Résolution de niveaux du Sokoban

 $Poulpo Gaz,\ darth-mole$

16 mai 2023

Candidat n° 012345

Plan

Le jeu du Sokoban

Principe de résolution

Réduction de l'espace de recherche

Analyse statique

Analyse dynamique

Recherche dirigée par une heuristique

Optimisations

Résultats

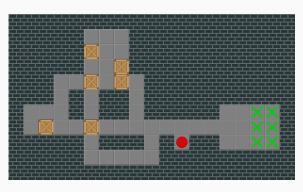
Annexe

Le jeu du Sokoban

Le jeu du Sokoban

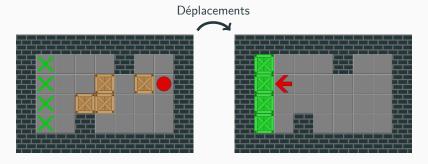


Hiroyuki Imabayashi

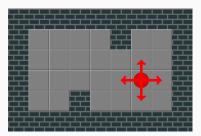


XSokoban

But du jeu

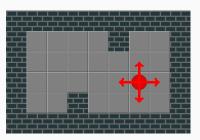


Règles

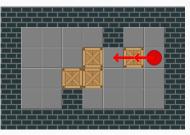


Déplacements autorisés

Règles

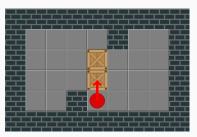


Déplacements autorisés





Règles

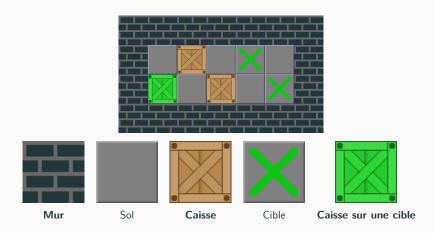








Tuiles



Problématique et réalisation

Quelles stratégies adopter pour trouver une solution le plus rapidement possible à un niveau de Sokoban?

```
Welcome to sokoshell - Version 1.0-SNAPSHOT
Type 'help' to show help. More help for a command with 'help command'
sokoshell>
```

Lien avec le thème de l'année

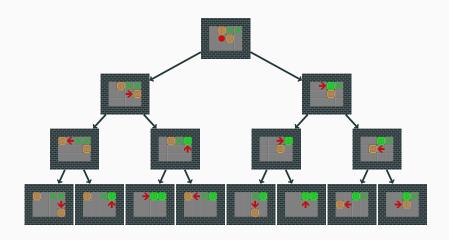


Lien avec le thème de l'année

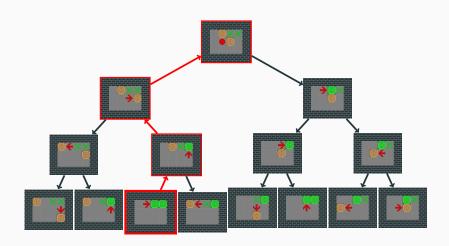


Principe de résolution

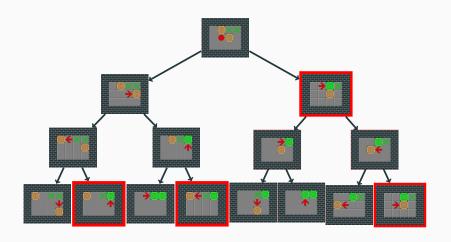
Arbre des états



Arbre des états



Arbre des états



Calcul du hash d'un état - Hash de Zobrist

Propriétés du XOR:

- 1. a XOR a = 0
- 2. XOR commutatif, associatif
- 3. XOR préserve l'aléatoire

Initialisation:

$$T = \begin{pmatrix} \text{caisse} & \text{joueur} & \text{case} \\ 6357 & 5742 \\ -1378 & 42 \\ \vdots & \vdots \\ 93268 & -278 \end{pmatrix} \quad 0 \\ 1 \\ \vdots \\ wh - 1$$

Calcul du hash d'un état - Hash de Zobrist

Usage :
$$(c_1, ..., c_n)$$
 n caisses et p position du joueur : $h = \underset{i=0}{\overset{n}{\mathsf{NOR}}} T[c_i][0] \, \mathsf{XOR} \, T[p][1]$

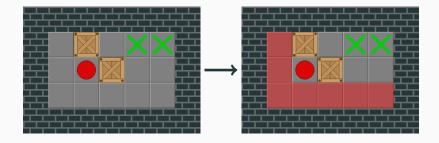
Calculer le hash d'un état à l'aide de son parent : $c_i \to c_i', p \to p'$ $h' = h \, XOR \, T[c_i][0] \, XOR \, T[c_i'][0] \, XOR \, T[p][1] \, XOR \, T[p'][1]$

