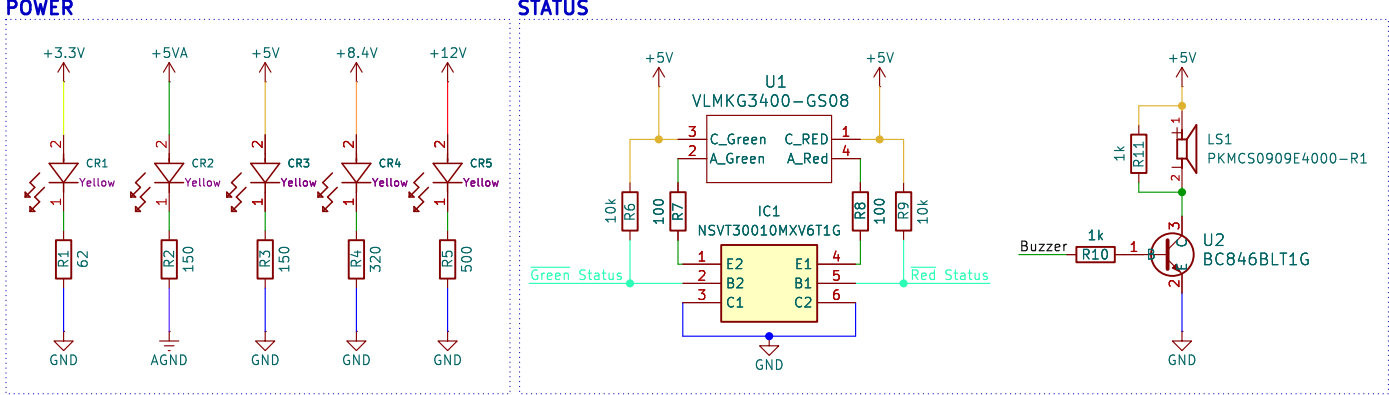


## LEDs Drivers



Guilherme Coelho

Miguel Amorim

Porto Space Team

Sheet: /

File: HYDRA.kicad\_sch

**Title: Hydraulic Regulation & Actuation system**

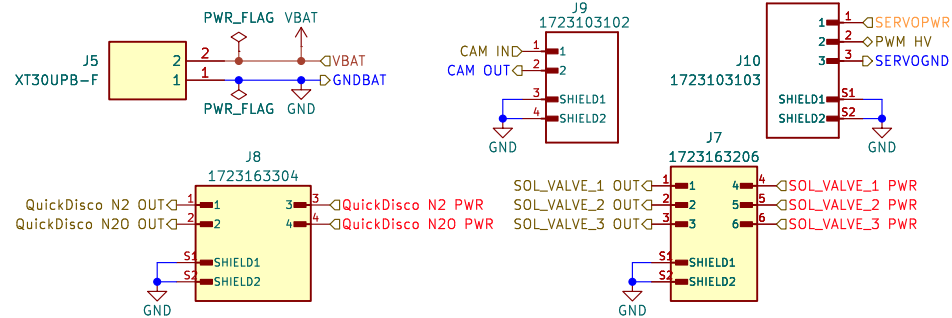
Size: User Date: 2025-09-01

KiCad E.D.A. 9.0.3

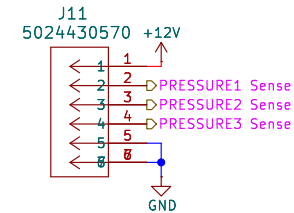
Rev:

Id: 1/6

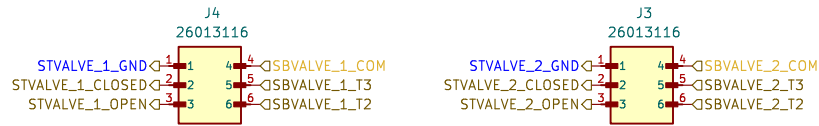
## JZ-500 2x1.5mm<sup>2</sup> 16AWG



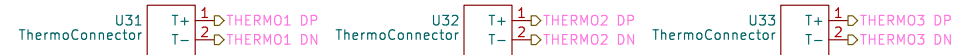
## Igus Chainflex M12x1 4x0.34m<sup>2</sup> 22AWG



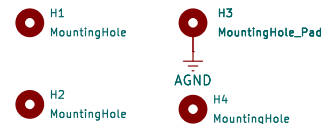
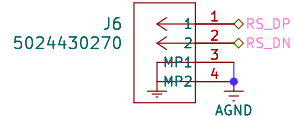
## TRONIC-CY (LiY-CY) 3x0.5mm<sup>2</sup> 20AWG



## Igus Chainflex CF THERMO 2x0.23mm<sup>2</sup> 24AWG



## CAN-BUS 1x2x0.22m<sup>2</sup> 24AWG



Guilherme Coelho  
Miguel Amorim

**Porto Space Team**

Sheet: /IO Connectors/  
File: IO Connectors.kicad\_sch

**Title: Hydraulic Regulation & Actuation system**

Size: User

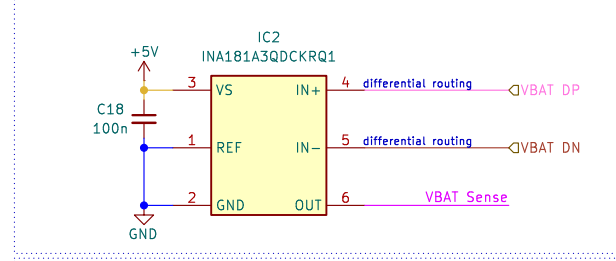
Date:

