

Data Structure

Q1. Insertion Sort

void insertionSort (int A[], int n)

{

 for(i = 1 ; i < n ; i++)

 {

 j = i - 1;

 x = A[i];

 while (j > -1 && A[j] > x)

 {

 A[j+1] = A[j];

 j --;

 }

}

Insertion sort performs two operations :

it scans through the list, comparing each pair of elements, & it swaps elements if they are out of order. Each operation contributes to the running time of the algorithm. If the input is already in sorted

order, insertion sort compares $O(n)$ elements & performs no swaps (in the above code, the inner loop is never triggered). Therefore, in the best case, insertion sort runs in $O(n)$ time.

In an insertion sort algorithm, there are always two constraints in time complexity. One is shifting the elements & the other one is comparison of the " ". The time complexity is also dependent on the data structure which is used while sorting.

If we use ^{array as} data structure then shifting takes $O(n^2)$ in the worst case. While using link list data structure, searching takes $O(n^2)$.

Sort 50, 40, 30, 20, 10 using arrays

If we solve above list using array data structure we can use binary search for comparison which will lead to a time complexity of $O(n \log n)$ but shifting takes $O(n^2)$. Therefore, the total time complexity becomes $O(n^2)$

To solve this problem, link list can be used. In a link list shifting takes $O(1)$ as new element can be inserted at their right pos. without shifting. Here as we cannot use binary search for comparison which will lead to a time complexity of $O(n^2)$ even though shifting takes a constant amount of time.

As we have observed in the above examples above, in both the cases the time complexity is not getting reduced. Hence we are using an improvised insertion sort taking additional space to sort the elements.

from: UKESSAYS (Providers of free study resources)

In the insertion sort techniques proposed here, we will take $2n$ spaces in an array DS, where n is the total no. of elements. The insertion of elements will start from $(n-1)^{th}$ pos. of the array. The same procedure of a standard insertion sort is followed in this technique.

Finding the suitable positions of the elements to be inserted will be done using binary search. In the following cases we will discuss the details of our work:

Case 1. for the best case scenario in a standard insertion sort is the input elements in ascending order using proposed technique:

e.g. 10, 20, 30, 40, 50

i)

				10					
0	1	2	3	4	5	9	7	8	9

shift = 0 , comparison = 0

ii)

					10	20			
0	1	2	3	4	5	6	7	8	9

shift = 0 , comparison = 1

iii)

				10	20	30			
0	1	2	3	4	5	6	7	8	9

shift = 0 , comparison = 1

iv)

					10	20	30	40		
0	1	2	3	4	5	6	7	8	9	

shift = 0 , comparison = 1

v)

					10	20	30	40	50	
0	1	2	3	4	5	6	7	8	9	

shift = 0 , comparison = 1

total shift = 0, total comp. = $n - 1$

\therefore time complexity = $O(1) + O(n) = O(n)$

Case 2 for worst case scenario in a standard insertion sort is the input elements in descending order using proposed technique

e.g. 50, 40, 30, 20, 10

i)					50					
	0	1	2	3	4	5	6	7	8	9

shift = 0, comp. = 0

ii)					50 40					
	0	1	2	3	4	5	6	7	8	9
					40 50					
	0	1	2	3	4	5	6	7	8	9

shift = 1

comp = $\log 1$

iii)					40 50 30					
	0	1	2	3	4	5	6	7	8	9

				30 40 50						
	0	1	2	3	4	5	6	7	8	9

shift = 1, comp = $\log 2$

iv)				30 40 50 20						
	0	1	2	3	4	5	6	7	8	9

	20	30	40	50					
0	1	2	3	4	5	6	7	8	9

shift = 1, comp. = $\log 3$

v)

	20	30	40	50	10				
0	1	2	3	4	5	6	7	8	9

10	20	30	40	50					
0	1	2	3	4	5	6	7	8	9

shift = 1, comp. = $\log 4$

total shift = $n-1 = O(n)$

total comp = $\log(1*2*3*4)$
 $= n \log(n)$

\therefore complexity = $O(n \log n)$

case 3. for the average case scenario in a standard insertion sort, the input elements are in random order. We are following the same procedure but comp. is done via binary search algo., hence it takes $O(n \log n)$ for comp., for shifting the elements the time taken tends to $O(n^2)$ but is not equal to $O(n^2)$. As we have more spaces, there are possibilities that the shifting of some elements

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may be reduced because elements may be inserted both at the end as well as in the beginning

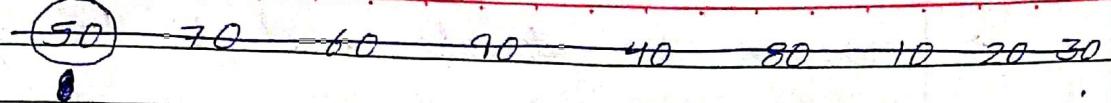
Q2 Quick sort (in-place sorting technique)

In quick sort an element is in sorted position if all elements before it are smaller & all the elements after it are ~~less~~ greater

