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MATHEMATICS II

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UNIT 3

SYSTEMS OF LINEAR EQUATIONS



On completion of this unit, you will be able to ...

- ... translate text into a system of linear equations (LES).
- ... express an LES using the extended matrix notation.
- ... find the solutions to an LES using the Gauss algorithm.
- ... use the Gauss algorithm to find the inverse of a matrix.



- 1. What is a linear equation system (LES)?
- 2. Explain how to find the solutions to an LES.
- 3. Can an LES have more than one solution? How do you find out?
- 4. Can an LES have no solution? How do you find out?

Example:

SmartShoes, Inc. sells sports shoes of three different models (A, B and C).

- Yesterday's revenues amounted to 1,980 EUR, where the selling prices per pair of shoes was 50 EUR for model A, 80 EUR for model B and 90 EUR for model C. $50x_1 + 80x_2 + 90x_3 = 1,980$
- In total, the company sold 30 pairs of shoes. $x_1 + x_2 + x_3 = 30$
- The number of model A pairs of shoes the company sold was as large as the sum of the model B and model C pairs. $x_1 x_2 x_3 = 0$

How many model A, model B and model C shoes did the company sell?

A linear equation system (LES) is a set of m equations and n variables (unknowns) $x_1, x_2, ..., x_n$ of the following general form:

$$a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = b_1$$

 $a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = b_2$
...

 $a_{m1}x_1 + a_{m2}x_2 + \cdots + a_{mn}x_n = b_m$

where
$$a_{ij} \in \mathbb{R}$$
, $b_i \in \mathbb{R}$ for $i = 1, ..., m$; $j = 1, ..., n$

A linear equation system is often written in a matrix notation:

$$A\vec{x} = \vec{b}$$
, where

Coefficient Matrix

Extended Coefficient Matrix

Variable Vector

Right-Hand Side Vector

$$A = \begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{pmatrix}$$

$$\vec{x} = \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix}$$

$$\vec{b} = \begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{pmatrix}$$

$$A = \begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{pmatrix} \qquad \vec{x} = \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} \qquad \vec{b} = \begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{pmatrix} \qquad A|b = \begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} & b_1 \\ a_{21} & a_{22} & \dots & a_{2n} & b_2 \\ \vdots & \vdots & & \vdots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} & b_m \end{pmatrix}$$

NUMBER OF SOLUTIONS

An LES can have no, exactly one, or infinitely many solutions.

Case 1:

One solution

$$50x_1 + 80x_2 + 90x_3 = 1,980$$

Example: $x_1 + x_2 + x_3 = 30$

 $x_1 - x_2 - x_3 = 0$

Case 2:

No solution

$$2x_1 + 2x_2 = 8$$

Case 3:

Infinitely many solutions

The Gauss Algorithm

- **Step 1:** Generate the extended matrix $A \mid b$
- Step 2: Choose i = 1.
- Step 3: Use elementary row operations to achieve that

 $a_{ii} \neq 0$ and $a_{ji} = 0$ for all j > i(i.e., all entries below a_{ii} must be 0)

Step 4: Increase index i by 1.

STOP if i = n

else go to step 3.

- interchanging rows
- multiplying a row with a scalar ≠ 0
- Adding (or subtracting) rows

Applying the Gauss algorithm to the SmartShoes example yields:

$$\begin{pmatrix}
50 & 80 & 90 & | & 1,980 \\
1 & 1 & 1 & | & 30 \\
1 & -1 & -1 & | & 0
\end{pmatrix}
\xrightarrow{\text{Swap rows}}
\begin{pmatrix}
1 & 1 & 1 & | & 30 \\
1 & -1 & -1 & | & 0 \\
50 & 80 & 90 & | & 1,980
\end{pmatrix}$$

$$\xrightarrow{\text{(2)-(1)}}
\begin{pmatrix}
1 & 1 & 1 & | & 30 \\
0 & -2 & -2 & | & -30 \\
0 & 30 & 40 & | & 480
\end{pmatrix}$$

$$\begin{pmatrix}
1 & 1 & 1 & | & 30 \\
0 & 1 & 1 & | & 15 \\
0 & 30 & 40 & | & 480
\end{pmatrix}$$

$$\begin{pmatrix}
1 & 1 & 1 & | & 30 \\
0 & 1 & 1 & | & 15 \\
0 & 0 & 1 & | & 15 \\
0 & 0 & 1 & | & 30
\end{pmatrix}$$

$$\begin{pmatrix}
1 & 1 & 1 & | & 30 \\
0 & 1 & 1 & | & 15 \\
0 & 0 & 1 & | & 35
\end{pmatrix}$$

$$\begin{pmatrix}
1 & 1 & 1 & | & 30 \\
0 & 1 & 1 & | & 15 \\
0 & 0 & 1 & | & 35
\end{pmatrix}$$

$$\begin{pmatrix}
1 & 1 & 1 & | & 30 \\
0 & 1 & 1 & | & 15 \\
0 & 0 & 1 & | & 35
\end{pmatrix}$$

Hence:
$$x_3 = 3$$

 $x_2 + x_3 = x_2 + 3 = 15$, so $x_2 = 12$
 $x_1 + x_2 + x_3 = x_1 + 12 + 3 = 30$, so $x_1 = 15$

If, during the Gauss algorithm, we obtain a row containing zeros only on the left, but a non-zero value on the right-hand side, original equation system contains a contradiction. Hence, the equation system has no solution.