Réduction de l'espace de recherche

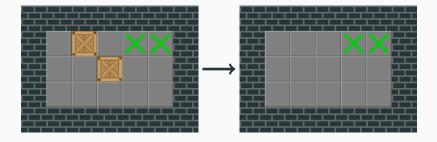
Analyse statique

Réduction de l'espace de recherche

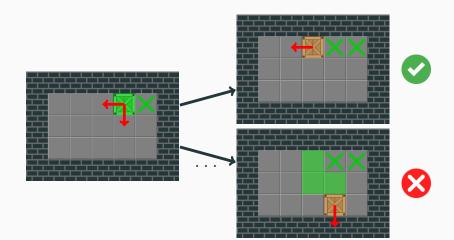
Détection des positions mortes (dead positions)

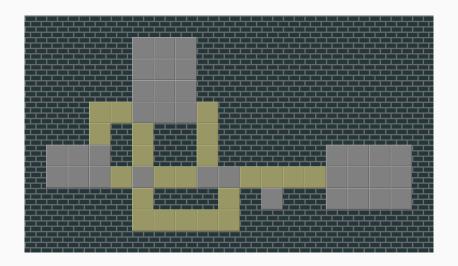


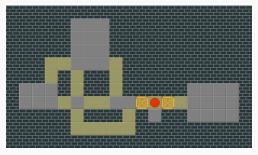
Détection des positions mortes (dead positions)

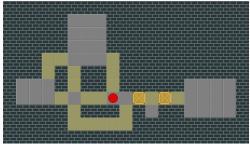


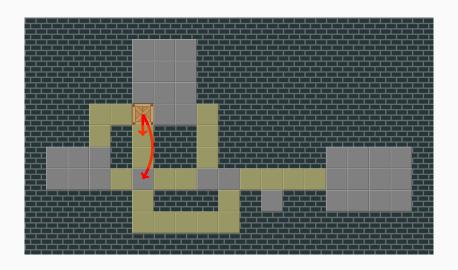
Détection des positions mortes (dead positions)

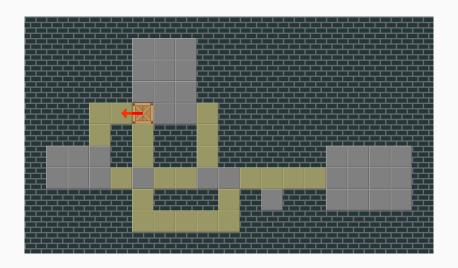


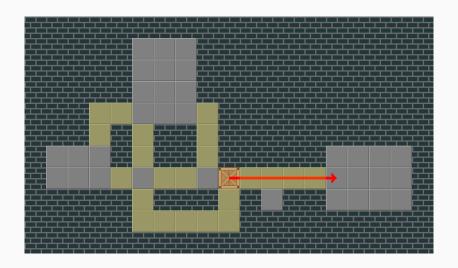




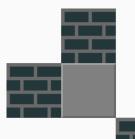


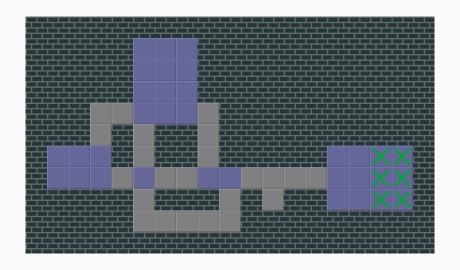


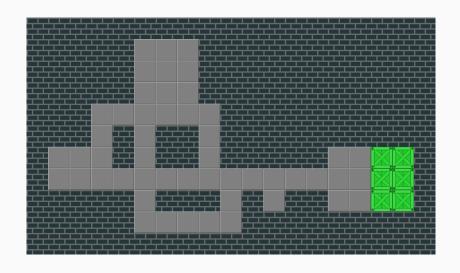


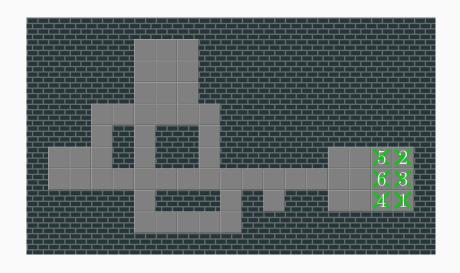


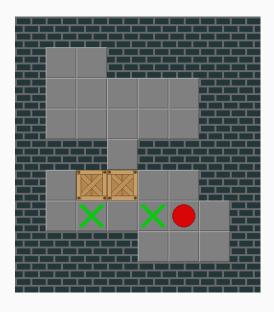








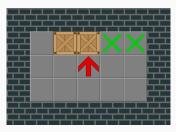


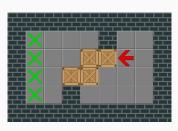


Réduction de l'espace de recherche

Analyse dynamique

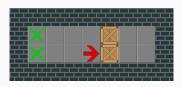
Détection d'impasses (deadlocks)





