Résolution de niveaux du Sokoban

Nom, Prénom

16 mai 2023

Numéro de candidat

Plan

Le jeu du Sokoban

Principe de résolution

Réduction de l'espace de recherche

Analyse statique

Analyse dynamique

Recherche dirigée par une heuristique

Optimisations

Résultats

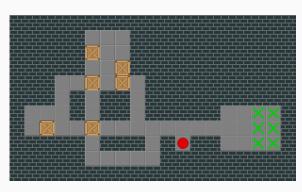
Annexe

Le jeu du Sokoban

Le jeu du Sokoban

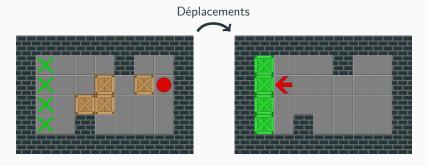


Hiroyuki Imabayashi

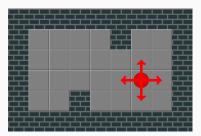


XSokoban

But du jeu

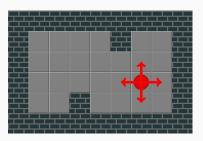


Règles

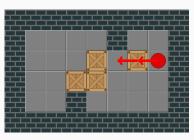


Déplacements autorisés

Règles

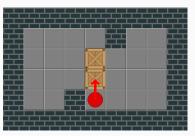


Déplacements autorisés

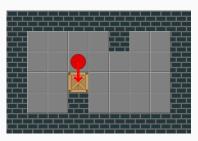




Règles

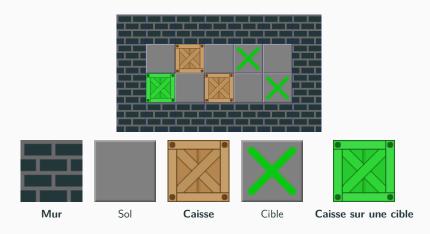








Tuiles



Problématique et réalisation

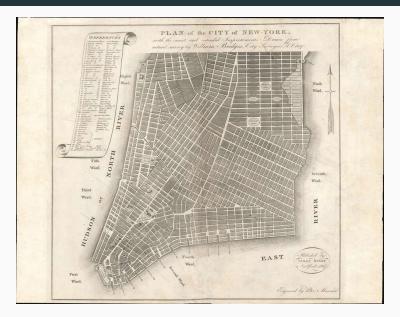
Quelles stratégies adopter pour trouver une solution le plus rapidement possible à un niveau de Sokoban?

```
Welcome to sokoshell - Version 1.0-SNAPSHOT
Type 'help' to show help. More help for a command with 'help command'
sokoshell>
```

Lien avec le thème de l'année

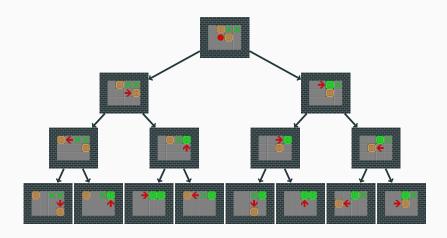


Lien avec le thème de l'année

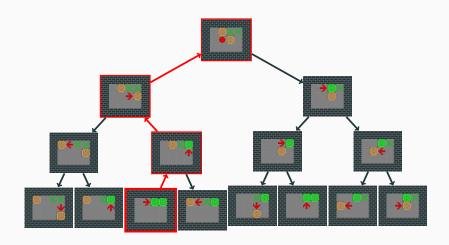


Principe de résolution

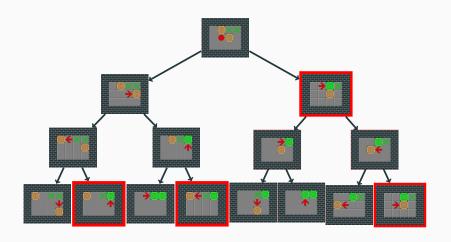
Arbre des états



Arbre des états



Arbre des états



Calcul du hash d'un état - Hash de Zobrist

Propriétés du XOR:

- 1. a XOR a = 0
- 2. XOR commutatif, associatif
- 3. XOR préserve l'aléatoire

Initialisation:

$$T = \begin{pmatrix} \text{caisse} & \text{joueur} & \text{case} \\ 6357 & 5742 \\ -1378 & 42 \\ \vdots & \vdots \\ 93268 & -278 \end{pmatrix} \quad \begin{matrix} 1 \\ \vdots \\ wh - 1 \end{matrix}$$

Calcul du hash d'un état - Hash de Zobrist

Usage :
$$(c_1, ..., c_n)$$
 n caisses et p position du joueur : $h = \underset{i=0}{\overset{n}{\mathsf{NOR}}} T[c_i][0] \, \mathsf{XOR} \, T[p][1]$

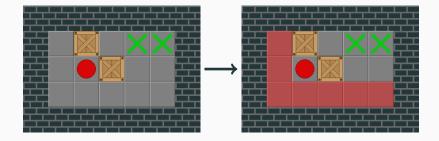
Calculer le hash d'un état à l'aide de son parent : $c_i \to c_i', p \to p'$ $h' = h \, \mathbf{XOR} \, T[c_i][0] \, \mathbf{XOR} \, T[c_i'][0] \, \mathbf{XOR} \, T[p][1] \, \mathbf{XOR} \, T[p'][1]$

Réduction de l'espace de recherche

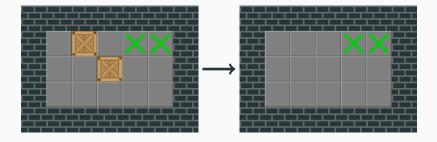
Réduction de l'espace de recherche

Analyse statique

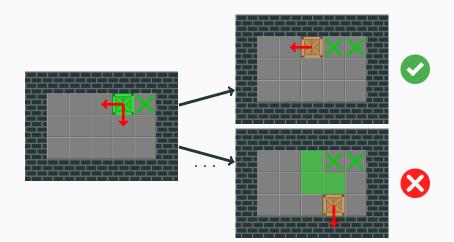
Détection des positions mortes (dead positions)

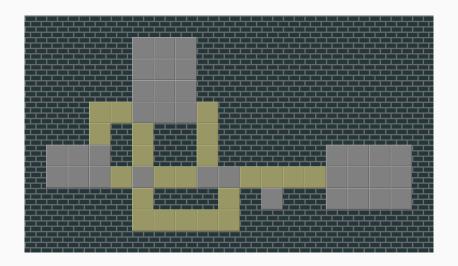


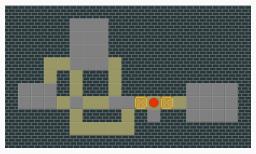
Détection des positions mortes (dead positions)

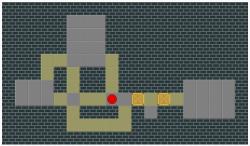


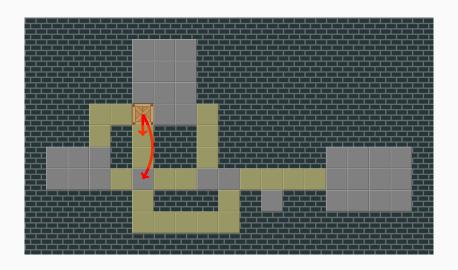
Détection des positions mortes (dead positions)

