```
import numpy as np
import pandas as pd
import matplotlib.pyplot as plt
class Neural_Network():
 def __init__(self,hidden_layer_list):
   self.hidden_layer_list=hidden_layer_list
   self.no_hidden_layer=len(hidden_layer_list)
 def train_dev_split(self,X,Y,train_size):
   m=int(train_size*X.shape[0])
   X_train=X[:m,:]
   X_dev=X[m:,:]
   Y_train=Y[:m]
   Y_dev=Y[m:]
   return X_train,Y_train,X_dev,Y_dev
 def Z_score_standardize(self,X,X_train_):
   Mean=np.mean(X_train_,axis=0)
   std=np.std(X_train_,axis=0)
   std[std==0]=1
   return (X-Mean)/std
 def min_max_normalize(self,X,X_train_):
   Min=np.min(X_train_,axis=0)
   Max=np.max(X_train_,axis=0)
   Range=Max-Min
   Range[Range==0]=1
   return (X-Min)/Range
 def parameters_init(self,optimization):
   self.w=[np.random.randn(x,y)*np.sqrt(2/x) for x,y in zip(self.hidden layer list[:-2],self.hidden layer list[1:-1])]
   self.w.append((np.random.randn(self.hidden\_layer\_list[-2]), self.hidden\_layer\_list[-1]))*np.sqrt(1/self.hidden\_layer\_list[-2]))
   self.b=[np.zeros((x)) for x in self.hidden_layer_list[1:]]
   if optimization=="Adam":
      self.vdw, self.sdw=[np.zeros(x.shape) for x in self.w], [np.zeros(x.shape) for x in self.w]
     self.vdb,self.sdb=[np.zeros(x.shape) for x in self.b],[np.zeros(x.shape) for x in self.b]
  def dropout(self,a):
   p=np.random.rand(a.shape[0],a.shape[1])<self.keep_prob</pre>
   a_dropout=(a*p)/self.keep_prob
   return a_dropout
 def forward_prop(self,X,dropout=False):
   if dropout:
     X=self.dropout(X)
   A=[X]
   a=X
   for i in range( self.no_hidden_layer):
     z=(a@self.w[i])+self.b[i]
     a=self.ReLU(z)
     if dropout:
       a=self.dropout(a)
   z=(a@self.w[self.no_hidden_layer])+self.b[self.no_hidden_layer]
   a=self.softmax(z)
   A.append(a)
   return A.a
 def Batch_GD(self,X_train,Y_train,iterations=100,learning_rate=0.5,L2_regularization_term=0,Exp_learning_rate_decay=None,Feature_Scaling="z
   self.d=dropout
   self.validation=validation
   self.iterations=iterations
   self.Feature_Scaling=Feature_Scaling
   self.alpha=learning_rate
   alpha1=self.alpha
   self.lamda=L2_regularization_term
   self.X_train_=np.copy(X_train)
   if Feature_Scaling=="Z_score_standardization":
     self.X_train_n=self.Z_score_standardize(X_train,self.X_train_)
   elif Feature Scaling=="min max normalization":
     self.X_train_n=self.min_max_normalize(X_train,self.X_train_)
   else:
      self.X_train_n=X_train
```

```
self.Y_train=Y_train.reshape(-1,1)
 self.m_train,self.n_train=self.X_train_.shape
 self.t=int(np.max(self.Y_train)+1) #No of labels possible
 O_train=self.one_hot(self.Y_train)
 self.J train list=[]
 self.train_accuracy=[]
 self.hidden_layer_list.insert(0,self.n_train)
 self.hidden_layer_list.append(self.t)
 self.parameters_init("Batch_GD")
