

Cloud-Enabled UV Disinfection System for Remote Healthcare Sanitization During Pandemics

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Abstract—In healthcare and public environments, maintaining hygiene standards is critical to preventing the spread of infections. Traditional disinfection methods are time-consuming, unreliable, and expose workers to harmful pathogens. To address these challenges, a cloud-connected UV disinfection robot is introduced, automating surface sterilization using UV-C light to ensure effective pathogen elimination while minimizing human exposure. The system integrates microcontroller, UV-C LEDs, environmental sensors, and navigation modules. By connecting to a cloud-based platform, the robot provides real-time monitoring and control through a human-machine interface, allowing operators to receive performance data. The solution incorporates real time data analysis to optimize disinfection parameters and environmental factors such as temperature, humidity, and air quality ensuring maximum efficiency. The use of UV-C technology, cloud connectivity, and advanced data analysis makes this system effective tool for controlling pandemics. This work also includes an Impact analysis and scoring of the environmental factors on pandemic spread.

Index Terms—AQI, HMI, IoT, Real Time Database, UV-C, UV Disinfection

I. INTRODUCTION

The COVID-19 epidemic had glaring effect of illuminating grave flaws in the control mechanisms of infections and disinfections in health systems worldwide. Contamination from surfaces of all locations where patients have high exposures is known to hugely boost the spreading of infectious illnesses [1]. It is suspected from studies that dangerous bacteria including Methicillin-Resistant Staphylococcus Aureus (MRSA) and others with long survival rates such as Severe Acute Respiratory Syndrome Coronavirus 2 (SARS-CoV-2) cause spread of Healthcare-Associated Infection (HAI) due to such longevity on surfaces. Fig.1 illustrates the need for enhanced disinfection procedures to lower mortality and stop the spread of diseases based on an examination of fatality rates from prior virus outbreaks.

Although conventional cleaning methods are necessary, it fails to address these concerns because residues are left on surfaces or fails to decontaminate areas of unreachable regions [2]–[7]. In high risk environment such as hospitals, and clinics, where cleanliness is a must have, this highlights the emergent need for innovative methods of disinfection. One of the prospective answers to these problems lies in UltraViolet (UV) disinfection methods [8]–[10]. Because the UltraViolet C (UVC) radiation damages DeoxyriboNucleic Acid (DNA) and RiboNucleic Acid (RNA) configurations of many types of bacteria, it has been shown that they are effective for killing or denaturing them, thus preventing their replication and transmission. UV disinfection presents a non-toxic residue-free alternative that is more suitable for healthcare facilities compared to chemical disinfectants. The use of UV-C technology in conjunction with traditional cleaning methods ensures higher disinfection levels.

In this context, the designing of an Human Machine Interface (HMI)-managed, semi-autonomous UV disinfection robot is the most significant innovation in techniques for pandemic mitigation [11]. Such a robot, unlike fully autonomous systems, allows its operators to accurately navigate through and disinfect critical areas with high touch points in real-time, ensuring perfect disinfection even in impossible-to-reach places that are inaccessible for traditional disinfection methods [12].

Healthcare facilities are more susceptible to cross-contamination during pandemics. Higher incidence of HAIs are known to result from the persistence of pathogens like MRSA and SARS-CoV-2 on high-touch surfaces including worktops, bed rails, and medical equipment. Healthcare institutions are at a higher risk of viral transmission during outbreaks like COVID-19 because of increased patient interaction and crowded spaces. Vigorous and frequent disinfection is critical for infection control because viruses may survive on surfaces for hours to days, as per research [13]–[16].