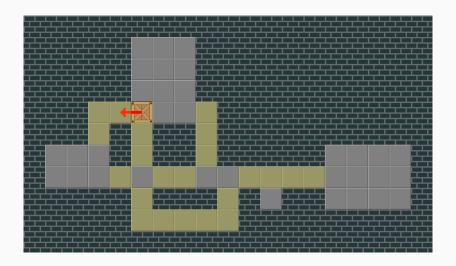


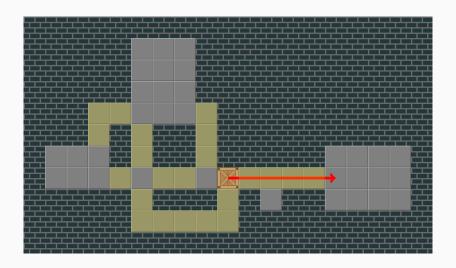




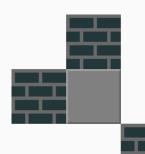


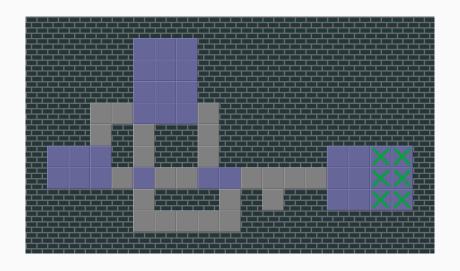


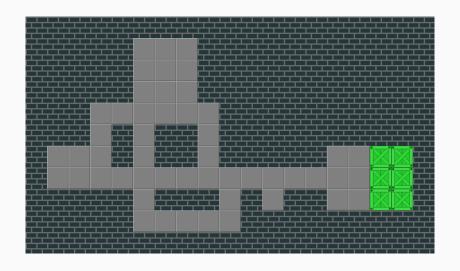


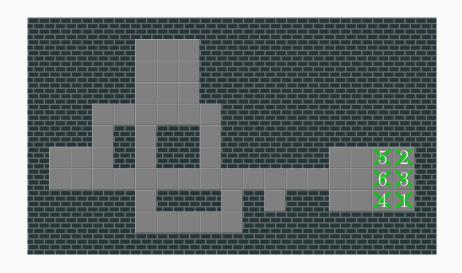


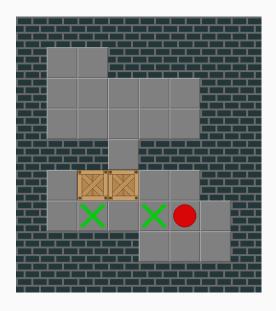








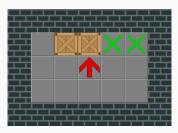


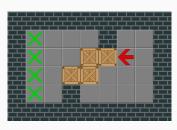


Réduction de l'espace de recherche

Analyse dynamique

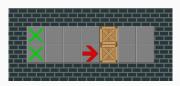
Détection d'impasses (deadlocks)





(a) Freeze deadlock n°1

(b) Freeze deadlock n°2



(c) PI Corral deadlock

Détection de freeze deadlocks



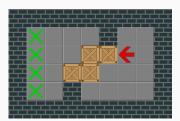
(a) Règle n°1

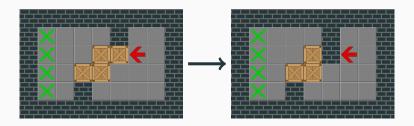


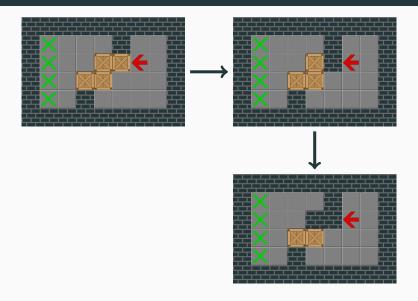
(b) Règle n°2

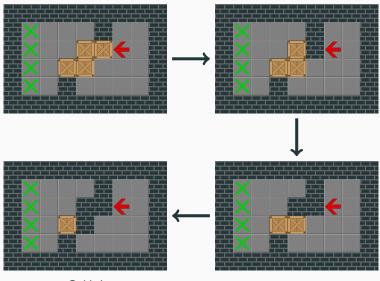


(c) Règle n°3



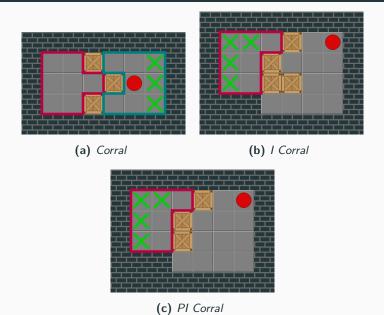




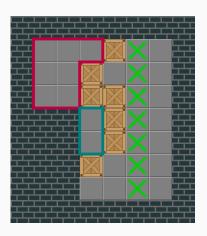


Gelée!