 if self.validation:
   if X dev.size>0 and Y dev.size>0:
      self.Y_dev=Y_dev.reshape(-1,1)
      O_dev=self.one_hot(self.Y_dev)
      self.J_dev_list=[]
     self.dev_accuracy=[]
      if Feature_Scaling=="Z_score_standardization":
        {\tt self.X\_dev\_n=self.Z\_score\_standardize}({\tt X\_dev,self.X\_train\_})
      elif Feature_Scaling=="min_max_normalization":
        self.X_dev_n=self.min_max_normalize(X_dev,self.X_train_)
      else:
        self.X_dev_n=X_dev
   else:
      print("Enter validation data in function call")
      return
 for i in range(iterations):
   a_train=self.forward_prop(self.X_train_n)[1]
   {\tt self.J\_train\_list.append(self.Sparse\_Categorical\_Cross\_Entropy(a\_train,0\_train))}
    self.train_accuracy.append(self.accuracy(self.Y_train,a_train))
   if validation:
      a_dev=self.forward_prop(self.X_dev_n)[1]
      self.J_dev_list.append(self.Sparse_Categorical_Cross_Entropy(a_dev,0_dev))
      self.dev_accuracy.append(self.accuracy(self.Y_dev,a_dev))
   A,a=self.forward prop(self.X train n,dropout=self.d)
   dw_list,db_list=self.backprop(A,a,O_train)
   self.w=[a-self.alpha*b for a,b in zip(self.w,dw_list)]
    self.b=[a-self.alpha*b for a,b in zip(self.b,db_list)]
    if Exp_learning_rate_decay and i%10==0:
        alpha=(Exp_learning_rate_decay**(i/10))*alpha1
 a_train=self.forward_prop(self.X_train_n)[1]
 self.J_train_list.append(self.Sparse_Categorical_Cross_Entropy(a_train,0_train))
 self.train_accuracy.append(self.accuracy(self.Y_train,a_train))
 if validation:
   a_dev=self.forward_prop(self.X_dev_n)[1]
    self.J_dev_list.append(self.Sparse_Categorical_Cross_Entropy(a_dev,O_dev))
   self.dev_accuracy.append(self.accuracy(self.Y_dev,a_dev))
def mini_batch_GD(self,X_train,Y_train,epochs=100,learning_rate=0.5,L2_regularization_term=0,Exp_learning_rate_decay=None,Feature_Scaling='
 if dropout:
   self.d=True
   self.keep prob=dropout probability
 else:
   self.d=False
 self.validation=validation
 self.iterations=epochs
 self.Feature_Scaling=Feature_Scaling
 self.alpha=learning_rate
 alpha1=self.alpha
 self.lamda=L2_regularization_term
 self.X_train_=np.copy(X_train)
 if Feature_Scaling=="Z_score_standardization":
   self.X_train_n=self.Z_score_standardize(X_train,self.X_train_)
 elif Feature_Scaling=="min_max_normalization":
   self.X_train_n=self.min_max_normalize(X_train,self.X_train_)
   self.X_train_n=X_train
 self.Y train=Y train.reshape(-1,1)
 self.m_train,self.n_train=self.X_train_.shape
 self.t=int(np.max(self.Y train)+1) #No of labels possible
 0_train=self.one_hot(self.Y_train)
 self.J_train_list=[]
 self.train_accuracy=[]
 self.hidden_layer_list.insert(0,self.n_train)
 self.hidden_layer_list.append(self.t)
  self.parameters_init("mini_batch_GD")
 if self.validation:
```

