

# Interpolação de Hermite

- Além dos valores  $y_i = f(x_i)$ ,  $i = 0, \dots, n$ , devemos conhecer os valores da derivada  $z_i = f'(x_i)$ ,  $i = 0, 1, \dots, n$ .

## Teorema 6.3:

- $n \geq 0$

- $x_i \in \mathbb{R}; i = 0, 1, \dots, n$   
distintos

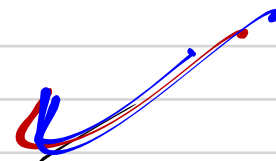
- $y_i \in \mathbb{R}; i = 0, 1, \dots, n$

- $z_i \in \mathbb{R}; i = 0, 1, \dots, n$

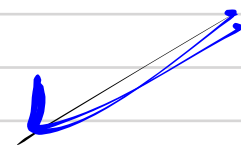
$\Rightarrow \exists!$  polinomio interpolador  
 $P_{2n+1} \in P_{2n+1}$

tal que

$$\left\{ \begin{array}{l} p_{2n+1}(x_i^0) = y_i^0 \end{array} \right.$$



$$\left\{ \begin{array}{l} p_{2n+1}(x_i^0) = z_i^0 \end{array} \right.$$



$$i = 0, 1, 2, \dots, n.$$

Prova:  $\boxed{n \geq 1}$

$$(x^n)^2 x^1 = x^{2n+1}$$

Defina:

$$H_k(x) = \left[ L_k^n(x) \right]^2 \cdot \left[ 1 - 2 \underbrace{L_k^n(x_k)}_1 \cdot \underbrace{(x - x_k)}_0 \right]$$

$$K_k(x) = \left[ L_k^n(x) \right]^2 \cdot (x - x_k)$$

$$L_k^n(x) = \prod_{\substack{j=0 \\ j \neq k}}^n \frac{(x - x_j)}{(x_k - x_j)}$$

$$L_k(x_i) = \begin{cases} 0, & i \neq k \\ 1, & i = k \end{cases}$$

Defina:

$$p_{2n+1}(x) = \sum_{k=0}^n \left[ \underbrace{H_k(x)}_{y_i} \cdot y_k + \underbrace{K_k(x)}_{z_i} \cdot z_k \right]$$

Verificando:

$p_{2n+1} \in P_{2n+1}(\mathbb{R})$ , pois

$H_k, K_k \in P_{2n+1}(\mathbb{R})$ .

calculando as derivadas:

$$H'_k(x) = 2L_k(x) \cdot L'_k(x) \cdot \left[ 1 - 2L'_k(x_k) \underbrace{(x - x_k)}_{=0} \right] + \left[ L''_k(x) \right]^2 \cdot (-2L'_k(x_k))$$

$$\left. \begin{array}{c} H'_k(x_i) = 0, \quad i = 0, 1, \dots, n \\ \uparrow \end{array} \right\}$$

$$H_k(x_i) = \begin{cases} 0, & i \neq k \\ 1, & i = k \end{cases}$$



$$K_k(x) = 2 \underbrace{L_k(x)}_1 \cdot \underbrace{L_k(x)}_1 \cdot \underbrace{(x - x_k)}_{=0} + [L_k(x)]^2$$

$$K_k(x_i) = \begin{cases} 0, & i \neq k \\ 1, & i = k \end{cases}$$

$i \neq k$

=

$i = k$

=

↖

$$K_k(x) = 0; \quad i = 0, 1, \dots, n.$$

$$\Rightarrow p_{2n+1}(x_i) = y_i \quad \square$$

$$p_{2n+2}(x) = \sum_{k=0}^n \left[ \underbrace{H_k(x)}_{=0} \cdot y_k + \underbrace{K_k(x)}_{=0} \cdot z_k \right]$$

$$p_{2n+2}(x_i) = z_i$$



## Unicidade

Supor que existe  $q_{z_{n+1}} \in \mathcal{P}_{z_{n+1}}$   
tal que :

$$\begin{cases} q_{z_{n+1}}(x^j) = y_i^j \\ q_{z_{n+1}}(x^i) = z_i^0 \end{cases}$$