Example:

$$\begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 3 & 6 & 12 \end{pmatrix} \xrightarrow{\text{(3)/3}} \begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 1 & 2 & 4 \end{pmatrix} \xrightarrow{\text{(3)}-\text{(1)}} \begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 0 & 0 & 1 \end{pmatrix}$$

$$\stackrel{\text{(3)}-\text{(1)}}{\leftarrow} \text{contradiction}$$

$$\xrightarrow{\text{on solution}} \text{no solution}$$

If the resulting upper triangular matrix of the Gauss algorithm contains less equations r than variables n, the equation system has **infinitely many** solutions: We can choose variables x_{r+1}, \dots, x_n freely and calculate the values of the remaining variables by solving the inequalities bottom-up.

Example:

$$\begin{pmatrix} 1 & 2 & 3 & 4 & 5 \\ 0 & 1 & 6 & 7 & 8 \end{pmatrix}$$

```
set x_3 = s and x_4 = t for any s, t \in \mathbb{R}
x_2 + 6s + 7t = 8 \text{ (from equation 2), hence}
x_2 = 8 - 6s - 7t
x_1 + 2x_2 + 3s + 4t = 5 \text{ (from equation 1), hence}
x_1 = 5 - 2x_2 - 3s - 4t
= 5 - 2(8 - 6s - 7t) - 3s - 4t = -11 + 9s + 10t
```

The Extended Gauss Algorithm (to find an inverse matrix)

- **Step 1:** Generate the extended matrix (A|E), where E is the unit matrix.
- **Step 2:** Choose i = 1.
- Step 3: Use elementary row operations to achieve that

```
a_{ii} \neq 0 and a_{ji} = 0 for all j \neq i
(i.e., all entries below and above a_{ii} must be 0)
```

Difference to standard Gauss algorithm

- Step 4: If step 3 yields a null row in A: STOP (A does not have an inverse)
- **Step 5:** Increase index i by 1.

STOP if i = n; else go to step 3.

APPLICATIONS OF THE EXTENDED GAUSS ALGORITHM

Example: Find the inverse of
$$A = \begin{pmatrix} 1 & 1 & 0 \\ 1 & 1 & 1 \\ 0 & 2 & 2 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 1 & 0 & 1 & 0 & 0 \\ 1 & 1 & 1 & 0 & 0 & 1 \\ 0 & 2 & 2 & 0 & 0 & 1 \end{pmatrix} \xrightarrow{(2) - (1)} \begin{pmatrix} 1 & 1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & -1 & 1 & 0 \\ 0 & 2 & 2 & 0 & 0 & 1 \end{pmatrix} \xrightarrow{(2) \leftrightarrow (3)} \begin{pmatrix} 1 & 1 & 0 & 1 & 0 & 0 \\ 0 & 2 & 2 & 0 & 0 & 1 \\ 0 & 0 & 1 & -1 & 1 & 0 \end{pmatrix}$$

 $=A^{-1}$, i.e. inverse of A



You are now able to ...

- ... translate text into a system of linear equations (LES).
- ... express an LES using the extended matrix notation.
- ... find the solutions to an LES using the Gauss algorithm.
- use the Gauss algorithm to find the inverse of a matrix.

SESSION 2

TRANSFER TASK 1

At a student club's summer party, soda, beer and cola were sold. All beverages were sold in bottles. At their retailer, the student club purchased soda at a price of 1 EUR per bottle, and both beer and cola at a price of 2 EUR per bottle. At the party, soda was then sold at 2 EUR per bottle, beer at 4 EUR per bottle and cola at 3 EUR per bottle.

The party's revenues with beverages amounted to 1,670 EUR. The retailer's bill was 945 EUR, and 550 bottles were consumed in total. How many bottles of soda, beer and cola have been sold each?

TRANSFER TASK 1 PRESENTATION OF THE RESULTS

Please present your results.

The results will be discussed in plenary.



SESSION 2

TRANSFER TASK 2

Use the extended Gauss algorithm to find the inverse of the following matrices (or show that the matrix does not have an inverse):

$$A = \begin{pmatrix} 3 & 6 & 4 \\ 1 & 4 & 2 \\ 2 & 2 & 2 \end{pmatrix}, \qquad B = \begin{pmatrix} 4 & 1 & 1 \\ 1 & 0 & 2 \\ 1 & 5 & 0 \end{pmatrix}$$

TRANSFER TASK 2 PRESENTATION OF THE RESULTS

Please present your results.

The results will be discussed in plenary.





1. Every linear system of equations ...

- a) ... has one solution.
- b) ... may have a solution.
- c) ... has an infinite number of solutions.
- d) ... has no solution.



2. Which one of the following row operations may change the set of solutions of a linear system of equations?

- a) the swapping of two rows
- b) replacing one row with the sum of said row and another row
- c) replacing one row with the difference between said row and another row.
- d) multiplication of all row elements by any real number



3. Which one of the following scenarios does **not** occur after applying the Gaussian algorithm?

- a) The final expanded matrix has more rows than columns.
- b) The final expanded matrix has an equal number of rows and columns.
- C) The final expanded matrix has more columns than rows.
- d) The final expanded matrix is an upper triangular matrix.

LIST OF SOURCES

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Robbiano L. (2011). *Linear algebra for everyone*. Springer.