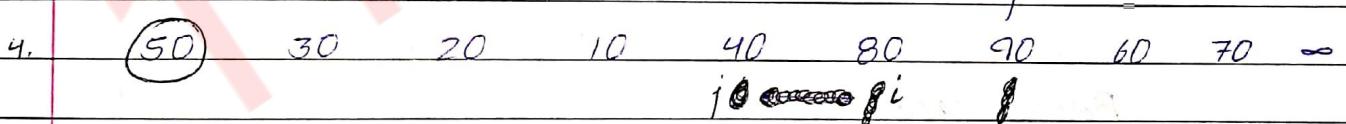
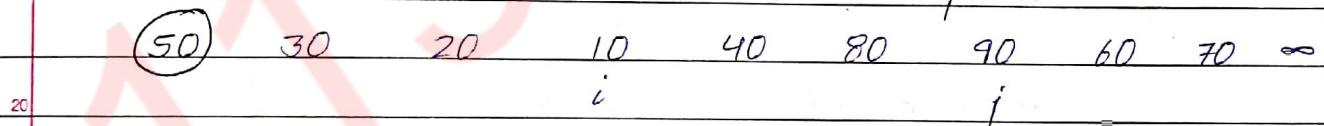
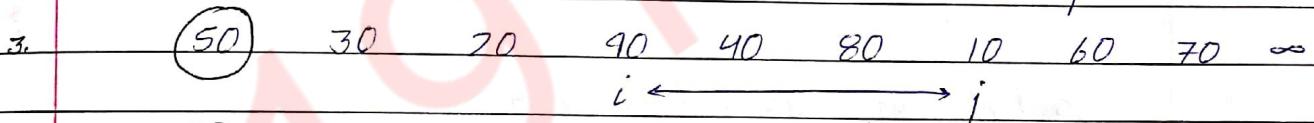
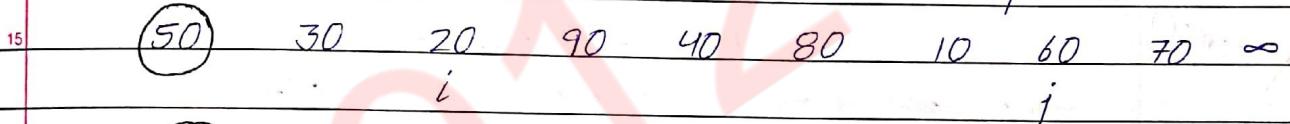
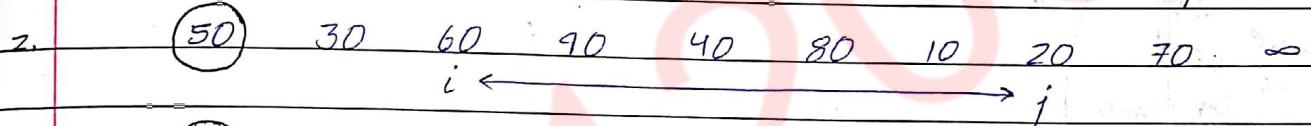
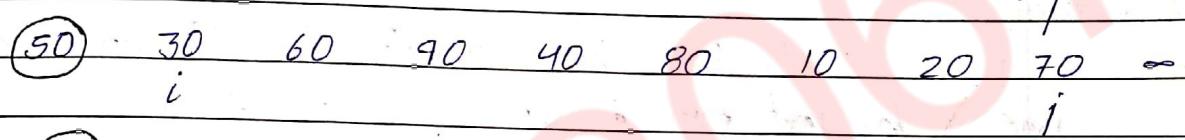
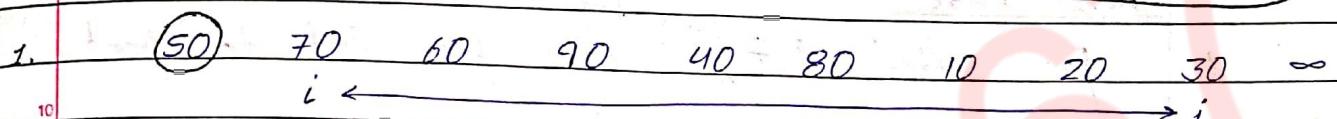
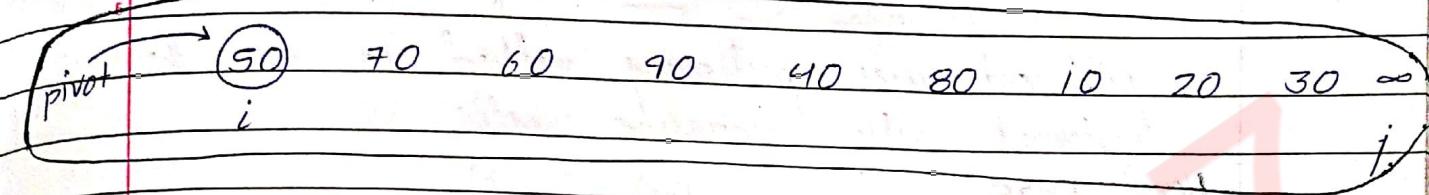
40 30 20 50 90 70 80 at sorted position

(pivot) (element which have to find its place in list)