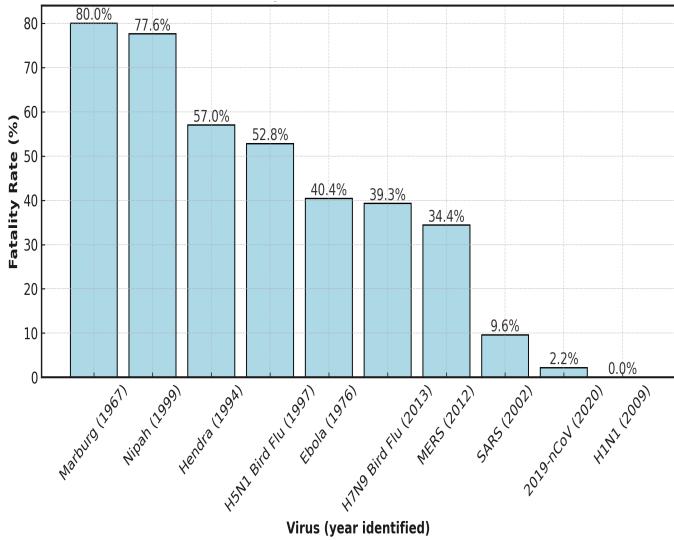


Fig. 1. Fatality Rate of Major Virus Outbreaks Worldwide

The proposed UV disinfection robot, combining cutting-edge UV-C technology with an intuitive HMI system, enables medical professionals to precisely target vital areas while minimizing pathogen exposure [17]. The robot allows for quicker, safer, and more effective means of maintaining hygienic standards in hospital environments by lowering dependency on dangerous chemical disinfectants. Moreover, it reduces the time needed for manual cleaning duties, allowing healthcare professionals to focus on patient care [18]–[20].

The main objective of this research is to meet the urgent demand for scalable, effective disinfection solutions that protect patients, medical staff, and guests. Semi-autonomous design of the robot increases the effectiveness of disinfection processes and offers a proactive approach to pandemic mitigation by reducing the risk of infection transmission in hospital environments [21], [22].

II. METHODOLOGY

The methodology of the cloud-connected UV-C disinfection robot is centered on designing a robust, scalable, and efficient system for autonomous disinfection in healthcare environments. The following sections outline the system architecture, hardware integration, software design, and implementation process.

A. System Architecture

The architecture is divided into hardware and software components, integrated to provide automated disinfection, real-time monitoring, and remote control [7]. The core elements include:

- 1) Control unit: The heart of the operation is an ESP32 WROOM32 microcontroller that controls and coordinates sensors and actuators together with communication devices [12].
- 2) Sensors: Environmental sensors to ensure optimal conditions for disinfection, such as a DHT22 module for

temperature and humidity, and MQ-135 air quality sensor. There is a HC-SR04 ultrasonic sensor for obstacle detection. Also ESP32 CAM for realtime video streaming for HMI Control [7].

- 3) Actuators: UV-C LEDs (Light Emitting Diode) for germicidal disinfection and gear motors for mobility, controlled by an L298N motor driver [5].
- 4) Connectivity: A Google firebase platform allows cloud data logging, remote monitoring, and control via a web interface.
- 5) Power supply: Dual 12V batteries power the robot and UV-C LEDs, ensuring long-term operation.

The circuit has been designed with Fritzing software. The proposed block diagram of the disinfection robot is shown in Fig.2.

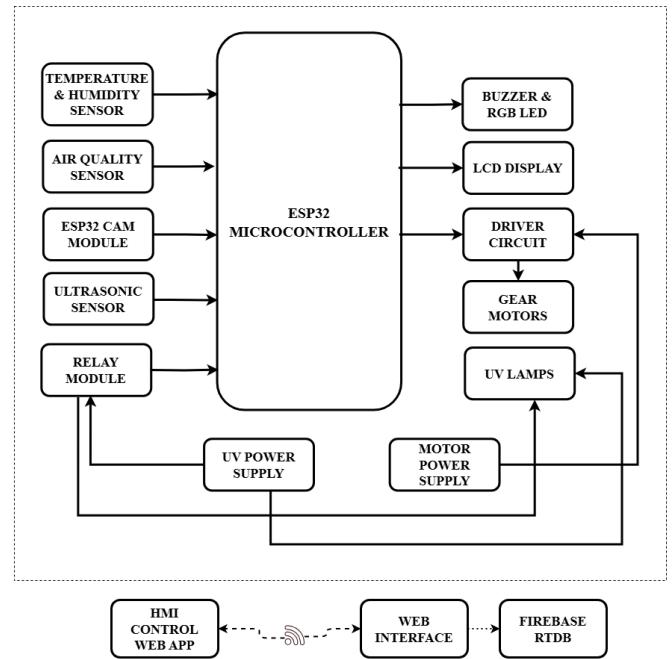


Fig. 2. Cloud Connected UV Disinfection Robot

B. Software Design

The whole software system is designed using the Visual Studio Code. It supports the cloud aspect with firebase integration. The control logic module constitutes:

- 1) Cloud integration: Utilizes firebase for real-time data logging by using Real Time Data Base(RTDB), remote system control, and visualization of environmental data.
- 2) Web interface: It is implemented by using HTML & CSS along with Python Flask framework. It provides users with remote access to monitor operational parameters and system status.
- 3) HMI interface: It provides a fully fledged control to the user for controlling the robot by means of real time streaming through camera and joystick controls.

