OpenCV Installation

opency installation can be done in 2 ways

- conda install -c conda-forge opency
- pip install opency-python (if you want to install using pip)

```
In [1]: import cv2 import numpy as np
```

Load/Read image

```
In [2]: # Load an image using 'imread' specifying the path to image
img = cv2.imread('image_examples/Modi.jpg')
# Our 'input.jpg' is now Loaded and stored in python as a varaible we named 'img
```

Let's take a closer look at how images are stored

```
In [3]: print(img)
```

Shape gives the dimensions of the image array

```
In [4]: img.shape
    #The 3D dimensions are 1358 pixels in height * 1500 pixels wide
    #3 means that there are 3 components (RGB) that make up this image

Out[4]: (1358, 1500, 3)

In [5]: int(img.shape[0]) # height

Out[5]: 1358

In [6]: int(img.shape[1]) # width

Out[6]: 1500
```

Display the image

```
In [7]: # To display our image variable, we use 'imshow'
# The first parameter will be title shown on image window
# The second parameter is the image variable
cv2.imshow('PM', img)

# 'waitKey' allows us to input information when a image window is open
# By Leaving it blank it just waits for anykey to be pressed before continuing.
# By placing numbers (except 0), we can specify a delay for
# how long you keep the window open (time is in milliseconds here)
cv2.waitKey()

# This closes all open windows
# Failure to place this will cause your program to hang
cv2.destroyAllWindows()
```

Save image

Resize Image

```
In [10]: img = cv2.imread('image_examples/Modi.jpg')
    resized_image = cv2.resize(img,(500,500))
    cv2.imshow('Modi Image', resized_image)
    cv2.waitKey()
    cv2.destroyAllWindows()
```

Face Detection using HAAR Cascade Classifiers

```
In [11]: # We point OpenCV's CascadeClassifier function to where our classifier (XML file
         face_classifier = cv2.CascadeClassifier('Haarcascades/haarcascade_frontalface_def
         # Load our image then convert it to grayscale
         image = cv2.imread('image_examples/Modi.jpg')
         image = cv2.resize(img,(500,500))
         gray = cv2.cvtColor(image, cv2.COLOR_BGR2GRAY)
         ### Tuning Cascade Classifiers - detectMultiScale(input image, **Scale Factor**
         faces = face_classifier.detectMultiScale(gray, 1.05, 5)
         # Scale Factor - Specifies how much we reduce the image size each time we scale.
         # E.g. in face detection we typically use 1.3. This means we reduce the image by
         # Smaller values, like 1.05 will take longer to compute, but will increase the rd
         ## Min Neighbors**
         # Specifies the number of neighbors each potential window should have in order to
         # Typically set between 3-6.
         # It acts as sensitivity setting, low values will sometimes detect multiples face
         # High values will ensure less false positives, but you may miss some faces.
```

In [12]: print(faces)

[[205 79 217 217]]

```
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         # Typically set between 3-6.
         # It acts as sensitivity setting, low values will sometimes detect multiples face
         # High values will ensure less false positives, but you may miss some faces.
         # When no faces detected, face classifier returns and empty tuple
         if faces is ():
             print("No faces found")
         # We iterate through our faces array and draw a rectangle
         # over each face in faces
         for (x,y,w,h) in faces:
             cv2.rectangle(image, (x,y), (x+w,y+h), (255,255,15), 2)
         cv2.imshow('Face Detection', image)
         cv2.waitKey()
         cv2.destroyAllWindows()
         <>:23: SyntaxWarning: "is" with a literal. Did you mean "=="?
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         <ipython-input-13-590732366d05>:23: SyntaxWarning: "is" with a literal. Did you
```

```
mean "=="?
  if faces is ():
```

Face & Eye Detection using HAAR Cascade Classifiers in Image

```
In [14]: face classifier = cv2.CascadeClassifier('Haarcascades/haarcascade frontalface def
         eye_classifier = cv2.CascadeClassifier('Haarcascades/haarcascade_eye.xml')
         img = cv2.imread('image examples/modi.jpg')
         resized_image = cv2.resize(img,(500,500))
         gray = cv2.cvtColor(resized_image, cv2.COLOR_BGR2GRAY)
         faces = face classifier.detectMultiScale(gray, 1.3, 5)
         # When no faces detected, face_classifier returns and empty tuple
         if faces is ():
             print("No Face Found")
         for (x,y,w,h) in faces:
             cv2.rectangle(resized_image,(x,y),(x+w,y+h),(255,0,0),2)
             roi_gray = gray[y:y+h, x:x+w]
             roi_color = resized_image[y:y+h, x:x+w]
             eyes = eye_classifier.detectMultiScale(roi_gray)
             for (ex,ey,ew,eh) in eyes:
                 cv2.rectangle(roi_color,(ex,ey),(ex+ew,ey+eh),(0,255,0),2)
         cv2.imshow('img', resized_image)
         cv2.waitKey(0)
         cv2.destroyAllWindows()
         <>:11: SyntaxWarning: "is" with a literal. Did you mean "=="?
         <>:11: SyntaxWarning: "is" with a literal. Did you mean "=="?
         <ipython-input-14-21ba305368a2>:11: SyntaxWarning: "is" with a literal. Did you
         mean "=="?
           if faces is ():
```

