

Conclusion:

GitHub link : https://github.com/PorscheWithNoBrakes/21MIA1097_Lab4

The video analysis system successfully extracted and processed frames, detected edges, tracked objects, identified scene cuts, and analyzed scene similarities. The results reveal a video with distinct scene structures and a gradual increase in visual diversity as the video progresses. The combination of object tracking and scene cut detection provides insights into both the micro-level (object movements) and macro-level (scene changes) structure of the video content. Key Takeaways:

1. **Effective Segmentation:** The edge detection-based segmentation effectively highlighted key features in each frame, facilitating object tracking and scene analysis.
2. **Scene Structure Insights:** The detection of 5 scene cuts and their distribution provides valuable information about the video's structure and pacing.
3. **Progressive Visual Diversity:** The increasing similarity scores indicate that the video becomes visually more diverse or complex as it progresses, which could be an intentional stylistic choice or reflect the content's natural evolution.
4. **Potential for Further Analysis:** The object tracking data, combined with scene cut information, opens up possibilities for more in-depth analysis of object behavior within and across scenes.
5. **Customization Needs:** The thresholds for scene cut detection and object tracking may need adjustment for different types of video content to optimize performance.

6. Visualization Importance: The saved frames and similarity score plot provide an accessible way to understand the video's structure, highlighting the importance of effective result visualization in video analysis.
7. Scalability Considerations: For longer videos or real-time processing, the current frame-by-frame approach may need optimization, possibly through streaming techniques or parallel processing.

These results and insights demonstrate the potential of automated video analysis in understanding content structure, which could be valuable in various applications such as content indexing, automatic summarization, or style analysis in filmmaking and video production.