

Graph Embedding

S. Zhou

Word2Vec

DeepWalk

 ${\bf Node 2 Vec}$

 ${\tt Struc2Vec}$

LINE

SDNE

图表示学习

Zhou Shen

School of Computer Science, Wuhan University

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Outline

Graph Embedding

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 ${\bf DeepWalk}$

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Struc2Vec

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- 3 Node2Vec
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- 6 SDNE



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1-of-N Encoding

bag =
$$[0 \ 1 \ 0 \ 0 \ 0]$$

$$cat = [0 \ 0 \ 1 \ 0 \ 0]$$

$$dog = [0 \ 0 \ 0 \ 1 \ 0]$$

elephant =
$$[0 \ 0 \ 0 \ 0 \ 1]$$



Word2Vec One-Word Context

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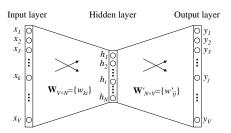


Figure 1: A simple CBOW model with only one word in the context

$$\mathbf{h} = \mathbf{W}^T \mathbf{x} = \mathbf{W}_{(k,\cdot)}^T := \mathbf{v}_{w_I}^T, u_j = \mathbf{v}_{w_j}' h$$
 (1)

$$p(w_j \mid w_I) = y_j = \frac{\exp(u_j)}{\sum_{i'=1}^{V} \exp(u_{i'})}$$
(2)



Word2Vec Objective Function

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$$\max p(w_{O} \mid w_{I}) = \max y_{j^{*}}$$

$$= \max \log y_{j^{*}}$$

$$= u_{j^{*}} - \log \sum_{j'=1}^{V} \exp(u_{j'}) := -E$$
(3)

常用变形

$$\min E = -u_{j^*} + \log \sum_{j'=1}^{V} \exp(u_{j'})$$



Word2Vec

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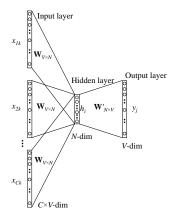
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$$\mathbf{h} = \frac{1}{C} (\mathbf{v}_{w_1} + \mathbf{v}_{w_2} + \dots + \mathbf{v}_{w_C})^T$$

$$E = -\log p \left(w_O \mid w_{I,1}, \dots, w_{I,C} \right)$$

$$= -u_{j^*} + \log \sum_{j'=1}^{V} \exp \left(u_{j'} \right)$$

Figure 2: Continuous bag-of-word model



Word2Vec Skip-Gram

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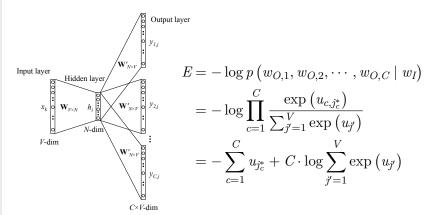


Figure 3: The skip-gram model.



Word2Vec Hierarchical Softmax

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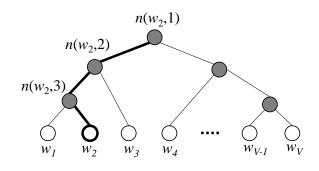
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$$p(w = w_O) = \prod_{i=1}^{L(w)-1} \sigma\left([n(w, j+1) = \text{ch}(n(w, j))] \cdot \mathbf{v}'_{n(w, j)} {}^{T}\mathbf{h} \right)$$



Word2Vec Negative Sample

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1. 词频计算

$$weight(w_i) = \frac{count(w_i)^{0.75}}{\sum_{j}^{V} count(w_j)^{0.75}}$$

2. 目标函数

$$E = -\log \sigma \left(\mathbf{v}_{w_O}^{\prime} \mathbf{h}\right) - \sum_{w \in \mathcal{W}_{\text{out}}} \log \sigma \left(-\mathbf{v}_{w_j}^{\prime} \mathbf{h}\right)$$



DeepWalk

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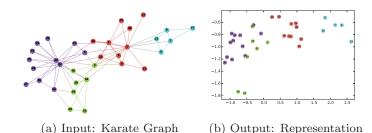
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Definition

Problem Definition Let G = (V, E), where V are the members of the network, and E be its edgs. Our goal is to learn $X_E \in \mathcal{R}^{|V| \times d}$, where d is number of latent dimensions.



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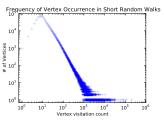
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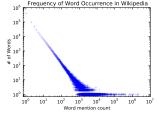
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- (a) YouTube Social Graph
- (b) Wikipedia Article Text

Connection

The power-law distribution of vertices appearing in the short random walks follows a power-law, much like the distribution of words in natural language.



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 \blacksquare give a sequence of random walk from vertice i

$$W_i^n = \{v_1, v_2, v_3, \cdots, v_n\}$$
 (4)

2 maximize the likehood

$$\Pr\left(v_i \mid (\Phi(v_1), \Phi(v_2), \cdots, \Phi(v_{i-1}))\right) \tag{5}$$

Mapping Function Φ

 $\Phi: v \in V \longrightarrow \mathcal{R}^{|V| \times d}$ where d is the number of dimensions



DeepWalk Disadvantages and Optimizations

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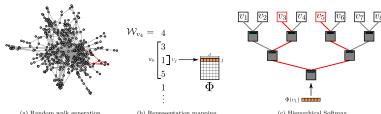
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- As the walk length grows, computing this objective function becomes unfeasible.
- Restricts the order in which vertices appear



(b) Representation mapping.





