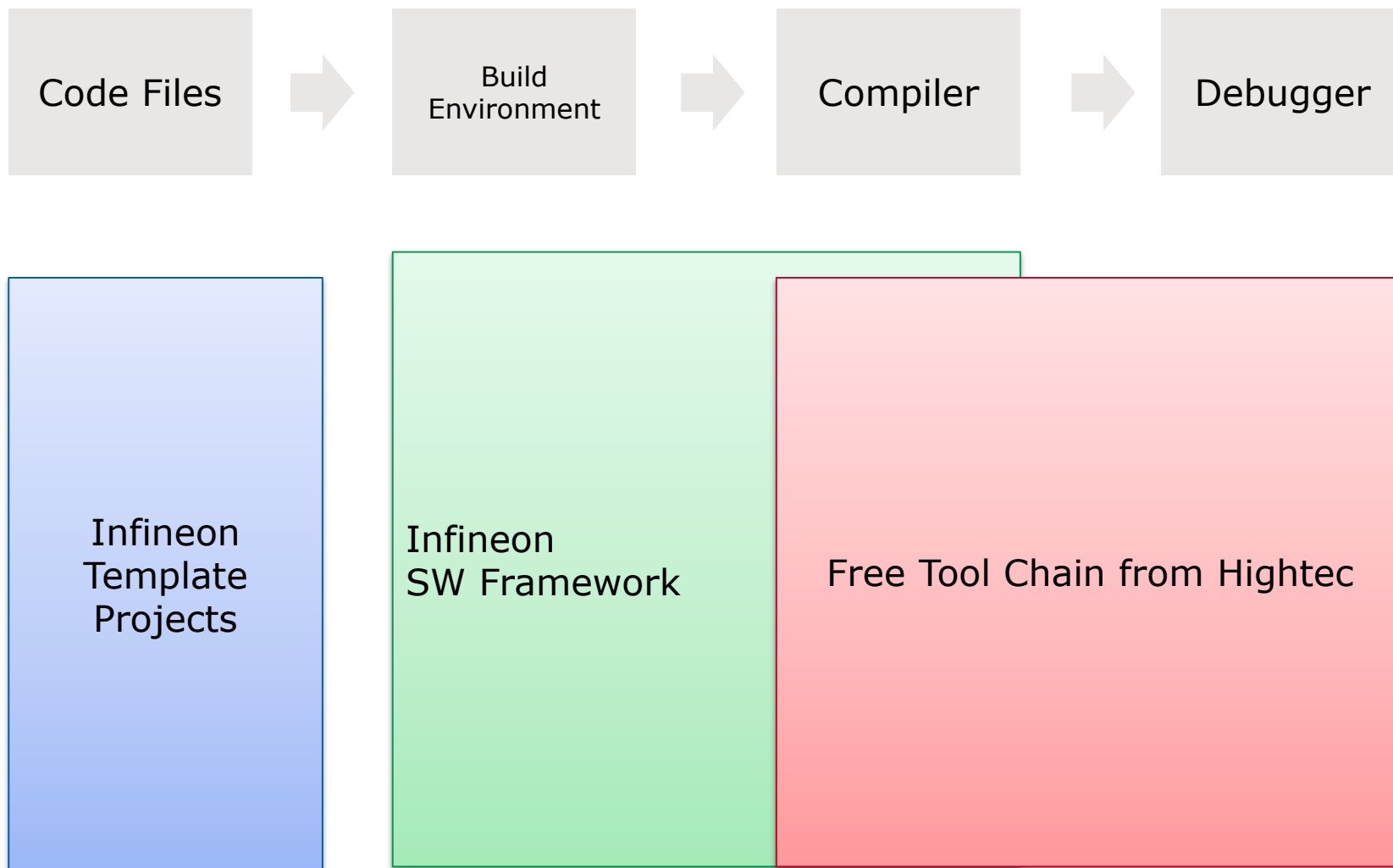


AURIX 2G Hands-on – First Blinky

IFCN ATV SMD GC SAE MC



Tool Overview for Handson



Hightec Free Entry Toolchain

- › GNU Compiler 4.9.1.0
- › PLS Debugger (UDE Desktop)
- › Hightec Eclipse IDE
- › Example Project

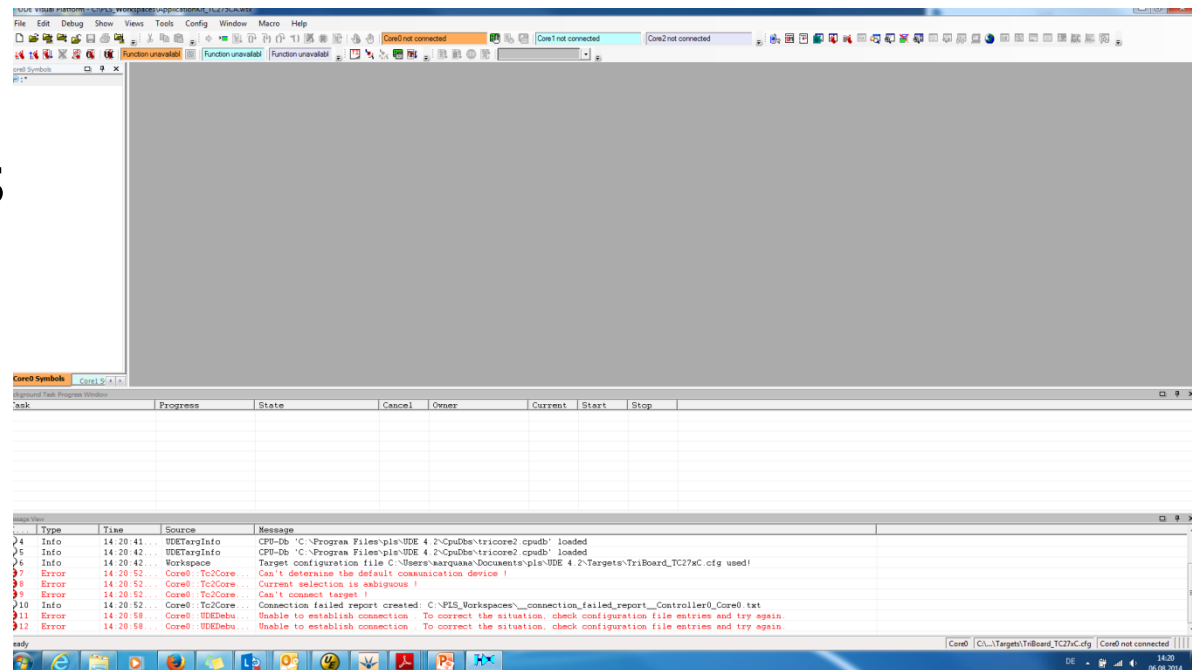
Free TriCore™ Entry Tool Chain

The easiest way to start with a TriBoard.

