

# MCAL User Manual for Iom

## 32-bit TriCore™ AURIX™ TC3xx microcontroller

### About this document

#### Scope and purpose

This User Manual is intended to enable users to integrate the Microcontroller Abstraction Layer (MCAL) software for the TriCore™ AURIX™ family of 32-bit microcontrollers.

This document describes responsibilities of integrator in-charge of integrating MCAL software with the basic software (BSW) stack. This document also provides detailed information on safety, configuration and functions along with examples of usage of significant features.

*Note: Detailed information about package installation, safety and other generic information that are common across all modules are provided in MCAL User Manual General.*

#### Intended audience

This document is intended for anyone using the Iom module of the TC3xx MCAL software.

#### Document conventions

**Table 1** Conventions

Convention	Explanation
<b>Bold</b>	Emphasizes heading levels, column headings, table and figure captions, screen names, windows, dialog boxes, menus, sub-menus
<i>Italics</i>	Denotes variable(s) and reference(s)
Courier	Denotes APIs, functions, interrupt handlers, events, data types, error handlers, file/folder names, directories, command line inputs, code snippets
New	
>	Indicates that a cascading sub-menu opens when you select a menu item
[cover parentID=<alpha numeric value>]	Used for traceability completeness. Reader should ignore these.

#### Reference documents

This User Manual should be read in conjunction with the following documents:

- AURIX™ TC3xx MCAL User Manual General

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## IOM driver

# 1 IOM driver

## 1.1 User information

### 1.1.1 Description

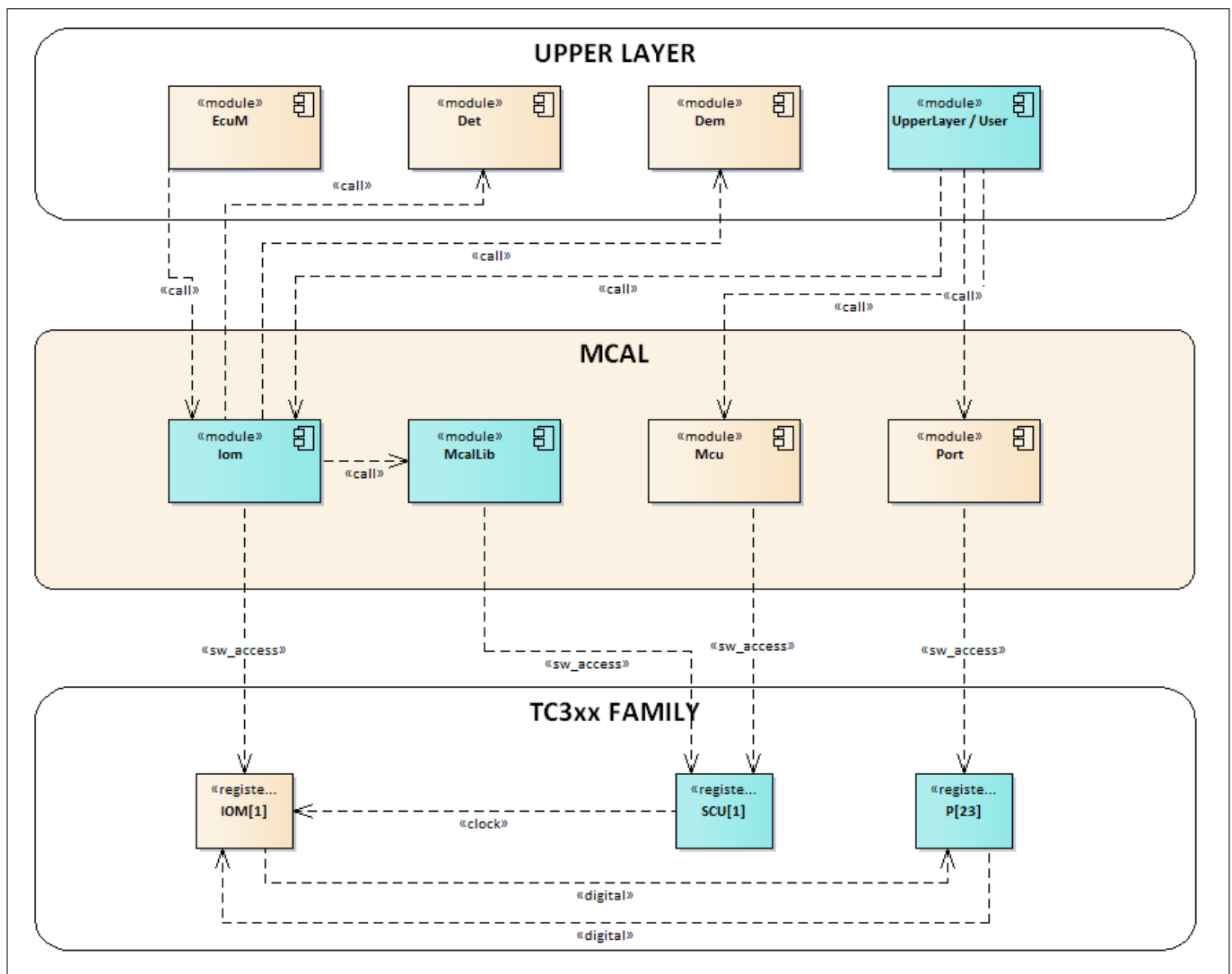
The Input-Output Monitor (IOM) driver serves as a comparison unit, checking the correct operation of the system peripherals output that may serve as input to the monitoring function. The monitoring function should be achieved by configuring the IOM hardware. It generates global system event to the SMU.

The IOM driver initializes and controls the IOM unit of the microcontroller. The driver also provides services for the user to initialize and set the threshold values for the internal units of the IOM. It should also provide services to reset the IOM kernel.

The service should be provided to combine individual or multiple local events in order to generate a single global system event. The IOM driver is heavily dependent on initialization and configurations.

### 1.1.2 Hardware-software mapping

This section describes the system view of the IOM driver and peripherals administered by it.



**Figure 1 Mapping of hardware-software interfaces**

---

**IOM driver****1.1.2.1 IOM: primary hardware peripheral****Hardware functional features**

The IOM driver is needed for the input output monitoring of signals.

**Users of the hardware**

The IOM driver exclusively utilizes the IOM IP for its functionality.

**Hardware diagnostic features**

Not applicable.

**Hardware events**

Not applicable.

**1.1.2.2 SCU: primary hardware peripheral**

The SCU is needed for the CLOCK for the registers, and ENDINIT functionality is used to update certain registers.

**Hardware functional features**

The IOM driver depends on the SCU for the clock, ENDINIT and reset functionalities.

**Users of the hardware**

The SCU module supplies the clock for all the peripherals and the MCU driver is responsible for configuring the clock tree. In order to avoid conflicts, update to the ENDINIT protected registers is performed using the MCALLIB.

**Hardware diagnostic features**

The SMU alarms configured for the SCU are not monitored by the IOM driver.

**Hardware events**

Hardware events from the SCU are not used by the IOM driver.

**1.1.2.3 Port: dependent hardware peripheral****Hardware functional features**

The PORT driver controls all access to the pins required by the IOM for input and output configuration.

**Users of the hardware**

The port pads are configured and used by the PORT and DIO drivers.

**Hardware diagnostic features**

Not applicable.

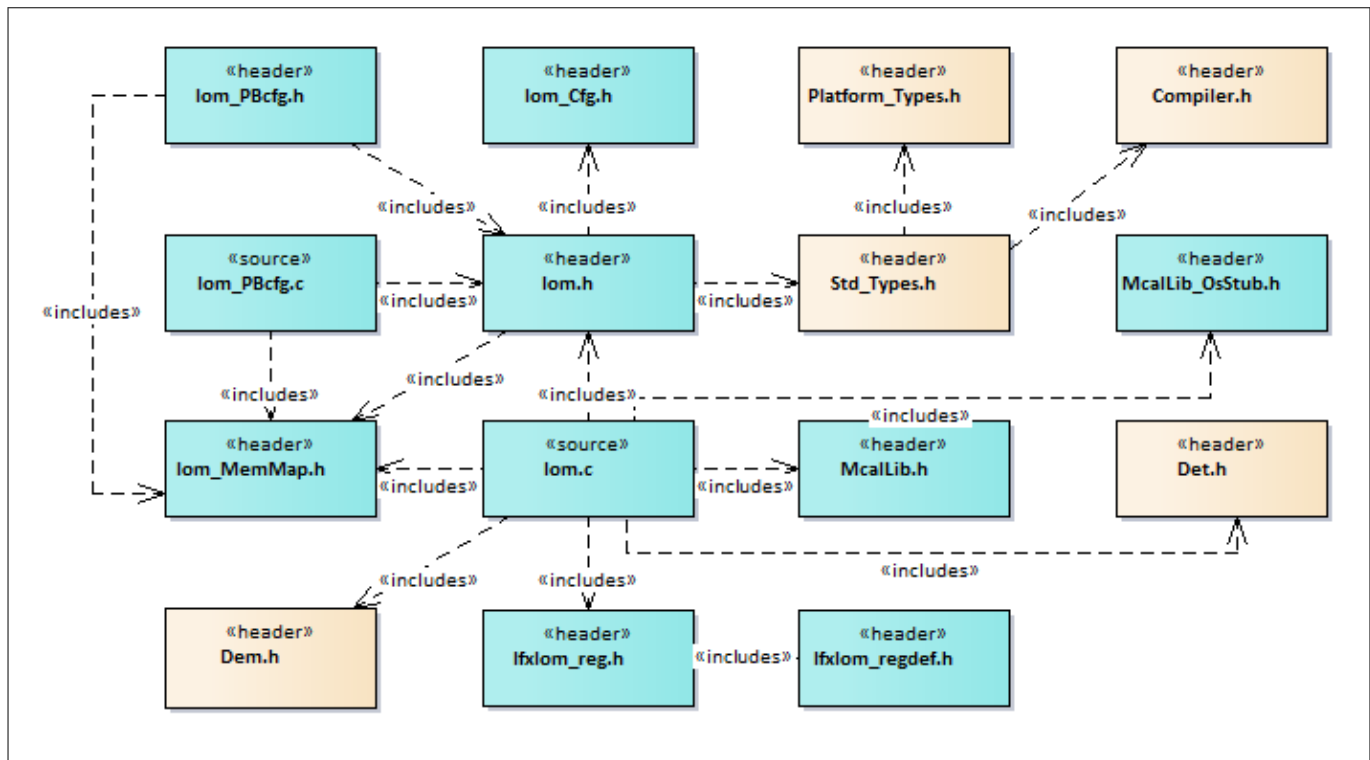
**Hardware events**

Not applicable.

**1.1.3 File structure****1.1.3.1 C file structure**

This section provides details of the C files of the IOM driver.