KiCad E.D.A. 9.0.3

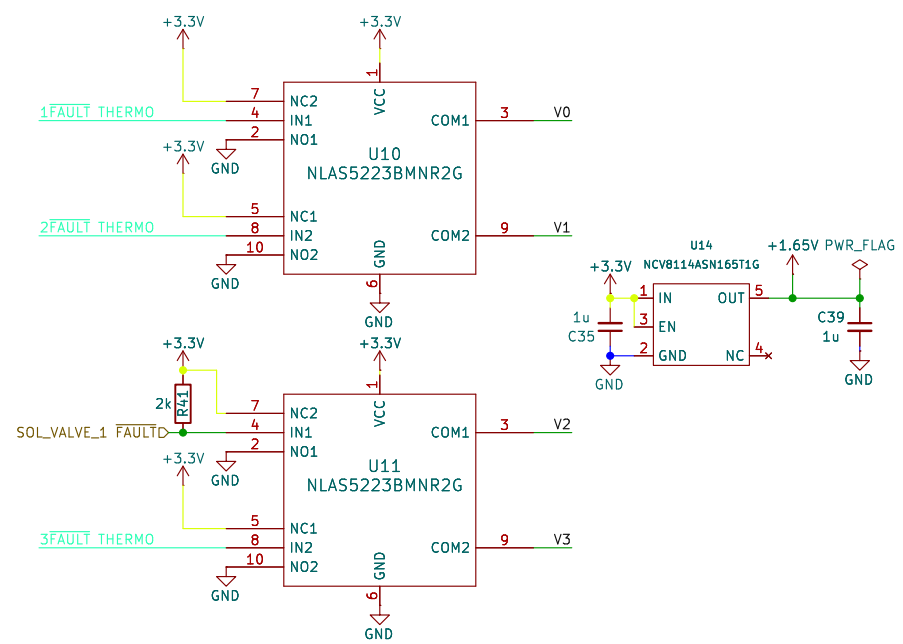
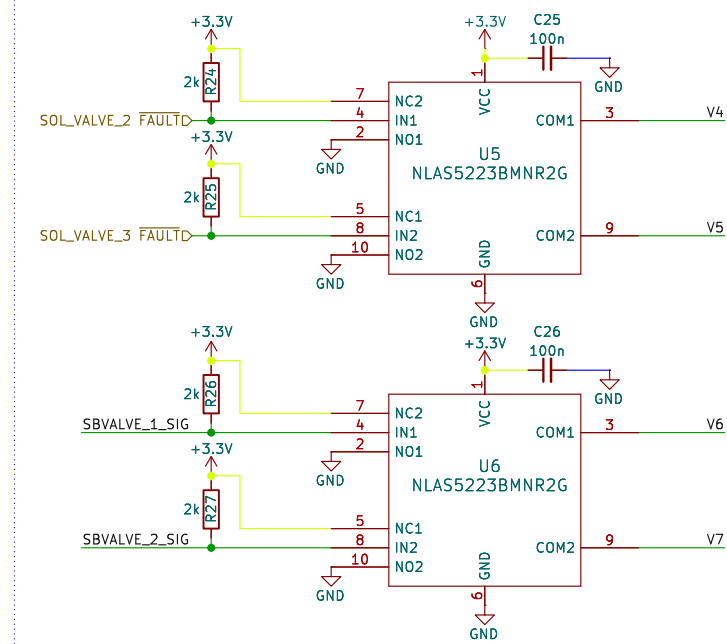
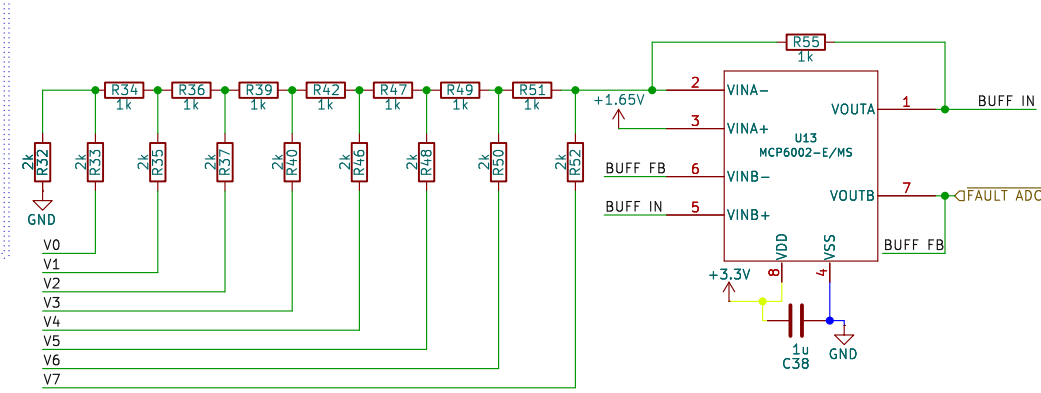
Rev:

Id: 6/6

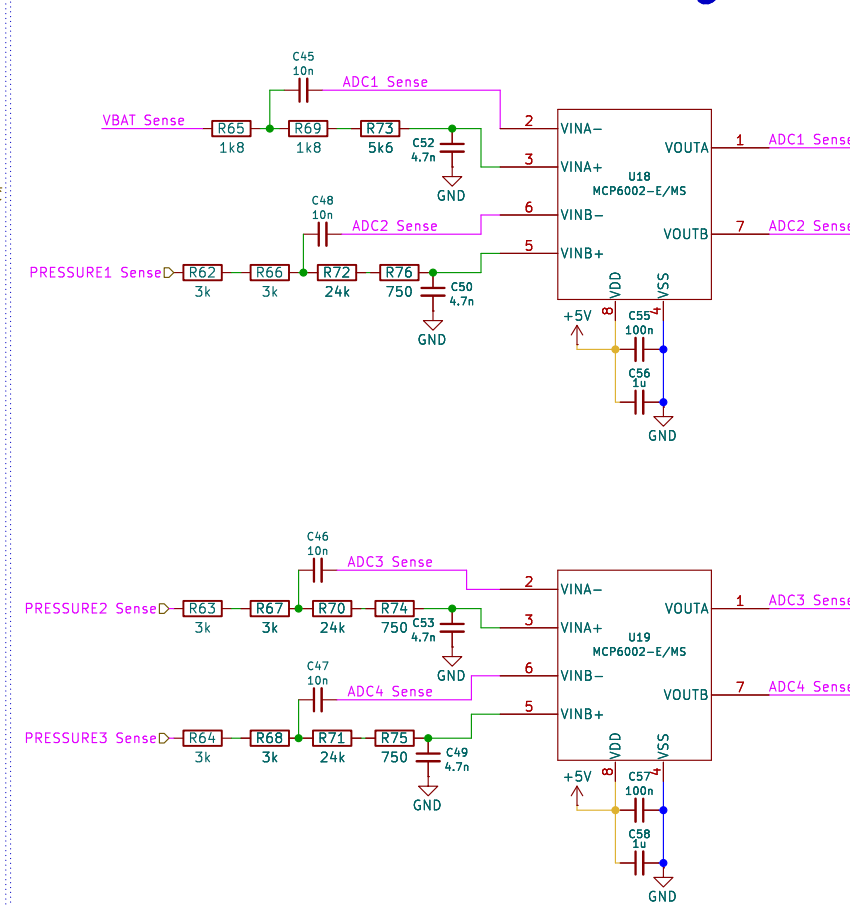
## Current Sensor



## FAULTS AQUISITION ADC

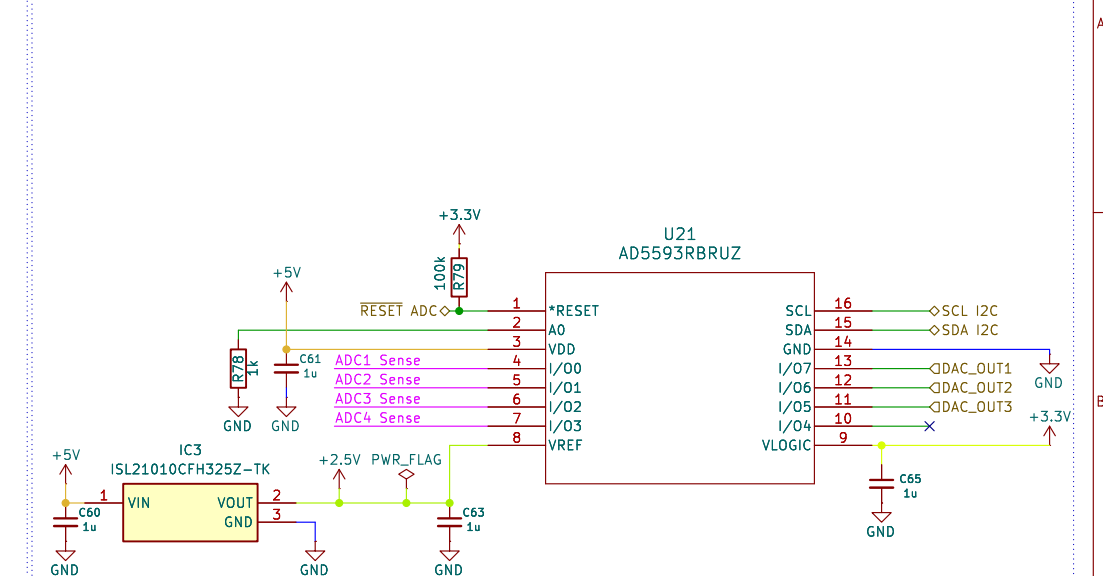


## 2nd Order Low Pass Active Bessel Filter – Anti Aliasing



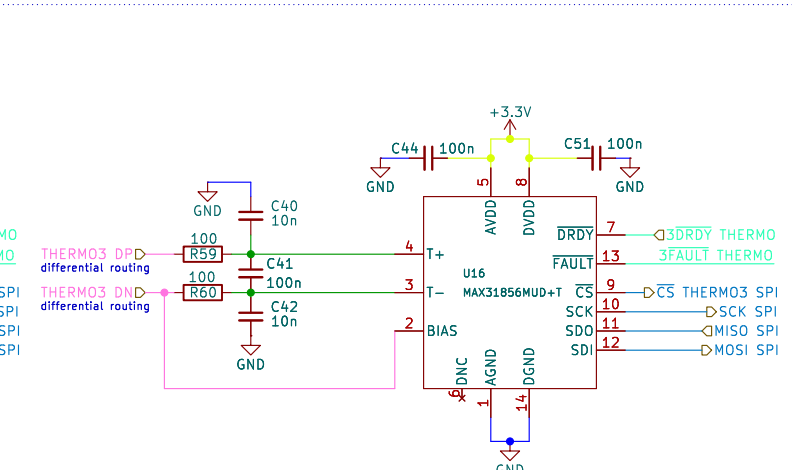
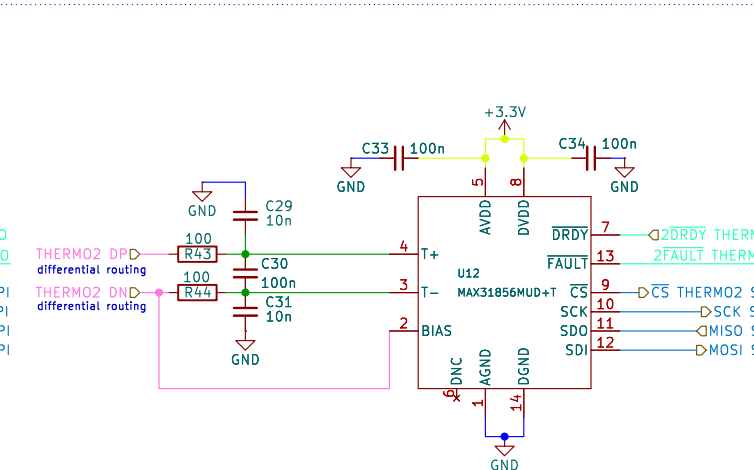
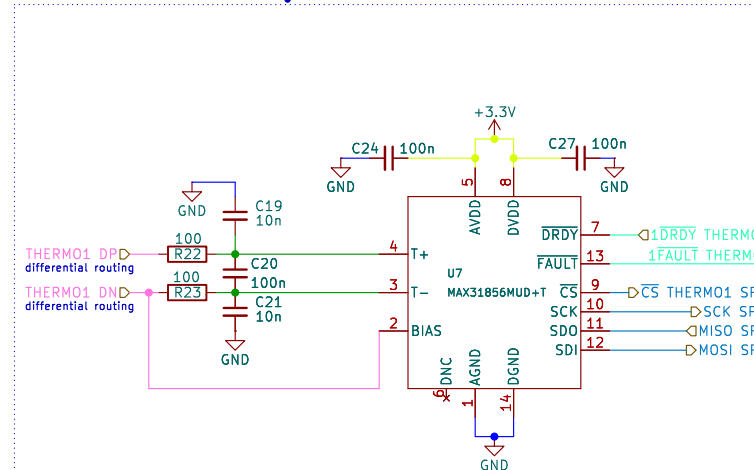
Current Sense Channel:  $F_c = 5\text{kHz}$   
Pressure Sense Channels:  $F_c = 1.5\text{kHz}$

