Introduction to PyElastica Software

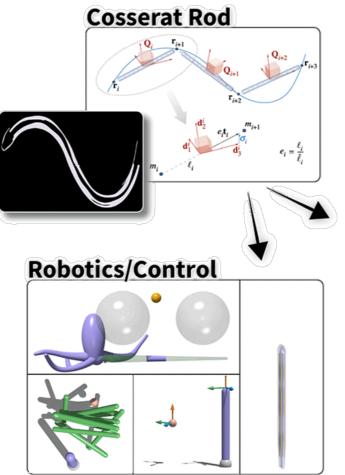
Spring 2022

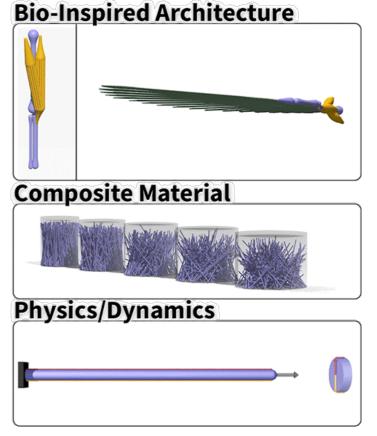
Instructor: Saravana Prashanth Murali Babu



What is PyElastica?

Elastica is a free and open-source software on Python platform for the simulation of assemblies of slender, one-dimensional bodies using Cosserat rod theory.







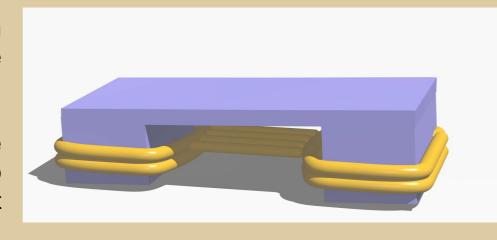
Examples on PyElastica

- → Soft Robotics and Bio-robotics
- → Control of Soft Matter Structures
- → Traveling wave Locomotion



Soft Robotics and Bio-robotics

- ➤ Biohybrid machines have been developed using muscles to actuate soft robotic structures.
- > Soft and flexible robots require optimization of their designs prior to fabrication, reducing development time and cost.

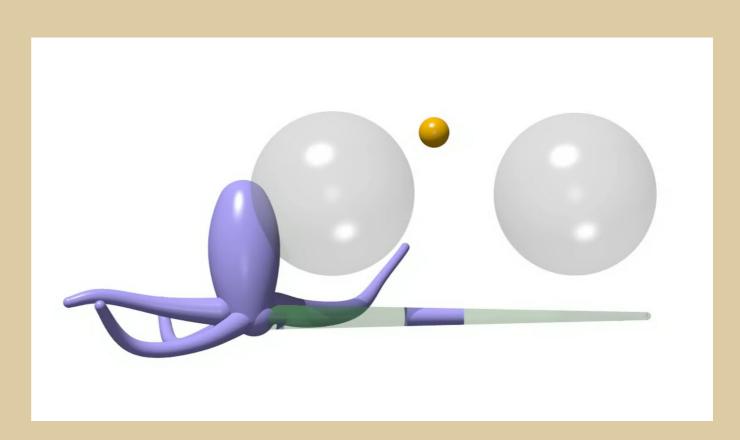




Pagan-Diaz., et al., 2018

Control of Soft Matter Structures

- ➤ Soft robots and structures have many more degrees of freedom than rigid structures, making the system too complex to control.
- Cosserat rod theory can be used model soft slender structures allowing a framework within which novel control strategies for these difficult problems can be developed.

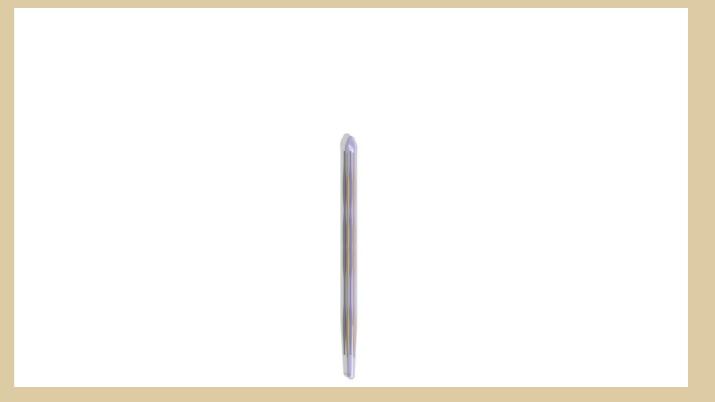


H. -S. Chang et al., 2020



Traveling wave Locomotion

- Cosserat rods can be used to understand how different gaits affect swimming and slithering speed.
- ➤ Snakes and slender swimmers, such as eels, can be modeled either as a single rod or as the interaction of multiple rods representing different muscle groups.