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\Rightarrow i will look for element "greater" than pivot element
 \Rightarrow j " " " " " smaller or equal "



50, 30, 20, 10 \Rightarrow exchange pivot & 'j' element

\Rightarrow if 'i' element is greater than pivot & 'j' element is smaller than pivot, then exchange elements at 'i' & 'j'

left side

right side

(40 30 20 10) (50) (80 90 60 70, ~)

partitioning position

(new sort again it with)
quicksort

(sort again it with)
quicksort

\Rightarrow quicksort is applied recursively on left & right side

⇒ minimum two elements must be there for quick sort

⇒ ∞ will act as infinity for right list & partitioning element will act as infinity for left list

5

∴ quicksort uses partitioning method to sort the element with recursive calls

Worst case

for sorted list (ascending) j move from last to front

10

∴ if list have n elements, j moves n times

here time
is used
for
comparisons

for next turn j move $(n-1)$ times

:

2

1

$$1 + 2 + 3 + \dots + n$$

15

$$\text{time complexity} = \frac{n(n+1)}{2} = O(n^2)$$

#

sorted in descending order

20

$$\text{comparisons (time complexity)} \approx O(n^2)$$

Best case

⇒ assume element from ① ② 15 elements

⇒ let partitioning is done at middle

1

15

level 1

partitioning
element

quicksort
call

1, 15

8 ①

level 2

1, 7

① 9, 15

4 ②

12

13 ③

level 3

1, 3

5, 7

9, 11

13, 15

2 ④

6 ⑤

8 ⑥

14 ⑦

level 4

1, 1

3, 3

5, 5

7, 7

9, 9

11, 11

13, 13

15, 15

1 ⑧

3 ⑨

5 ⑩

7 ⑪

9 ⑫

11 ⑬

13 ⑭

15 ⑮

⇒ if we select randomly any element as pivot then this is called randomized quick sort.

for level 1 → n comp.

" 2 → "

" 3 → "

5 " 4 → no comp

let assume there are 16 elements

$$\frac{16}{2} = \frac{8}{2} = \frac{4}{2} = \frac{2}{2} = 1$$

$$\therefore \log_2(16) = 4 \text{ level} \quad (\text{for } n=16)$$

$$\log_2(n) = n \quad (\text{for } n=n)$$

$$\therefore \text{total comparisons} = O(n)$$

& comparisons are done for $= O(\log n)$ times

∴ time complexity (time for comp.) $= O(n \log n)$

first element

Best case → if partitioning is in middle
time $\rightarrow O(n \log n)$

Worst case → if partitioning is done
on either side (i.e. for sorted list)
time $\rightarrow O(n^2)$

Average case $\rightarrow O(n \log n)$

⇒ if we select middle element as pivot, then

best case → sorted list $\rightarrow O(n \log n)$

worst " → partitioning at any end $\rightarrow O(n^2)$

⇒ Quick sort is also called as
④ partition exchange sort
⑥ selection " "

Quick v/s Selection

- # in quick sort we select an element & then find its position in the list
- # but for selection we select a position & then find element for it

fun^c to find partitioning position in the list

```
int partition ( int A[], int l, int h )
{
    int pivot = A[l];
    int i = l, j = h;
    do
    {
        do
        {
            i++;
        } while (A[i] ≤ pivot);
        do
        {
            j--;
        } while (A[j] > pivot);
        if (i < j)
            swap ( A[i], A[j] );
    } while (i < j);
    swap ( A[l], A[j] );
    return j;
}
```

// swap pivot & 'j' element

⇒ write quicksort fun^c using above partition fun^c to sort the elements

30

Bubble sort
(in-place sorting technique)

1st pass will give max. no.
2nd " " " two max. no.

A	8	5	7	3	2		(n = 5)
	0	1	2	3	4		

comparison 1 (swap if ~~first~~ second no. is small)

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1st pass

8	5	5	5	5	5
5	8	7	7	7	7
7	7	8	3	3	
3	3	3	8	2	
2	2	2	2	8	

⇒ 4 comparison
⇒ 4 swap

largest element is sorted

2nd pass

9	5	5	5	5	5
7	7	7	3	3	
3	3	7	2		
2	2	2	7		
8	8	8	8	8	

⇒ 3 comp.
⇒ 3 swap. (max)

two elements are sorted

3rd pass

⇒ three element are sorted

⇒ 2 comp.