## IOM driver



**Figure 2** **lom\_C\_File\_Structure-1.png**

### Table 2 C file structure

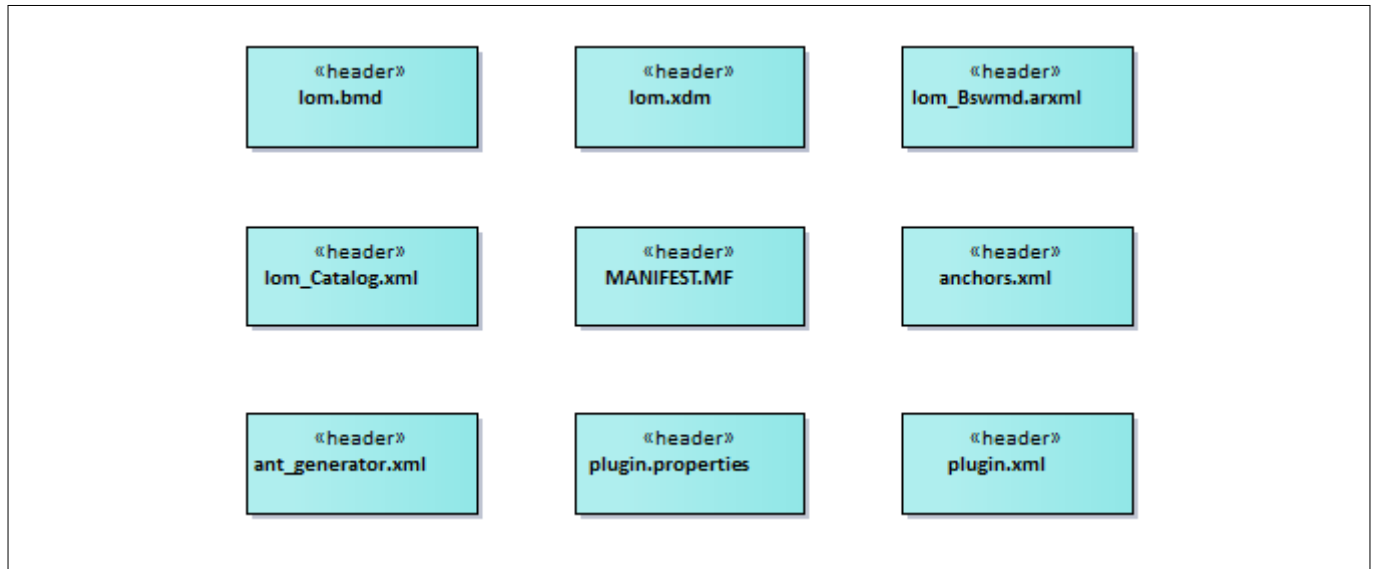
Filename	Description
Std_Types.h	Standard type declaration file as defined by AUTOSAR. It is independent of compiler or platform.
Compiler.h	Provides macros for the encapsulation of definitions and declarations
Platform_Types.h	Platform-specific type declaration file as defined by AUTOSAR
IfxIom_reg.h	SFR header file for the IOM
Det.h	Provides the exported interfaces of the DET
McalLib_OsStub.h	McalLib_OsStub.h provides macros to support user mode of the TriCore™.
Iom_MemMap.h	File (Static) containing the memory section definitions used by the IOM driver
Iom_Cfg.h	Header file (Generated) containing constants and pre-processor macros as #defines
Iom.c	File (Static) containing implementation of the APIs
Iom_PBCfg.h	File (Generated) containing declaration of the post-build configuration data structures
Iom_PBCfg.c	File (Generated) containing a definition of the configuration data structures
McalLib.h	The header file (Static) defining prototypes of data structures and APIs of end-init and delay services and included by McalLib.c



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### 1.1.3.2 Code generator plugin files

This section provides details of the code generator plugin files of the IOM driver.



**Figure 3** Iom\_Code\_Generator\_Plugin\_Files-1.png

**Table 3** Code generator plugin files

File name	Description
anchors.xml	Tresos anchors support file for the IOM driver
Iom.xdm	Iom.xdm Tresos format XML data model schema file
Iom.bmd	AUTOSAR format XML data model schema file (for each device)
Iom_Catalog.xml	AUTOSAR format catalog file
Iom_Bswmd.arxml	AUTOSAR format module description file
MANIFEST.MF	Tresos plugin support file containing the metadata for the IOM driver
plugin.xml	Tresos plugin support file for the IOM driver
plugin.properties	Tresos plugin support file for the IOM driver
ant_generator.xml	Tresos support file to generate and rename multiple post-build configurations when using the variation point

### 1.1.4 Integration hints

This section lists the key points that an integrator or user of the IOM driver must consider.

#### 1.1.4.1 Integration with AUTOSAR Stack

This section lists the modules, which are not part of MCAL, but are required to integrate the IOM driver.

- ECuM**

The ECU Manager module is a part of the AUTOSAR stack that manages common aspects of ECU. Specifically, in the context of MCAL, EcuM is used for initialization and de-initialization of the software

## IOM driver

drivers. The EcuM module provided in the MCAL package is a stub code and needs to be replaced with a complete EcuM module during the integration phase.

- **Memory Mapping**

Memory mapping is a concept from AUTOSAR that allows relocation of text, variables, constants and configuration data to user-specific memory regions. To achieve this, all the relocatable elements of the driver are encapsulated in different memory-section macros. These macros are defined in the `Iom_MemMap.h` file. The `Iom_MemMap.h` file is provided in the MCAL package as a stub code. The integrator must place appropriate compiler pragmas within the memory-section macros. The pragmas ensure that the elements are relocated to the correct memory region. A sample implementation listing the memory-section macros is shown as follows.

```
#if defined IOM_START_SEC_VAR_CLEARED_QM_LOCAL_32
    #ifdef _TASKING_C_TRICORE_
        /*****User pragmas here*****/
    #undef IOM_START_SEC_VAR_CLEARED_QM_LOCAL_32
    #undef MEMMAP_ERROR
    #elif defined IOM_STOP_SEC_VAR_CLEARED_QM_LOCAL_32
    #ifdef _TASKING_C_TRICORE_
        /*****User pragmas here*****/
    #undef IOM_STOP_SEC_VAR_CLEARED_QM_LOCAL_32
    #undef MEMMAP_ERROR

    /***** CONFIG DATA *****/
    #elif defined IOM_START_SEC_CONFIG_DATA_QM_LOCAL_UNSPECIFIED
    #ifdef _TASKING_C_TRICORE_
        /*****User pragmas here*****/
    #undef IOM_START_SEC_CONFIG_DATA_QM_LOCAL_UNSPECIFIED
    #undef MEMMAP_ERROR
    #elif defined IOM_STOP_SEC_CONFIG_DATA_QM_LOCAL_UNSPECIFIED
    #ifdef _TASKING_C_TRICORE_
        /*****User pragmas here*****/
    #undef IOM_STOP_SEC_CONFIG_DATA_QM_LOCAL_UNSPECIFIED
    #undef MEMMAP_ERROR

    /***** CODE *****/
    #elif defined IOM_START_SEC_CODE_QM_LOCAL
    #ifdef _TASKING_C_TRICORE_
        /*****User pragmas here*****/
    #undef IOM_START_SEC_CODE_QM_LOCAL
    #undef MEMMAP_ERROR
    #elif defined IOM_STOP_SEC_CODE_QM_LOCAL
    #ifdef _TASKING_C_TRICORE_
        /*****User pragmas here*****/
    #undef IOM_STOP_SEC_CODE_QM_LOCAL
    #undef MEMMAP_ERROR

    #endif

    #if defined MEMMAP_ERROR
    #error "Iom_MemMap.h, wrong pragma command"
    #endif
```

---

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- **DET**

The DET module is a part of the AUTOSAR stack that handles all the development and runtime errors reported by the BSW modules. The IOM driver reports all the development errors to the DET module through the `Det_ReportError()` API. The user of the IOM driver must process all the errors reported to the DET module through the `Det_ReportError()` API. The `Det.h` and `Det.c` files are provided in the MCAL package as a stub code and need to be replaced with a complete DET module during the integration phase.

- **DEM**

The IOM driver reports all the production errors through the interfaces provided by the DEM module. The user of the IOM driver shall process all the production errors (fail/pass) reported to the DEM module. The interface used for reporting in AUTOSAR version 4.2.2 is `Dem_ReportErrorStatus()` and for AUTOSAR version 4.4.0 is `Dem_SetEventStatus()`. The `Dem.h` and `Dem.c` files are provided in the MCAL package as a stub code and needs to be replaced with a complete DEM module during the integration phase.

- **SchM**

The SchM is not required for the integration of the IOM driver.

- **Safety error**

The IOM library does not report any safety errors.

- **Notification and callbacks**

The IOM driver does not provide any callbacks or notifications.

- **Operating system**

The IOM driver does not program any Service Request(SR). The OS or the application must ensure the correct type of service and interrupt priority is configured in the SR register. Enabling and disabling of interrupts must also be managed by the OS or the application.

### **1.1.4.2 Multicore and Resource Manager**

The IOM driver does not support execution on multiple cores in parallel.

### **1.1.4.3 MCU support**

The system clock is set up through the MCU driver. The MCU initialization should be performed before using the IOM APIs to ensure the clock supply to the IOM hardware.

### **1.1.4.4 Port support**

The PORT driver configures the port pins of the entire microcontroller. The user must configure the port pins used by the IOM driver through the PORT configuration and initialize the port pins prior to invoking the IOM initialization.

### **1.1.4.5 DMA support**

The IOM driver does not use any services provided by the DMA driver.

### **1.1.4.6 Interrupt connections**

The IOM driver does not use any interrupt source.

### **1.1.4.7 Example usage**

This section explains one of the example usage of the IOM driver for a nominal case.

---

## IOM driver

### Configuration of the driver

The IOM driver is configured before usage and the configuration files are generated and made available during the software build process.

### Initialization of the driver

The code sequence for initializing the IOM driver is as follows:

```
#include "Iom.h"
#include "Mcu.h"
#include "Port.h"

extern const Iom_ConfigType Iom_Config;

/* MCU Initialization */
Mcu_Init(&Mcu_Config);
Mcu_InitClock( 0 );
while(Mcu_GetPllStatus() != MCU_PLL_LOCKED);
Mcu_DistributePllClock();

/* Port Initialization */
Port_Init(&Port_Config);

/* Iom Initialization */
Iom_Init(&Iom_Config);

/* Further APIs of IOM driver can be called now */
```

The following code snippet shows call to `Iom_ClrResetStatus()` and `Iom_ResetKernel()` APIs.

```
/* To Reset the Kernel */
Iom_ResetKernel();

/* To Clear the Reset status */
Iom_ClrResetStatus();
```

The following code is used to set values using for the `Iom_SetLamThreshold()` and `Iom_Iom_SetLamConfig()` APIs.

```
/* To set the Threshold value for Lam */
Iom_SetLamThreshold(LamNo,ThresholdValue);

/*To update the configuration of Lam unit */
Iom_SetLamConfig(LamNo,ConfigurationValue);
```

---

**IOM driver**

The following code is used to read values from the Iom\_GetResetStatus(), Iom\_GetLamThreshold() and Iom\_GetEcmThresVal() APIs.

```
/* To read threshold value of the counter in Ecm */
ThresVal = Iom_GetEcmThresVal(CounterNo)
/* CounterNo = Counter number in ECM */

/* To read the Lam threshold value */
status32 = Iom_GetLamThreshold(LamNo);
/* LamNo = LAM unit number */

/* read the kernel reset status bit */
status8 = Iom_GetResetStatus();
```

**Deinitialization of the driver**

The following code is used to de-initialize IOM the driver.

```
/* Iom De-Initialization */
Iom_DeInit();
```

**1.1.5 Key architectural considerations**

There are no key architectural considerations for IOM driver.

**1.2 Assumptions of Use (AoU)**

There are no AoU for IOM driver.

**1.3 Reference information****1.3.1 Configuration interfaces**

The following diagram depicts the hierarchy along with their configuration parameters.