(a) Freeze deadlock n°1

(b) Freeze deadlock n°2



(c) PI Corral deadlock

Détection de freeze deadlocks



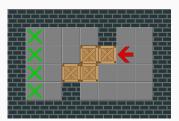
(a) Règle n°1

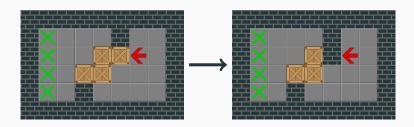


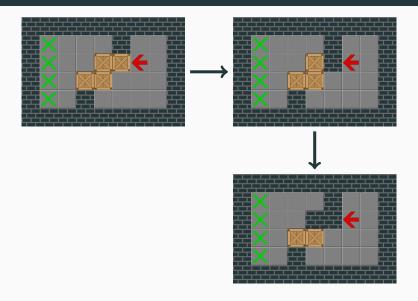
(b) Règle n°2

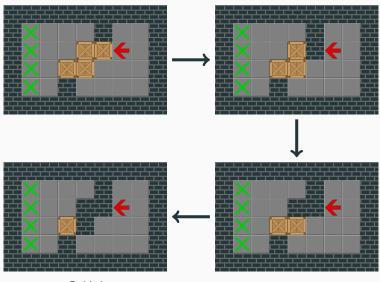


(c) Règle n°3



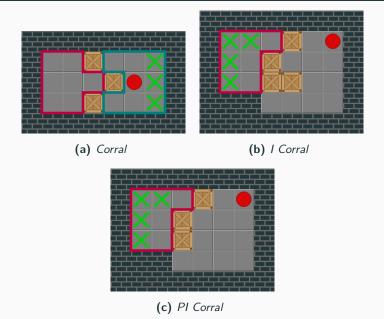




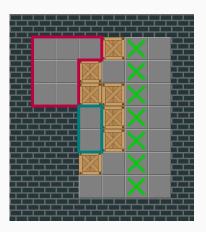


Gelée!

Détection de PI Corral deadlocks



Détection de PI Corral deadlocks



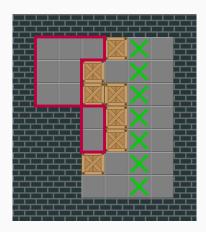


Table de deadlocks

	11	12	13	14		
	7	8	9	10		
=	4	5		6		
	1	2	1	3		
		++	++	++	44	111

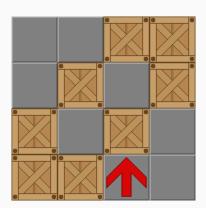
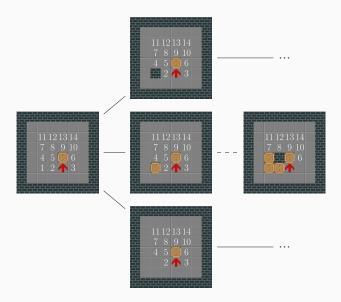


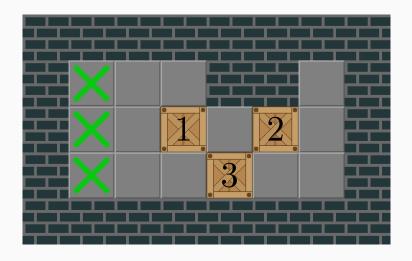
Table de deadlocks



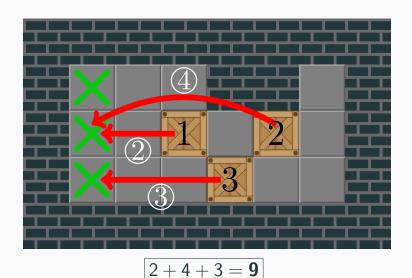
Recherche dirigée par une

heuristique

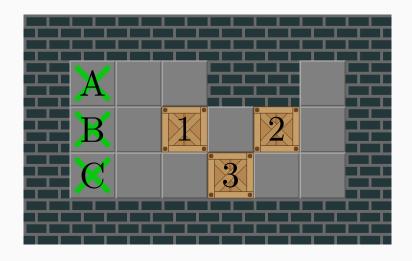
Heuristique simple (Simple Lower Bound)



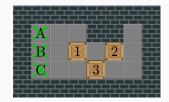
Heuristique simple (Simple Lower Bound)



Heuristique gloutonne (Greedy Lower Bound)



Heuristique gloutonne (Greedy Lower Bound)