⇒ max. 2 swap

4th pass

⇒ four element are sorted, so 5th

⇒ 1 comp

⇒ max. 1 swap

element will automatically get sorted

$$\Rightarrow \text{no. of passes} = 4 = (n-1) \text{ passes} = O(n)$$

$$\Rightarrow \text{no. of comp} = 1 + 2 + 3 + 4 \quad (\text{for } n=5)$$

$$1 + 2 + 3 + \dots + n-1$$

(for n)

$$= \frac{n(n+1)}{2}$$

$$\approx O(n^2)$$

$$\Rightarrow \text{max. no. swap} = 1 + 2 + 3 + 4 \quad (\text{for } n=5)$$

$$1 + 2 + 3 + \dots + n-1$$

(for $n=n$)

$$\approx \frac{n(n-1)}{2}$$

$$\approx O(n^2)$$

void bubblesort (int A [], int n)

{ int flag;

for (i = 0; i < n-1; i++)

// no. of pass

{ flag = 0;

for (j = 0; j < n-1-i; j++)

// no. of comp.
or swap

{ if (A[j] > A[j+1])

{

swap (A[j], A[j+1])

}

flag = 1;

} if (flag == 0) break;

// no swapping
is done

}

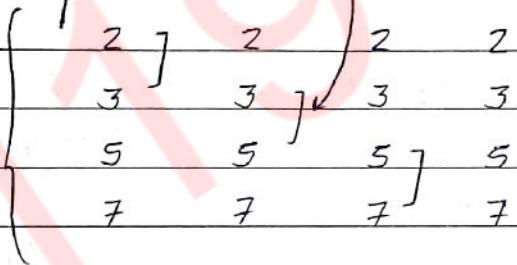
∴ time complexity $\approx O(n^2)$

15

⇒ Adaptive comparison

1st pass

already
sorted
list
(n=4)



no. of comp = n-1

no. of swap = 0

time complexity $\approx O(n)$

∴ time for bubble sort

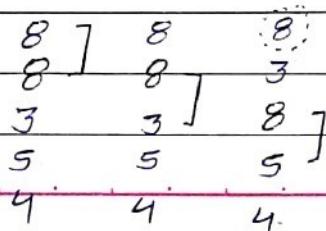
minimum $\approx O(n)$

25

maximum $\approx O(n^2)$

∴ bubble sort is ^{not} _{nature} adaptive by $\text{ } \text{ } \text{ } \text{ } \text{ }$, we make it adaptive
by using flag

⇒ 30 Stable



(∵ bubble sort is
stable)

30

Merge sort

1. Merging two list. (merging of two sorted list & creating a single " . . . ")

Merge : is the process of merging multiple sorted list into a new single sorted list

(i) \rightarrow	0	1	2	3	4	
A	2	10	18	20	23	
B	4	9	19	25		

\Rightarrow we will compare $A[i]$ & $B[j]$, & store smaller element in $C[k]$

C	2	4	9	10	19	19	20	23	25	
k \rightarrow	0	1	2	3	4	5	6	7	8	

\Rightarrow as soon as one of the list is finished & have some elements remaining in other list, copy all the remaining elements in $C[k]$ array as it is

```
void merge (int A[], int B[], int m, int n)
{   int i, j, k;
    i = j = k = 0;
```

```
    while (i < m && j < n)
    {
```

```
        if (A[i] <= B[j])
            C[k++] = A[i++];
```

```
        else
            C[k++] = B[j++];
```

```
    }
```

```
    for ( ; i < m ; i++)
        C[k++] = A[i];
```

```
    for ( ; j < n ; j++)
        C[k++] = B[j];
    }
```

\therefore time complexity $\Theta(m+n)$

2. Merging two list in single Array

(i) \rightarrow	mid	\downarrow	(j) \rightarrow	h	
A	2	5	8	12	

0	1	2	3	4	5	6	7
List 1				List 2			

⇒ here also we compare $A[i]$ & $A[j]$, & will copy smaller element into $B[k]$, & will copy remaining element

B		2		3		5		6		7		8		10		12	
---	--	---	--	---	--	---	--	---	--	---	--	---	--	----	--	----	--

5

⇒ I ^{COPY} array B to array A

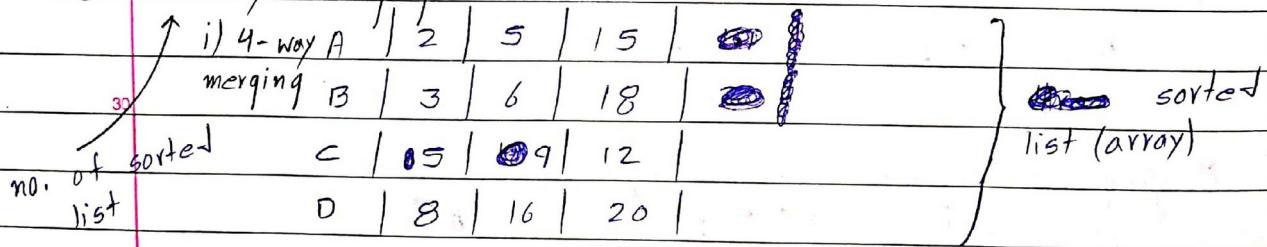
```

void merge ( int A[], int l, int h, int mid )
{
    int i = 0, j, k;
    i = l, j = mid + 1, k = l;
    int B[h++];
    while ( i <= mid & & j <= h )
    {
        if ( A[i] < A[j] )
            B[k++] = A[i++];
        else
            B[k++] = A[j++];
    }
    for ( ; i <= mid ; i++ )
        B[k++] = A[i];
    for ( ; j <= h ; j++ )
        B[k++] = A[j];
    for ( i = l ; i <= h ; i++ ) // array A = B
        A[i] = B[i];
}