## IOM driver

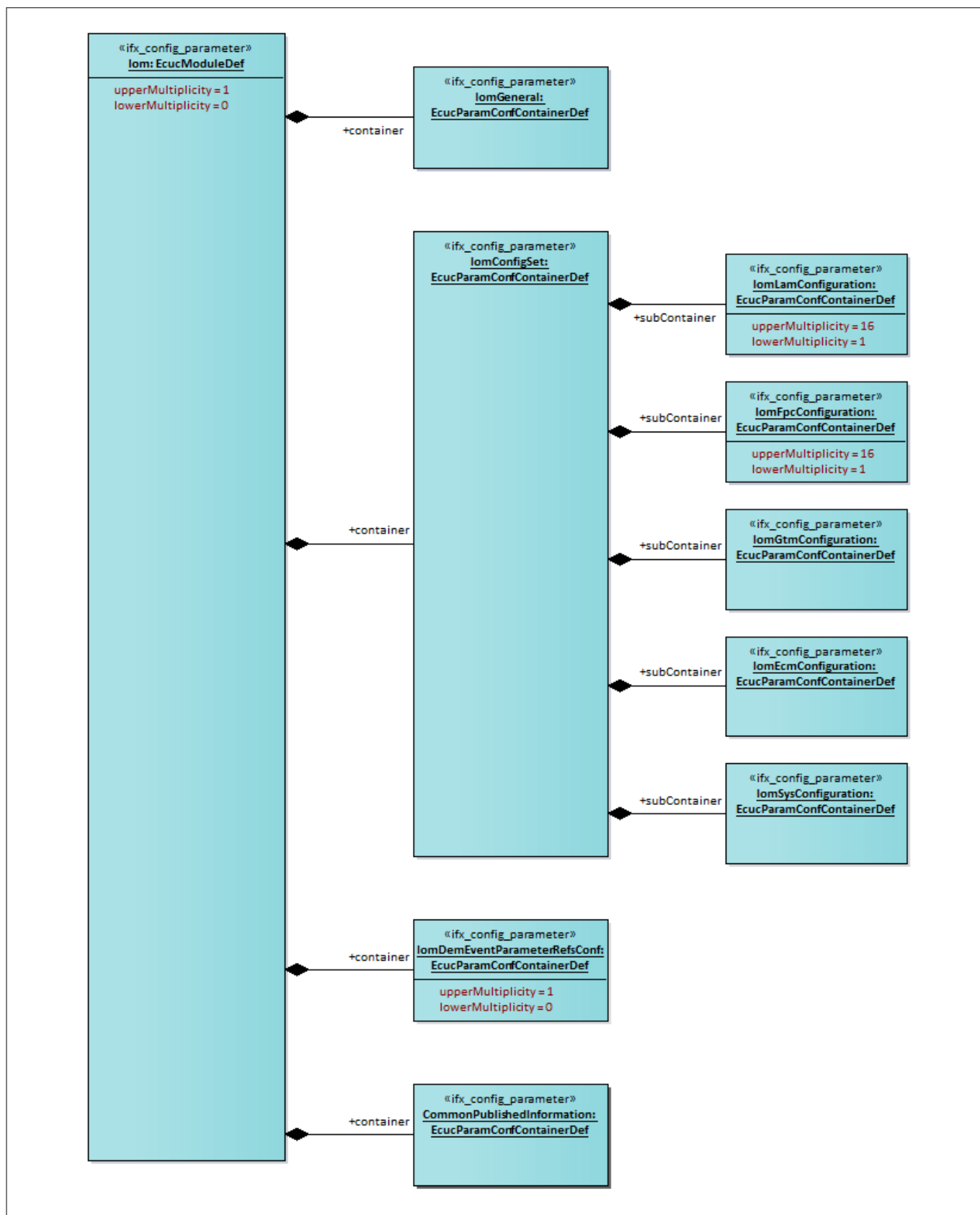


Figure 4 Configuration container relationship

## IOM driver

### 1.3.1.1 Container: CommonPublishedInformation

Multiplicity Configuration Class: -

#### 1.3.1.1.1 ArMajorVersion

**Table 4** Specification for ArMajorVersion

<b>Name</b>	ArMajorVersion		
<b>Description</b>	This parameter provides the major version of the AUTOSAR specification.		
<b>Multiplicity</b>	1..1	<b>Type</b>	EcucIntegerParamDef
<b>Range</b>	0 - 255		
<b>Default value</b>	4		
<b>Post-build variant value</b>	FALSE	<b>Post-build variant multiplicity</b>	-
<b>Value configuration class</b>	Published-Information	<b>Multiplicity configuration class</b>	-
<b>Origin</b>	IFX	<b>Scope</b>	LOCAL
<b>Dependency</b>	-		
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0		

#### 1.3.1.1.2 ArMinorVersion

**Table 5** Specification for ArMinorVersion

<b>Name</b>	ArMinorVersion		
<b>Description</b>	This parameter provides the minor version of the AUTOSAR specification.		
<b>Multiplicity</b>	1..1	<b>Type</b>	EcucIntegerParamDef
<b>Range</b>	0 - 255		
<b>Default value</b>	As per the selected Autosar version		
<b>Post-build variant value</b>	FALSE	<b>Post-build variant multiplicity</b>	-
<b>Value configuration class</b>	Published-Information	<b>Multiplicity configuration class</b>	-
<b>Origin</b>	IFX	<b>Scope</b>	LOCAL
<b>Dependency</b>	-		
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0		

#### 1.3.1.1.3 ArPatchVersion

**Table 6** Specification for ArPatchVersion

<b>Name</b>	ArPatchVersion		
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**IOM driver**
**Table 6 Specification for ArPatchVersion (continued)**

<b>Description</b>	This parameter provides the patch version of the AUTOSAR specification.		
<b>Multiplicity</b>	1..1	<b>Type</b>	EcucIntegerParamDef
<b>Range</b>	0 - 255		
<b>Default value</b>	As per the selected Autosar version		
<b>Post-build variant value</b>	FALSE	<b>Post-build variant multiplicity</b>	-
<b>Value configuration class</b>	Published-Information	<b>Multiplicity configuration class</b>	-
<b>Origin</b>	IFX	<b>Scope</b>	LOCAL
<b>Dependency</b>	-		
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0		

**1.3.1.1.4 ModuleId**
**Table 7 Specification for ModuleId**

<b>Name</b>	ModuleId		
<b>Description</b>	This parameter provides the module ID of IOM.		
<b>Multiplicity</b>	1..1	<b>Type</b>	EcucIntegerParamDef
<b>Range</b>	0 - 65535		
<b>Default value</b>	255		
<b>Post-build variant value</b>	FALSE	<b>Post-build variant multiplicity</b>	-
<b>Value configuration class</b>	Published-Information	<b>Multiplicity configuration class</b>	-
<b>Origin</b>	IFX	<b>Scope</b>	LOCAL
<b>Dependency</b>	-		
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0		

**1.3.1.1.5 Release**
**Table 8 Specification for Release**

<b>Name</b>	Release		
<b>Description</b>	This parameter indicates the TC3xx device derivative used for the implementation.		
<b>Multiplicity</b>	1..1	<b>Type</b>	EcucStringParamDef
<b>Range</b>	String		
<b>Default value</b>	As per hardware derivative		



**IOM driver**
**Table 8 Specification for Release (continued)**

<b>Post-build variant value</b>	FALSE	<b>Post-build variant multiplicity</b>	-
<b>Value configuration class</b>	Published-Information	<b>Multiplicity configuration class</b>	-
<b>Origin</b>	IFX	<b>Scope</b>	LOCAL
<b>Dependency</b>	-		
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0		

**1.3.1.1.6 SwMajorVersion**
**Table 9 Specification for SwMajorVersion**

<b>Name</b>	SwMajorVersion		
<b>Description</b>	This parameter provides the major version of the software.		
<b>Multiplicity</b>	1..1	<b>Type</b>	EcucIntegerParamDef
<b>Range</b>	0-255		
<b>Default value</b>	As per Driver version		
<b>Post-build variant value</b>	FALSE	<b>Post-build variant multiplicity</b>	-
<b>Value configuration class</b>	Published-Information	<b>Multiplicity configuration class</b>	-
<b>Origin</b>	IFX	<b>Scope</b>	LOCAL
<b>Dependency</b>	-		
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0		

**1.3.1.1.7 SwMinorVersion**
**Table 10 Specification for SwMajorVersion**

<b>Name</b>	SwMinorVersion		
<b>Description</b>	This parameter provides the minor version of the software.		
<b>Multiplicity</b>	1..1	<b>Type</b>	EcucIntegerParamDef
<b>Range</b>	0-255		
<b>Default value</b>	As per Driver version		
<b>Post-build variant value</b>	FALSE	<b>Post-build variant multiplicity</b>	-
<b>Value configuration class</b>	Published-Information	<b>Multiplicity configuration class</b>	-
<b>Origin</b>	IFX	<b>Scope</b>	LOCAL

**IOM driver**
**Table 10 Specification for SwMajorVersion (continued)**

<b>Dependency</b>	-
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0

**1.3.1.1.8 SwPatchVersion**
**Table 11 Specification for SwMajorVersion**

<b>Name</b>	SwPatchVersion		
<b>Description</b>	This parameter provides the patch version of the software.		
<b>Multiplicity</b>	1..1	<b>Type</b>	EcucIntegerParamDef
<b>Range</b>	0-255		
<b>Default value</b>	As per Driver version		
<b>Post-build variant value</b>	FALSE	<b>Post-build variant multiplicity</b>	-
<b>Value configuration class</b>	Published-Information	<b>Multiplicity configuration class</b>	-
<b>Origin</b>	IFX	<b>Scope</b>	LOCAL
<b>Dependency</b>	-		
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0		

**1.3.1.1.9 VendorId**
**Table 12 Specification for VendorId**

<b>Name</b>	VendorId		
<b>Description</b>	This parameter provides the vendor ID.		
<b>Multiplicity</b>	1..1	<b>Type</b>	EcucIntegerParamDef
<b>Range</b>	0 - 65535		
<b>Default value</b>	17		
<b>Post-build variant value</b>	FALSE	<b>Post-build variant multiplicity</b>	-
<b>Value configuration class</b>	Published-Information	<b>Multiplicity configuration class</b>	-
<b>Origin</b>	IFX	<b>Scope</b>	LOCAL
<b>Dependency</b>	-		
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0		

**1.3.1.2 Container: IomGtmConfiguration**

This container holds the Lam Configuration.

**IOM driver**

Multiplicity Configuration Class: -

**1.3.1.2.1 IomGtmInputx**
**Table 13 Specification for IomGtmInputx**

<b>Name</b>	IomGtmInputx		
<b>Description</b>	Disables/Enables the GTM input signal x to be included in EXOR combiner. x varies from 0 to 7. IOM_DISABLE_GTM_INPUT – disables the selected GTM input signal. IOM_ENABLE_GTM_INPUT – enables the selected GTM input signal.		
<b>Multiplicity</b>	1..1	<b>Type</b>	EcucEnumerationParamDef
<b>Range</b>	IOM_DISABLE_GTM_INPUT IOM_ENABLE_GTM_INPUT		
<b>Default value</b>	IOM_DISABLE_GTM_INPUT		
<b>Post-build variant value</b>	TRUE	<b>Post-build variant multiplicity</b>	-
<b>Value configuration class</b>	Post-Build	<b>Multiplicity configuration class</b>	-
<b>Origin</b>	IFX	<b>Scope</b>	LOCAL
<b>Dependency</b>	-		
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0		

**1.3.1.3 Container: IomEcmConfiguration**

This container holds the ECM Configuration.

Multiplicity Configuration Class: -

**1.3.1.3.1 IomEcmThresholdx**
**Table 14 Specification for IomEcmThresholdx**

<b>Name</b>	IomEcmThresholdx		
<b>Description</b>	Indicates threshold count value for the counter x (varies from 0 to 3) of the ECM module. Upon counter meet this value, the counter event output becomes high for one clock cycle. If the count is set to zero, the counter is disabled		
<b>Multiplicity</b>	1..1	<b>Type</b>	EcucIntegerParamDef
<b>Range</b>	0 to 15		
<b>Default value</b>	0		
<b>Post-build variant value</b>	TRUE	<b>Post-build variant multiplicity</b>	-
<b>Value configuration class</b>	Post-Build	<b>Multiplicity configuration class</b>	-

**IOM driver**
**Table 14 Specification for IomEcmThresholdx (continued)**

<b>Origin</b>	IFX	<b>Scope</b>	LOCAL
<b>Dependency</b>	-		
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0		

**1.3.1.3.2 IomEcmEventSelx**
**Table 15 Specification for IomEcmEventSelx**

<b>Name</b>	IomEcmEventSelx		
<b>Description</b>	Determines which LAM channel event output is routed to counter x(varies from 0 to 3) of ECM module.		
<b>Multiplicity</b>	1..1	<b>Type</b>	EcucIntegerParamDef
<b>Range</b>	0 to 15		
<b>Default value</b>	0		
<b>Post-build variant value</b>	TRUE	<b>Post-build variant multiplicity</b>	-
<b>Value configuration class</b>	Post-Build	<b>Multiplicity configuration class</b>	-
<b>Origin</b>	IFX	<b>Scope</b>	LOCAL
<b>Dependency</b>	-		
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0		

**1.3.1.4 Container: IomEventCombModGlobalSel**

This container holds the ECM Configuration.

Multiplicity Configuration Class: -

**1.3.1.4.1 IomEcmEventCombSelx**
**Table 16 Specification for IomEcmEventCombSelx**

<b>Name</b>	IomEcmEventCombSelx x varies from 0 to 15		
<b>Description</b>	Add/Remove LAMx (x varies from 0 to 15) output event in global event generation. IOM_DISABLE_CHANNEL_EVENT- disables LAM output event in global event generation. IOM_ENABLE_CHANNEL_EVENT - enables LAM output event in global event generation.		
<b>Multiplicity</b>	1..1	<b>Type</b>	EcucEnumerationParamDef
<b>Range</b>	IOM_DISABLE_CHANNEL_EVENT IOM_ENABLE_CHANNEL_EVENT		

**IOM driver**
**Table 16 Specification for IomEcmEventCombSelx (continued)**

Default value	IOM_DISABLE_CHANNEL_EVENT		
Post-build variant value	TRUE	Post-build variant multiplicity	-
Value configuration class	Post-Build	Multiplicity configuration class	-
Origin	IFX	Scope	LOCAL
Dependency			
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0		

**1.3.1.4.2 IomEcmAccEventCombSelx**
**Table 17 Specification for IomEcmAccEventCombSelx**

Name	IomEcmAccEventCombSelx x varies from 0 to 3		
Description	Add/Remove counter x output event in global event generation. IOM_DISABLE_COUNT_EVENT- disables counter x output event in global event generation. IOM_ENABLE_COUNT_EVENT - enables counter x output event in global event generation.  <i>Note: x varies from 0 to 3.</i>		
Multiplicity	1..1	Type	EcucEnumerationParamDef
Range	IOM_DISABLE_COUNT_EVENT IOM_ENABLE_COUNT_EVENT		
Default value	IOM_DISABLE_COUNT_EVENT		
Post-build variant value	TRUE	Post-build variant multiplicity	-
Value configuration class	Post-Build	Multiplicity configuration class	-
Origin	IFX	Scope	LOCAL
Dependency			
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0		

**1.3.1.5 Container: IomSysConfiguration**

This container holds the ECM Configuration.