DeepWalk Algorithm

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Algorithm 1 DeepWalk (G, w, d, γ, t)

Input: graph G(V, E)window size wembedding size dwalks per vertex γ walk length t

Output: matrix of vertex representations $\Phi \in \mathbb{R}^{|V| \times d}$

- 1: Initialization: Sample Φ from $\mathcal{U}^{|V| \times d}$
- 2: Build a binary Tree T from V
- 2. fan i 0 ta t da
- 3: for i = 0 to γ do
- 4: $\mathcal{O} = \text{Shuffle}(V)$
- 5: for each $v_i \in \mathcal{O}$ do
- 6: $W_{v_i} = RandomWalk(G, v_i, t)$
- 7: SkipGram(Φ , W_{v_i} , w)
- 8: end for
- 9: end for

Corollary

$$\underset{\Phi}{\operatorname{minimize}} - \log \Pr \left(\left\{ v_{i-w}, \cdots, v_{i-1}, v_{i+1}, \cdots, v_{i+w} \right\} \mid \Phi \left(v_{i} \right) \right)$$



DeepWalk 复现结果

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micro-F1	Label Node% 原文结果 复现结果	36.00	38.20	30 39.60 39.75	40.30	41.00	41.30	41.50		
macro-F1	24701111	21.30	23.80	25.30 25.33	26.30	27.30	27.60	27.90	28.20	28.90



Node2Vec Classic Search Strategies

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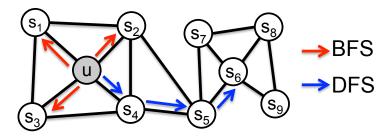
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- 1. The neighborhoods sampled by BFS lead to embeddings that correspond closely to structural equivalence.
- 2. DFS can freely explore network neighborhoods which is important in discovering homophilous communities.



Node2Vec Search Bias α

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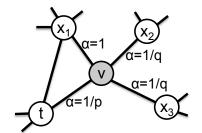
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$$\alpha_{pq}(t,x) = \begin{cases} \frac{1}{p} & \text{if } d_{tx} = 0\\ 1 & \text{if } d_{tx} = 1\\ \frac{1}{q} & \text{if } d_{tx} = 2 \end{cases}$$