```

3. Merging multiple list

a) M-way merging



⇒ we will compare $A[i]$, $B[j]$, $C[k]$, $D[l]$ elements & copy smallest element in $E[m]$, & copy remaining elements

Two - way merging

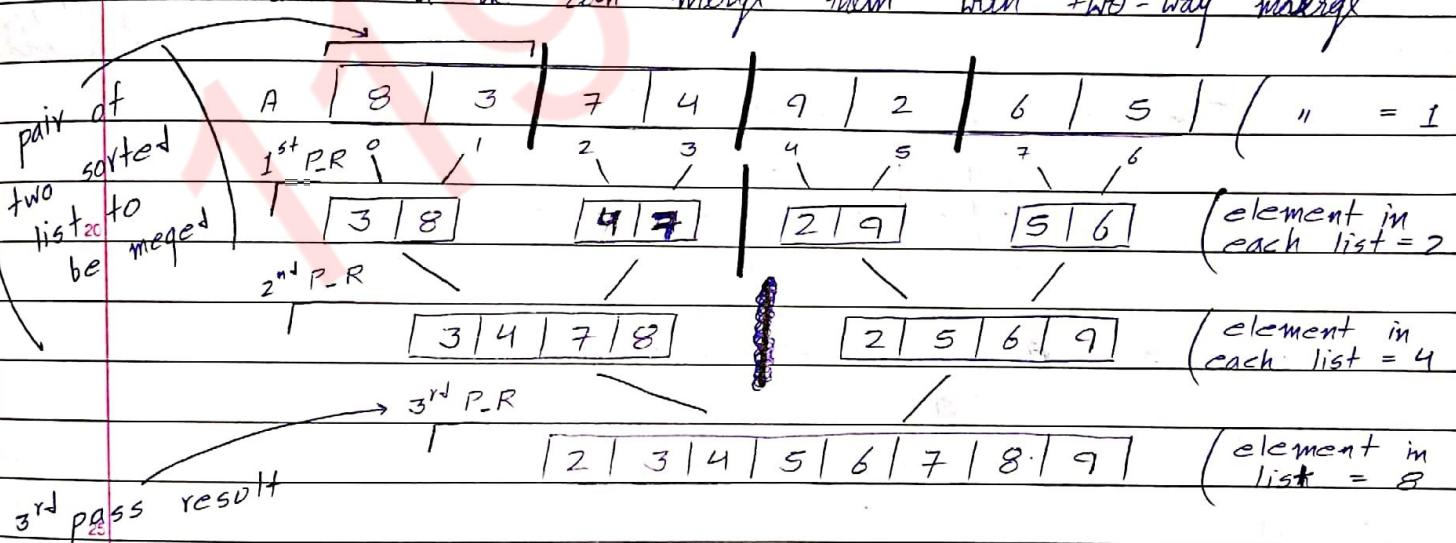
5
⇒ we will select two sorted array at a time & merge them, this process will continue unless we get a single sorted array

Two-way iterative merge sort

A 8 3 7 4 9 2 6 5 (n=8)
0 1 2 3 4 5 6 7

let A is array containing 8 sorted list (i.e. each element)

15 & each list contain one single element, ∵ each list is sorted & we can merge them with two-way merge



elements merged in 1st pass = $O(n)$
 2nd .. = $O(n)$
 3rd pass = $O(n)$

30 & merging is done for $O(\log n)$ times ($\log_2 8 = 3$)

∴ time complexity $O(n \log n)$

```

void Tmerge (int A[], int n)
{
    int p, i, l, mid, h;
    for (p = 2; p <= n; p = p * 2) // pass
    {
        for (i = 0; i + p - 1 < n; i = i + p)
        {
            l = i;
            h = i + p - 1;
            mid =  $\lfloor (l+h)/2 \rfloor$ ;
            merge (A, l, mid, h);
        }
    }
    if ( $p/2 < n$ )
        merge (A, 0,  $p/2-1, n-1$ ); // for
} // merging if n is odd