Multiplicity Configuration Class: -

**IOM driver**
**1.3.1.5.1 IomClcSleepModeEn**
**Table 18 Specification for IomClcSleepModeEn**

<b>Name</b>	IomClcSleepModeEn		
<b>Description</b>	Used to enable or disable the sleep mode of the module. FALSE – disable module sleep mode TRUE – enable module sleep mode		
<b>Multiplicity</b>	1..1	<b>Type</b>	EcucBooleanParamDef
<b>Range</b>	TRUE FALSE		
<b>Default value</b>	FALSE		
<b>Post-build variant value</b>	TRUE	<b>Post-build variant multiplicity</b>	-
<b>Value configuration class</b>	Post-Build	<b>Multiplicity configuration class</b>	-
<b>Origin</b>	IFX	<b>Scope</b>	LOCAL
<b>Dependency</b>	-		
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0		

**1.3.1.5.2 IomClcRmcVal**
**Table 19 Specification for IomClcRmcVal**

<b>Name</b>	IomClcRmcVal		
<b>Description</b>	Determines 8 bit clock divider value in the RUN mode.		
<b>Multiplicity</b>	1..1	<b>Type</b>	EcucIntegerParamDef
<b>Range</b>	1 to 255		
<b>Default value</b>	1		
<b>Post-build variant value</b>	TRUE	<b>Post-build variant multiplicity</b>	-
<b>Value configuration class</b>	Post-Build	<b>Multiplicity configuration class</b>	-
<b>Origin</b>	IFX	<b>Scope</b>	LOCAL
<b>Dependency</b>	-		
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0		

**1.3.1.6 Container: IomGeneral**

The container contains all the general configuration parameters for the IOM driver.

Multiplicity Configuration Class: -

**IOM driver**
**1.3.1.6.1 IomVersionInfoApi**
**Table 20 Specification for IomVersionInfoApi**

<b>Name</b>	IomVersionInfoApi		
<b>Description</b>	Parameter adds or removes the Iom_GetVersionInfo() API from the code. The default value of this parameter is set to false to minimize the executable code size		
<b>Multiplicity</b>	1..1	<b>Type</b>	EcucBooleanParamDef
<b>Range</b>	TRUE FALSE		
<b>Default value</b>	FALSE		
<b>Post-build variant value</b>	FALSE	<b>Post-build variant multiplicity</b>	-
<b>Value configuration class</b>	Pre-Compile	<b>Multiplicity configuration class</b>	-
<b>Origin</b>	IFX	<b>Scope</b>	LOCAL
<b>Dependency</b>	-		
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0		

**1.3.1.6.2 IomDelInitApi**
**Table 21 Specification for IomDelInitApi**

<b>Name</b>	IomDelInitApi		
<b>Description</b>	Parameter adds or removes the Iom_DelInit () API from the code. The default value of this parameter is set to false to minimize the executable code size		
<b>Multiplicity</b>	1..1	<b>Type</b>	EcucBooleanParamDef
<b>Range</b>	TRUE FALSE		
<b>Default value</b>	FALSE		
<b>Post-build variant value</b>	FALSE	<b>Post-build variant multiplicity</b>	-
<b>Value configuration class</b>	Pre-Compile	<b>Multiplicity configuration class</b>	-
<b>Origin</b>	IFX	<b>Scope</b>	LOCAL
<b>Dependency</b>	-		
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0		

**IOM driver**
**1.3.1.6.3 IomDevErrorDetect**
**Table 22 Specification for IomDevErrorDetect**

<b>Name</b>	IomDevErrorDetect		
<b>Description</b>	Parameter enables or disables the Default Error Tracer (DET) detection and reporting.		
<b>Multiplicity</b>	1..1	<b>Type</b>	EcucBooleanParamDef
<b>Range</b>	TRUE FALSE		
<b>Default value</b>	TRUE		
<b>Post-build variant value</b>	FALSE	<b>Post-build variant multiplicity</b>	-
<b>Value configuration class</b>	Pre-Compile	<b>Multiplicity configuration class</b>	-
<b>Origin</b>	IFX	<b>Scope</b>	LOCAL
<b>Dependency</b>	-		
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0		

**1.3.1.6.4 IomIndex**
**Table 23 Specification for IomIndex**

<b>Name</b>	IomIndex		
<b>Description</b>	Specifies instance id for this module instance.		
<b>Multiplicity</b>	1..1	<b>Type</b>	EcucIntegerParamDef
<b>Range</b>	0 to 255		
<b>Default value</b>	0		
<b>Post-build variant value</b>	FALSE	<b>Post-build variant multiplicity</b>	-
<b>Value configuration class</b>	Pre-Compile	<b>Multiplicity configuration class</b>	-
<b>Origin</b>	IFX	<b>Scope</b>	LOCAL
<b>Dependency</b>	-		
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0		

**1.3.1.6.5 IomRuntimeApiMode**
**Table 24 Specification for IomRuntimeApiMode**

<b>Name</b>	IomRuntimeApiMode		
<b>Description</b>	The parameter defines the privilege mode in which the runtime APIs would operate.		



**IOM driver**
**Table 24 Specification for IomRuntimeApiMode (continued)**

	Since IOM driver accesses the SFRs, it is more efficient to operate the IOM driver in supervisor mode. Hence, the default mode of operation is a supervisor.		
<b>Multiplicity</b>	1..1	<b>Type</b>	EcucEnumerationParamDef
<b>Range</b>	IOM_MCAL_SUPERVISOR IOM_MCAL_USER1		
<b>Default value</b>	IOM_MCAL_SUPERVISOR		
<b>Post-build variant value</b>	FALSE	<b>Post-build variant multiplicity</b>	-
<b>Value configuration class</b>	Pre-Compile	<b>Multiplicity configuration class</b>	-
<b>Origin</b>	IFX	<b>Scope</b>	LOCAL
<b>Dependency</b>	-		
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0		

**1.3.1.6.6 IomInitDeInitApiMode**
**Table 25 Specification for IomInitDeInitApiMode**

<b>Name</b>	IomInitDeInitApiMode		
<b>Description</b>	Configuration parameter defines the privilege mode in which the initialization and deinitialization APIs would operate.  Since IOM driver accesses the SFRs, it is more efficient to operate the IOM driver in supervisor mode. Hence, the default mode of operation is a supervisor.		
<b>Multiplicity</b>	1..1	<b>Type</b>	EcucEnumerationParamDef
<b>Range</b>	IOM_MCAL_SUPERVISOR IOM_MCAL_USER1		
<b>Default value</b>	IOM_MCAL_SUPERVISOR		
<b>Post-build variant value</b>	FALSE	<b>Post-build variant multiplicity</b>	-
<b>Value configuration class</b>	Pre-Compile	<b>Multiplicity configuration class</b>	-
<b>Origin</b>	IFX	<b>Scope</b>	LOCAL
<b>Dependency</b>	-		
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0		

**1.3.1.7 Container: IomDemEventParameterRefsConf**

This container holds the ECM Configuration.

Multiplicity Configuration Class: - Pre-Compile

**IOM driver**
**1.3.1.7.1 IomClcFailureNotification**
**Table 26 Specification for IomClcFailureNotification**

<b>Name</b>	IomClcFailureNotification		
<b>Description</b>	The parameter defines whether CLC failure DEM notification is enabled or not.		
<b>Multiplicity</b>	0..1	<b>Type</b>	
<b>Range</b>	Reference to Node: DemEventParameter		
<b>Default value</b>	NULL		
<b>Post-build variant value</b>	FALSE	<b>Post-build variant multiplicity</b>	FALSE
<b>Value configuration class</b>	Pre-Compile	<b>Multiplicity configuration class</b>	Pre-Compile
<b>Origin</b>	IFX	<b>Scope</b>	LOCAL
<b>Dependency</b>	-		
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0		

**1.3.1.8 Container: IomFpcConfiguration**

This container holds the Fpc Configuration.

Multiplicity Configuration Class: - Pre-Compile

**1.3.1.8.1 IomFpcHwUnit**
**Table 27 Specification for IomFpcHwUnit**

<b>Name</b>	IomFpcHwUnit		
<b>Description</b>	Identification number for Fpc unit.		
<b>Multiplicity</b>	1..1	<b>Type</b>	EcucIntegerParamDef
<b>Range</b>	0-15		
<b>Default value</b>	0		
<b>Post-build variant value</b>	TRUE	<b>Post-build variant multiplicity</b>	-
<b>Value configuration class</b>	Post-Build	<b>Multiplicity configuration class</b>	-
<b>Origin</b>	IFX	<b>Scope</b>	LOCAL
<b>Dependency</b>	-		
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0		

**IOM driver**
**1.3.1.8.2 IomFpcCompareVal**
**Table 28 Specification for IomFpcCompareVal**

<b>Name</b>	IomFpcCompareVal		
<b>Description</b>	This parameter is used to set the compare value of Fpc.		
<b>Multiplicity</b>	1..1	<b>Type</b>	EcucIntegerParamDef
<b>Range</b>	0-65535		
<b>Default value</b>	0		
<b>Post-build variant value</b>	TRUE	<b>Post-build variant multiplicity</b>	-
<b>Value configuration class</b>	Post-Build	<b>Multiplicity configuration class</b>	-
<b>Origin</b>	IFX	<b>Scope</b>	LOCAL
<b>Dependency</b>	-		
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0		

**1.3.1.8.3 IomFpcMode**
**Table 29 Specification for IomFpcMode**

<b>Name</b>	IomFpcMode		
<b>Description</b>	<p>Used to select a mode of operation for FPC.</p> <p>IOM_MOD_0_BOTHEDGES_DD – FPC is configured to operate in delayed debounce filter mode on both edges</p> <p>IOM_MOD_1_BOTHEDGES_ID – FPC is configured to operate in immediate debounce filter mode on both edges</p> <p>IOM_MOD_2_RISINGEDGE_ID – FPC is configured to operate in Delayed debounce filter mode on the rising edge and no filtering on falling edge</p> <p>IOM_MOD_3_FALLINGEDGE_ID - FPC is configured to operate in immediate debounce filter mode on falling edge and no filtering on rising edge</p> <p>IOM_MOD_4_RISING_DD_FALLING_ID - FPC is configured to operate in delayed debounce filter mode on the rising edge and immediate debounce filter mode on falling edge</p> <p>IOM_MOD_5_RISING_ID_FALLING_DD - FPC is configured to operate in immediate debounce filter mode on the rising edge and delayed debounce filter mode on the falling edge.</p> <p>IOM_MOD_6_RISINGEDGE_PRESCALER – prescaler mode is triggered on the rising edge</p> <p>IOM_MOD_7_FALLINGEDGE_PRESCALER – prescaler mode is triggered on a falling edge.</p>		
<b>Multiplicity</b>	1..1	<b>Type</b>	EcucEnumerationParamDef
<b>Range</b>	IOM_MOD_0_BOTHEDGES_DD IOM_MOD_1_BOTHEDGES_ID		

**IOM driver**
**Table 29 Specification for IomFpcMode (continued)**

	IOM_MOD_2_RISINGEDGE_ID IOM_MOD_3_FALLINGEDGE_ID IOM_MOD_4_RISING_DD_FALLING_ID IOM_MOD_5_RISING_ID_FALLING_DD IOM_MOD_6_RISINGEDGE_PRESCALER IOM_MOD_7_FALLINGEDGE_PRESCALER		
<b>Default value</b>	IOM_MOD_0_BOTHEGES_DD		
<b>Post-build variant value</b>	TRUE	<b>Post-build variant multiplicity</b>	-
<b>Value configuration class</b>	Post-Build	<b>Multiplicity configuration class</b>	-
<b>Origin</b>	IFX	<b>Scope</b>	LOCAL
<b>Dependency</b>	-		
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0		