Zhang, X. et al., 2019



Installing steps for PyElastica

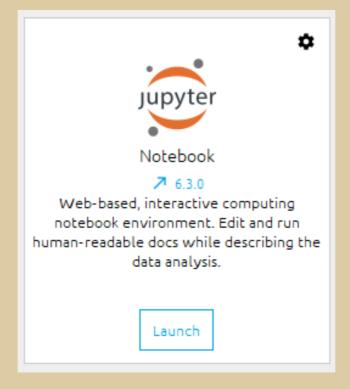


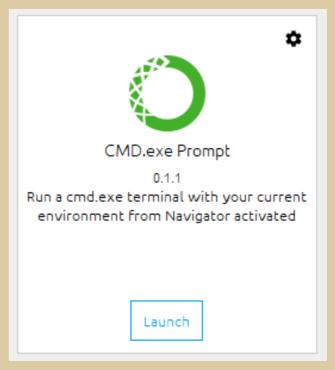
Step 1: Anaconda Navigator



- → Download Anaconda Individual Edition at link
- → Run **Anaconda3 installer** as administrator
- → Open Anaconda Navigator
- → Launch CMD.exe Prompt and Jupyter Notebook









Step 2: Numpy and Matplotlib



- → Launch CMD.exe Prompt
- → Run the code *conda install -c anaconda numpy* at conda prompt
- → Run the code *conda install -c conda-forge matplotlib* at conda prompt or run one of the alternative codes provided on the <u>link</u>

```
C:\windows\system32\cmd.exe — X

Microsoft Windows [Version 10.0.19043.1466]
(c) Microsoft Corporation. All rights reserved.

(base) C:\Users\joti>conda install -c conda-forge matplotlib
Collecting package metadata (current_repodata.json): done
Solving environment: done

# All requested packages already installed.

(base) C:\Users\joti>conda install -c conda-forge matplotlib
```



Step 3: PyElastica



- → Launch CMD.exe Prompt
- → Run the code *conda install pip* at conda prompt
- → Run the code *pip install pyelastica* at conda prompt

```
C:\windows\system32\cmd.exe — X

Collecting package metadata (current_repodata.json): done
Solving environment: done

# All requested packages already installed.

(base) C:\Users\joti>conda install pip
Collecting package metadata (current_repodata.json): done
Solving environment: done

# All requested packages already installed.

(base) C:\Users\joti>pip install pyelastica
```

Check additional information about PyElastica at link

GitHub: PyElastica



Step 4: Ffmpeg and Pickle



- → Launch CMD.exe Prompt
- → Run the code *conda install -c conda-forge ffmpeg* at conda prompt or run one of the alternative codes provided on the <u>link</u>
- → Run the code *conda install -c conda-forge pickle5* at conda prompt or run one of the alternative codes provided on the <u>link</u>

```
C:\windows\system32\cmd.exe — X

Microsoft Windows [Version 10.0.19043.1466]

(c) Microsoft Corporation. All rights reserved.

(base) C:\Users\joti>conda install -c conda-forge pickle5
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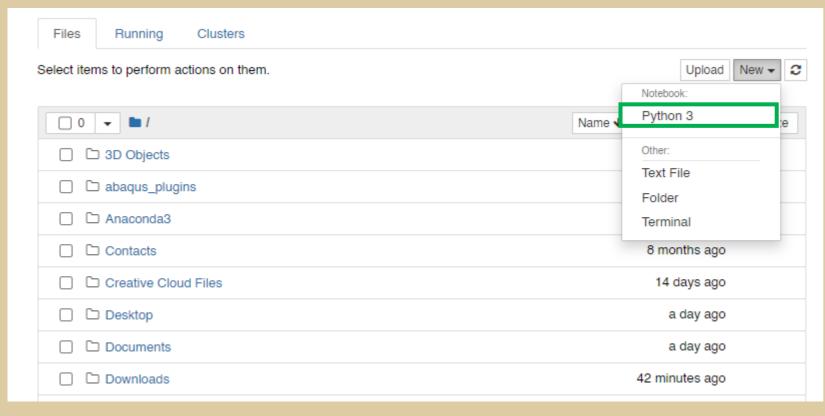


Step 5: Jupyter Notebook



Code Information

- → Open Jupyter Notebook in Anaconda Navigator
- → Open a **New Notebook**
- → Import the libraries: Numpy, Matplotlib, Elastica





In [1]: import numpy
 import matplotlib
 import elastica