```

Two way recursive merge sort

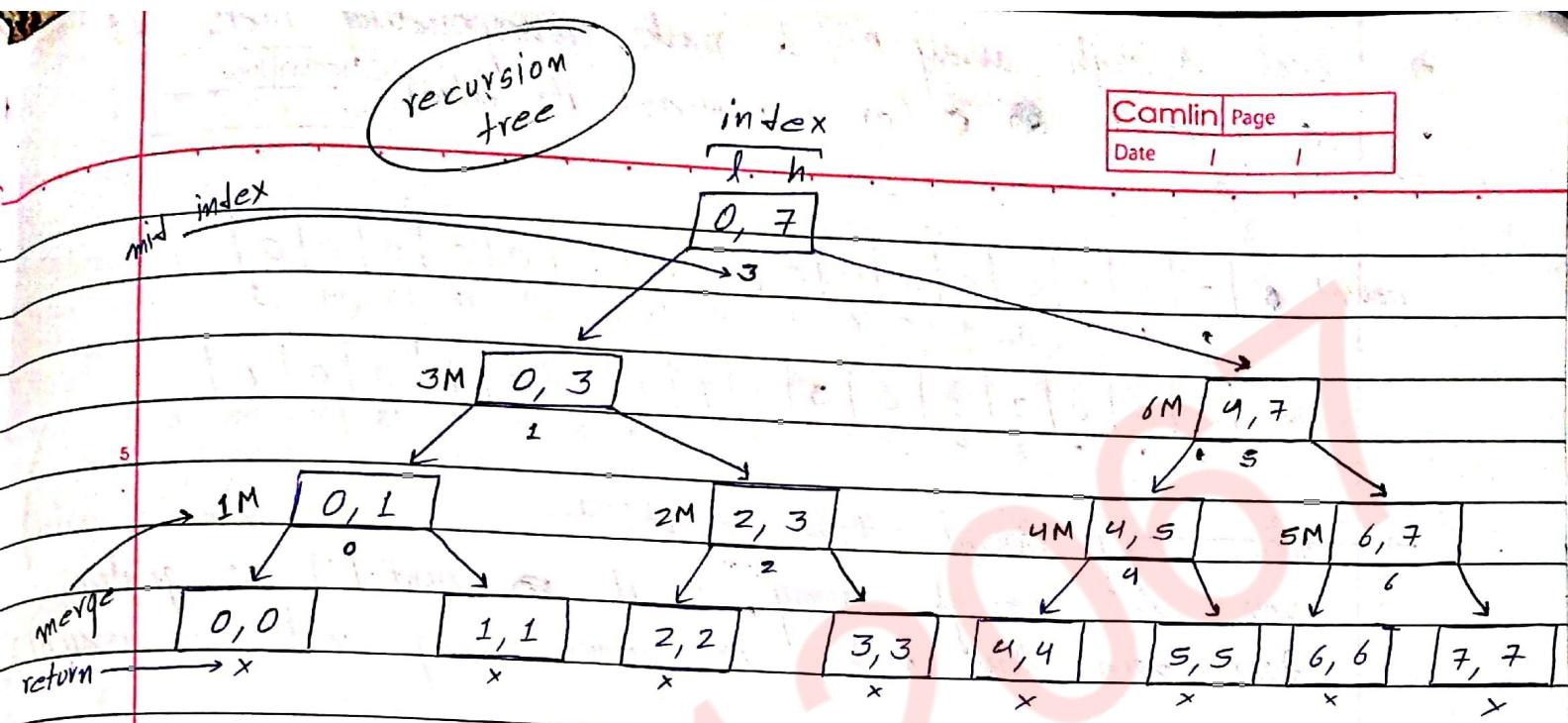
A	1	8	2	mid	9	6	5	3	7	4	h
	0	1	2	3	4	5	6	7	8	9	

```

void mergesort (int A[], int l, int h)
{
    if (l < h)
    {
        mid =  $\lfloor (l+h)/2 \rfloor$ ;
        mergesort (A, l, mid);
        mergesort (A, mid + 1, h);
        merge (A, l, mid, h);
    }
}

```

merge is done in post order



no. of elements merged in each level = $O(n)$
 (expect last level)

merging is done for $O(\log n)$

\therefore time complexity = $(O(n \log n))$

space complexity

space for array A = n

" " auxiliary array B = n

stack size required = $\log n$

\therefore total space = $O(n + \log n)$

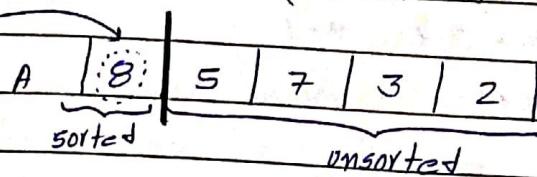
\Rightarrow Out of comparison based sorting only merge sort require extra space

→ shifting & comparison is done from back side
 → shifting & comp. is done from back side

Insertion sort

(insertion is done in increasing order)

Let this
is already
sorted

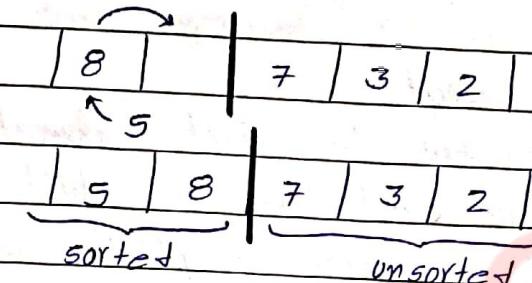


1st pass (n=5)

a. Insert (5)

{ 5 moves in
element front }

10



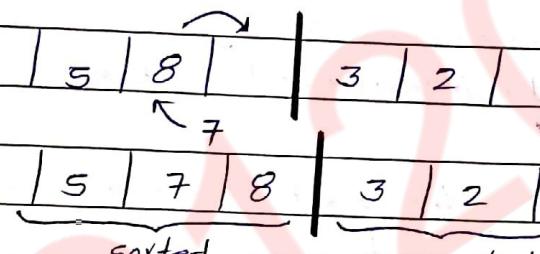
comp. = 1

swap = 1
or shift

2nd pass

Insert (7)