**1.3.1.8.4 IomFpcMonInputSel**
**Table 30 Specification for IomFpcMonInputSel**

<b>Name</b>	IomFpcMonInputSel		
<b>Description</b>	This parameter is used to select the monitor input signal. IOM_PNIN_0 – signal input from port logic is selected IOM_MON0_1 – monitor input signal 0 is selected IOM_MON1_2 - monitor input signal 1 is selected IOM_MON2_3 - monitor input signal 2 is selected		
<b>Multiplicity</b>	1..1	<b>Type</b>	EcucEnumerationParamDef
<b>Range</b>	IOM_PNIN_0 IOM_MON0_1 IOM_MON1_2 IOM_MON2_3		
<b>Default value</b>	IOM_PNIN_0		
<b>Post-build variant value</b>	TRUE	<b>Post-build variant multiplicity</b>	-
<b>Value configuration class</b>	Post-Build	<b>Multiplicity configuration class</b>	-
<b>Origin</b>	IFX	<b>Scope</b>	LOCAL
<b>Dependency</b>	-		
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0		

**IOM driver**
**1.3.1.8.5 IomFpcReferInputSel**
**Table 31 Specification for IomFpcReferInputSel**

<b>Name</b>	IomFpcReferInputSel		
<b>Description</b>	This parameter is used to select the reference input signal. IOM_PNIN_0 – signal input from port logic is selected IOM_REF0_1 – reference input signal 0 is selected IOM_REF1_2 – reference input signal 1 is selected IOM_REF2_3 – reference input signal 2 is selected. IOM_GTMC_4-reference input 3 is selected		
<b>Multiplicity</b>	1..1	<b>Type</b>	EcucEnumerationParamDef
<b>Range</b>	IOM_PNIN_0 IOM_REF0_1 IOM_REF1_2 IOM_REF2_3 IOM_GTMC_4		
<b>Default value</b>	IOM_PNIN_0		
<b>Post-build variant value</b>	TRUE	<b>Post-build variant multiplicity</b>	-
<b>Value configuration class</b>	Post-Build	<b>Multiplicity configuration class</b>	-
<b>Origin</b>	IFX	<b>Scope</b>	LOCAL
<b>Dependency</b>	-		
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0		

**1.3.1.8.6 IomFpcResetTimer**
**Table 32 Specification for IomFpcResetTimer**

<b>Name</b>	IomFpcResetTimer		
<b>Description</b>	Indicates whether FPC reset timer should be decremented or cleared on the glitch. IOM_TIMER_DECREMENT – Timer FPCK is decremented on the glitch. IOM_TIMER_CLEAR – Timer FPCK is cleared on the glitch.		
<b>Multiplicity</b>	1..1	<b>Type</b>	EcucEnumerationParamDef
<b>Range</b>	IOM_TIMER_DECREMENT IOM_TIMER_CLEAR		
<b>Default value</b>	IOM_TIMER_DECREMENT		
<b>Post-build variant value</b>	TRUE	<b>Post-build variant multiplicity</b>	-
<b>Value configuration class</b>	Post-Build	<b>Multiplicity configuration class</b>	-

**IOM driver**
**Table 32 Specification for IomFpcResetTimer (continued)**

<b>Origin</b>	IFX	<b>Scope</b>	LOCAL
<b>Dependency</b>	-		
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0		

**1.3.1.9 Container: IomLamConfiguration**

This container holds the Lam Configuration.

Multiplicity Configuration Class: - Pre-Compile

**1.3.1.9.1 IomLamHwUnit**
**Table 33 Specification for IomLamHwUnit**

<b>Name</b>	IomLamHwUnit		
<b>Description</b>	Identification number for LAM unit.		
<b>Multiplicity</b>	1..1	<b>Type</b>	EcucIntegerParamDef
<b>Range</b>	0-15		
<b>Default value</b>	0		
<b>Post-build variant value</b>	TRUE	<b>Post-build variant multiplicity</b>	-
<b>Value configuration class</b>	Post-Build	<b>Multiplicity configuration class</b>	-
<b>Origin</b>	IFX	<b>Scope</b>	LOCAL
<b>Dependency</b>	-		
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0		

**1.3.1.9.2 IomLamThreshold**
**Table 34 Specification for IomLamThreshold**

<b>Name</b>	IomLamThreshold		
<b>Description</b>	This parameter is used to set the threshold value for event window counter from which an event is generated.		
<b>Multiplicity</b>	1..1	<b>Type</b>	EcucIntegerParamDef
<b>Range</b>	0-16777215		
<b>Default value</b>	0		
<b>Post-build variant value</b>	TRUE	<b>Post-build variant multiplicity</b>	-
<b>Value configuration class</b>	Post-Build	<b>Multiplicity configuration class</b>	-

**IOM driver**
**Table 34 Specification for IomLamThreshold (continued)**

<b>Origin</b>	IFX	<b>Scope</b>	LOCAL
<b>Dependency</b>	-		
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0		

**1.3.1.9.3 IomLamInvReferSignal**
**Table 35 Specification for IomLamInvReferSignal**

<b>Name</b>	IomLamInvReferSignal		
<b>Description</b>	This parameter is used to enable/disable inversion of the reference signal to LAM FALSE – disables inversion of the reference signal to selected LAM module. TRUE – enables inversion of the reference signal to selected LAM module.		
<b>Multiplicity</b>	1..1	<b>Type</b>	EcucBooleanParamDef
<b>Range</b>	TRUE FALSE		
<b>Default value</b>	FALSE		
<b>Post-build variant value</b>	TRUE	<b>Post-build variant multiplicity</b>	-
<b>Value configuration class</b>	Post-Build	<b>Multiplicity configuration class</b>	-
<b>Origin</b>	IFX	<b>Scope</b>	LOCAL
<b>Dependency</b>	-		
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0		

**1.3.1.9.4 IomLamInvMonSignal**
**Table 36 Specification for IomLamInvMonSignal**

<b>Name</b>	IomLamInvMonSignal		
<b>Description</b>	This parameter is used to enable/disable inversion of monitor signal to LAM FALSE – disables inversion of monitor signal to selected LAM module. TRUE – enables inversion of monitor signal to selected LAM module.		
<b>Multiplicity</b>	1..1	<b>Type</b>	EcucBooleanParamDef
<b>Range</b>	TRUE FALSE		
<b>Default value</b>	FALSE		
<b>Post-build variant value</b>	TRUE	<b>Post-build variant multiplicity</b>	-
<b>Value configuration class</b>	Post-Build	<b>Multiplicity configuration class</b>	-

**IOM driver**
**Table 36 Specification for IomLamInvMonSignal (continued)**

<b>Origin</b>	IFX	<b>Scope</b>	LOCAL
<b>Dependency</b>	-		
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0		

**1.3.1.9.5 IomLamInvEventWin**
**Table 37 Specification for IomLamInvEventWin**

<b>Name</b>	IomLamInvEventWin		
<b>Description</b>	This parameter is used to enable/disable inversion of event window in the LAM module FALSE – disables inversion of event window signal in selected LAM module. TRUE – enables inversion of event window signal in selected LAM module.		
<b>Multiplicity</b>	1..1	<b>Type</b>	EcucBooleanParamDef
<b>Range</b>	TRUE FALSE		
<b>Default value</b>	FALSE		
<b>Post-build variant value</b>	TRUE	<b>Post-build variant multiplicity</b>	-
<b>Value configuration class</b>	Post-Build	<b>Multiplicity configuration class</b>	-
<b>Origin</b>	IFX	<b>Scope</b>	LOCAL
<b>Dependency</b>	-		
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0		

**1.3.1.9.6 IomLamMonSrcSelect**
**Table 38 Specification for IomLamMonSrcSelect**

<b>Name</b>	IomLamMonSrcSelect		
<b>Description</b>	The parameter defines whether monitor signal sourced directly or EXOR'd with a reference signal. IOM_MON_SIGNAL_FPCM – monitor signal is sourced directly from FPC monitor signal IOM_MON_SIGNAL_EXOR_FPCM – monitor signal is EXOR'd with FPC reference signal		
<b>Multiplicity</b>	1..1	<b>Type</b>	EcucEnumerationParamDef
<b>Range</b>	IOM_MON_SIGNAL_FPCM IOM_MON_SIGNAL_EXOR_FPCM		
<b>Default value</b>	IOM_MON_SIGNAL_FPCM		



**IOM driver**
**Table 38 Specification for IomLamMonSrcSelect (continued)**

<b>Post-build variant value</b>	TRUE	<b>Post-build variant multiplicity</b>	-
<b>Value configuration class</b>	Post-Build	<b>Multiplicity configuration class</b>	-
<b>Origin</b>	IFX	<b>Scope</b>	LOCAL
<b>Dependency</b>	-		
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0		

**1.3.1.9.7 IomLamRunMode**
**Table 39 Specification for IomLamRunMode**

<b>Name</b>	IomLamRunMode		
<b>Description</b>	<p>The parameter defines whether event window generation is free running or gated with monitor or reference signal.</p> <p>IOM_EVENT_WINDOW_FREE_RUNNING – event window generation is free running.</p> <p>IOM_EVENT_WINDOW_GATED – event window generation is gated with monitor or reference signal.</p>		
<b>Multiplicity</b>	1..1	<b>Type</b>	EcucEnumerationParamDef
<b>Range</b>	IOM_EVENT_WINDOW_FREE_RUNNING IOM_EVENT_WINDOW_GATED		
<b>Default value</b>	IOM_EVENT_WINDOW_FREE_RUNNING		
<b>Post-build variant value</b>	TRUE	<b>Post-build variant multiplicity</b>	-
<b>Value configuration class</b>	Post-Build	<b>Multiplicity configuration class</b>	-
<b>Origin</b>	IFX	<b>Scope</b>	LOCAL
<b>Dependency</b>	-		
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0		

**1.3.1.9.8 IomLamEventWinSelect**
**Table 40 Specification for IomLamEventWinSelect**

<b>Name</b>	IomLamEventWinSelect		
<b>Description</b>	<p>The parameter defines whether event window generation is from monitor signal or reference signal.</p> <p>IOM_EVENT_WIN_GEN_REFER – event window generation is determined from the reference signal.</p> <p>IOM_EVENT_WIN_GEN_MON – event window generation is determined from the monitor signal.</p>		

**IOM driver**
**Table 40 Specification for IomLamEventWinSelect (continued)**

<b>Multiplicity</b>	1..1	<b>Type</b>	EcucEnumerationParamDef
<b>Range</b>	IOM_EVENT_WIN_GEN_REFER IOM_EVENT_WIN_GEN_MON		
<b>Default value</b>	IOM_EVENT_WIN_GEN_REFER		
<b>Post-build variant value</b>	TRUE	<b>Post-build variant multiplicity</b>	-
<b>Value configuration class</b>	Post-Build	<b>Multiplicity configuration class</b>	-
<b>Origin</b>	IFX	<b>Scope</b>	LOCAL
<b>Dependency</b>	-		
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0		

**1.3.1.9.9 IomLamDisableEvents**
**Table 41 Specification for IomLamDisableEvents**

<b>Name</b>	IomLamDisableEvents		
<b>Description</b>	The parameter defines whether to suppress alarm outputs from LAM block to the ECM. FALSE – disables alarm output from LAM to ECM. TRUE – enables alarm output from LAM to ECM.		
<b>Multiplicity</b>	1..1	<b>Type</b>	EcucBooleanParamDef
<b>Range</b>	TRUE FALSE		
<b>Default value</b>	FALSE		
<b>Post-build variant value</b>	TRUE	<b>Post-build variant multiplicity</b>	-
<b>Value configuration class</b>	Post-Build	<b>Multiplicity configuration class</b>	-
<b>Origin</b>	IFX	<b>Scope</b>	LOCAL
<b>Dependency</b>	-		
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0		

**1.3.1.9.10 IomLamEveWinActiveEdgeSelect**
**Table 42 Specification for IomLamEveWinActiveEdgeSelect**

<b>Name</b>	IomLamEveWinActiveEdgeSelect		
<b>Description</b>	The parameter defines which active edges of reference and monitor signals are used for event window generation.		