Détection de PI Corral deadlocks



Détection de PI Corral deadlocks



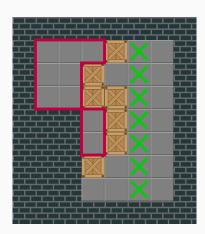


Table de deadlocks

11	12	13	14	
7	8	9	10	
4	5		6	
1	2	1	3	
				

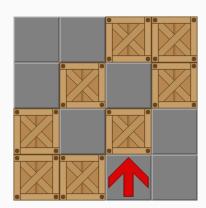
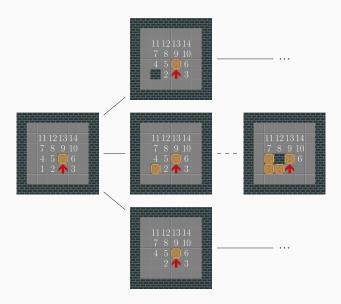


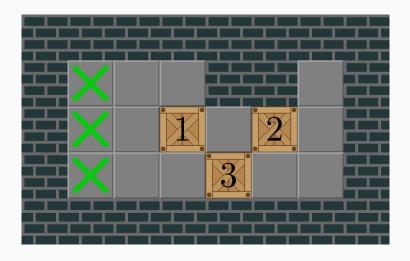
Table de deadlocks



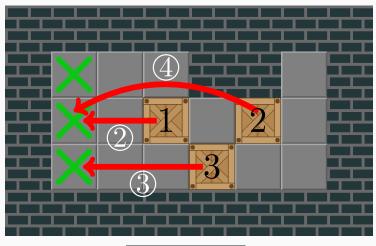
Recherche dirigée par une

heuristique

Heuristique simple (Simple Lower Bound)

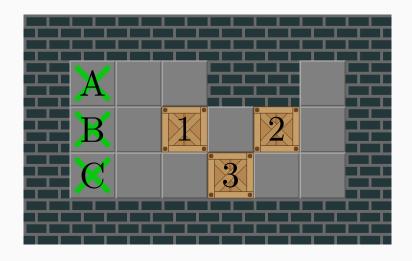


Heuristique simple (Simple Lower Bound)

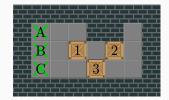


$$2+4+3=9$$

Heuristique gloutonne (Greedy Lower Bound)



Heuristique gloutonne (Greedy Lower Bound)

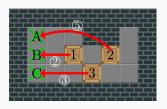


$1 \rightarrow A$	3
$1 \rightarrow B$	2
$1 \rightarrow C$	3
$2 \rightarrow A$	4
$2 \rightarrow B$	4
2 → <i>C</i>	5
$3 \rightarrow A$	5
$3 \rightarrow B$	4
3 → <i>C</i>	3



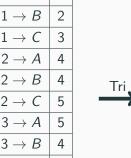
$1 \to \mathbf{B}$	2
1 o A	3
1 o C	3
$3 o \mathbf{C}$	3
$2 \rightarrow B$	4
$3 \rightarrow B$	4
$2 \rightarrow A$	5
2 → <i>C</i>	5
$3 o \mathbf{A}$	5