Capture a video

```
In [15]: # Doing some Face Recognition with the webcam

import cv2
video = cv2.VideoCapture(0)

while True:
    check, frame = video.read()
    gray = cv2.cvtColor(frame, cv2.COLOR_BGR2GRAY)
    cv2.imshow('Video',gray)
    if cv2.waitKey(1) == ord('q'):
        break

video.release()
cv2.destroyAllWindows()
```

Face & Eye Detection using HAAR Cascade Classifiers

```
In [16]: # Defining a function that will do the detections
         face_cascade = cv2.CascadeClassifier('Haarcascades/haarcascade_frontalface_defaul
         eye_cascade = cv2.CascadeClassifier('Haarcascades/haarcascade_eye.xml')
         def detect(gray, frame):
             faces = face_cascade.detectMultiScale(gray, 1.3, 5)
             for (x, y, w, h) in faces:
                 cv2.rectangle(frame, (x, y), (x+w, y+h), (255, 0, 0), 2)
                 roi_gray = gray[y:y+h, x:x+w]
                 roi_color = frame[y:y+h, x:x+w]
                 eyes = eye_cascade.detectMultiScale(roi_gray, 1.1, 3)
                 for (ex, ey, ew, eh) in eyes:
                     cv2.rectangle(roi_color, (ex, ey), (ex+ew, ey+eh), (0, 255, 0), 2)
             return frame
         # Doing some Face Recognition with the webcam
         video_capture = cv2.VideoCapture(0)
         while True:
             _, frame = video_capture.read()
             gray = cv2.cvtColor(frame, cv2.COLOR_BGR2GRAY)
             canvas = detect(gray, frame)
             cv2.imshow('Video', canvas)
             if cv2.waitKey(1)==ord('q'):
                 break
         video capture.release()
         cv2.destroyAllWindows()
```

Pedistrian Detection

```
In [17]: # Create our body classifier
         body_classifier = cv2.CascadeClassifier('Haarcascades\haarcascade_fullbody.xml')
         # Initiate video capture for video file
         cap = cv2.VideoCapture('image_examples/walking.avi')
         # Loop once video is successfully loaded
         while cap.isOpened():
             # Read first frame
             ret, frame = cap.read()
             gray = cv2.cvtColor(frame, cv2.COLOR_BGR2GRAY)
             # Pass frame to our body classifier
             bodies = body_classifier.detectMultiScale(gray, 1.2, 3)
             # Extract bounding boxes for any bodies identified
             for (x,y,w,h) in bodies:
                 cv2.rectangle(frame, (x, y), (x+w, y+h), (0, 255, 255), 2)
                 cv2.imshow('Pedestrians', frame)
             if cv2.waitKey(1)==ord('q'):
                 break
         cap.release()
         cv2.destroyAllWindows()
```

```
In [18]: import time
         # Create our body classifier
         car_classifier = cv2.CascadeClassifier('Haarcascades\haarcascade_car.xml')
         # Initiate video capture for video file
         cap = cv2.VideoCapture('image_examples/cars.avi')
         # Loop once video is successfully loaded
         while cap.isOpened():
             time.sleep(.05)
             # Read first frame
             ret, frame = cap.read()
             gray = cv2.cvtColor(frame, cv2.COLOR_BGR2GRAY)
             # Pass frame to our car classifier
             cars = car_classifier.detectMultiScale(gray, 1.4, 2)
             # Extract bounding boxes for any bodies identified
             for (x,y,w,h) in cars:
                 cv2.rectangle(frame, (x, y), (x+w, y+h), (0, 255, 255), 2)
                 cv2.imshow('Cars', frame)
             if cv2.waitKey(1)==ord('q'):
                 break
         cap.release()
         cv2.destroyAllWindows()
```