## ADC & DAC

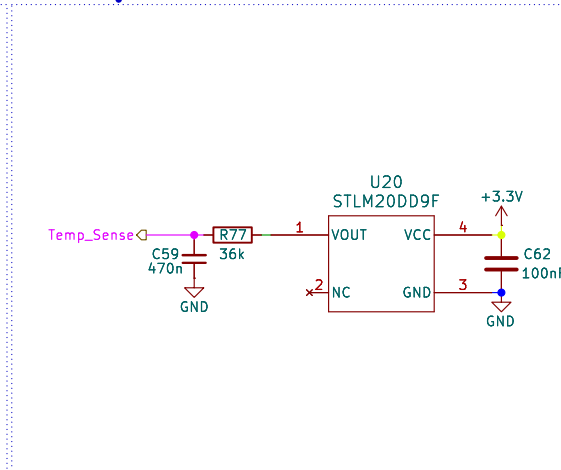


8 Channel 12Bit ADC/DAC  
ADDR I2C: 'h11

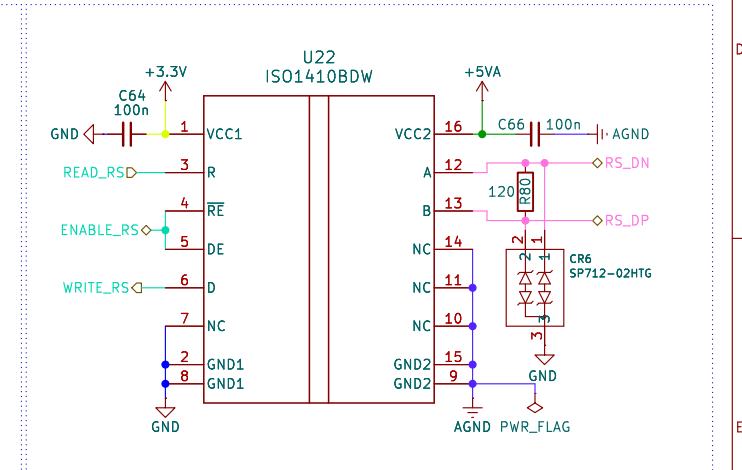
## Thermocouples



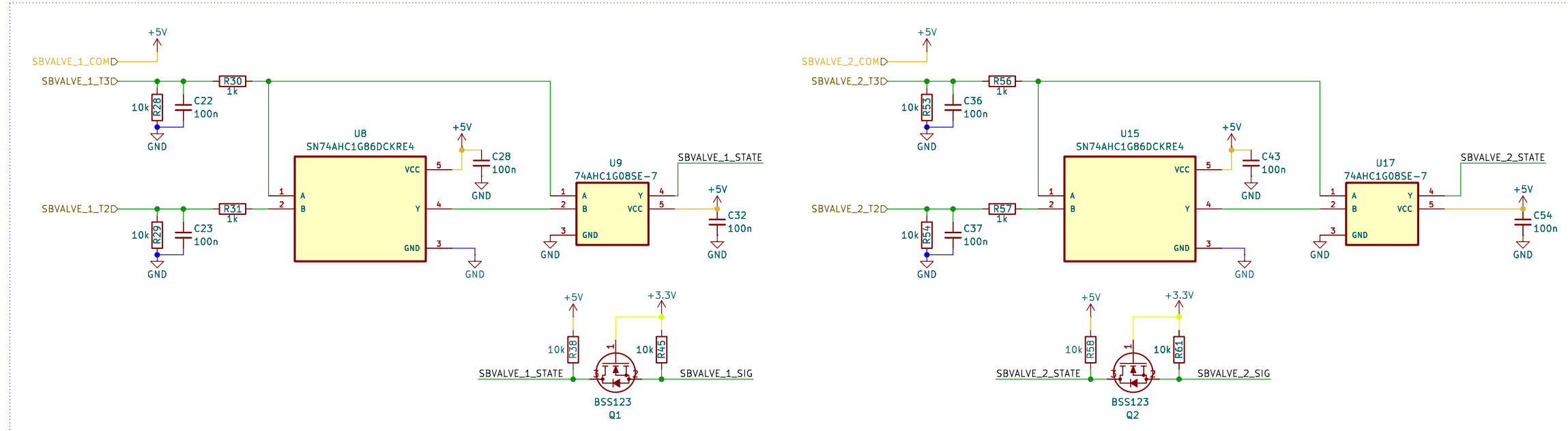
## Temperature Sensor



## RS-485 Transceiver

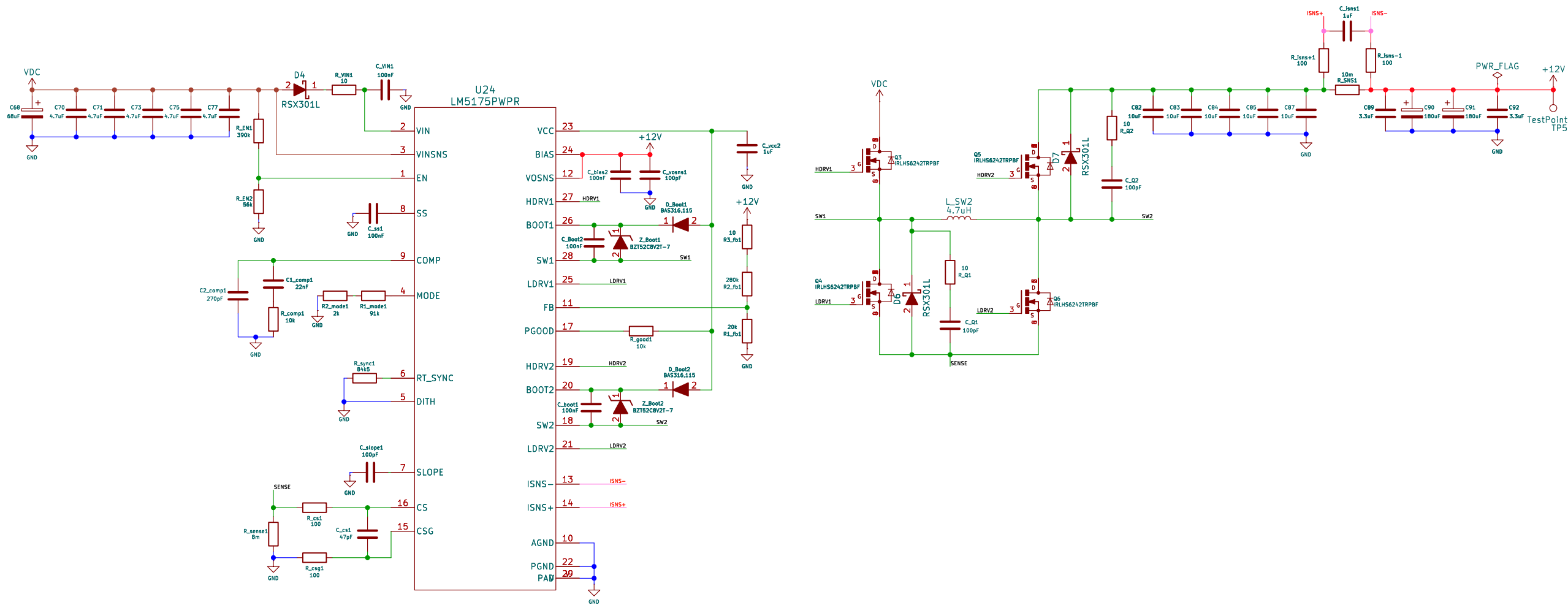


## SBVALVES ACTUATOR POSITION



Buck–Boost DC–DC 10–36V to 12V Converter

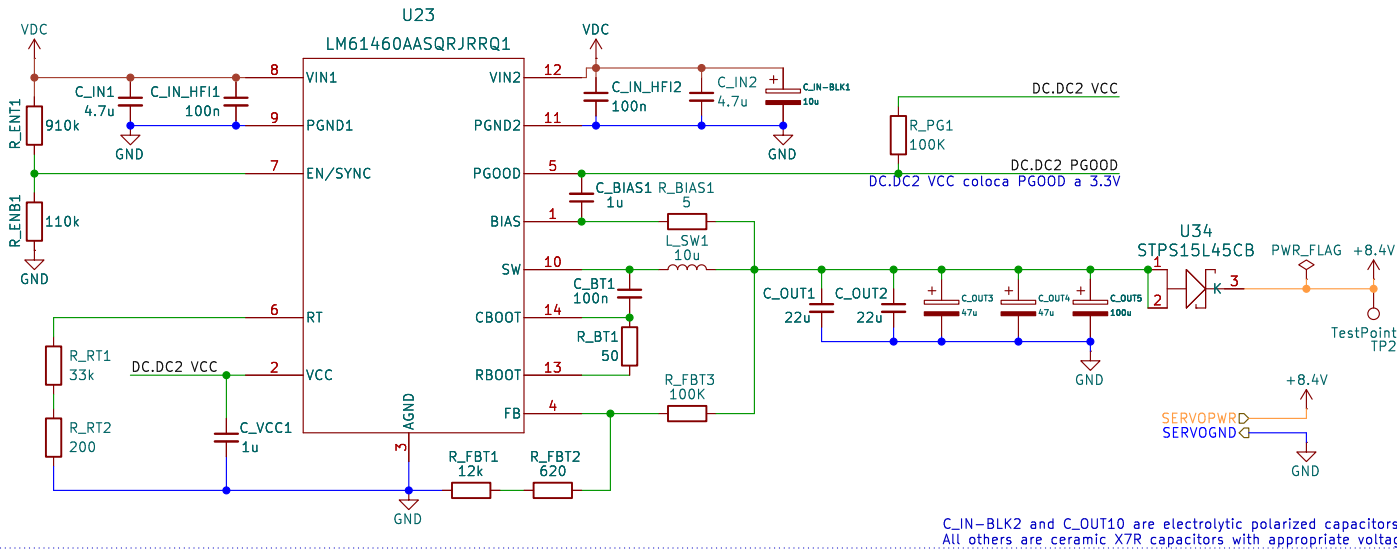
VDC: 12.8V nominal, 14.6V charged



Buck DC–DC >15V to 8.4V Converter

VDC: 12.8V nominal, 14.6V charged