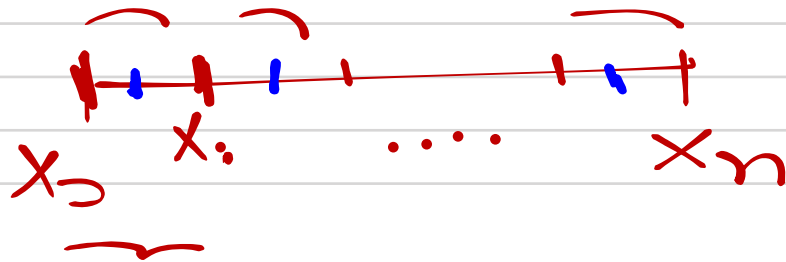
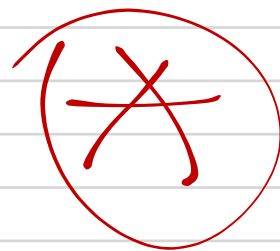
Consequentemente,

$$\in \mathcal{P}_{12n+1}$$

$$\underbrace{p_{2n+1}(x)} - \underbrace{q_{2n+1}(x)} = \underbrace{\tilde{f}(x)}_{=}$$

se avalia em  $(n+1)$  pontos distintos.

$$\boxed{x_i, i = 0, 1, \dots, n.}$$



pelos mesmos argumentos

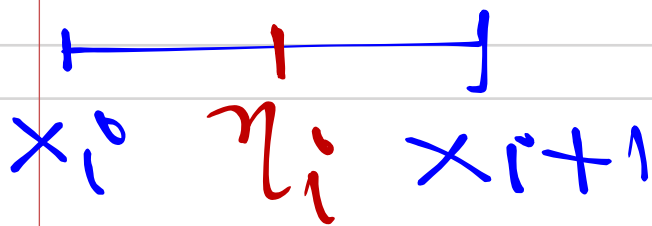
$$\pi(x) = p_{2n+1}(x) - q_{2n+1}(x) \in \mathcal{P}_{2n}$$

também se anula em

$(n+2)$  pontos, pois

$$\pi(x_i) = z_i^0 - z_i^0 = 0.$$

$\mathbb{Q} \times \textcircled{*}$   $\Pi$  se amula  $m(n+1)$   
 pontos, então aplicando  
 o Teo de Rolle nos  
 $n$  subintervalos, vamos  
 encontrar  $n$  pontos que  
 amulam  $\Pi$  :  $\eta_i \in (x_i, x_{i+1})$ ,  
 $i = \overline{0, 1, \dots, n-1}$ .



Esta forma acumulamos  
 $n + n + 1 = 2n + 1$  zeros  
para  $\pi^{\rightarrow}$ .

mas  $\pi^{\rightarrow} \in P_{2n}$ , e não  
podemos ter  $2n + 1$  zeros  
para  $\pi^{\rightarrow} \in P_2$ , a menos que

$\pi' \equiv 0$  ou seja

$$p_{2n+1} \equiv q_{2n+1}$$

$\Rightarrow$

$$p_{2n+1} - q_{2n+1} = \text{Constante}$$

Como,  $p_{2n+1}(x_i) - q_{2n+1}(x_i) = 0$ ,  
 $\forall i=0,1,\dots,n$ , então Constante = 0 QED

$$\boxed{n=0}$$

$$\underline{k=0}$$

$$H_0(x) = 1 \quad \& \quad K_0(x) = (x - x_0)$$

$$1 = H_0(x) = \underbrace{[L_0(x)]^2}_{\substack{\swarrow \\ \text{Lagrange}}} \cdot \underbrace{[1 - L_0(x_0)]}_{\equiv} (x - x_0)$$

para  $x = x_0$

$$1 = [L_0(x_0)]^2 \Rightarrow L_0(x_0) = \pm 1$$

$L_0 \in P_0$   $\xRightarrow{\text{Lagrange}} L_0(x_0) = 1 \Rightarrow L_0(x) = 1$

$$(x - x_0) = h_0(x) = \underbrace{[L_0(x)]^2}_{\downarrow} \cdot (x - x_0)$$

$$x \neq x_0 \Rightarrow L_0(x) = \pm 1$$

Lagrange  
 $\Rightarrow$

$$L_0(x) = 1.$$



Example 6.2.