Version 4.6.2.1 (with TC275C Support)

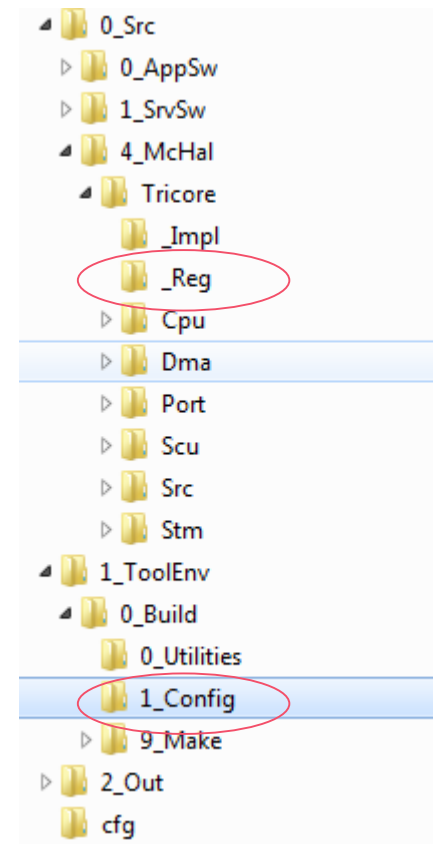


- › We will use
 - Debugger from PLS
 - GNU compiler





Infineon SW Framework

- › Build Environment for quick start
- › Supports three compilers (Hightec, Tasking, Windriver)
- › **Eclipse** or Command Line based compiling
- › Provides SW Templates for each derivative
 - Special Function Registers
 - Map Files
 - Startup
 - Basic Drivers
 - Main.c for every core



Start Eclipse

- › Start Eclipse with StartFw.bat
 - Otherwise you will see errors while compiling because environment variables are not set correctly

	StartFw	10.07.2014 09:59	Windows Batch File	1 KB
	StartFwDos	10.07.2014 13:44	Windows Batch File	1 KB

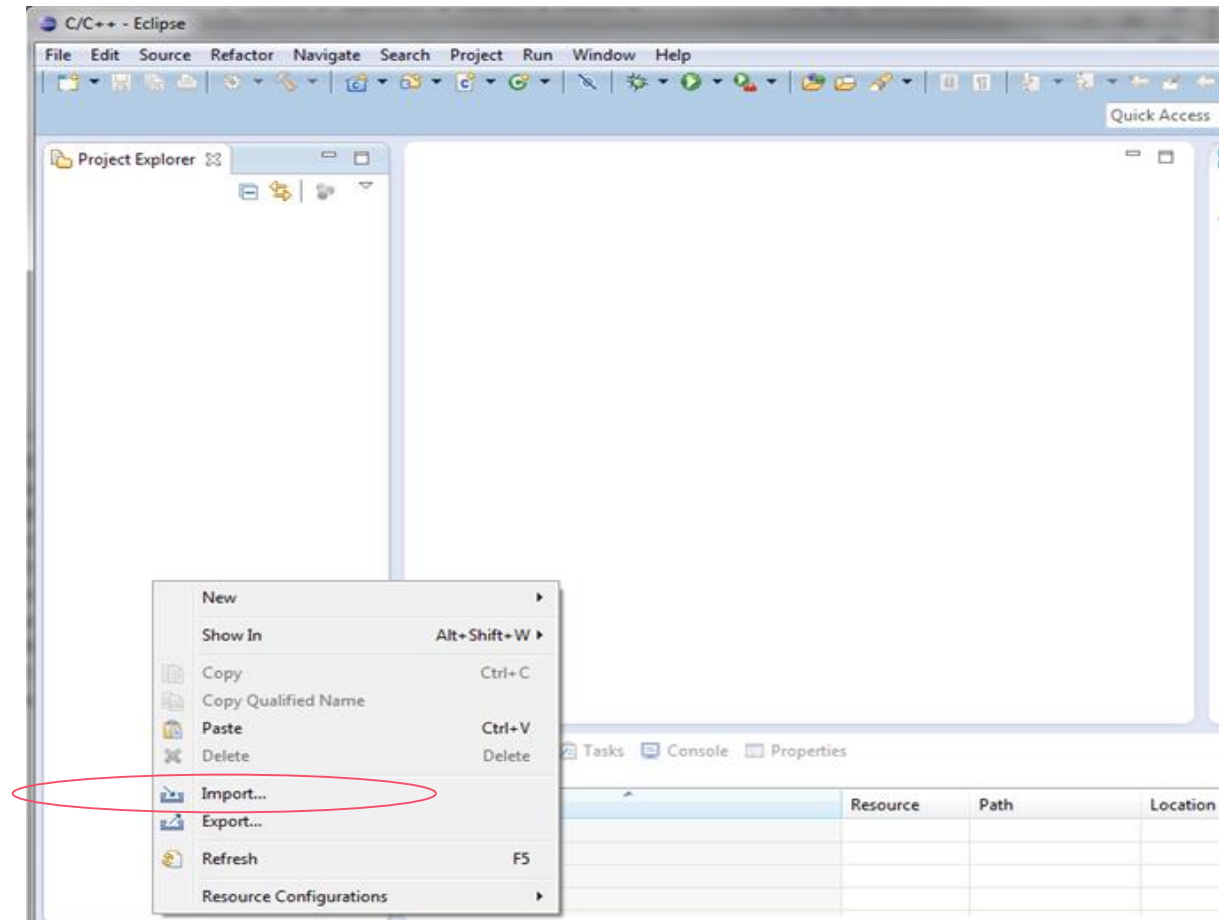
- It should look like this:



- If you want to use a different Editor you can also use StartFwDos.bat to open a terminal window
- Type make and hit enter to compile in that case