Vout is set to 8.9V to compensate Diode drops.  
The Schottky diode has a 425mV forward voltage drop.

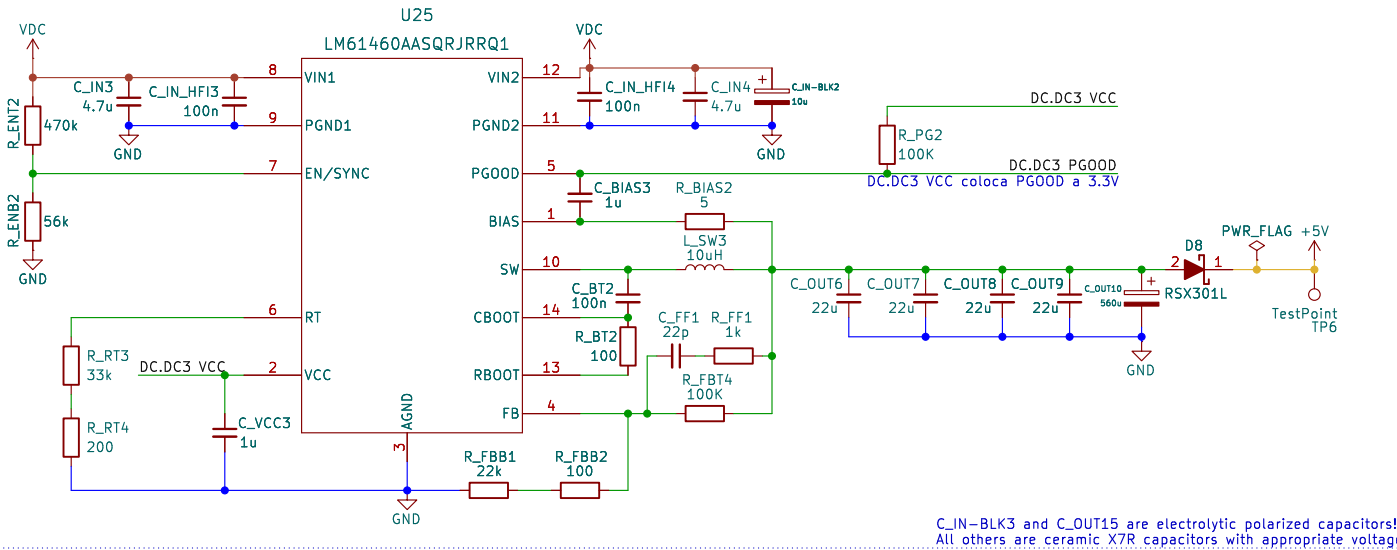


C\_IN-BLK2 and C\_OUT10 are electrolytic polarized capacitors!  
All others are ceramic X7R capacitors with appropriate voltage ratings.

Buck DC–DC >15V to 5V Converter

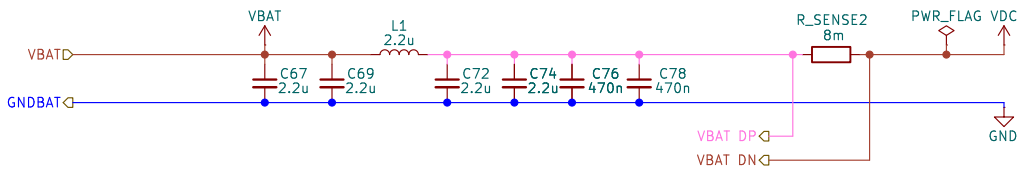
VDC: 12.8V nominal, 14.6V charged

Vout is set to 5.5V to compensate Diode drops.  
The Schottky diode has a 420mV forward voltage drop.