15



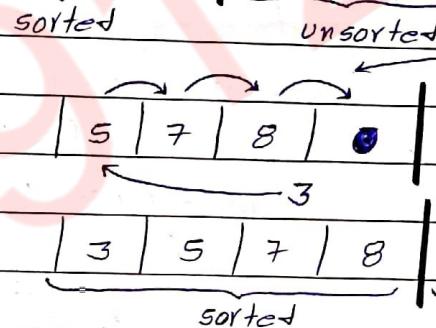
max. comp = 2

max. swap = 2
or shift

3rd pass

Insert (3)

20



(shifting is done
from back side)

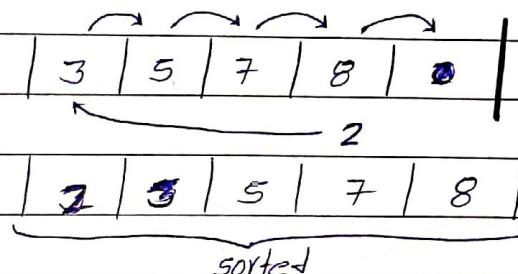
3 comp. (max)

3 swap. (max)
or shift

4th pass

Insert (2)

25



comp = 4

swap = 4
or shift

$$\Rightarrow \text{no. of pass} = 4$$

$$\approx n-1$$

(for $n=5$)

(for $n=n$)

$$\Rightarrow \text{no. of comp.} = 1 + 2 + 3 + 4$$

$n=5$

$$1 + 2 + 3 + \dots + n-1$$

$n=n$

$$\approx n(n-1) \approx O(n^2)$$

c.g.

6	8	12	14	18	20	
	j		i			

$$\begin{aligned}
 \text{no. of swap} &= 1+2+3+4 & (n=5) \\
 \text{or shift} & 1+2+3+\dots+n-1 & (n=n) \\
 &\frac{n(n-1)}{2} \\
 &\approx O(n^2)
 \end{aligned}$$

⇒ no intermediate result

⇒ with array we have to shift elements for insertion sort
 ⇒₁₀ but with LL we don't have to shift elements, ∵ insertion sort is more compatible with LL than array

void insertionsort (int A[], int n)

{

for (i = 1; i < n; i++) // pass

{

j = i - 1;

x = A[i];

while (j > -1 & A[j] > x) // shift or comp.

A[j + 1] = A[j];

j = j - 1;

}

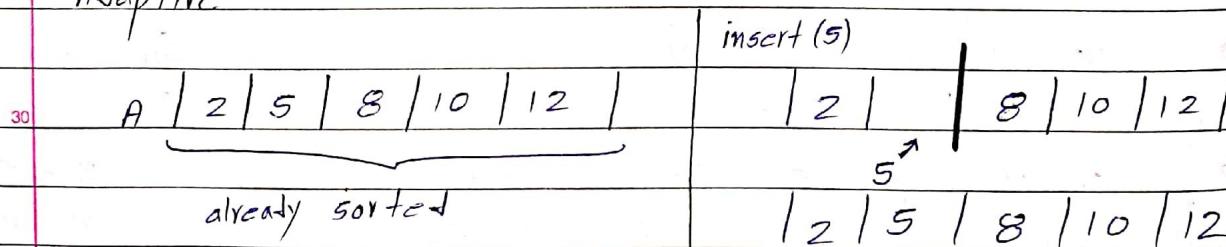
A[j + 1] = x

}

}

∴ time complexity $\approx O(n^2)$

⇒ Adaptive



$$\text{no. of comp} = n-1 = O(n)$$

$$\text{no. of shift} = 0$$

$$\therefore \text{time complexity} = O(n)$$

\Rightarrow_5 insertion sort is adaptive by nature; we don't have used flag here to make it adaptive

time required for insertion sort

$$\max = O(n^2)$$

$$\min = O(n)$$

10

\Rightarrow if list is sorted in ascending order (best case)
 (time) comp. = $O(n)$ ~~comp.~~
 shift = $O(1)$

\Rightarrow_{15} if list is sorted in descending order (worst case)
~~comp.~~ shift = $O(n^2)$
 (time complexity) comp. = $O(n^2)$