Heuristique gloutonne (Greedy Lower Bound)



$$2+3+5=10$$

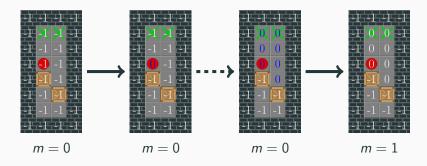
1 o A	3
1 o B	2
$1 \rightarrow C$	3
$2 \rightarrow A$	4
$2 \rightarrow B$	4
2 → <i>C</i>	5
$3 \rightarrow A$	5
$3 \rightarrow B$	4
3 → <i>C</i>	3

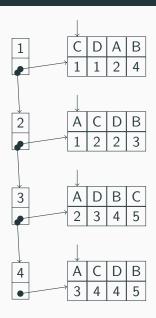


$1 \to \mathbf{B}$	2
1 o A	3
1 o C	3
$3 o \mathbf{C}$	3
$2 \rightarrow B$	4
3 → <i>B</i>	4
$2 \rightarrow A$	5
2 → <i>C</i>	5
f 3 ightarrow f A	5

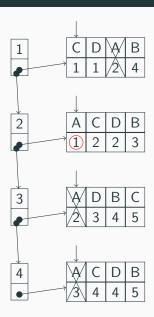
Optimisations

Parcours de graphes : démarquer tous les noeuds en $\mathcal{O}(1)$

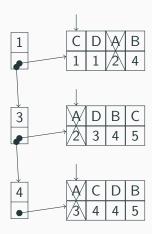




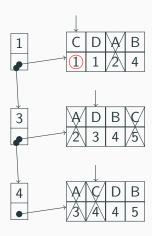
h =



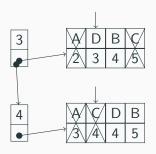
$$h = 1 +$$



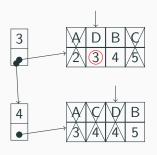
$$h = 1 +$$



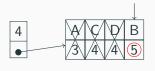
$$h = 1 + 1 +$$



$$h = 1 + 1 +$$



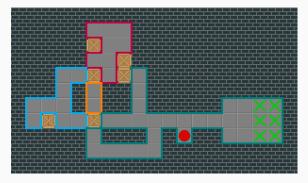
$$h = 1 + 1 + 3 +$$



$$h = 1 + 1 + 3 + 5 = 10$$

Calcul des *corrals* en O(wh)

Utilisation de *Union-Find* : partition de [0; wh - 1].



Calcul des *corrals* en $\mathcal{O}(wh)$

```
1: procedure CORRAL(x, y)
        if not solid(x,y) then
 2:
           createSingleton(x, y)
 3:
 4:
        else
           if solid(x-1, y) and solid(x,y-1) then
 5:
               createSingleton(x, y)
 6:
           else if not solid(x-1, y) and solid(x,y-1) then
 7:
               addToCorral(x-1,y, x,y)
 8:
           else if solid(x-1, y) and not solid(x,y-1) then
 9:
               addToCorral(x,y-1, x,y)
10:
11:
           else
               addToCorral(x-1,y, x,y)
12:
               union(x,y-1, x,y)
13:
           end if
14:
        end if
15:
```

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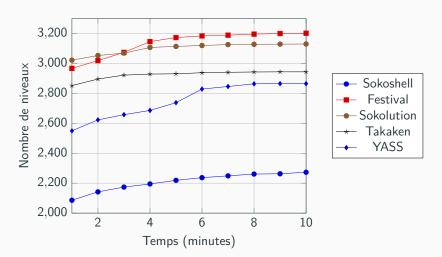
Résultats

Nombre de niveaux résolus

Collection	Nombre de niveaux	A*	fess0	Festival	Sokolution	Takaken	YASS
XSokoban	90	11	15	90	90	90	89
Large test suite	3272	2204	2273	3202	3130	2944	2865

Statistiques

Nombre de niveaux résolus (cumulés) en fonction du temps



Statistiques

Temps moyen passé par niveaux

Solveur	A*	fess0	Festival	Sokolution	Takaken	YASS
Temps moyen	3min 28s	3min 16s	3s	2s	7s	24s

Annexe

Tableau des complexités