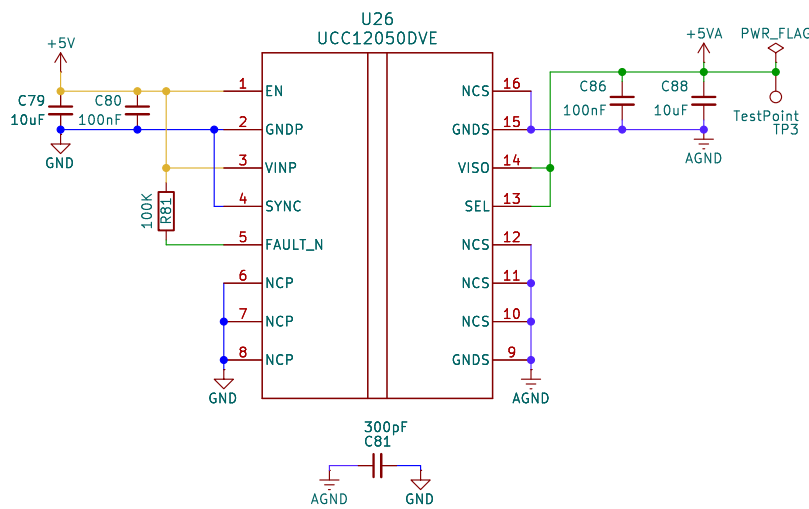


C\_IN-BLK3 and C\_OUT15 are electrolytic polarized capacitors!  
All others are ceramic X7R capacitors with appropriate voltage ratings.