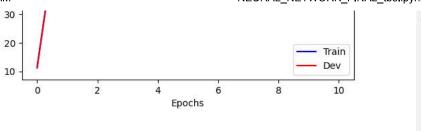
```
if X_dev.size>0 and Y_dev.size>0:
      self.Y_dev=Y_dev.reshape(-1,1)
      O_dev=self.one_hot(self.Y_dev)
      self.J_dev_list=[]
     self.dev accuracy=[]
      if Feature_Scaling=="Z_score_standardization":
        self.X_dev_n=self.Z_score_standardize(X_dev,self.X_train_)
      elif Feature_Scaling=="min_max_normalization":
        self.X_dev_n=self.min_max_normalize(X_dev,self.X_train_)
      else:
        self.X dev n=X dev
   else:
      print("Enter validation data in function call")
 train_data=np.append(self.X_train_n,0_train,axis=1)
 for i in range(epochs):
    a_train=self.forward_prop(self.X_train_n)[1]
   self.J_train_list.append(self.Sparse_Categorical_Cross_Entropy(a_train,0_train))
   self.train_accuracy.append(self.accuracy(self.Y_train,a_train))
   if validation:
      a_dev=self.forward_prop(self.X_dev_n)[1]
      self.J_dev_list.append(self.Sparse_Categorical_Cross_Entropy(a_dev,O_dev))
      self.dev_accuracy.append(self.accuracy(self.Y_dev,a_dev))
   np.random.shuffle(train data)
   mini_batch_list=[train_data[k:k+mini_batch_size,:] for k in range(0,self.m_train,mini_batch_size)]
   for mini_batch in mini_batch_list:
      self.mini_batch_update(mini_batch)
 a_train=self.forward_prop(self.X_train_n)[1]
 self.J_train_list.append(self.Sparse_Categorical_Cross_Entropy(a_train,0_train))
 self.train_accuracy.append(self.accuracy(self.Y_train,a_train))
 if validation:
   a dev=self.forward prop(self.X dev n)[1]
   self.J_dev_list.append(self.Sparse_Categorical_Cross_Entropy(a_dev,O_dev))
   self.dev_accuracy.append(self.accuracy(self.Y_dev,a_dev))
def mini_batch_update(self,mini_batch):
 x=mini_batch[:,:self.n_train]
 o=mini_batch[:,self.n_train:]
 A,a=self.forward_prop(x,dropout=self.d)
 dw_list,db_list=self.backprop(A,a,o)
 self.w=[a-self.alpha*b for a,b in zip(self.w,dw_list)]
 self.b=[a-self.alpha*b for a,b in zip(self.b,db_list)]
def Adam(self,X_train,Y_train,epochs=100,learning_rate=0.5,L2_regularization_term=0,beta1=0.9,beta2=0.999,epsilon=10**(-8),Exp_learning_rat
 self.beta1=beta1
  self heta2=heta2
 self.epsilon=epsilon
 self.mini_batch_size=mini_batch_size
 if dropout:
   self.d=True
   self.keep_prob=dropout_probability
 else:
   self.d=False
 self.validation=validation
 self.iterations=epochs
 self.Feature_Scaling=Feature_Scaling
 self.alpha=learning_rate
 alpha1=self.alpha
 self.lamda=L2_regularization_term
 self.X_train_=np.copy(X_train)
 if Feature_Scaling=="Z_score_standardization":
   self.X_train_n=self.Z_score_standardize(X_train,self.X_train_)
 elif Feature_Scaling=="min_max_normalization":
   self.X_train_n=self.min_max_normalize(X_train,self.X_train_)
 else:
   self.X_train_n=X_train
 self.Y train=Y train.reshape(-1,1)
 self.m_train,self.n_train=self.X_train_.shape
 self.t=int(np.max(self.Y train)+1) #No of labels possible
 0_train=self.one_hot(self.Y_train)
 self.J_train_list=[]
 self.train_accuracy=[]
 self.hidden_layer_list.insert(0,self.n_train)
 self.hidden_layer_list.append(self.t)
 self.parameters_init("Adam")
```

```
if self.validation:
   if X_dev.size>0 and Y_dev.size>0:
      self.Y_dev=Y_dev.reshape(-1,1)
     0_dev=self.one_hot(self.Y_dev)
     self.J_dev_list=[]
      self.dev_accuracy=[]
      if Feature_Scaling=="Z_score_standardization":
        self.X_dev_n=self.Z_score_standardize(X_dev,self.X_train_)
      elif Feature_Scaling=="min_max_normalization":