Node2Vec

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Dirac₂ v

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```
Algorithm 1 The node2vec algorithm.
LearnFeatures (Graph G = (V, E, W), Dimensions d, Walks per
  node r, Walk length l, Context size k, Return p, In-out a)
  \pi = \text{PreprocessModifiedWeights}(G, p, q)
  G' = (V, E, \pi)
  Initialize walks to Empty
  for iter = 1 to r do
    for all nodes u \in V do
       walk = node2vecWalk(G', u, l)
       Append walk to walks
  f = StochasticGradientDescent(k, d, walks)
  return f
node2vecWalk (Graph G' = (V, E, \pi), Start node u, Length l)
  Inititalize walk to [u]
  for walk iter = 1 to l do
     curr = walk[-1]
     V_{curr} = \text{GetNeighbors}(curr, G')
     s = AliasSample(V_{ourr}, \pi)
     Append s to walk
  return walk
```

Corollary

$$\max_{f} \sum_{u \in V} \left[\sum_{n_i \in N_S(u)} f(n_i) \cdot f(u) - \log Z_u \right]$$



Struc2Vec

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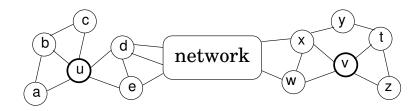


Figure 1: An example of two nodes (u and v) that are structurally similar (degrees 5 and 4, connected to 3 and 2 triangles, connected to the rest of the network by two nodes), but very far apart in the network.

Limitation

Structurally similar nodes will never share the same context if their distance (hop count) is larger than the Skip-Gram window.



Struc2Vec

Structural Similarity

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 $f_k(u, v) = f_{k-1}(u, v) + g(s(R_k(u)), s(R_k(v)))$ $k \ge 0 \text{ and } |R_k(u)|, |R_k(v)| > 0$ (6)

符号解释

 $f_k(u, v)$ structural distance when consider k-hop neighborhoods

 $R_k(u)$ the ring of nodes at distance k

s(S) the ordered degree sequence

g(a, b) DTW Function



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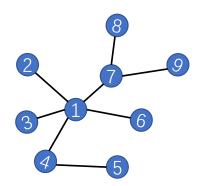
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Example

$$R_1(1) = \{2, 3, 4, 6, 7\}$$

$$R_2(1) = \{5, 8, 9\}$$

$$s(R_1(1)) = \{1, 1, 1, 2, 3\}$$

$$s(R_2(1)) = \{1, 1, 1\}$$



$\begin{array}{c} Struc2Vec \\ {\tt DTW} \end{array}$

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Dynamic Time Warping

利用动态规划的思想来计算两条不等长序列的相似度

动态转移方程如下:

$$\begin{split} g(i,j) &= \min\{g(i-1,j), g(i,j-1), g(i-1,j-1)\} + d(i,j) \\ \\ d(a,b) &= \frac{\max(a,b)}{\min(a,b)} - 1 \end{split}$$



LINE Overview

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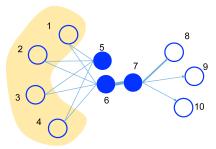


Figure 1: A toy example of information network. Edges can be undirected, directed, and/or weighted. Vertex 6 and 7 should be placed closely in the low-dimensional space as they are connected through a strong tie. Vertex 5 and 6 should also be placed closely as they share similar neighbors.



LINE First-Order Proximity

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The Joint Probability between v_i and v_i :

$$p_1(v_i, v_j) = \frac{1}{1 + \exp(-\vec{u}_i^T \cdot \vec{u}_j)}$$

Empirical Probability $\hat{p}_1(i,j) = \frac{w_{ij}}{W}$

$$O_1 = d(\hat{p}_1(\cdot, \cdot), p_1(\cdot, \cdot))$$

where $d(\cdot, \cdot)$ is the distance between two distributions.

Objective Function

min
$$O_1 = -\sum_{(i,j) \in E} w_{ij} \log p_1(v_i, v_j)$$



LINE Second-Order Proximity

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The Probability of Context v_i generated by vertex v_i as:

$$p_2\left(v_j \mid v_i\right) = \frac{\exp\left(\vec{u}_j^T \cdot \vec{u}_i\right)}{\sum_{k=1}^{|V|} \exp\left(\vec{u}_k'^T \cdot \vec{u}_i\right)}$$

Empirical Probability $\hat{p}_1(v_j \mid v_i) = \frac{w_{ij}}{d_i}$

Objective Function

$$O_2 = -\sum_{(i,j)\in E} w_{ij} \log p_2 \left(v_j \mid v_i\right)$$



LINE Optimization

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1. Negative Sample

$$\log \sigma \left(\vec{u}_{j}^{\prime T} \cdot \vec{u}_{i} \right) + \sum_{i=1}^{K} E_{v_{n} \sim P_{n}(v)} \left[\log \sigma \left(-\vec{u}_{n}^{T} \cdot \vec{u}_{i} \right) \right]$$

where $\sigma(x) = \frac{1}{1 + exp(-x)}$ is the sigmoid function.

2. Edge Sample - Alias Sample



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Unsupervised Component Unsupervised Component (Local structure preserved cost) (Local structure preserved cost) \hat{x}_i parameter sharing $\widehat{y}_{i}^{(1)}$ $\widehat{y}_{i}^{(1)}$ Supervised Component (Global structure preserved cost) Laplacian $y_i^{(K)}$ **Eigenmaps** $y_i^{(1)}$ parameter sharing x_i x_i Vertex i Vertex j



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Encoder and Decoder

$$\mathbf{y}_{i}^{(1)} = \sigma \left(W^{(1)} \mathbf{x}_{i} + \mathbf{b}^{(1)} \right)$$
$$\mathbf{y}_{i}^{(k)} = \sigma \left(W^{(k)} \mathbf{y}_{i}^{(k-1)} + \mathbf{b}^{(k)} \right), k = 2, \dots, K$$

First-Order Proximity Loss Function

$$\mathcal{L}_{1st} = \sum_{i,j=1}^{n} s_{i,j} \left\| \mathbf{y}_{i}^{(K)} - \mathbf{y}_{j}^{(K)} \right\|_{2}^{2}$$
$$= \sum_{i,j=1}^{n} s_{i,j} \left\| \mathbf{y}_{i} - \mathbf{y}_{j} \right\|_{2}^{2}$$



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The autoencoder goal is to minimize:

$$\mathcal{L} = \sum_{i=1}^{n} \left\| \hat{\mathbf{x}}_i - \mathbf{x}_i \right\|_2^2$$

Structural Similarity $x_i = s_i$

$$\mathcal{L}_{2nd} = \sum_{i=1}^{n} \|(\hat{\mathbf{x}}_i - \mathbf{x}_i) \odot \mathbf{b}_i\|_2^2$$
$$= \|(\hat{X} - X) \odot B\|_F^2$$



SDNE Objective Function

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正则化部分

$$\mathcal{L}_{reg} = \frac{1}{2} \sum_{k=1}^{K} \left(\left\| W^{(k)} \right\|_{F}^{2} + \left\| \hat{W}^{(k)} \right\|_{F}^{2} \right)$$

损失函数

$$\mathcal{L}_{mix} = \mathcal{L}_{2nd} + \alpha \mathcal{L}_{1st} + \nu \mathcal{L}_{reg}$$

$$= \|(\hat{X} - X) \odot B\|_F^2 + \alpha \sum_{i=1}^n s_{i,j} \|\mathbf{y}_i - \mathbf{y}_j\|_2^2 + \nu \mathcal{L}_{reg}$$