\Rightarrow stable

20 A | 3 | 5 | 8 | 10 | 12 | 5 |

insert (5) | 3 | 5 | 8 | 10 | 12 | 5 |

| 3 | 5 | 5 | 8 | 10 | 12 |

25

\therefore insertion sort is stable

Q3) two - way merging

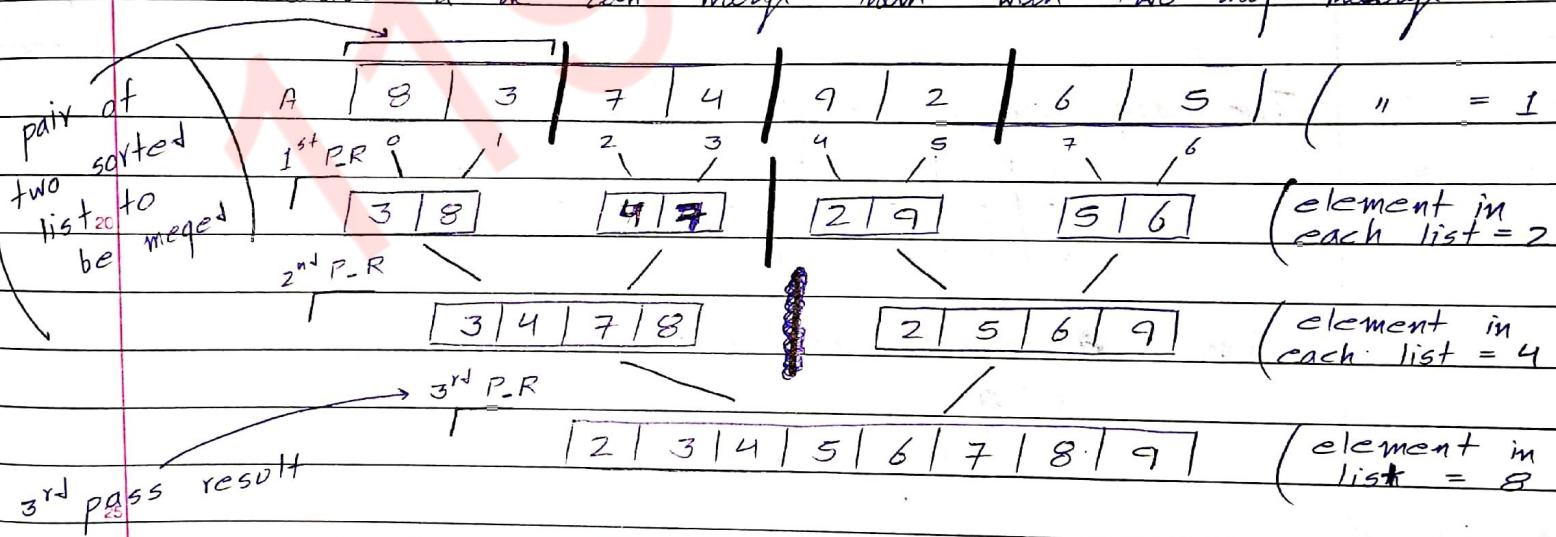
5
⇒ we will select two array at a time & merge them,
this process will continue unless we get a single sorted
array

10 Two-way iterative merge sort

A | 8 | 3 | 7 | 4 | 9 | 2 | 6 | 5 | (n=8)
0 1 2 3 4 5 6 7

let A is array containing 8 sorted list (i.e. each element)

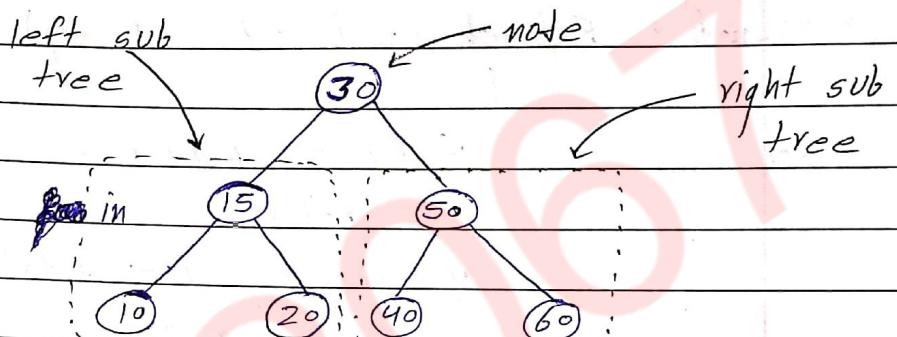
15 & each list contain one single element, ∵ each list
is sorted & we can merge them with two-way merge



So, we have used the above two-way merge sort, the only difference is, here we are handling the strings, in place of numbers.

To compare capital letters with small letters, we have compared capital letters as small letters by adding 32 to each capital letter when encountered in the string.

Q4 BST intro



it is a binary tree which for every node all the elements

on its left sub tree are smaller than element on that node & all the elements on its right sub tree are greater than element on that node.

- ⇒ it will not have duplicate elements
- ⇒ inorder traversal give elements in sorted order
- ⇒ no. of BST for 'n' nodes (given in inorder)

$$= \binom{2^n C_n}{n+1} \text{ trees}$$

```
node * Rinsert (node * p, int key)
```

```
{
```

```
    node * t;
```

```
    if (p == NULL)
```

```
{
```

```
        t = malloc ( );
```

```
        t -> data = key;
```

```
        t -> lchild = t -> rchild = NULL;
```

```
        return t;
```

```
}
```

```
    if (key < p -> data)
```

```
        p -> lchild = insert (p -> lchild, key);
```

```
    else if (key > p -> data)
```

```
        p -> rchild = insert (p -> rchild, key);
```

```
    return p;
```

```
}
```

```
int main ()
```

```
{
```

```
    node * root = NULL;
```

```
    root = insert (root, 30);
```

```
    insert (root, 20);
```

```
}
```

For this specific function we have created dynamic array by using malloc to store name during runtime.

And then we compare each letter of name to decide whether it will be left or right child of the root name.