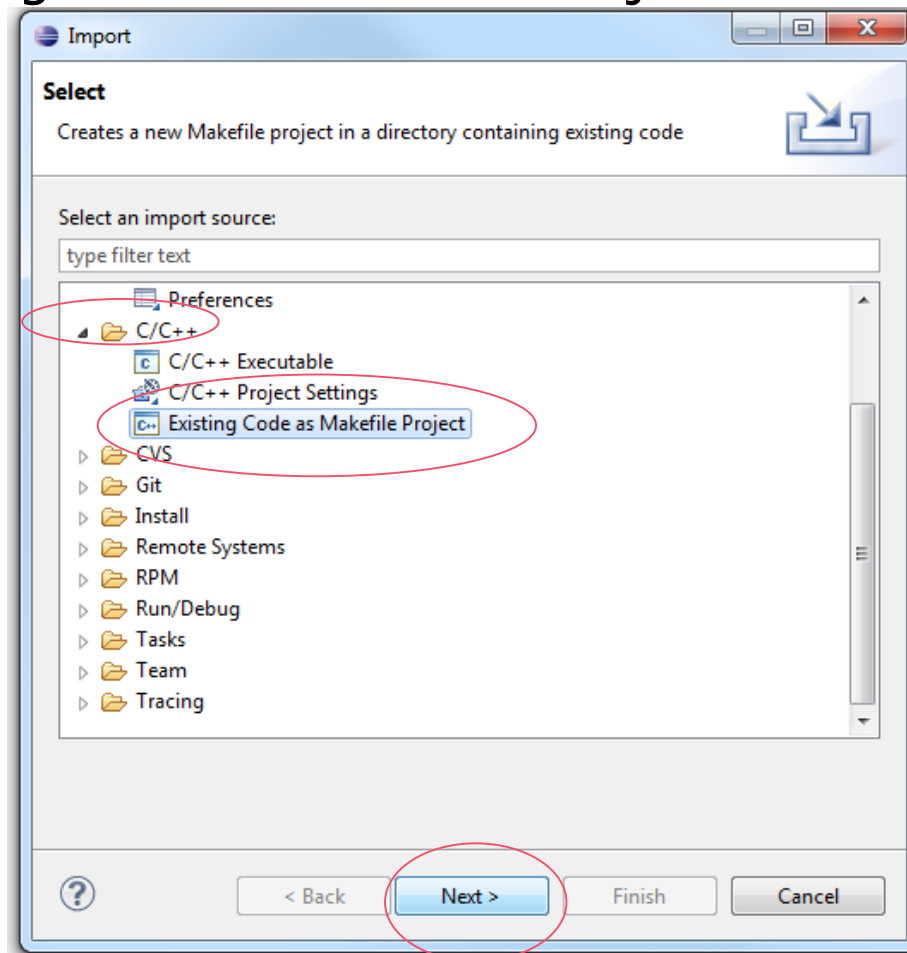
Add a project

- › Right click into the free white space on the left
- › Select Import



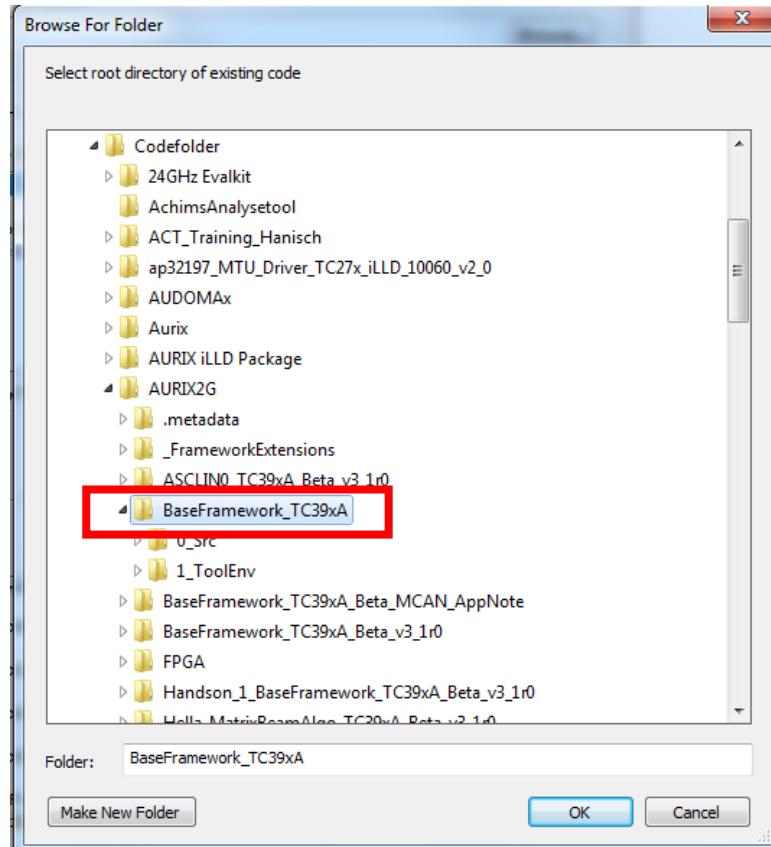
Add a project

- › Select C\C++
- › Select Existing Code as Makefile Project
- › Next...



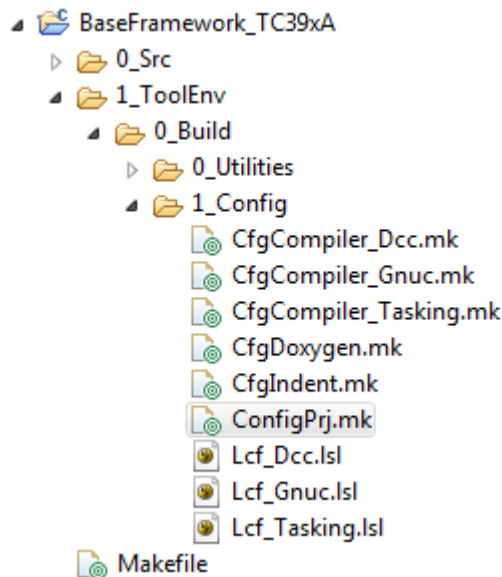
Add a project

- › Click „Browse“
- › Select the template project for the TC39x (you specified the path to the template projects during the installation).
- › OK...



Configure the Compile Environment of the Project

- › Open the Configuration folder for the Tool Environment



- › Open ConfigPrj.mk
- › Select GNU compiler by commenting/uncommenting the correct lines (GNU is default)

```
#Configure the tool chain for each core type
#TOOL_CHAIN_MAIN:=Tasking
TOOL_CHAIN_MAIN:=Gnuc
#TOOL_CHAIN_MAIN:=Dcc
```

Configure the Compile Environment of the Project



- › Open CfgCompilerGNUUC.mk
- › Set TOOLCHAIN_DIR_MAIN to the path where you installed the Hightec Free Entry Toolchain

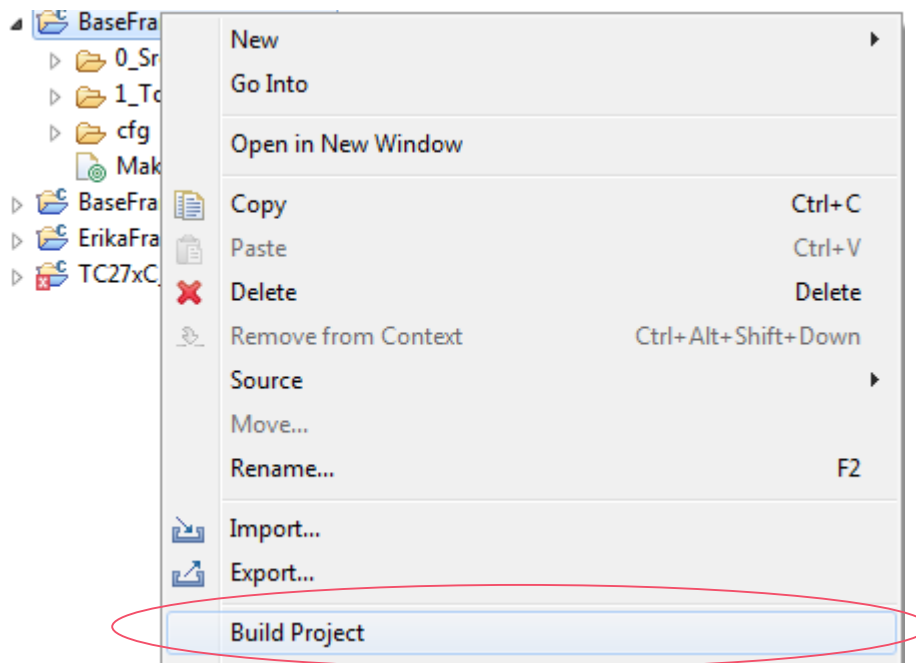
SystemDisk (C:) ▶ HIGHTEC ▶ toolchains ▶ tricore ▶ v4.9.1.0-infineon-1.1 ▶

```
L
2 #Start##### Configuration for MAIN Core #####
3
4 TOOLCHAIN_DIR_MAIN:=C:\HIGHTEC\toolchains\tricore\v4.9.1.0-infineon-1.1
```

- › Save the file

Compile the Project

- › Right-click on the Project Name in the Project Explorer
- › Select „Build Project“