**IOM driver**
**Table 42 Specification for IomLamEveWinActiveEdgeSelect (continued)**

	<p>IOM_NEITHER_CLR_NEITHER_GATE – neither edge used to clear event window counter and gate event generation.</p> <p>IOM_NEITHER_CLR_POS_GATE - neither edge used to clear event window counter and positive edge used to gate event generation</p> <p>IOM_NEITHER_CLR_NEG_GATE - neither edge used to clear event window counter and negative edge used to gate event generation</p> <p>IOM_NEITHER_CLR_EITHER_GATE - neither edge used to clear the event window counter and either edge used to gate event generation.</p> <p>IOM_POS_CLR_NEITHER_GATE - positive edge used to clear event window counter and neither edge used to gate event generation.</p> <p>IOM_POS_CLR_POS_GATE - positive edge used to clear event window counter and gate event generation.</p> <p>IOM_POS_CLR_NEG_GATE - positive edge used to clear event window counter and negative edge used to gate event generation.</p> <p>IOM_POS_CLR_EITHER_GATE - positive edge used to clear event window counter and either edge used to gate event generation.</p> <p>IOM_NEG_CLR_NEITHER_GATE - negative edge used to clear event window counter and neither edge used to gate event generation.</p> <p>IOM_NEG_CLR_POS_GATE – negative edge used to clear event window counter and positive edge used to gate event generation.</p> <p>IOM_NEG_CLR_NEG_GATE - negative edge used to clear event window counter and to gate event generation.</p> <p>IOM_NEG_CLR_EITHER_GATE - negative edge used to clear event window counter and either edge used to gate event generation.</p> <p>IOM_EITHER_CLR_NEITHER_GATE - either edge used to clear event window counter and neither edge used to gate event generation.</p> <p>IOM_EITHER_CLR_POS_GATE - either edge used to clear event window counter and positive edge used to gate event generation.</p> <p>IOM_EITHER_CLR_NEG_GATE - either edge used to clear event window counter and negative edge used to gate event generation.</p> <p>IOM_EITHER_CLR_EITHER_GATE - either edge used to clear event window counter and to gate event generation.</p>		
<b>Multiplicity</b>	1..1	<b>Type</b>	EcucEnumerationParamDef
<b>Range</b>	<p>IOM_NEITHER_CLR_NEITHER_GATE</p> <p>IOM_NEITHER_CLR_POS_GATE</p> <p>IOM_NEITHER_CLR_NEG_GATE</p> <p>IOM_NEITHER_CLR_EITHER_GATE</p> <p>IOM_POS_CLR_NEITHER_GATE</p> <p>IOM_POS_CLR_POS_GATE</p> <p>IOM_POS_CLR_NEG_GATE</p> <p>IOM_POS_CLR_EITHER_GATE</p> <p>IOM_NEG_CLR_NEITHER_GATE</p> <p>IOM_NEG_CLR_POS_GATE</p>		

**IOM driver**
**Table 42 Specification for IomLamEveWinActiveEdgeSelect (continued)**

	IOM_NEG_CLR_NEG_GATE IOM_NEG_CLR_EITHER_GATE IOM_EITHER_CLR_NEITHER_GATE IOM_EITHER_CLR_POS_GATE IOM_EITHER_CLR_NEG_GATE IOM_EITHER_CLR_EITHER_GATE		
<b>Default value</b>	IOM_NEITHER_CLR_NEITHER_GATE		
<b>Post-build variant value</b>	TRUE	<b>Post-build variant multiplicity</b>	-
<b>Value configuration class</b>	Post-Build	<b>Multiplicity configuration class</b>	-
<b>Origin</b>	IFX	<b>Scope</b>	LOCAL
<b>Dependency</b>	-		
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0		

**1.3.1.9.11 IomLamMonInputSel**
**Table 43 Specification for IomLamMonInputSel**

<b>Name</b>	IomLamMonInputSel		
<b>Description</b>	A parameter to select the monitor output signal from FPC block to LAM block.		
<b>Multiplicity</b>	1..1	<b>Type</b>	EcucEnumerationParamDef
<b>Range</b>	IOM_MONITOR_SIGNAL_FPCx x varies from 00 to 15		
<b>Default value</b>	IOM_MONITOR_SIGNAL_FPC00		
<b>Post-build variant value</b>	TRUE	<b>Post-build variant multiplicity</b>	-
<b>Value configuration class</b>	Post-Build	<b>Multiplicity configuration class</b>	-
<b>Origin</b>	IFX	<b>Scope</b>	LOCAL
<b>Dependency</b>	-		
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0		

**1.3.1.9.12 IomLamRefInputSel**
**Table 44 Specification for IomLamRefInputSel**

<b>Name</b>	IomLamRefInputSel		
<b>Description</b>	A parameter to select the reference output signal from FPC block to LAM block.		
<b>Multiplicity</b>	1..1	<b>Type</b>	EcucEnumerationParamDef

**IOM driver**
**Table 44 Specification for IomLamRefInputSel (continued)**

<b>Range</b>	IOM_REFER_SIGNAL_FPCx x varies from 00 to 15		
<b>Default value</b>	IOM_REFER_SIGNAL_FPC00		
<b>Post-build variant value</b>	TRUE	<b>Post-build variant multiplicity</b>	-
<b>Value configuration class</b>	Post-Build	<b>Multiplicity configuration class</b>	-
<b>Origin</b>	IFX	<b>Scope</b>	LOCAL
<b>Dependency</b>	-		
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0		

**1.3.1.10 Container: IomClcConfiguration**

This container holds the Clc Configuration.

Multiplicity Configuration Class: - Pre-Compile

**1.3.1.10.1 IomClcSleepModeEn**
**Table 45 Specification for IomClcSleepModeEn**

<b>Name</b>	IomClcSleepModeEn		
<b>Description</b>	Used to enable or disable sleep mode of the module.		
<b>Multiplicity</b>	0..1	<b>Type</b>	EcucBooleanParamDef
<b>Range</b>	TRUE FALSE		
<b>Default value</b>	FALSE		
<b>Post-build variant value</b>	FALSE	<b>Post-build variant multiplicity</b>	-
<b>Value configuration class</b>	Post Build	<b>Multiplicity configuration class</b>	-
<b>Origin</b>	IFX	<b>Scope</b>	LOCAL
<b>Dependency</b>	-		
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0		

**1.3.1.10.2 IomClcRmcVal**
**Table 46 IomClcRmcVal**

<b>Name</b>	IomClcRmcVal
<b>Description</b>	Determines 8 bit clock divider value in the RUN mode.

**IOM driver**
**Table 46 IomCltRmcVal (continued)**

<b>Multiplicity</b>	1..1	<b>Type</b>	EcucIntegerParamDef
<b>Range</b>	1-255		
<b>Default value</b>	1		
<b>Post-build variant value</b>	FALSE	<b>Post-build variant multiplicity</b>	-
<b>Value configuration class</b>	Post Build	<b>Multiplicity configuration class</b>	-
<b>Origin</b>	IFX	<b>Scope</b>	LOCAL
<b>Dependency</b>	-		
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0		

**1.3.1.11 Container: Iom**

Configuration of the Iom(Input Output Manager)

Multiplicity Configuration Class: -

**1.3.1.11.1 Config Variant**
**Table 47 Specification of Config Variant**

<b>Name</b>	Config Variant		
<b>Description</b>	-		
<b>Multiplicity</b>	1..1	<b>Type</b>	EcucIntegerParamDef
<b>Range</b>	Variant Post Build: Post Build Support		
<b>Default value</b>	Variant Post Build		
<b>Post-build variant value</b>	False	<b>Post-build variant multiplicity</b>	-
<b>Value configuration class</b>	Pre-Compile	<b>Multiplicity configuration class</b>	-
<b>Origin</b>	IFX	<b>Scope</b>	LOCAL
<b>Dependency</b>	-		
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0		

**1.3.2 Functions – Type definitions**

This section describes all the type definitions used by APIs.

**IOM driver**
**1.3.2.1 Iom\_RstStatusType**
**Table 48 Specification for Iom\_RstStatusType**

<b>Syntax</b>	Iom_RstStatusType	
<b>Type</b>	uint8	
<b>File</b>	Iom.h	
<b>Range</b>	0	No kernel reset was executed
	1	Kernel reset was executed
	255	Indicates invalid value
<b>Description</b>	Indicates the reset status of the kernel.	
<b>Source</b>	IFX	
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0	

**1.3.2.2 Iom\_Ecm\_ThresType**
**Table 49 Specification for Iom\_Ecm\_ThresType**

<b>Syntax</b>	Iom_Ecm_ThresType	
<b>Type</b>	uint8	
<b>File</b>	Iom.h	
<b>Range</b>	0-15	Threshold count value
	255	Indicates invalid value
<b>Description</b>	Indicates the threshold value of the counter in ECM.	
<b>Source</b>	IFX	
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0	

**1.3.2.3 Iom\_Fpc\_CompareType**
**Table 50 Specification for Iom\_Fpc\_CompareType**

<b>Syntax</b>	Iom_Fpc_CompareType	
<b>Type</b>	uint32	
<b>File</b>	Iom.h	
<b>Range</b>	0x0 – 0xFFFF	Fpc compare value
	0xFFFFFFFF	Indicates invalid value
<b>Description</b>	Indicates the compare value of the FPC.	
<b>Source</b>	IFX	
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0	

## IOM driver

### 1.3.2.4 Iom\_FpcStatusType

**Table 51 Specification for Iom\_FpcStatusType**

<b>Syntax</b>	Iom_FpcStatusType	
<b>Type</b>	uint 8	
<b>File</b>	Iom.h	
<b>Range</b>	0-3	Fpc edge status
	255	Indicates invalid value
<b>Description</b>	Indicates the value of the FPC edge status	
<b>Source</b>	IFX	
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0	

### 1.3.2.5 Iom\_Ecm\_EveHistype

**Table 52 Specification for Iom\_Ecm\_EveHisType**

<b>Syntax</b>	Iom_Ecm_EveHisType	
<b>Type</b>	uint32	
<b>File</b>	Iom.h	
<b>Range</b>	0x0 – 0xFFFF	ECM event trigger history
	0xFFFFFFFF	Indicates invalid value
<b>Description</b>	Indicates the ECM event history	
<b>Source</b>	IFX	
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0	

### 1.3.2.6 Iom\_Lam\_Configtype

**Table 53 Specification for Iom\_Lam\_ConfigType**

<b>Syntax</b>	Iom_Lam_ConfigType	
<b>Type</b>	uint32	
<b>File</b>	Iom.h	
<b>Range</b>	0x0 - 0xFFFFFFFFu	
<b>Description</b>	Indicates to the Lam Configuration Value	
<b>Source</b>	IFX	
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0	



**IOM driver**
**1.3.2.7 Iom\_Lam\_ThresType**
**Table 54 Specification for Iom\_Lam\_ThresType**

<b>Syntax</b>	Iom_Lam_ThresType
<b>Type</b>	UInt32
<b>File</b>	Iom.h
<b>Range</b>	0-0xFFFFFFFFu
<b>Description</b>	Indicates the threshold value of the Lam.
<b>Source</b>	IFX
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0

**1.3.2.8 Iom\_Lam\_CountType**
**Table 55 Specification for Iom\_Lam\_CountType**

<b>Syntax</b>	Iom_Lam_CountType	
<b>Type</b>	uint32	
<b>File</b>	Iom.h	
<b>Range</b>	0x0-0xFFFFF	LAM count
	0xFFFFFFFF	Indicates invalid value
<b>Description</b>	Indicates to the count value of the Lam event.	
<b>Source</b>	IFX	
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0	

**1.3.2.9 Iom\_Ecm\_EveSelType**
**Table 56 Specification for Iom\_Ecm\_EveSelType**

<b>Syntax</b>	Iom_Ecm_EveSelType	
<b>Type</b>	UInt32	
<b>File</b>	Iom.h	
<b>Range</b>	0-0xFFFFFu	ECM global event selection
	0xFFFFFFFF	Indicates invalid value
<b>Description</b>	Indicates the value of the global event selection register.	
<b>Source</b>	IFX	
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0	

**IOM driver**
**1.3.2.10 Iom\_EventHistory**
**Table 57 Specification for Iom\_EventHistory**

<b>Syntax</b>	Iom_EventHistory
<b>Type</b>	Enumeration
<b>File</b>	Iom.h
<b>Range</b>	IOM_EVETRIG_HISTORY_A = 0U, IOM_EVETRIG_HISTORY_B = 1U, IOM_EVETRIG_HISTORY_C = 2U, IOM_EVETRIG_HISTORY_D = 3U,
<b>Description</b>	Selects the history of the events recorded.
<b>Source</b>	IFX
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0

**1.3.2.11 Iom\_FpcConfigType**
**Table 58 Specification for Iom\_FpcConfigType**

<b>Syntax</b>	Iom_FpcConfigType	
<b>Type</b>	Structure	
<b>File</b>	Iom.h	
<b>Range</b>	uint32 FpcCfg	FPC control value and compare value
	Uint16 FpcUnitNo	FPC unit Id
<b>Description</b>	Type for the definition of Fpc Module	
<b>Source</b>	IFX	
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0	

**1.3.2.12 Iom\_LamConfigType**
**Table 59 Specification for Iom\_LamConfigType**

<b>Syntax</b>	Iom_LamConfigType	
<b>Type</b>	Structure	
<b>File</b>	Iom.h	
<b>Range</b>	uint32 LamentWinCount	LAM event window threshold
	uint32 LamCfg	LAM configuration register value
	uint16 LamNo	LAM unit Id
<b>Description</b>	Type definition of the Lam module.	
<b>Source</b>	IFX	
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0	

## IOM driver

### 1.3.2.13 Iom\_EcmConfigType

**Table 60 Specification for Iom\_EcmConfigType**

<b>Syntax</b>	Iom_EcmConfigType	
<b>Type</b>	structure	
<b>File</b>	Iom.h	
<b>Range</b>	uint32 EcmCountConfig	ECM counter configuration register value
	uint32 EcmGlobEntSel	ECM global event selection register value
<b>Description</b>	Type definition for the ECM module.	
<b>Source</b>	IFX	
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0	

### 1.3.2.14 Iom\_ConfigType

**Table 61 Specification for Iom\_ConfigType**

<b>Syntax</b>	Iom_ConfigType
<b>Type</b>	Structure
<b>File</b>	Iom.h
<b>Description</b>	Defines the type for data structure containing the set of configuration parameters required for initializing the IOM driver.
<b>Source</b>	IFX
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0

## 1.3.3 Functions - APIs

This section lists all the APIs of the IOM driver.