       self.X_dev_n=self.min_max_normalize(X_dev,self.X_train_)
      else:
        self.X_dev_n=X_dev
    else:
      print("Enter validation data in function call")
      return
 train_data=np.append(self.X_train_n,0_train,axis=1)
 for i in range(epochs):
   a_train=self.forward_prop(self.X_train_n)[1]
   self.J train list.append(self.Sparse Categorical Cross Entropy(a train,0 train))
    self.train_accuracy.append(self.accuracy(self.Y_train,a_train))
   if validation:
     a_dev=self.forward_prop(self.X_dev_n)[1]
     self.J_dev_list.append(self.Sparse_Categorical_Cross_Entropy(a_dev,0_dev))
     self.dev_accuracy.append(self.accuracy(self.Y_dev,a_dev))
    np.random.shuffle(train data)
   mini_batch_list=[train_data[k:k+mini_batch_size,:] for k in range(0,self.m_train,mini_batch_size)]
   j=1
   for mini_batch in mini_batch_list:
     self.Adam_update(mini_batch,i,j)
      j+=1
 a_train=self.forward_prop(self.X_train_n)[1]
  self.J train list.append(self.Sparse Categorical Cross Entropy(a train,O train))
 self.train_accuracy.append(self.accuracy(self.Y_train,a_train))
 if validation:
   a_dev=self.forward_prop(self.X_dev_n)[1]
   {\tt self.J\_dev\_list.append(self.Sparse\_Categorical\_Cross\_Entropy(a\_dev,0\_dev))}
    self.dev_accuracy.append(self.accuracy(self.Y_dev,a_dev))
def Adam update(self,mini_batch,i,j):
 k=self.mini_batch_size*i+j
 x=mini_batch[:,:self.n_train]
 o=mini_batch[:,self.n_train:]
 A,a=self.forward_prop(x,dropout=self.d)
 dw_list,db_list=self.backprop(A,a,o)
 self.vdw=[(self.beta1*(a)+(1-self.beta1)*b) for a,b in zip(self.vdw,dw_list)]
 self.vdb=[(self.beta1*(a)+(1-self.beta1)*b) for a,b in zip(self.vdb,db_list)]
 self.sdw=[(self.beta2*(a)+(1-self.beta2)*(b**2)) for a,b in zip(self.sdw,dw list)]
 self.sdb=[(self.beta2*(a)+(1-self.beta2)*(b**2)) for a,b in zip(self.sdb,db_list)]
 self.w=[a-((self.alpha*b)/(np.sqrt(c)+self.epsilon)) for a,b,c in zip(self.w,self.vdw,self.sdw)]
 self.b=[a-((self.alpha*b)/(np.sqrt(c)+self.epsilon)) for a,b,c in zip(self.b,self.vdb,self.sdb)]
def backprop(self,A,a,o):
 dw_list,db_list=[],[]
 dz=a-o
 db=(1/o.shape[0])*(np.sum(dz,axis=0))
 dw=(1/o.shape[0])*(A[-2].T@dz)+((self.lamda/o.shape[0])*self.w[-1])
 dw_list.append(dw)
 db_list.append(db)
 for i in range(self.no_hidden_layer):
   dz=(dz@(self.w[-(1+i)].T))*self.ReLU_derivative(A[-(2+i)])
   dw = (1/o.shape[0])*(A[-(3+i)].T@dz) + ((self.lamda/o.shape[0])*self.w[-(2+i)])
   db=(1/o.shape[0])*(np.sum(dz,axis=0))
   dw_list.insert(0,dw)
   db_list.insert(0,db)
 return dw_list,db_list
def Results(self,Cost_learning_curve=True,Accuracy_learning_curve=True,Table_showing_predicted_vs_actual=True): #is used to print the resu
 li=np.arange(0,self.iterations+1)
 if Cost_learning_curve:
   print("Final Cost of training data is: ",self.J_train_list[-1],"\n")
    if self.validation:
      print("Final Cost of dev data is: ",self.J_dev_list[-1],"\n")
```

```
plt.plot(li,self.J_train_list,color="blue",label="Training Cost")
    if self.validation:
     plt.plot(li,self.J_dev_list,color="Red",label="Dev cost")
    plt.xlabel("Epochs")
    plt.ylabel("Cost")
    plt.title("Cost vs Iterations curve")
    plt.legend()
    plt.show()
    print("\n")
  if Accuracy learning curve:
    print("Final Accuracy of training data is: ",self.train_accuracy[-1],"%")
    print("\n")
    if self.validation:
     print("Final Accuracy of dev data is: ",self.dev_accuracy[-1],"%")
    plt.plot(li,self.train_accuracy,color="blue",label="Train")