group 3 :  $2n+1 = 3$

$$\Rightarrow n = 1$$

$$\Rightarrow k = 0, 1$$

$$\begin{array}{ccc} * & \xrightarrow{\quad} & * \\ 0 = \kappa_0 & & \kappa_1 = 1 \end{array}$$

$$P_3(0) = \_$$

$$P_3(1) = \_$$

$$\overline{P}_3(0) = \_$$

$$\overline{P}_3(1) = \_$$

Obs: Para  $f: [a, b] \rightarrow \mathbb{R}$   
derivável em  $[a, b]$  obtém-se  
o polinômio interpolador de  
Hermite de  $f$  passando  
por  $P_{2n+1}(x_i) = f(x_i) = y_i$  e

$$P'_{2n+1}(x_i) = f'(x_i) = z_i \\ i = 0, 1, \dots, n.$$

Ex 89:  $p_{n+1} \approx f$

Th 6.4:

$$|f(x) - p_{n+1}(x)| \leq \frac{M_{2n+2}}{(2n+2)!} [T_{n+1}(x)]^2$$

$$M_{2n+2} = \max_{\eta \in [a,b]} |f^{(2n+2)}(\eta)|$$

# SPLINES

Obs: O fenômeno de Runge  
pode ser evitado  
usando os zeros de  
Chebyshev :

$$x_i = \frac{(a+b)}{2} + \frac{(b-a)}{2} \cos\left(\frac{i\pi}{n}\right)$$

$$i = 0, 1, \dots, n.$$

A função  $f$ , em geral,  
não é conhecida nos  
zeros do polinômio  
de Chebyshev ou o  
conj. de dados conhecido  
 $(x_i, y_i)$  não corresponde

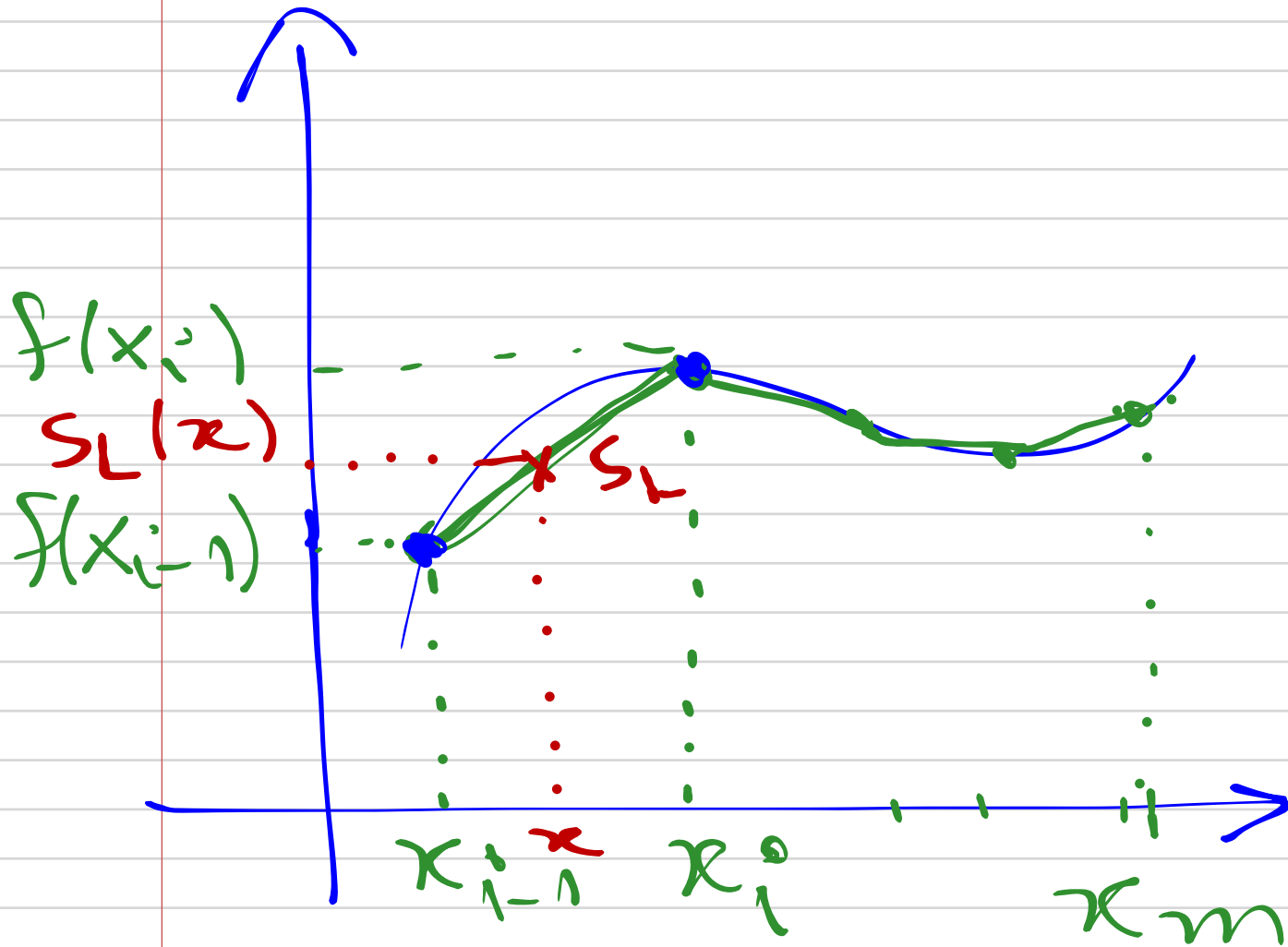
aos  $n+1$  Zeros de  
Chebyshev.