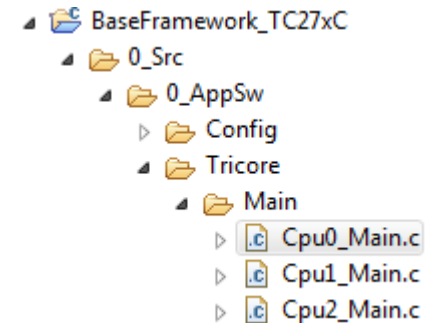
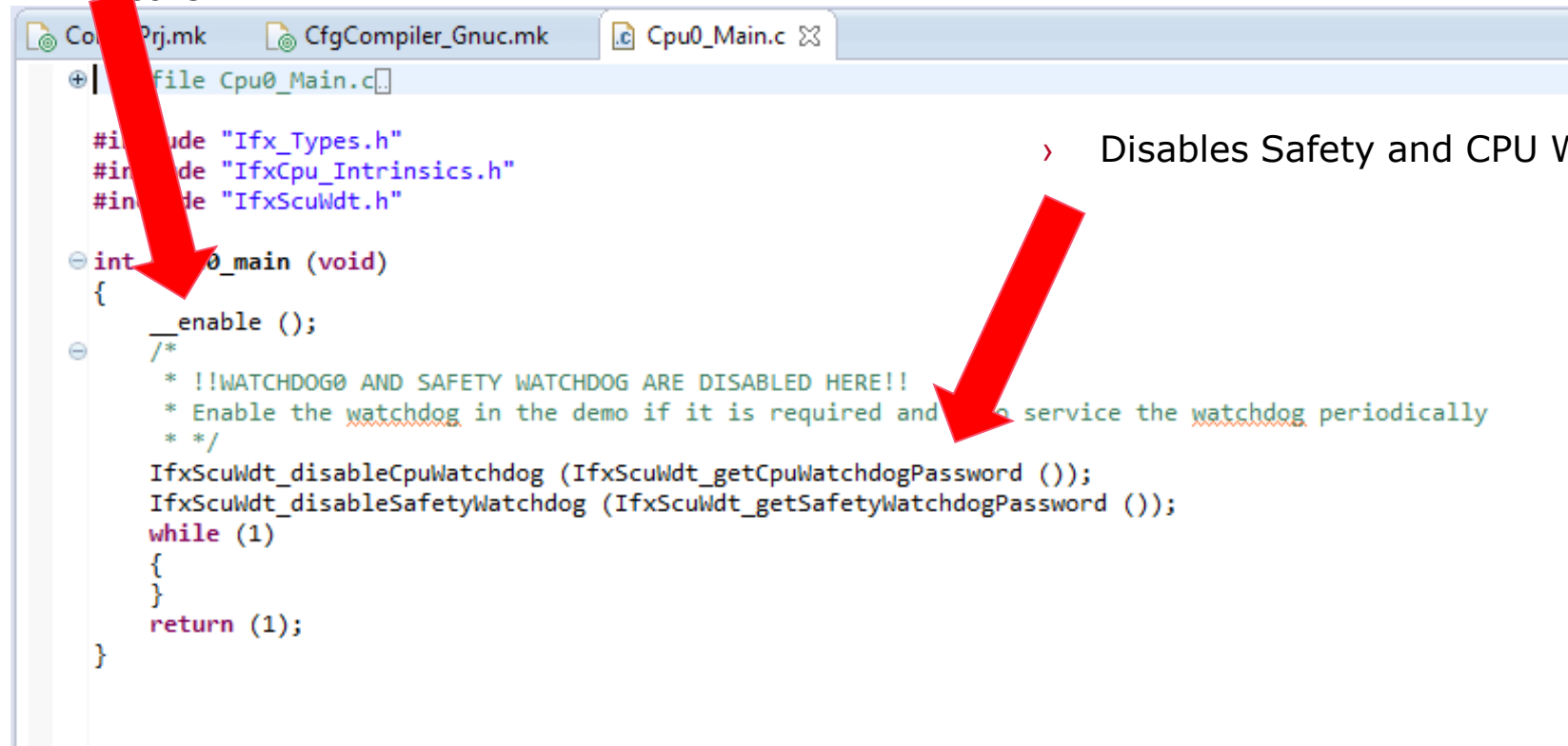


Hello LED with AURIX 2G

> Open Source File Cpu0_Main.c

>

> Used to enable interrupts for this core

```

file Cpu0_Main.c
#include "Ifx_Types.h"
#include "IfxCpu_Intrinsics.h"
#include "IfxScuWdt.h"

int _0_main (void)
{
    __enable ();

    /*
     * !!WATCHDOG0 AND SAFETY WATCHDOG ARE DISABLED HERE!!
     * Enable the watchdog in the demo if it is required and to service the watchdog periodically
     */
    IfxScuWdt_disableCpuWatchdog (IfxScuWdt_getCpuWatchdogPassword ());
    IfxScuWdt_disableSafetyWatchdog (IfxScuWdt_getSafetyWatchdogPassword ());
    while (1)
    {
    }
    return (1);
}
    
```

> Disables Safety and CPU Watchdogs

CPU and Safety Watchdogs

- › Each CPU has one dedicated Watchdog timer
- › Additionally there is a Safety Watchdog
 - Timeout Watchdog
 - Protection of important registers
 - ENDINIT Protection
- › Correct access to protected registers (also in case of disabled watchdogs)
 - Clear corresponding ENDINIT Bit
 - Access Register
 - Set corresponding ENDINIT Bit
- › **EACH step is MANDATORY / Wrong access will end in Reset**

Use routines provided by IFX in IfxScuWdt.h



Toggle LED – Port Operation

- › Input/Output defined by
 - IOCR
- › Output
 - Pin state can be modified
 - OMSR
 - OMCR
 - OMR
 - OUT
 - One Internal HW-unit at a time
- › Input
 - Input signal can be used by multiple peripherals