C. Implementation Workflow

- The implementation process follows a structured workflow:
- 1) Initialization: System startup includes sensor calibration and connectivity establishment with firebase [12].
 - 2) Environmental monitoring: Sensors are used to monitor temperature, humidity, and air quality to maintain optimal conditions for disinfection [13].
 - 3) Data logging: Sensor data and operational logs are constantly uploaded to firebase for analysis and review [7].
 - 4) User interaction: Remotely monitor, control, and adjust disinfection parameters through an internet-enabled interface.

D. Framework Design

The UV disinfection robot's framework is designed to combine a number of sensors and parts in order to provide remote accessibility, environmental monitoring, and efficient disinfection. The system is a dependable and effective solution for healthcare and public sanitization because of its structural and functional design, which centers on sensor integration, regulated UV disinfection, and cloud connectivity and real time surveillance. The framework designed for the UV robot is shown in Fig.3.

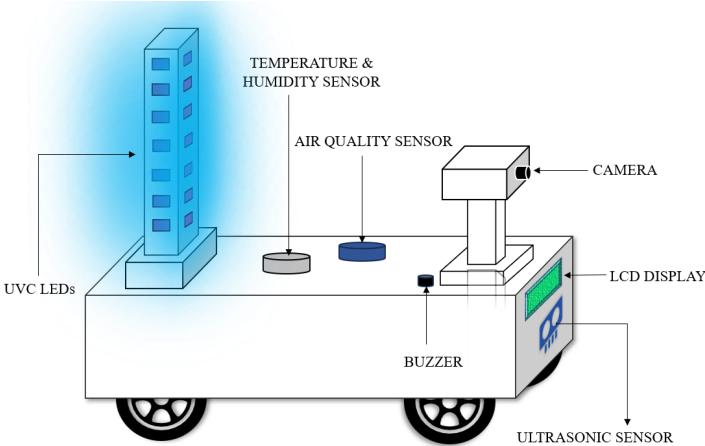


Fig. 3. Framework designed for UV Disinfection Robot

The methodology also integrates insights from the earlier advanced automation system involving many sensors. Concepts from these implementations were adapted to enhance the modularity and control systems for the UV-C robot, leveraging previously developed expertise to ensure robust hardware-software synergy and system resilience.

III. RESULTS AND DISCUSSIONS

The impact of environmental factors were assessed using a threshold-based scoring approach combined with normalization to determine impact percentages.

A. Selection of impact scores

Impact scores assigned to each environmental factor were based on the literature available, epidemiological studies, and expert consultations. The scoring is achieved by a range from 3 to 9, showing the comparative difference that the factor presents in influencing pandemic spread. A progressive incremental gap of two units is used in the selection of 3, 5, 7, and 9 offering a balanced step size that guarantees significant contrast between impact levels. Larger gaps, like 3, could oversimplify the scoring system, decreasing granularity and interpretability, while smaller gaps, like 1, could lead to inadequate separation, making the thresholds less effective in differentiating across groups. The two-point increment ensures that the scale is both intuitive and sensitive to changes in the factors under analysis by striking a balance between clarity and resolution. Since lower threshold values like 1 and 2 suggest minimal or inconsequential effects, which are at odds with the environmental components under analysis, they were avoided. The rationale for scores is as follows:

- Temperature (T): Research indicates that lower temperatures increase the survival of viruses and their transmission through aerosols. Hence, scores of 7, 5, and 3 were given to low, moderate, and high temperatures respectively as given in the equation (1) respectively, to indicate their effects on the dynamics of transmission.
- Humidity (H): Droplets survive longer at lower humidity values (< 40%). An optimal humidity for droplet stability lies within 40% – 60%. At high humidity (> 60%), coalescence and settling become enhanced factors reducing the transmission of disease. The humidity levels and their impact scores are given in equation (2).
- Wind speed (W): According to the equation (3), low air movement (< 1.5 m/s) enhances the stagnation of virus-laden particles, whereas stronger winds (> 5 m/s) spread and dilute the airborne particles. Therefore, the lower wind speed was rated as higher to indicate higher risk.
- Air Quality Index (AQI): Poor air quality, especially the AQI values that are more than 150, worsens respiratory problems and risks the vulnerabilities to infections, thus justifying the more significant score. Lower AQI values (< 50) correspond to conditions that are healthier and less risky. The detailed AQI levels along with their impact scores are shown in equation (4).

B. Environmental Factors and Thresholds

The environmental factors and their thresholds were calibrated in the following manner:

- Temperature (T):

$$S_T = \begin{cases} 9 & \text{if } T < 10^\circ C \\ 7 & \text{if } 10^\circ C \leq T \leq 20^\circ C \\ 5 & \text{if } 20^\circ C \leq T \leq 30^\circ C \\ 3 & \text{if } T > 30^\circ C \end{cases} \quad (1)$$

- Humidity (H):

$$S_H = \begin{cases} 9 & \text{if } H < 30\% \\ 7 & \text{if } 30\% \leq H \leq 40\% \\ 5 & \text{if } 40\% \leq H \leq 60\% \\ 3 & \text{if } H > 60\% \end{cases} \quad (2)$$

- Wind Speed (W):

$$S_W = \begin{cases} 7 & \text{if } W < 1.5 \text{ m/s} \\ 5 & \text{if } 1.5 \text{ m/s} \leq W \leq 3 \text{ m/s} \\ 3 & \text{if } W > 5 \text{ m/s} \end{cases} \quad (3)$$

- Air Quality Index (AQI):

$$S_{AQI} = \begin{cases} 3 & \text{if } AQI < 50 \\ 5 & \text{if } 50 \leq AQI \leq 100 \\ 7 & \text{if } AQI > 100 \\ 9 & \text{if } AQI > 150 \end{cases} \quad (4)$$

C. Normalization and Impact Percentage

To emphasize the relative contributions of environmental elements, impact scores are normalized. Clear comparisons of influence on pandemic propagation are not possible with direct summarization. The process of normalization facilitates comprehension. By converting raw scores into percentages, the impact of each component is accurately analysed. Absolute values lack a clear reference in the absence of normalization, which makes meaningful comparisons challenging. In addition to facilitating organized evaluation and avoiding distortions from differences in score ranges or measurement units, this approach maintains linkages among components while eliminating dependencies on the original scales. Normalization is crucial for assessing environmental impacts on pandemic dynamics because it improves clarity, comparability, and interpretability. The raw impact scores (S) are normalized to compute impact percentages:

$$P_i = \left(\frac{S_i}{\sum_{i=1}^n S_i} \right) \times 100 \quad (5)$$

Where:

- P_i : Impact percentage of the i^{th} factor.
- S_i : Score of the i^{th} factor.
- n : Total number of factors.

According to equation (5) the impact percentage of the environmental factors are calculated. Table I shows the key environmental factors affecting the effectiveness of pandemic mitigation by UV-C disinfection calculated as per equation (5). It reports typical values for temperature, humidity, wind speed, and AQI in the environment under test. A corresponding score S_i based on predefined thresholds is calculated and normalized with the help of percentage P_i .

- 1) Temperature: A normal value of 31°C corresponds to a score of 3, meaning the effect is moderate (18.8%) on the dynamics of the pandemic.

TABLE I
ENVIRONMENTAL FACTORS AND THEIR IMPACT IN LOCAL AREA(THRISSUR)

Factor	Value	Score (S_i)	Impact % (P_i)
Temperature (T)	31°C	3	18.8%
Humidity (H)	74%	3	18.8%
Wind Speed (W)	1.5–3 m/s	5	31.25%
AQI	58	5	31.25%

- 2) Humidity: With 74%, the score is still 3 and almost the same level of influence as temperature.
- 3) Wind Speed: 1.5–3 m/s; the corresponding score is 5 that implies an impact at the higher level of 31.25%.
- 4) AQI: Classified as moderate, with a score of 5, and equal wind speed in its contribution to the overall effect.