Então, o uso da  
interpolação por partes,  
os splines, são

mucho utilizadas.



# Spline linear



$$\underline{\underline{(x, S_L(x))}} = \underline{\underline{(x_{i-1}, f(x_{i-1}))}} +$$

$$\underline{\underline{\Delta \left[ (x_i, f(x_i)) - (x_{i-1}, f(x_{i-1})) \right]}}$$

$$\begin{cases} x = x_{i-1} + \Delta (x_i - x_{i-1}) & \textcircled{1} \\ S_L(x) = f(x_{i-1}) + \underline{\underline{\Delta (f(x_i) - f(x_{i-1}))}}} & \textcircled{2} \end{cases}$$

Wz ①

$$\lambda = \frac{(x - x_{i-1})}{(x_0 - x_{i-1})} \rightarrow \textcircled{2}$$

$$S_2(x) = f(x_{i-1}) + \frac{(x - x_{i-1})}{(x_0 - x_{i-1})} \cdot (f(x_0) - f(x_{i-1}))$$

$\Rightarrow$

$$S_L(x) = \underbrace{(x_i^0 - x)}_{(x_i^0 - x_{i-1}^0)} \cdot f(x_{i-1}^0) +$$

$$+ \frac{(x - x_{i-1}^0)}{(x_i^0 - x_{i-1}^0)} \cdot f(x_i^0) \quad .$$

$$\boxed{x \in [x_{i-1}^0, x_i^0]} \quad .$$



Para escrever uma spline para todo  $x \in [a, b]$ ,