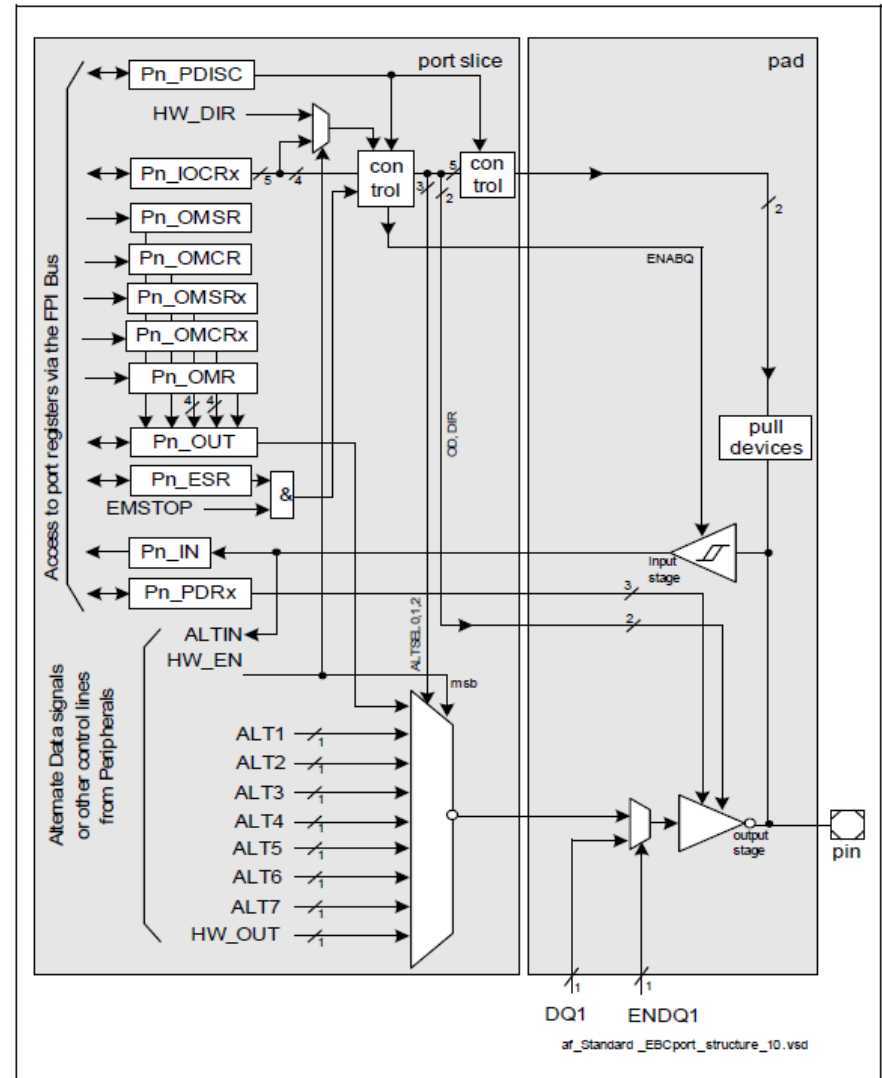


Figure 14-1 General Structure of a Port Pin

Toggle LED – What to do

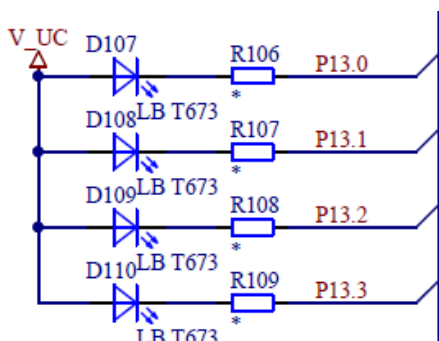
- › We select P33.4
- › Applicationboard see below
- › Configure the pin as an output
 - configure the bit field P33_IOCRA.B.PC4 to 0x10

0XX10_B

Input pull-up device connected¹⁾



10000 _B	Output	Push-pull	General-purpose output
10001 _B			Alternate output function 1
10010 _B			Alternate output function 2
10011 _B			Alternate output function 3



Pn_IOCRA (n=33-34)

Port n Input/Output Control Register 0

(F003 B210_H + n*100_H)

Reset Value: 1010 1010_H

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
PC3				0				PC2				0			
rw				r				rw				r			
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
PC1				0				PC0				0			
rw				r				rw				r			

Field	Bits	Type	Description
PC0, PC1, PC2, PC3	[7:3], [15:11], [23:19], [31:27]	rw	Port Control for Port n Pin 0 to 3 This bit field determines the Port n line x functionality (x = 0-3) according to the coding table (see Table 14-5).

Accessing Registers and bit Fields

- › Add `#include „Ifx_reg.h“`
 - Adds all the register definition headers of the Template project
- › Each Register is defined with `<Modulname>_<Registername>` as a Union with 32 bit access (.U) and bit field access (.B.)
- › Two lines can have the same effect:
 - › `P33_IOC4.U = (0x10 << 0); //Configure Pin 4 of Port 33 as output`
 - › `P33_IOC4.B.PC4 = 0x10; //Configure Pin 4 of Port 33 as output`

Toggle LED – What to do

› AURIX provides a simple way to toggle a pin

– Output Modification Register

– Reset

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
PCL	PCL	PCL	PCL	PCL	PCL	PCL	PCL	PCL	PCL	PCL	PCL	PCL	PCL	PCL	PCL
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
W	W	W	W	W	W	W	W	W	W	W	W	W	W	W	W

– Set

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
PS	PS	PS	PS	PS	PS	PS	PS	PS	PS	PS	PS	PS	PS	PS	PS
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
W	W	W	W	W	W	W	W	W	W	W	W	W	W	W	W

– Both -> Toggle

› `P33_OMR.U |= (0x1 << 4) | (0x1 << 20);`

Status Check

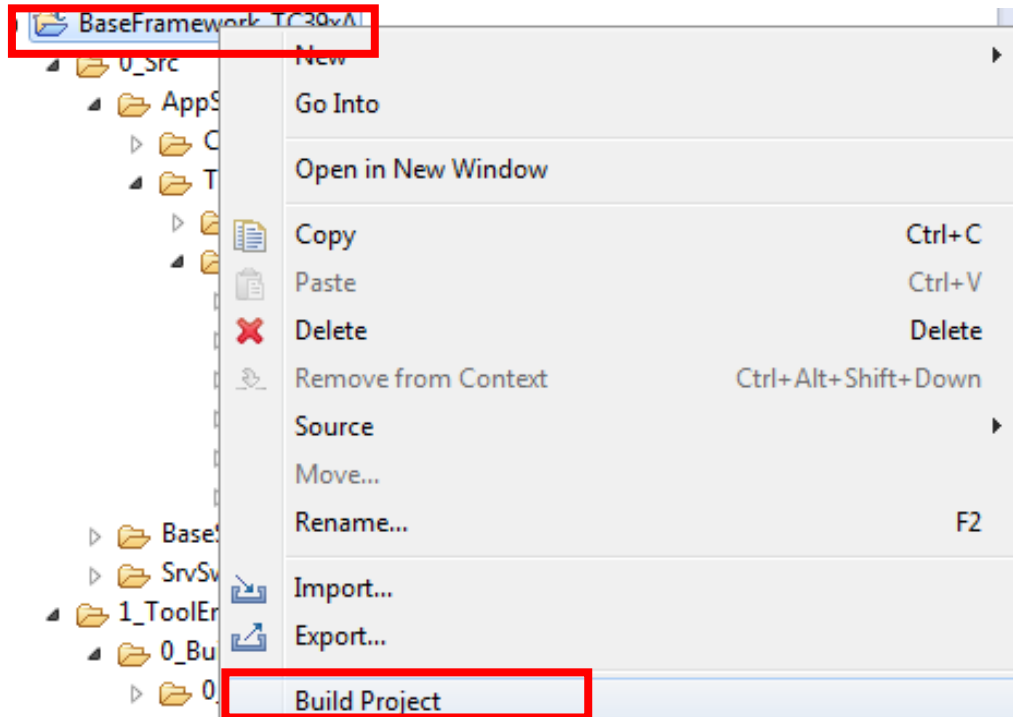
```

⊕ * \file Cpu0_Main.c
:
: #include "Ifx_Types.h"
: #include "IfxCpu.h"
: #include "IfxScuWdt.h"
:
: IfxCpu_syncEvent cpuSyncEvent=0;
:
: int core0_main (void)
: {
:     IfxCpu_enableInterrupts();
:     /*
:     * !!WATCHDOG0 AND SAFETY WATCHDOG ARE DISABLED HERE!!
:     * Enable the watchdog in the demo if it is required and also service the watchdog periodically
:     */
:     IfxScuWdt_disableCpuWatchdog (IfxScuWdt_getCpuWatchdogPassword ());
:     IfxScuWdt_disableSafetyWatchdog (IfxScuWdt_getSafetyWatchdogPassword ());
:
:     /* Cpu sync event wait*/
:     IfxCpu_emitEvent(&cpuSyncEvent);
:     IfxCpu_waitEvent(&cpuSyncEvent, 1);
:
:     while (1)
:     {
:         P33_IOC4.B.PC4 = 0x10;
:     }
:     return (1);
: }