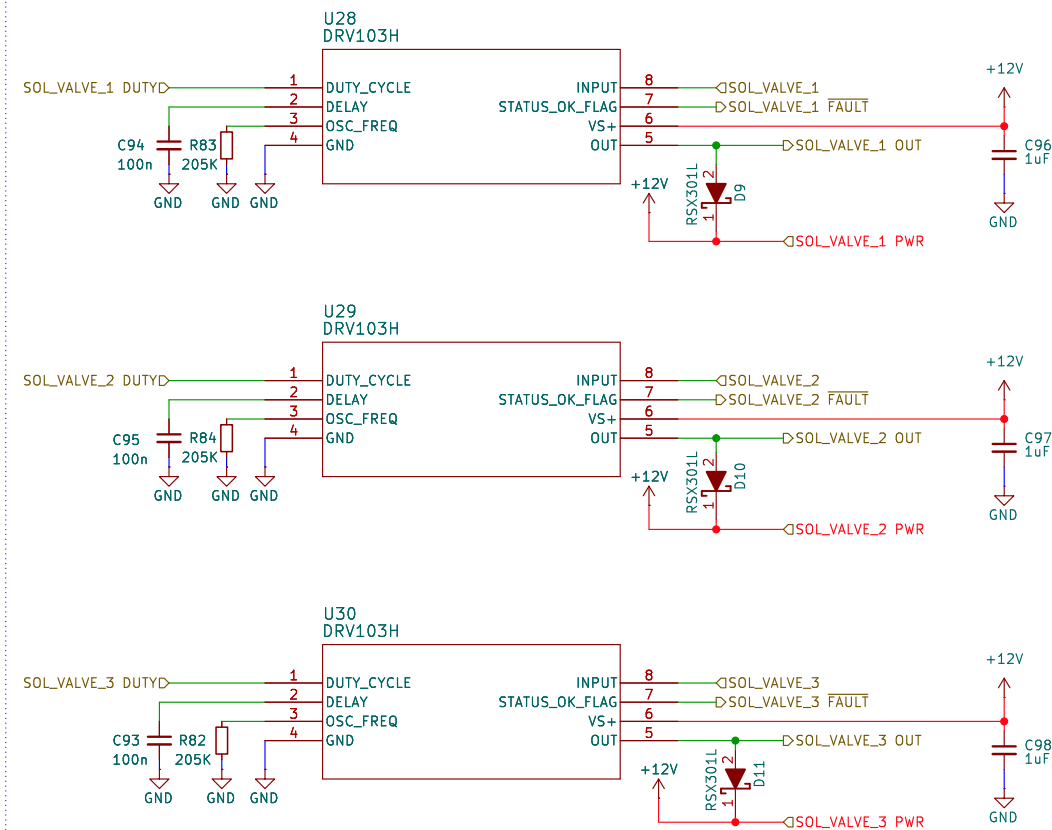
EMI Filter



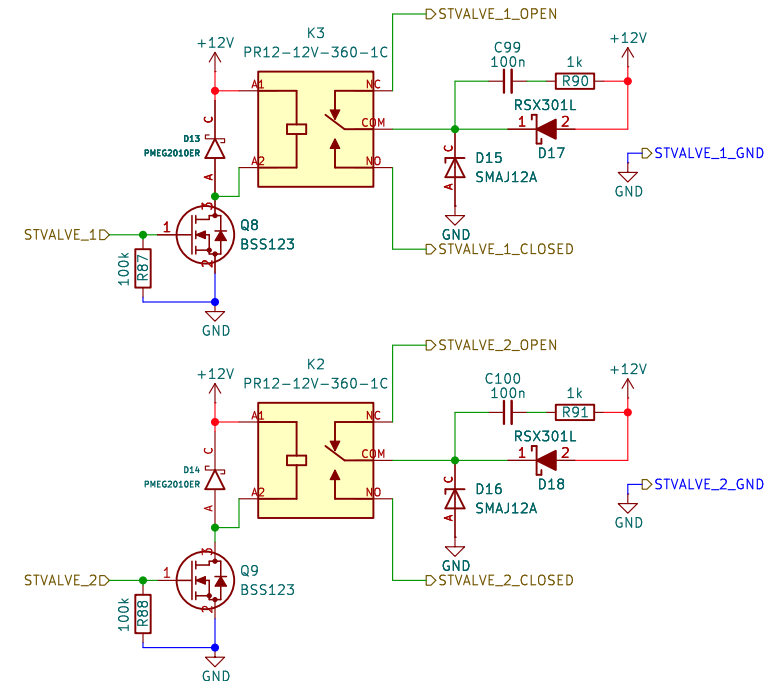
Galvanically Isolated Buck Converter



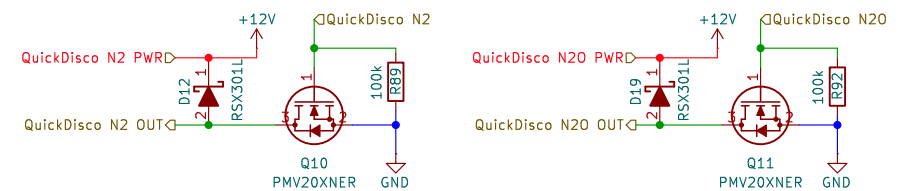
## Controlled Solenoid Valve Drivers



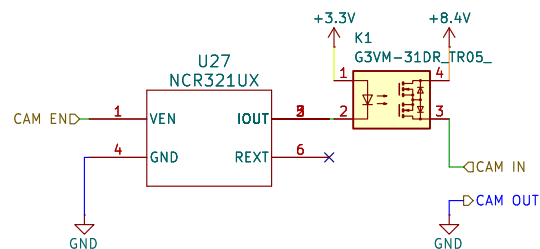
## Steel Ball Valve Actuators



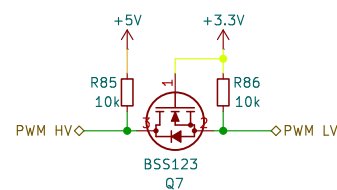
## Solenoid Valve Drivers



## Camera Driver



## ServoMotor Signal



Guilherme Coelho  
Miguel Amorim

**Porto Space Team**

Sheet: /Actuation Unit/

File: Actuation Unit.kicad\_sch

**Title: Hydraulic Regulation & Actuation system**

Size: User

Date:

Rev:

KiCad E.D.A. 9.0.3

Id: 5/6

The PCB layout for the MCU1 RP2040 includes the following components and connections:

- Power and Grounding:**
  - +3.3V:** Connected to the MCU1 VDD pin via a 1k resistor (R12) and a 1uF capacitor (C1) to ground.
  - 100nF for each DVDD, IOVDD, USB\_VDD, ADC\_AVDD1, ADC\_AVDD2:** Connected to the MCU1 DVDD, IOVDD, USB\_VDD, and ADC\_AVDD1 pins via 100nF capacitors (C5, C7, C8, C9, C10, C11, C12, C14) to ground.
  - 1uF as close as possible to VREG\_OUT!:** Connected to the MCU1 VREG\_OUT pin via a 1uF capacitor (C3) to ground.
  - 1uF as close as possible to VREG\_IN!:** Connected to the MCU1 VREG\_IN pin via a 1uF capacitor (C6) to ground.
- Reset (RST):** Connected to the MCU1 RST pin via a 1k resistor (R17) and a 1uF capacitor (C1) to ground.
- USB:**
  - USB\_DP:** Connected to the MCU1 USB\_DP pin via a 1k resistor (R13).