Fig.4 displays a graph that compares the scores given to each environmental factor: temperature, humidity, wind speed, and AQI. The bar chart format helps emphasize the relative weight of each factor so that one can easily determine the dominant contributors.

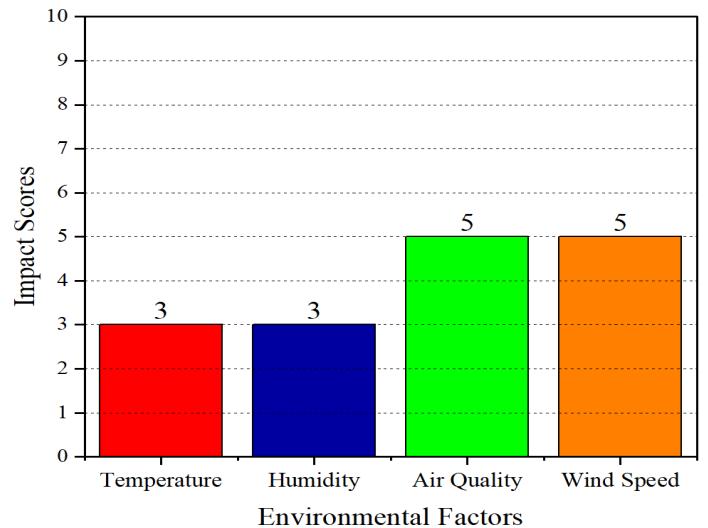


Fig. 4. Environmental Factors and their Respective Scores

Score Distribution

Environmental factors affecting pandemic dynamics were analyzed based on a scoring framework using threshold values derived from relevant studies. The highest scores are given to wind speed and AQI as 5, due to their leading roles in the spread of viruses and effectiveness of mitigation. These factors significantly affect the dispersion of airborne pathogens. High wind speeds contribute to both increased transmission

in crowded areas and rapid dispersion in open environments, which can potentially reduce localized viral load. Similarly, elevated AQI values, which are associated with poor air quality, are correlated with higher respiratory vulnerability, thereby increasing infection risks. Temperature and humidity scored a moderate score of 3, meaning it is a secondary yet notable influence. Although their effects on transmission are less direct than those of wind speed and AQI, research indicates that extreme temperature fluctuations and humidity can influence the survival rates of viruses and their potential for transmission. For example, low humidity has been linked to increased stability of viral aerosols, which increases the chances of airborne transmission, while higher humidity may promote droplet settling, thus reducing airborne persistence. Temperature fluctuations may have indirect impacts upon host immune functions, hence infection rates also. The ranking system is provided with a numeral basis of measurement to interpret ecological contributions toward trends in the outbreak, further calling for focused targeted mitigation measures responsive to predominant agents.

Visual Insights from Bar Chart

Fig.4 clearly plots the hierarchy of these environmental factors. Comparing the wider bars for wind speed and AQI with shorter bars for temperature and humidity gives an idea that former two play more dominant roles in pandemic dynamics. This intuitive visualization clearly reveals that wind speed and air quality need to be focused upon much more in health policy. With all this visualization enabled, furthermore trend identification is possible as well as comparison with others. With historical data as well as comparing it to present time, patterns or differences through seasons and space may also bring out, resulting in refinement towards predictive models that could possibly show better insights during the coming next pandemics with a strategy evolved based on upcoming trends.

Strategic Implications

The analysis identifies the most important environmental factors that need to be monitored and controlled to optimize pandemic response strategies. Wind speed and AQI should be closely monitored using sensor networks and AI-driven predictive analytics. Policy recommendations include real-time air quality alerts, enforcement of pollution control measures, and adjustment of public safety guidelines based on wind conditions, such as restricting outdoor gatherings in high-wind, high-AQI scenarios. Secondary factors include temperature and humidity. These seem minor, but they are essential for extreme weather conditions. For instance, in low-humidity environments, enhanced indoor air regulation strategies such as humidification in hospitals and public spaces could mitigate the risks of transmission.

This could similarly apply through adapting responses such as modifying Heating, Ventilation, and Air Conditioning (HVAC) settings based on seasonal variations to enhance comfort and reduce viral spread by improving indoor air quality.