```

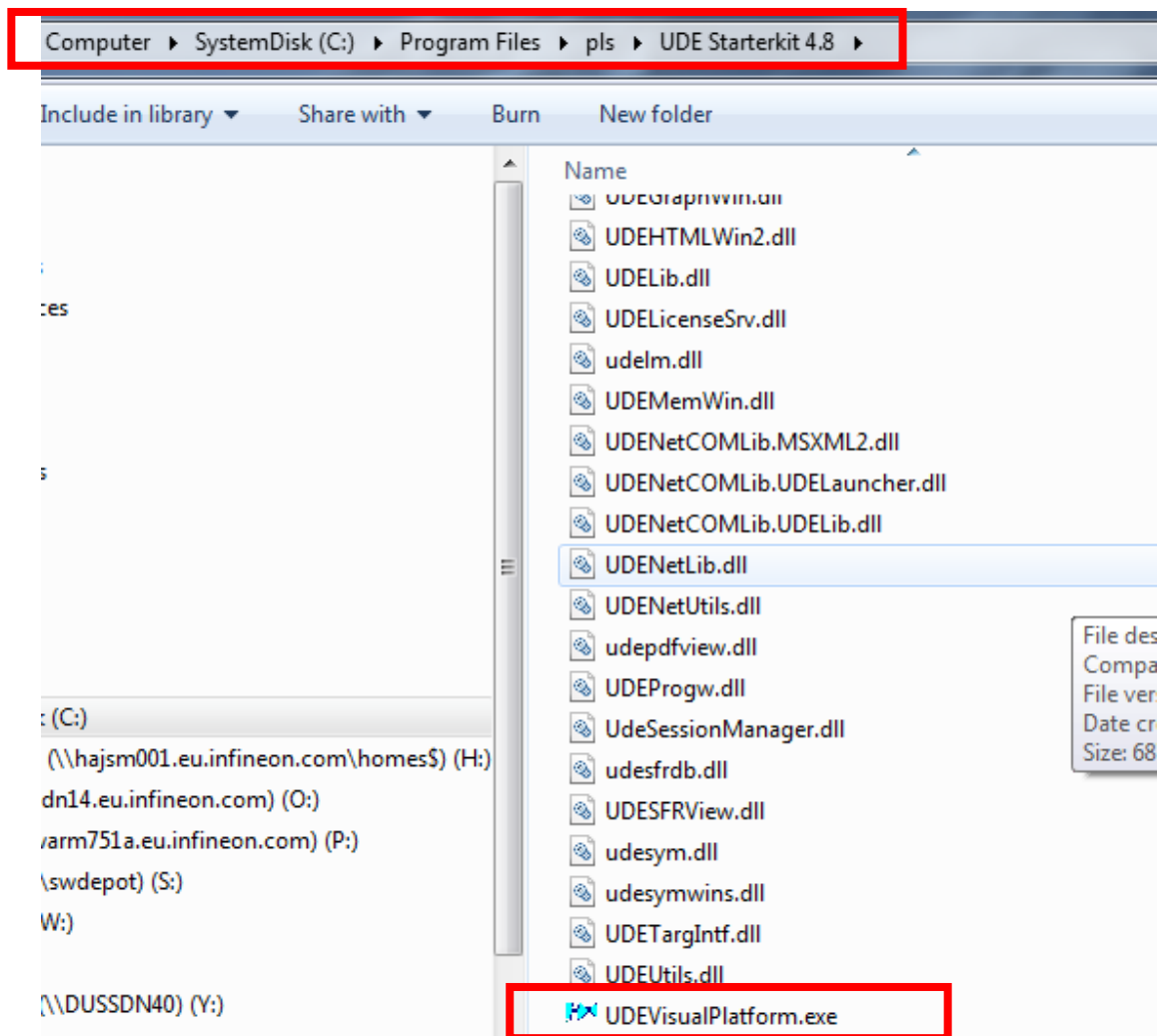
Compile the Project

- Right click on project name and select „Build Project“



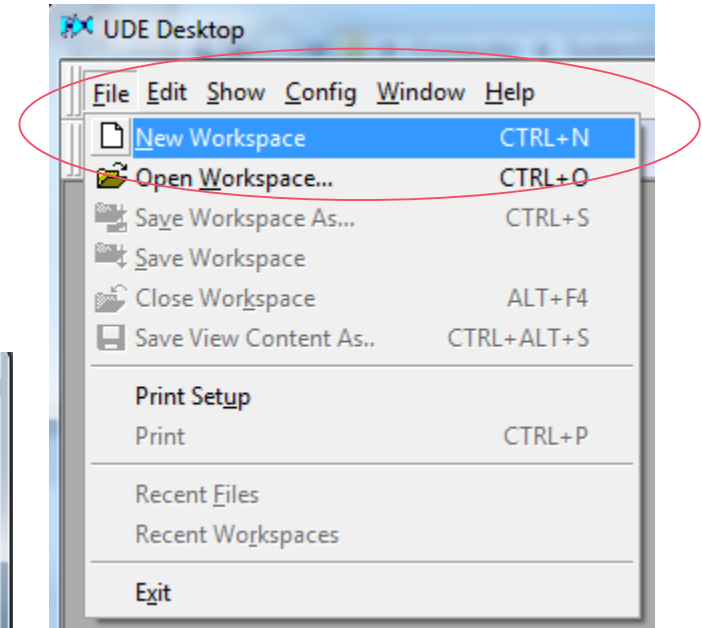
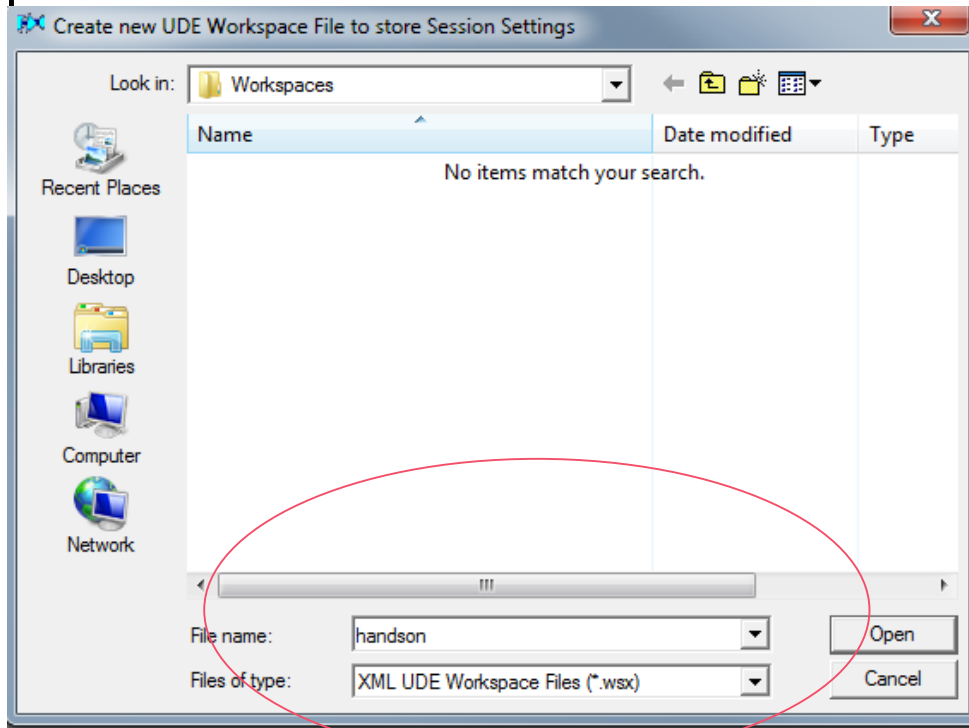
Debug the Project