### 1.3.3.1 Iom\_Init

**Table 62 Specification for Iom\_Init API**

<b>Syntax</b>	<pre>void Iom_Init (   const Iom_ConfigType * const ConfigPtr )</pre>	
<b>Service ID</b>	0x5F	
<b>Sync/Async</b>	Synchronous	
<b>ASIL Level</b>	QM	
<b>Reentrancy</b>	Non Reentrant	
<b>Parameters (in)</b>	ConfigPtr	Pointer to configuration set

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**IOM driver**
**Table 62 Specification for Iom\_Init API (continued)**

<b>Parameters (out)</b>	-	
<b>Parameters (in-out)</b>	-	
<b>Return</b>	void	-
<b>Description</b>	This API initializes the IOM driver. This function will initialize all relevant registers of IOM hardware with the values of structure referenced by the parameter ConfigPtr. The IOM initialization status is set at the end of the Initialization function execution.	
<b>Source</b>	IFX	
<b>Error handling</b>	IOM_E_INIT, IOM_E_PARAM_CONFIG, IOM_E_CLC_ENABLE_ERR	
<b>Configuration dependencies</b>	-	
<b>User hints</b>	-	
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0	

**1.3.3.2 Iom\_DeInit**
**Table 63 Specification for Iom\_DeInit API**

<b>Syntax</b>	void Iom_DeInit ( void )	
<b>Service ID</b>	0x60	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Non Reentrant	
<b>ASIL Level</b>	QM	
<b>Parameters (in)</b>	-	-
<b>Parameters (out)</b>	-	
<b>Parameters (in-out)</b>	-	
<b>Return</b>	void	-
<b>Description</b>	This API deinitializes the IOM driver. Service for deinitializing all hardware registers to their power on reset state. This API is only available when IomDeInitApi is configured as true	
<b>Source</b>	IFX	
<b>Error handling</b>	IOM_E_UNINIT	
<b>Configuration dependencies</b>	-	
<b>User hints</b>	-	
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0	

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**IOM driver**
**1.3.3.3 Iom\_ResetKernel**
**Table 64 Specification for Iom\_ResetKernel API**

<b>Syntax</b>	void Iom_ResetKernel ( void )	
<b>Service ID</b>	0x61	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Reentrant	
<b>ASIL Level</b>	QM	
<b>Parameters (in)</b>	-	-
<b>Parameters (out)</b>	-	
<b>Parameters (in-out)</b>	-	
<b>Return</b>	void	
<b>Description</b>	This API resets the IOM module kernel.	
<b>Source</b>	IFX	
<b>Error handling</b>	IOM_E_UNINIT	
<b>Configuration dependencies</b>	-	
<b>User hints</b>	-	
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0	

**1.3.3.4 Iom\_GetResetStatus**
**Table 65 Specification for Iom\_GetResetStatus API**

<b>Syntax</b>	Iom_RstStatusType Iom_GetResetStatus ( void )	
<b>Service ID</b>	0x62	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Reentrant	
<b>ASIL Level</b>	QM	
<b>Parameters (in)</b>	-	-
<b>Parameters (out)</b>	-	
<b>Parameters (in-out)</b>	-	
<b>Return</b>	Iom_RstStatusType	Reset status for IOM kernel.
<b>Description</b>	This API returns the reset status for IOM kernel.	
<b>Source</b>	IFX	
<b>Error handling</b>	IOM_E_UNINIT	
<b>Configuration dependencies</b>	-	
<b>User hints</b>	-	

**IOM driver**
**Table 65 Specification for Iom\_GetResetStatus API (continued)**

<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0
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**1.3.3.5 Iom\_ClrResetStatus**
**Table 66 Specification for Iom\_ClrResetStatus API**

<b>Syntax</b>	void Iom_ClrResetStatus ( void )	
<b>Service ID</b>	0x63	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Reentrant	
<b>ASIL Level</b>	QM	
<b>Parameters (in)</b>	-	-
<b>Parameters (out)</b>	-	
<b>Parameters (in-out)</b>	-	
<b>Return</b>	void	-
<b>Description</b>	This service clear the kernel reset status bit.	
<b>Source</b>	IFX	
<b>Error handling</b>	IOM_E_UNINIT	
<b>Configuration dependencies</b>	-	
<b>User hints</b>	-	
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0	

**1.3.3.6 Iom\_ClrFpcEdgeStatus**
**Table 67 Specification for Iom\_ClrFpcEdgeStatus API**

<b>Syntax</b>	void Iom_ClrFpcEdgeStatus (const uint8 FpcNo, const uint8 Edge )	
<b>Service ID</b>	0x64	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Reentrant	
<b>ASIL Level</b>	QM	
<b>Parameters (in)</b>	FpcNo	FPC unit number
	Edge	Indicates rising edge or falling edge or both edges to be cleared.
<b>Parameters (out)</b>	-	
<b>Parameters (in-out)</b>	-	
<b>Return</b>	void	-

**IOM driver**
**Table 67 Specification for Iom\_ClrFpcEdgeStatus API (continued)**

<b>Description</b>	This API provides service to clear rising, falling or both edge.
<b>Source</b>	IFX
<b>Error handling</b>	IOM_E_UNINIT, IOM_E_PARAM_FPC, IOM_E_PARAM_EDGE
<b>Configuration dependencies</b>	-
<b>User hints</b>	-
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0

**1.3.3.7 Iom\_GetFpcEdgeStatus**
**Table 68 Specification for Iom\_GetFpcEdgeStatus API**

<b>Syntax</b>	Iom_FpcStatusType Iom_GetFpcEdgeStatus (const uint8 FpcNo, const uint8 Edge )	
<b>Service ID</b>	0x65	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Reentrant	
<b>ASIL Level</b>	QM	
<b>Parameters (in)</b>	FpcNo	FPC unit number
	Edge	Indicates rising edge or falling edge or both edges to be cleared
<b>Parameters (out)</b>	-	
<b>Parameters (in-out)</b>	-	
<b>Return</b>	Iom_FpcStatusType	Indicates the value of the FPC edge status
<b>Description</b>	This API provides service to read and return the FPC edge status register value.	
<b>Source</b>	IFX	
<b>Error handling</b>	IOM_E_UNINIT, IOM_E_PARAM_FPC, IOM_E_PARAM_EDGE	
<b>Configuration dependencies</b>	-	
<b>User hints</b>	-	
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0	

**1.3.3.8 Iom\_SetFpcCompare**
**Table 69 Specification for Iom\_SetFpcCompare API**

<b>Syntax</b>	void Iom_SetFpcCompare (const uint8 FpcNo, const uint16 CompVal )
<b>Service ID</b>	0x66
<b>Sync/Async</b>	Synchronous

**IOM driver**
**Table 69 Specification for Iom\_SetFpcCompare API (continued)**

<b>Reentrancy</b>	Reentrant	
<b>ASIL Level</b>	QM	
<b>Parameters (in)</b>	FpcNo	FPC unit number
	Edge	Compare value of the FPC unit
<b>Parameters (out)</b>	-	
<b>Parameters (in-out)</b>	-	
<b>Return</b>	void	-
<b>Description</b>	This API provides service to set FPC compare value.	
<b>Source</b>	IFX	
<b>Error handling</b>	IOM_E_UNINIT, IOM_E_PARAM_FPC	
<b>Configuration dependencies</b>	-	
<b>User hints</b>	-	
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0	

**1.3.3.9 Iom\_GetFpcCompare**
**Table 70 Specification for Iom\_GetFpcCompare API**

<b>Syntax</b>	Iom_Fpc_CompareType Iom_GetFpcCompare (const uint8 FpcNo)	
<b>Service ID</b>	0x67	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Reentrant	
<b>ASIL Level</b>	QM	
<b>Parameters (in)</b>	FpcNo	Fpc unit number
<b>Parameters (out)</b>	-	
<b>Parameters (in-out)</b>	-	
<b>Return</b>	Iom_Fpc_CompareType	Indicates the compare value of the Fpc
<b>Description</b>	This API provides service to set FPC compare value.	
<b>Source</b>	IFX	
<b>Error handling</b>	IOM_E_UNINIT, IOM_E_PARAM_FPC	
<b>Configuration dependencies</b>	-	
<b>User hints</b>	-	
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0	



**IOM driver**
**1.3.3.10 Iom\_SetLamConfig**
**Table 71 Specification for Iom\_SetLamConfig API**

<b>Syntax</b>	void Iom_SetLamConfig (const uint8 LamNo, const uint32 ConfigVal)	
<b>Service ID</b>	0x68	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Reentrant	
<b>ASIL Level</b>	QM	
<b>Parameters (in)</b>	LamNo	LAM unit number
	ConfigVal	LAM configuration value
<b>Parameters (out)</b>	-	
<b>Parameters (in-out)</b>	-	
<b>Return</b>	void	
<b>Description</b>	This API provides service to set LAM configuration.	
<b>Source</b>	IFX	
<b>Error handling</b>	IOM_E_UNINIT, IOM_E_PARAM_LAM	
<b>Configuration dependencies</b>	-	
<b>User hints</b>	-	
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0	

**1.3.3.11 Iom\_GetLamConfig**
**Table 72 Specification for Iom\_GetLamConfig API**

<b>Syntax</b>	Iom_Lam_ConfigType Iom_GetLamConfig (const uint8 LamNo)	
<b>Service ID</b>	0x69	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Reentrant	
<b>ASIL Level</b>	QM	
<b>Parameters (in)</b>	LamNo	Lam unit number
<b>Parameters (out)</b>	-	
<b>Parameters (in-out)</b>	-	
<b>Return</b>	Iom_Lam_ConfigType	Definition for Iom_Lam_ConfigType
<b>Description</b>	This API provides service to get LAM configuration.	
<b>Source</b>	IFX	
<b>Error handling</b>	IOM_E_UNINIT, IOM_E_PARAM_LAM	

---

**IOM driver**
**Table 72 Specification for Iom\_GetLamConfig API (continued)**

<b>Configuration dependencies</b>	-
<b>User hints</b>	-
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0

**1.3.3.12 Iom\_SetLamThreshold**
**Table 73 Specification for Iom\_SetLamThreshold API**

<b>Syntax</b>	void Iom_SetLamThreshold( const uint8 LamNo, const uint32 ThresVal)	
<b>Service ID</b>	0x6A	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Reentrant	
<b>ASIL Level</b>	QM	
<b>Parameters (in)</b>	LamNo	LAM unit number
	ThresVal	The threshold value of the LAM unit
<b>Parameters (out)</b>	-	
<b>Parameters (in-out)</b>	-	
<b>Return</b>	void	-
<b>Description</b>	This API provides service to set the threshold value of the LAM unit.	
<b>Source</b>	IFX	
<b>Error handling</b>	IOM_E_UNINIT, IOM_E_PARAM_LAM, IOM_E_PARAM_THRES	
<b>Configuration dependencies</b>	-	
<b>User hints</b>	-	
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0	

**1.3.3.13 Iom\_GetLamThreshold**
**Table 74 Specification for Iom\_GetLamThreshold API**

<b>Syntax</b>	Iom_Lam_ThresType Iom_GetLamThreshold(const uint8 LamNo)	
<b>Service ID</b>	0x6B	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Reentrant	
<b>ASIL Level</b>	QM	
<b>Parameters (in)</b>	LamNo	LAM unit number
<b>Parameters (out)</b>	-	