  - USB\_DN:** Connected to the MCU1 USB\_DN pin via a 1k resistor (R14).
  - USB\_D+:** Connected to the MCU1 USB\_D+ pin via a 1k resistor (R13).
  - USB\_D-:** Connected to the MCU1 USB\_D- pin via a 1k resistor (R14).
- MCU1 RP2040 Pins:**
  - GPIO0 - GPIO25:** Connected to the MCU1 GPIO0 - GPIO25 pins via 100k resistors (R15, R16).
  - GPIO26 - GPIO29:** Connected to the MCU1 GPIO26 - GPIO29 pins via 100k resistors (R15, R16).
  - GPIO0 - GPIO25:** Connected to the MCU1 GPIO0 - GPIO25 pins via 100k resistors (R15, R16).
  - GPIO26 - GPIO29:** Connected to the MCU1 GPIO26 - GPIO29 pins via 100k resistors (R15, R16).
- Crystal:** Connected to the MCU1 XIN and XOUT pins via a crystal (D1).
- SWCLK:** Connected to the MCU1 SWCLK pin via a 100k resistor (R15).
- SWD:** Connected to the MCU1 SWD pin via a 100k resistor (R16).
- TESTEN:** Connected to the MCU1 TESTEN pin via a 100k resistor (R16).

JP2  
Jumper\_2\_Open

USB\_B00T

4k

MCU CS SPI

MCU SD1 SPI

MCU SD2 SPI

GND

U3  
W25Q128JVSQ TR

1 /CS

2 DO(101)

3 /WP(102)

4 GND

5 DI(100)

6 CLK

7 /HOLD./RESET

8 VCC

+3.3V

C17  
100nF

GND

MCU SD3 SPI

MCU SCLK SPI

MCU SD0 SPI

[illegible]

The diagram shows the XTAL1 module (ASE-12.000MHZ-LC-T) with the following connections:

- Pin 1:** TRI-STATE(STBY)
- Pin 2:** GND/CASE
- Pin 3:** VDD OUTPUT
- Pin 4:** VDD OUTPUT

A 10k resistor is connected between +3.3V and GND. A crystal (C13, 1uF) is connected between pins 3 and 4, with +3.3V and GND connections.

Id: 2/6