› Open UdeVisualPlatform.exe



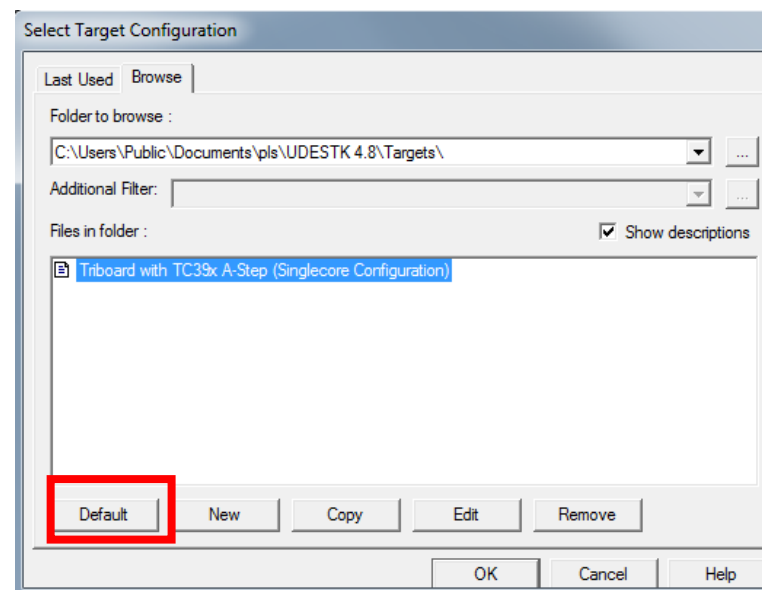
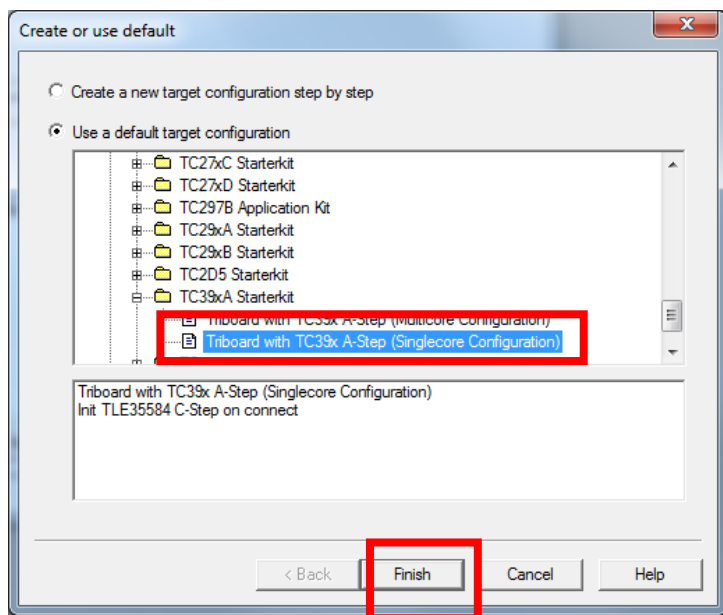
Create new Debug Workspace

- › Select „File“
- › Select „New Workspace“
- › Create a name
- › Open...



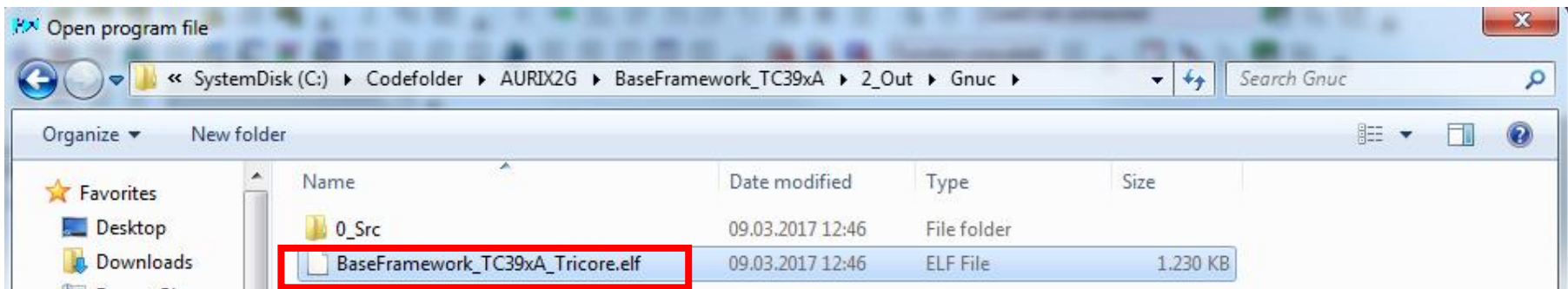
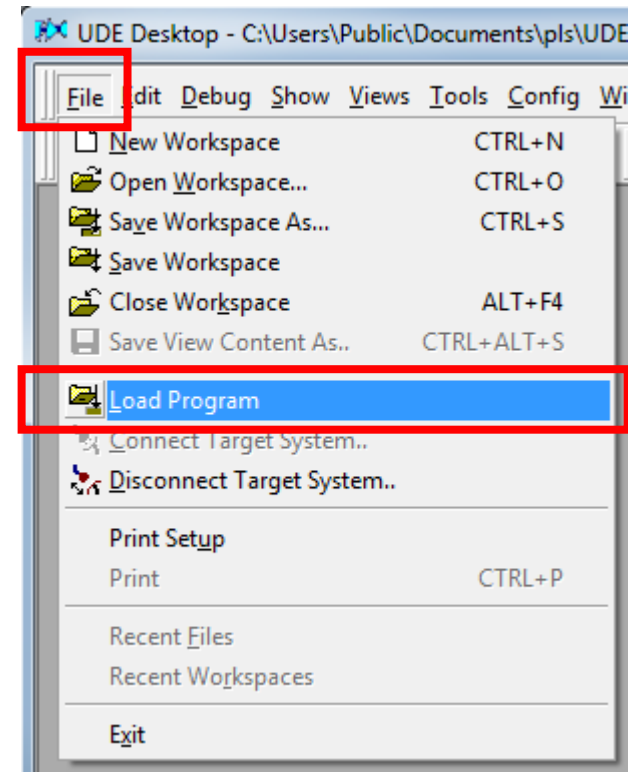
Select correct Target

- › Click **Default**
- › Select **Triboard with TC39x A-step**
- › Click **Ok**
- › Save it anywhere