    if self.validation:
      plt.plot(li,self.dev_accuracy,color="Red",label="Dev")
    plt.xlabel("Epochs")
    plt.ylabel("Accuracy")
    plt.title("Accuracy vs Epochs curve")
    plt.legend()
    plt.show()
    print("\n")
  if Table_showing_predicted_vs_actual:
    train_table=np.append(self.Y_train[:20,:],self.predict(self.X_train_n,True).reshape(-1,1)[:20,:],axis=1)
    df=pd.DataFrame(train_table,columns=["Actual","Predicted"])
    print("A table showing predicted labels and actual label for the first 20 examples of training data: ")
    print(df)
    print("\n")
    if self.validation:
     train_table=np.append(self.Y_dev[:20,:],self.predict(self.X_dev_n,True).reshape(-1,1)[:20,:],axis=1)
      df=pd.DataFrame(train_table,columns=["Actual","Predicted"])
      print("A table showing predicted labels and actual label for the first 20 examples of dev data: ")
      print(df)
def one_hot(self,Y): #One hot encoding the label array
 o=np.zeros((Y.shape[0],self.t))
 o[np.arange(len(Y)),Y.flatten().astype(int)]=1
  return o
def ReLU(self,z): #Returns ReLU
 return np.maximum(0,z)
def softmax(self,z): #finds softmax value for the output layer
  a=np.exp(z)/(np.sum(np.exp(z),axis=1).reshape(-1,1))
  return a
def ReLU_derivative(self,A): #derivative of the relu function
  return A>0
def Sparse_Categorical_Cross_Entropy(self,A,o): #finds the sparse categorical cross entropy loss
  loss=np.sum(np.nan_to_num(-np.log(A)*o))/A.shape[0]
  return loss
def accuracy(self,Y,A): # will be used to find the accuracy
  return (np.sum(np.argmax(A,axis=1)==(Y.flatten())))/A.shape[0]*100
def predict(self,X_test,normalized=False): #A predict function to predict labels for a given test data
  if normalized==False:
    if self.Feature_Scaling=="Z_score_standardization":
      X_test_n=self.Z_score_standardize(X_test,self.X_train_)
    elif self.Feature_Scaling=="min_max_normalization":
                                                                       #All these lines are to normalize the data if not done
     X test n=self.min max normalize(X test,self.X train )
    else:
      X_test_n=X_test
    X_{\text{test}_n=X_{\text{test}}}
  prediction=np.argmax(self.forward prop(X test n)[1], axis=1) # this step will do the prediction
  return prediction
```

```
df=pd.read_csv("/content/drive/MyDrive/Woc/classification_train.csv")
df_arr=np.array(df)
X=df_arr[:,2:]
Y=df_arr[:,1]

Model=Neural_Network([100])
X_train,Y_train,X_dev,Y_dev=Model.train_dev_split(X,Y,0.8)
Model.Adam(X_train,Y_train,epochs=10,learning_rate=0.002,L2_regularization_term=0,beta1=0.9,beta2=0.999,epsilon=10**-8,Exp_learning_rate_deca
Model.Results()
```



A table showing predicted labels and actual label for the first 20 examples of train $\mbox{\sc Actual}$ $\mbox{\sc Predicted}$

	ACCUAL	TTEGICCEG
0	8	8
1	4	4
2	1	1
3	8	8
4	2	6
5	0	0
6	7	7
7	4	4
8	1	1
9	7	7
10	9	9
11	0	0
12	1	1
13	7	7
14	2	4
15	3	0
16	2	4
17	3	3
18	4	4
19	8	8

A table showing predicted labels and actual label for the first 20 examples of dev ${\tt d}$

	Actual	Predicted
0	4	4
1	0	0
2	1	1
3	1	1
4	6	6
5	6	4
6	2	4
7	4	4

df_test=pd.read_csv("/content/drive/MyDrive/Woc/classification_test.csv")

X_test=np.array(df_test)[:,1:]

id=np.array(df_test)[:,0].reshape(-1,1)

 ${\sf X=Model.Z_score_standardize}({\sf X_test,X_train})$

Y_predict=Model.predict(X,True).reshape(-1,1)

arr=np.append(id,Y_predict,axis=1)

df=pd.DataFrame(arr)

df.to_csv("Neural_Network_test_csv")

10 1 1

×