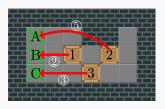


1 o A	3
1 o B	2
$1 \rightarrow C$	3
$2 \rightarrow A$	4
$2 \rightarrow B$	4
2 → <i>C</i>	5
$3 \rightarrow A$	5
3 → <i>B</i>	4
3 → <i>C</i>	3



$1 \to \mathbf{B}$	2
1 o A	3
1 o C	3
$3 o \mathbf{C}$	3
$2 \rightarrow B$	4
3 → <i>B</i>	4
$2 \rightarrow A$	5
2 → <i>C</i>	5
f 3 ightarrow f A	5

Heuristique gloutonne (Greedy Lower Bound)



$$2+3+5=10$$

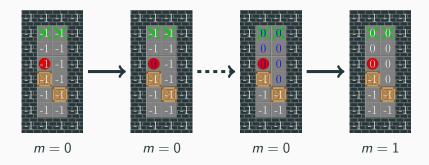
1 o A	3
1 o B	2
$1 \rightarrow C$	3
$2 \rightarrow A$	4
$2 \rightarrow B$	4
2 → <i>C</i>	5
$3 \rightarrow A$	5
3 → <i>B</i>	4
3 → <i>C</i>	3

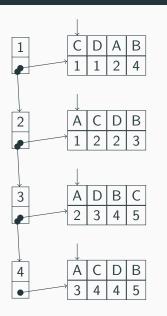


$1 \to \mathbf{B}$	2
1 o A	3
1 o C	3
$3 o \mathbf{C}$	3
$2 \rightarrow B$	4
$3 \rightarrow B$	4
$2 \rightarrow A$	5
2 → <i>C</i>	5
$3 o \mathbf{A}$	5

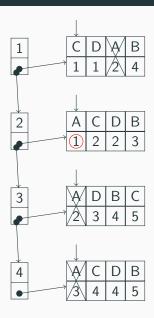
Optimisations

Parcours de graphes : démarquer tous les noeuds en $\mathcal{O}(1)$

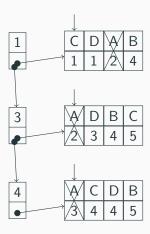




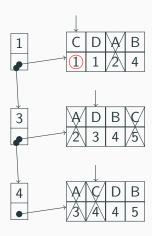
h =



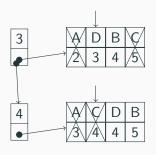
$$h = 1 +$$



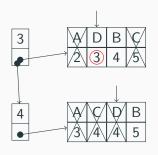
$$h = 1 +$$



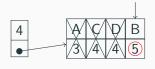
$$h = 1 + 1 +$$



$$h = 1 + 1 +$$



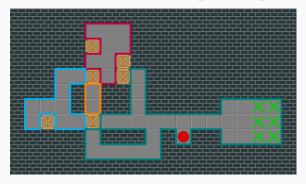
$$h = 1 + 1 + 3 +$$



$$h = 1 + 1 + 3 + 5 = 10$$

Calcul des *corrals* en O(wh)

Utilisation de *Union-Find* : partition de [0; wh - 1].



Calcul des *corrals* en O(wh)

```
1: procedure CORRAL(x, y)
        if not solid(x,y) then
 2:
           createSingleton(x, y)
 3:
 4:
        else
           if solid(x-1, y) and solid(x,y-1) then
 5:
               createSingleton(x, y)
 6:
           else if not solid(x-1, y) and solid(x,y-1) then
 7:
               addToCorral(x-1,y, x,y)
 8:
           else if solid(x-1, y) and not solid(x,y-1) then
 9:
               addToCorral(x,y-1, x,y)
10:
11:
           else
               addToCorral(x-1,y, x,y)
12:
               union(x,y-1, x,y)
13:
           end if
14:
                                                                      61/66
        end if
15:
```

Résultats

Nombre de niveaux résolus

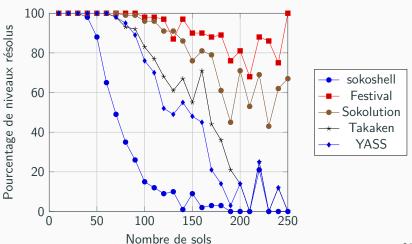
Limite de temps: 10 min. Limite de RAM: 32 Gb.

Ensemble de niveaux	XSokoban	Large test suite
Nombre de niveaux	90	3272
A*	11	2204
fess0	15	2273
Festival (Yaron Shoham)	90	3202
Sokolution (Florent Diedler)	90	3130
Takaken (Ken'ichiro Takahashi)	90	2944
YASS (Brian Damgaard)	89	2865

Statistiques

Temps moyen passé par niveaux

Solveur	A*	fess0	Festival	Sokolution	Takaken	YASS
Temps moyen	3min 28s	3min 16s	3s	2s	7s	24s



Annexe

Tableau des complexités