**IOM driver**
**Table 74 Specification for Iom\_GetLamThreshold API (continued)**

<b>Parameters (in-out)</b>	-	
<b>Return</b>	Iom_Lam_ThresType	Indicates the threshold value of the Lam
<b>Description</b>	This service is provided to read and return the selected LAM unit threshold value.	
<b>Source</b>	IFX	
<b>Error handling</b>	IOM_E_UNINIT, IOM_E_PARAM_LAM	
<b>Configuration dependencies</b>	-	
<b>User hints</b>	-	
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0	

**1.3.3.14 Iom\_GetLamEntWinCount**
**Table 75 Specification for Iom\_GetLamEntWinCount API**

<b>Syntax</b>	Iom_Lam_CountType Iom_GetLamEntWinCount(const uint8 LamNo)	
<b>Service ID</b>	0x6C	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Non Reentrant	
<b>ASIL Level</b>	QM	
<b>Parameters (in)</b>	LamNo	LAM unit number
<b>Parameters (out)</b>	-	
<b>Parameters (in-out)</b>	-	
<b>Return</b>	Iom_Lam_CountType	Indicates the Count value of the Lam event
<b>Description</b>	This service is provided to read and return LAM unit event window count register value.	
<b>Source</b>	IFX	
<b>Error handling</b>	IOM_E_UNINIT, IOM_E_PARAM_LAM	
<b>Configuration dependencies</b>	-	
<b>User hints</b>	-	
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0	

**1.3.3.15 Iom\_SetEcmGlobalEveSel**
**Table 76 Specification for Iom\_SetEcmGlobalEveSel API**

<b>Syntax</b>	void Iom_SetEcmGlobalEveSel(const uint32 EventSel)
---------------	--

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**IOM driver**
**Table 76 Specification for Iom\_SetEcmGlobalEveSel API (continued)**

<b>Service ID</b>	0x6D	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Reentrant	
<b>ASIL Level</b>	QM	
<b>Parameters (in)</b>	EventSel	Value to change ECM global event selection register.
<b>Parameters (out)</b>	-	
<b>Parameters (in-out)</b>	-	
<b>Return</b>	void	-
<b>Description</b>	This service is provided to set/change ECM global event selection register.	
<b>Source</b>	IFX	
<b>Error handling</b>	IOM_E_UNINIT, IOM_E_PARAM_EVESEL	
<b>Configuration dependencies</b>	-	
<b>User hints</b>	-	
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0	

**1.3.3.16 Iom\_GetEcmGlobalEveSel**
**Table 77 Specification for Iom\_GetEcmGlobalEveSel API**

<b>Syntax</b>	Iom_Ecm_EveSelType Iom_GetEcmGlobalEveSel(void)	
<b>Service ID</b>	0x6E	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Reentrant	
<b>ASIL Level</b>	QM	
<b>Parameters (in)</b>	void	-
<b>Parameters (out)</b>	-	
<b>Parameters (in-out)</b>	-	
<b>Return</b>	Iom_Ecm_EveSelType	Indicates the value of the global event selection register.
<b>Description</b>		
<b>Source</b>	IFX	
<b>Error handling</b>	IOM_E_UNINIT	
<b>Configuration dependencies</b>	-	
<b>User hints</b>	-	

**IOM driver**
**Table 77 Specification for Iom\_GetEcmGlobalEveSel API (continued)**

<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0
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**1.3.3.17 Iom\_SetEcmThresVal**
**Table 78 Specification for Iom\_SetEcmThresVal API**

<b>Syntax</b>	void Iom_SetEcmThresVal(const uint8 CounterNo, const uint8 CountVal, const uint8 SelInput)	
<b>Service ID</b>	0x6F	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Reentrant	
<b>ASIL Level</b>	QM	
<b>Parameters (in)</b>	CounterNo	Counter number
	CountVal	The threshold value of the selected counter
	SelInput	LAM channel output is routed to counter
<b>Parameters (out)</b>	-	
<b>Parameters (in-out)</b>	-	
<b>Return</b>	void	
<b>Description</b>		
<b>Source</b>	IFX	
<b>Error handling</b>	IOM_E_UNINIT, IOM_E_PARAM_CNT, IOM_E_PARAM_THRES	
<b>Configuration dependencies</b>	-	
<b>User hints</b>	-	
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0	

**1.3.3.18 Iom\_GetEcmThresVal**
**Table 79 Specification for Iom\_GetEcmThresVal API**

<b>Syntax</b>	Iom_Ecm_ThresType Iom_GetEcmThresVal(const uint8 CounterNo)	
<b>Service ID</b>	0x70	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Reentrant	
<b>ASIL Level</b>	QM	
<b>Parameters (in)</b>	CounterNo	Counter number in Ecm
<b>Parameters (out)</b>	-	

---

**IOM driver**
**Table 79 Specification for Iom\_GetEcmThresVal API (continued)**

<b>Parameters (in-out)</b>	-	
<b>Return</b>	Iom_Ecm_ThresType	Indicates the threshold value of the counter in ECMs
<b>Description</b>	This service is provided to read and return threshold value of the selected ECM counter.	
<b>Source</b>	IFX	
<b>Error handling</b>	IOM_E_UNINIT, IOM_E_PARAM_CNT	
<b>Configuration dependencies</b>	-	
<b>User hints</b>	-	
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0	

**1.3.3.19 Iom\_GetEcmEveTrigHis**
**Table 80 Specification for Iom\_GetEcmEveTrigHis API**

<b>Syntax</b>	Iom_Ecm_EveHisType Iom_GetEcmEveTrigHis(const Iom_EventHistory EveHistory)	
<b>Service ID</b>	0x71	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Reentrant	
<b>ASIL Level</b>	QM	
<b>Parameters (in)</b>	EveHistory	Event trigger history recorded in ETA, ETB,ETC and ETD
<b>Parameters (out)</b>	-	
<b>Parameters (in-out)</b>	-	
<b>Return</b>	Iom_Ecm_EveHisType	Ecm event trigger history
<b>Description</b>	This service is provided to read and return the ECM event trigger history.	
<b>Source</b>	IFX	
<b>Error handling</b>	IOM_E_UNINIT, IOM_E_PARAM_EVEHSTRY	
<b>Configuration dependencies</b>	-	
<b>User hints</b>	-	
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0	

**1.3.3.20 Iom\_ClrEcmStatusHistory**
**Table 81 Specification for Iom\_ClrEcmStatusHistory API**

<b>Syntax</b>	void Iom_ClrEcmStatusHistory(void)
---------------	------------------------------------

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**IOM driver**
**Table 81 Specification for Iom\_ClrEcmStatusHistory API (continued)**

<b>Service ID</b>	0x72	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Reentrant	
<b>ASIL Level</b>	QM	
<b>Parameters (in)</b>	void	-
<b>Parameters (out)</b>	-	
<b>Parameters (in-out)</b>	-	
<b>Return</b>	void	-
<b>Description</b>	This service will reset the ECM event trigger status history.	
<b>Source</b>	IFX	
<b>Error handling</b>	IOM_E_UNINIT	
<b>Configuration dependencies</b>	-	
<b>User hints</b>	-	
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0	

**1.3.3.21 Iom\_GetVersionInfo**
**Table 82 Specification for Iom\_GetVersionInfo API**

<b>Syntax</b>	void Iom_GetVersionInfo (Std_VersionInfoType * const versioninfo)	
<b>Service ID</b>	0x73	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Non Reentrant	
<b>ASIL Level</b>	QM	
<b>Parameters (in)</b>	versioninfo	Pointer to where to store the version information of the IOM driver
<b>Parameters (out)</b>	-	
<b>Parameters (in-out)</b>	-	
<b>Return</b>	void	-
<b>Description</b>	API returns the version information of the IOM module.  <i>Note: This API is available only when IomVersionInfoApi is configured as true.</i>	
<b>Source</b>	IFX	
<b>Error handling</b>	IOM_E_PARAM_INVALID	
<b>Configuration dependencies</b>	IomVersionInfoApi	

## IOM driver

**Table 82**      **Specification for Iom\_GetVersionInfo API (continued)**

<b>User hints</b>	-
<b>Autosar Version</b>	Applicable for Autosar versions 4.2.2 and 4.4.0

### 1.3.4      Notifications and callbacks

The IOM driver does not provide any notifications and callbacks.

### 1.3.5      Scheduled functions

The IOM driver does not provide any scheduled functions.

### 1.3.6      Interrupt service routines

The IOM driver does not provide any interrupt handlers.

### 1.3.7      Callout

The IOM driver does not provide any callout.

### 1.3.8      Error Handling

This section describes the various errors reported by the IOM driver.

<b>Error Name: Description</b>	<b>Source</b>	<b>Error ID</b>	<b>Type</b>
<b>IOM_E_UNINIT:</b> An API called before invocation of Iom_Init.	IFX	0x11	DET
<b>IOM_E_INIT:</b> API Iom_Init service called while the IOM a driver has already been initialized.	IFX	0x10	DET
<b>IOM_E_PARAM_CONFIG:</b> The error is reported if API is invoked with a null pointer.	IFX	0x12	DET
<b>IOM_E_PARAM_INVALID:</b> The error is reported if API is invoked with null-pointer as a parameter.	IFX	0x13	DET
<b>IOM_E_PARAM_FPC:</b> The error is reported if API is invoked with wrong FPC number.	IFX	0x14	DET
<b>IOM_E_PARAM_LAM:</b> The error is reported if API is invoked with wrong LAM number.	IFX	0x15	DET



**IOM driver**

<b>Error Name: Description</b>	<b>Source</b>	<b>Error ID</b>	<b>Type</b>
<b>IOM_E_PARAM_EDGE:</b> The error is reported if API is invoked with wrong edge number.	IFX	0x16	DET
<b>IOM_E_PARAM_THRES:</b> The error is reported if API is invoked with an invalid threshold value.	IFX	0x17	DET
<b>IOM_E_PARAM_EVESEL:</b> The error is reported if API is invoked with invalid global event selection value.	IFX	0x18	DET
<b>IOM_E_PARAM_CNT:</b> The error is reported if API is invoked with the invalid counter value.	IFX	0x19	DET
<b>IOM_E_PARAM_CHNLSEL</b> : The error is reported if API is invoked with invalid channel select value.	IFX	0x20	DET
<b>IOM_E_PARAM_EVEHSTR Y:</b> The error is reported if API is invoked with invalid event history value.	IFX	0x21	DET
<b>IOM_E_CLC_ENABLE_ERR</b> : This error is reported when enabling of CLC (module clock) fails.	IFX	Assigned by DEM	DEM

### 1.3.9 Deviations and limitations

This section describes deviations and limitations of the IOM driver.

#### 1.3.9.1 Deviations

This section describes the deviations of the IOM driver.

##### 1.3.9.1.1 Software specification deviations

The IOM driver does not have any deviations.

##### 1.3.9.1.2 AMDC Violations

The IOM driver does not have any AMDC violations.

## Revision history

### 1.3.9.1.3 VSMD Violations

The IOM driver does not have any VSMD violations.

### 1.3.9.2 Limitations

The IOM driver does not have any limitations.

## Revision history

Major changes since the last revision

Date	Version	Description
2021-03-23	3.0	Document is released
2021-03-23	2.1	<ul style="list-style-type: none"> <li>Updated the filename from Iom_PBCfg.h to Iom_PBcfg.h in Table 2 C file structure</li> <li>Updated the filename from Iom_PBCfg.c to Iom_PBcfg.c in Table 2 C file structure</li> </ul>
2020-11-18	2.0	Document is released
2020-11-06	1.1	<ul style="list-style-type: none"> <li>Error handling format of all the APIs updated in Functions – APIs section</li> <li>Reference to Dem_SetEventStatus API for AUTOSAR 4.4.0 added in section DEM under Integration with AUTOSAR stack</li> <li>Autosar Version applicability information added in Configuration interfaces, Functions - Type definitions and Functions – APIs sections</li> <li>User hints added for all the APIs in Functions – APIs section</li> <li>Error Handling section format modified by consolidating all the errors to a single table</li> <li>Deviations and limitations section format updated</li> </ul>
2020-08-13	1.0	Document is released
2020-08-10	0.1	<ul style="list-style-type: none"> <li>Initial version</li> <li>IOM driver chapter moved from TC3xx_SW_MCAL_UM_DEMO to this document</li> </ul>

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