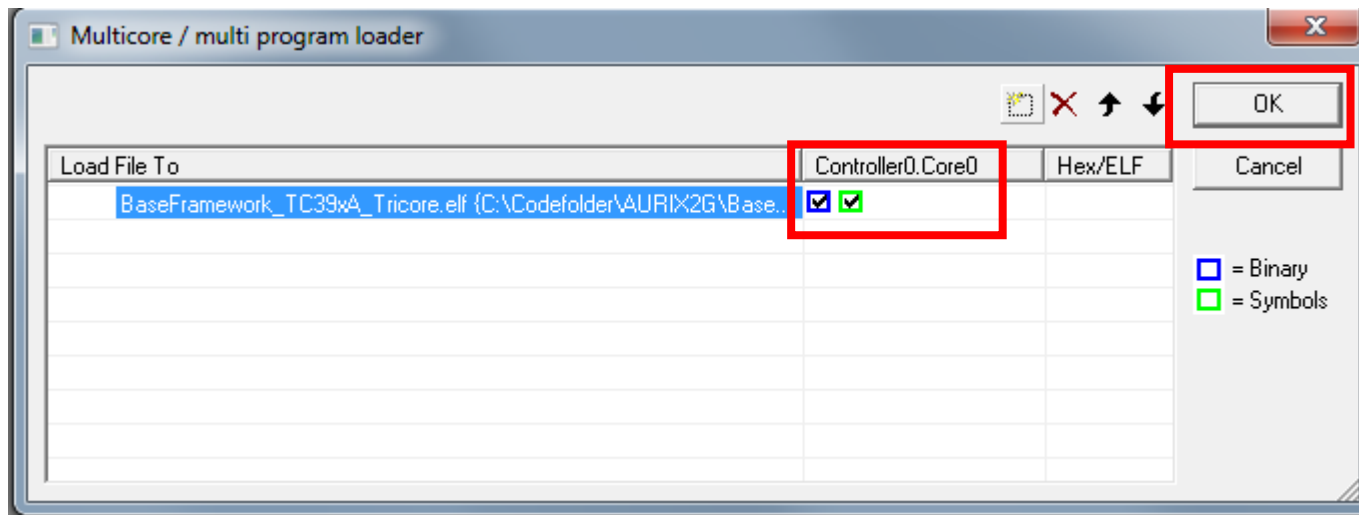


Load the program

- › Click File->Load Program
- › Navigate to your project folder
 - 2_Out\Gnuc
- › Select the .elf file
- › Open...



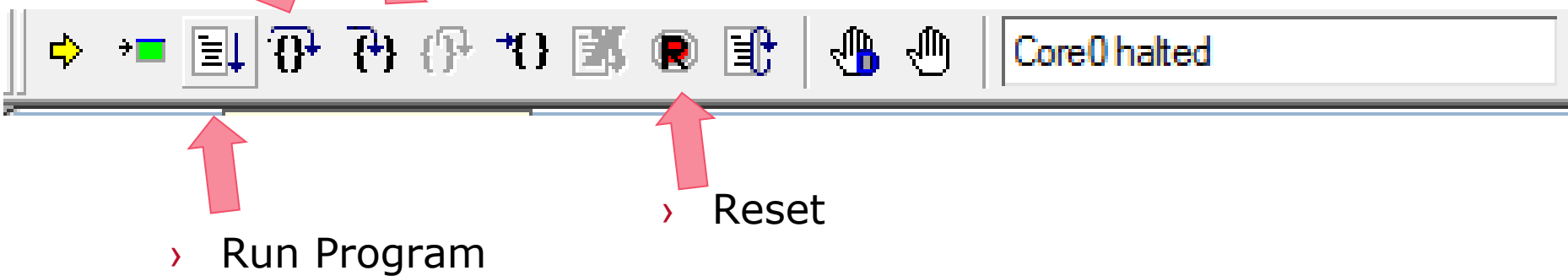
Program the device



- › Select „Program“
- › You should see a success message on the bottom

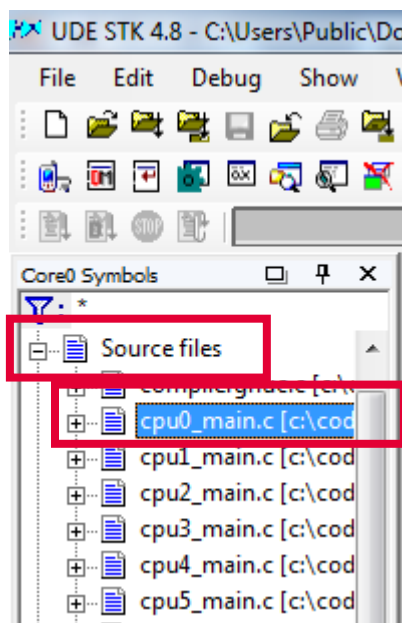
Message View				
I...	Type	Time	Source	Message
19	Info	09:08:42...	Core0::UDEMemtool	DF_EEPROM: Normal sensing mode detected
20	Info	09:08:42...	Core0::UDEMemtool	DF1: Normal sensing mode detected
21	Success	09:08:42...	Core0::UDEDebu...	Connection to TC39xA target established: TriCore (Core0). ID: 10205083h
22	Warning	09:08:48...	Core0::Tc2Core...	Write access to memory range 0xAF400000-0xAF405FFF refused !
23	Warning	09:08:49...	Core0::UDEDebu...	CRC check after download failed in memory range from AF400000H to AF4017F3H!
24	Success	09:08:49...	Core0::UDEDebu...	Program with ID 0x1 - code size 16910 bytes - was loaded!
25	Info	09:08:54...	Core0::UDEMemtool	Programming with special feature handling ...
26	Success	09:08:54...	Core0::PFLASH0	Program sections succeeded

Debug the Project



Open Cpu0_Main.c

- › On the left side chose „Source files“ and then cpu0_main.c
- › Double-click on cpu0_main.c to open it



```
int core0_main (void)
{
    IfxCpu_enableInterrupts();
    /*
     * !!WATCHDOG0 AND SAFETY WATCHDOG ARE DISABLED HERE!!
     * Enable the watchdog in the demo if it is required and also service the
     * */
    IfxScuWdt_disableCpuWatchdog (IfxScuWdt_getCpuWatchdogPassword ());
    IfxScuWdt_disableSafetyWatchdog (IfxScuWdt_getSafetyWatchdogPassword ());

    /* Cpu sync event wait*/
    IfxCpu_emitEvent(&cpuSyncEvent);
    IfxCpu_waitEvent(&cpuSyncEvent, 1);

    while (1)
    {
        P33_IOC4.B.PC4 = 0x10;
    }
    return (1);
}
```

Place Breakpoint

- › Place a breakpoint in the line toggling the LED pin
- › Let the program run
- › You see it stopping and the LED toggles each time the program is run

```
#include "Ifx_Types.h"
#include "IfxCpu.h"
#include "IfxScuWdt.h"

IfxCpu_syncEvent cpuSyncEvent=0;

int core0_main (void)
{
    IfxCpu_enableInterrupts();
    /*
     * !!WATCHDOG0 AND SAFETY WATCHDOG ARE DISABLED HERE!!
     * Enable the watchdog in the demo if it is required and also service the
     * */
    IfxScuWdt_disableCpuWatchdog (IfxScuWdt_getCpuWatchdogPassword ());
    IfxScuWdt_disableSafetyWatchdog (IfxScuWdt_getSafetyWatchdogPassword ());

    /* Cpu sync event wait*/
    IfxCpu_emitEvent(&cpuSyncEvent);
    IfxCpu_waitEvent(&cpuSyncEvent, 1);

    while (1)
    {
        P33_IOC4.B.PC4 = 0x10;
    }
    return (1);
}
```





Part of your life. Part of tomorrow.