The normalized impact percentages (P_i) of the environmental elements, divided into proportionate portions, are added to the graph in Figure 5. It allows for a complete and intuitive comprehension of each factor's contribution to the overall influence.

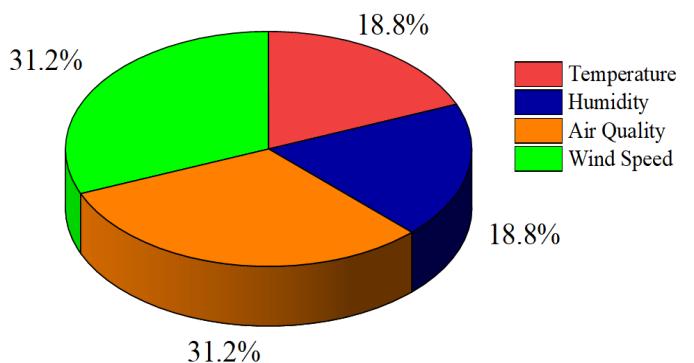


Fig. 5. Impact Percentage Distribution of Environmental Factors

Proportional Contributions

A proportional breakdown of environmental factors influencing pandemic dynamics reveals that wind speed and AQI each account for 31.25% of the total impact of the influencing factors. These two parameters are dominant in deciding airborne pathogen dispersion and inhalation risks.

They generally align with established epidemiological studies that conclude direct transmission with relation to poor air quality and associated high wind speeds.

In contrast, temperature and humidity each account for 18.8%, which comprises the residual portion of environmental influence. Although these values are relatively less, their impact is significant. Even small fluctuations in these parameters can affect the stability of virus, immune response of the host, and overall transmission risk. Research studies show that under extreme climatic conditions, the sum effect of temperature and humidity variations enhances viral persistence, thereby validating their status as key secondary parameters in the design of pandemic control measures. The weighted contribution of each factor, as described in Figure 5, further reinforces a data-driven decision-making approach, allowing targeted interventions based on environmental risk assessments.

Visual Insights from Pie Chart

The Figure 5 visually represents the proportional significance of these factors controlling the pandemic. The nearly equal distribution of wind speed and AQI indicates a co-dominant influence, suggesting that pandemic-prevention measures should include simultaneous monitoring and control of both. Although the shares are smaller, temperature and humidity still play a significant role in environmental impact analysis.

The graphical representation helps in interpreting relative significance and guides policy prioritization. These insights can be expanded by integrating time-series data and geospatial mapping to develop dynamic environmental risk models,

allowing real-time adjustments in mitigation protocols based on changing environmental conditions.

IV. CONCLUSION

All of the objectives that were set out for this work, which included developing, analyzing, and implementing a cloud-enabled UV disinfection robot, was completed. The system was designed with functionalities such as UV-C based disinfection, real-time environmental monitoring of temperature, humidity, and air quality, camera surveillance, and HMI control. The given environmental parameters were analyzed graphically for comprehensive impact analysis and performance optimization. The developed system is a wide progress in the current disinfection technologies as it incorporates IoT-enabled cloud connectivity to gain access and control from remote locations, increasing precision, efficiency, and adaptability. This differs from conventional UV disinfection systems, which do not have real-time monitoring and mechanical adaptation. Since this system dynamically responds to environmental factors that determine its optimal effectiveness. The analytical framework applied in this work further reinforces its effectiveness, as the impact analysis revealed that environmental factors such as wind speed and AQI were significant determinants of the disinfection efficiency. Temperature and humidity, although not significant under normal conditions, become crucial determinants when extremes occur and demand optimal deployment strategies to sustain performance. Future development of the system may continue to be channeled to further enhance automation by AI. The focus remains on improving its efficiency with environmental predictive modeling and, eventually, its integration into advanced robotics capable of autonomous navigation and AI decision-making for broader application in more diverse healthcare settings and public infrastructures. Its potential may even be extended toward incorporating high-resolution environmental mapping for better AI-driven analytics in making it possible for a more robust mechanism for determining disinfection efficiency. Being a robust framework and all-encompassing analytics approach, this system has rightly positioned itself for deployment in the real world. In addition to the present need for immediate healthcare sanitization, this solution answers more expansive purposes for applying its scalable approach to pandemics, industrial hygiene, and smart city infrastructure, bringing safer, sustainable environments.

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