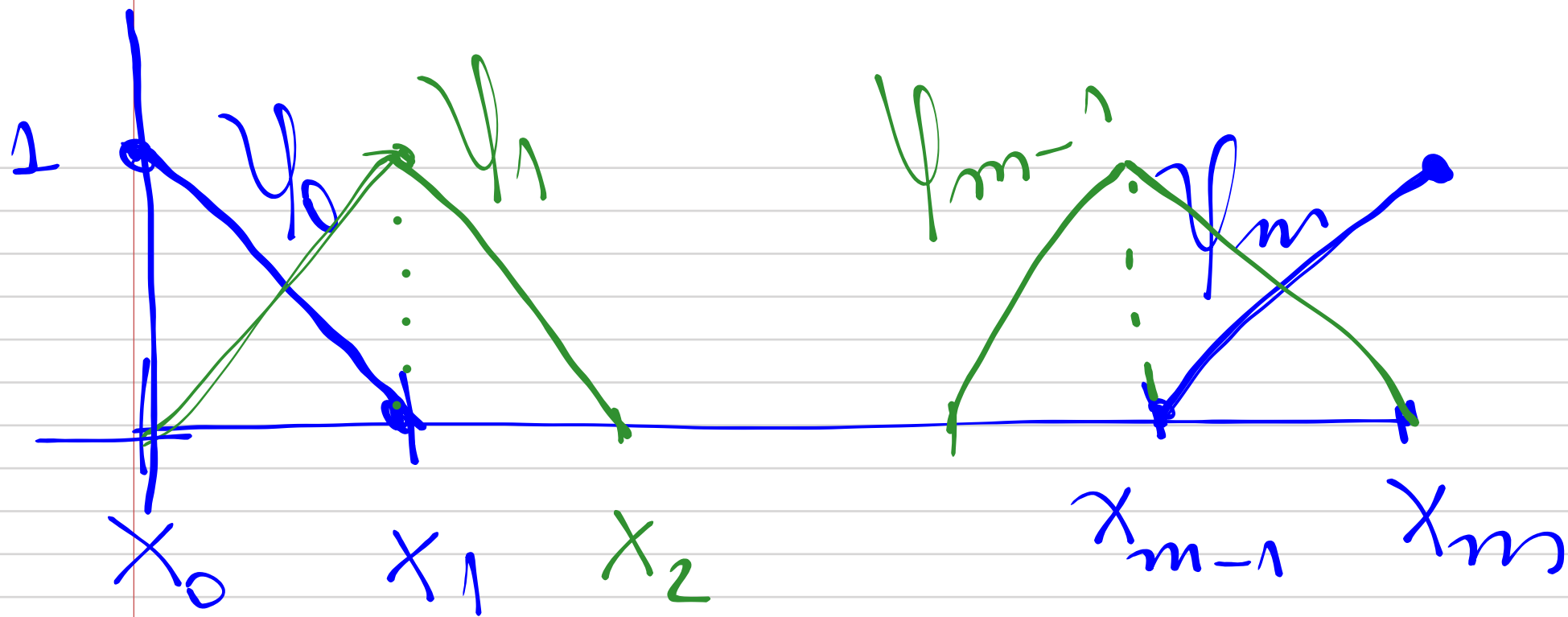
podemos usar uma base de funções e escrever

$$S(x) = \psi_0(x) \cdot f(x_0) + \psi_1(x) \cdot f(x_1) + \dots + \dots + \psi_m(x) \cdot f(x_m).$$

and

$$\psi_0(x) = \begin{cases} \frac{x_1 - x}{x_1 - x_0} & ; x \in [x_0, x_1] \\ 0 & ; x > x_1 \end{cases}$$

$$\psi_m(x) = \begin{cases} \frac{x - x_{m-1}}{x_m - x_{m-1}} & ; x \in [x_{m-1}, x_m] \\ 0 & ; x < x_{m-1} \end{cases}$$



$$V_k(x) = \begin{cases} \frac{x - x_{k-1}}{x_k - x_{k-1}}; & x \in [x_{k-1}, x_k] \\ \frac{x_{k+1} - x}{x_{k+1} - x_k}; & x \in [x_k, x_{k+1}] \\ 0; & \begin{matrix} x < x_{k-1} \\ x > x_{k+1} \end{matrix} \end{cases}$$



Ex 11.1...  $f \in C^2[a,b]$

•  $S_2$  interpola  $f$  in

$$a = x_0 < x_1 < \dots < x_m = b$$

$$\Rightarrow \|f - S_2(x)\|_{\infty} \leq \frac{1}{8} h^2 \cdot \|f''\|_{\infty}$$

$$h = \max_{1 \leq i \leq m} h_i; \quad h_i = |x_i - x_{i-1}|$$

Demonstração:

Aplicar Teo 6.2. em  
cada subintervalo com  $n=1$

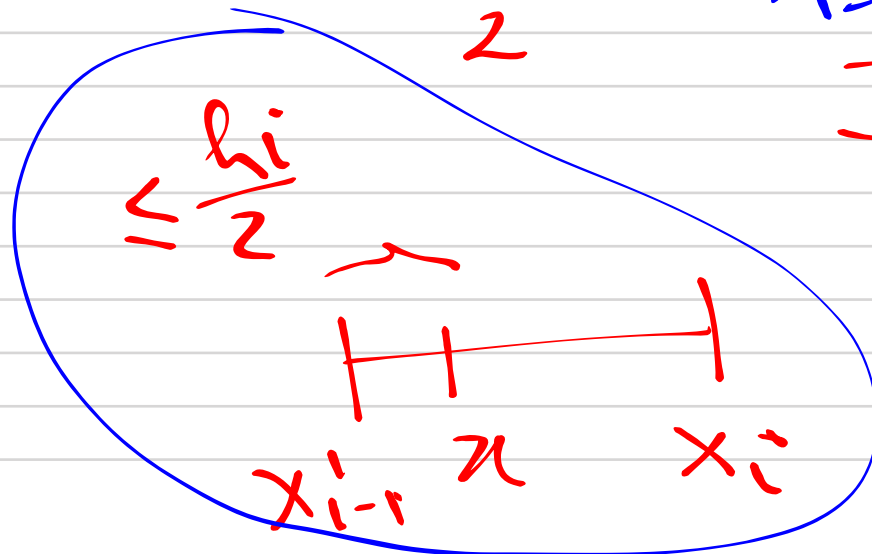
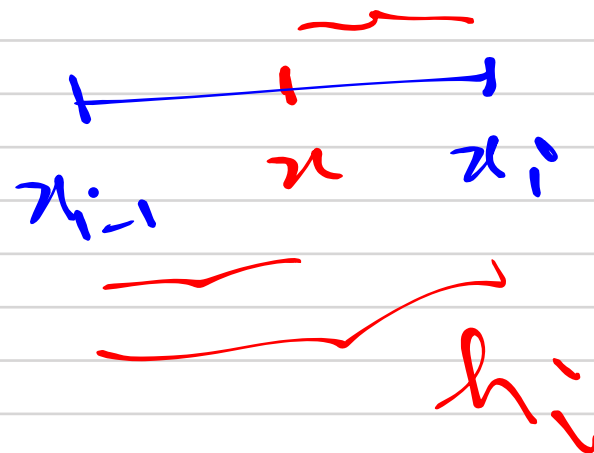
$$(K=0,1) \quad \begin{array}{ccc} * & \xrightarrow{\hspace{2cm}} & * \\ x_{i-1} & & x_i \end{array}$$

$$f(x) - S_L(x) = \frac{\textcircled{+} f''(\xi)}{2} \cdot (x - x_{i-1}) \cdot (x - x_i)$$

$$|f(x) - S_L(x)| = \frac{1}{2} |f''(\xi)| \cdot |x - x_{i-1}| \cdot |x - x_i|$$

$\leq \frac{h_i}{2}$

$$|x - x_i| \leq \frac{h_i}{2}$$



$$\|f - S_L\|_{\infty} = \max_{x \in [x_{i-1}, x_i]} |f(x) - S_L(x)| =$$

$$\leq \frac{1}{2} h_i \leq \frac{h_i}{2}$$

$$= \frac{1}{2} |f''(\xi)| \cdot \max_{x \in [x_{i-1}, x_i]} |x - x_i| \cdot |x - x_{i-1}|$$

$$= \frac{1}{8} |f''(\xi)| \cdot h^2 \leq \frac{1}{8} h^2 \cdot \|f''\|_{\infty}$$

$$\|f - S_L\|_{\infty} \leq \frac{1}{8} h^2 \|f''\|_{\infty}$$

$$\leq \frac{1}{4} h^2 \|f''\|_{\infty}.$$

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