

ANTI-LOCK BRAKING SYSTEM

TATA SIERRA SUV – MATLAB SCRIPT

1. Command Window Input & Results:

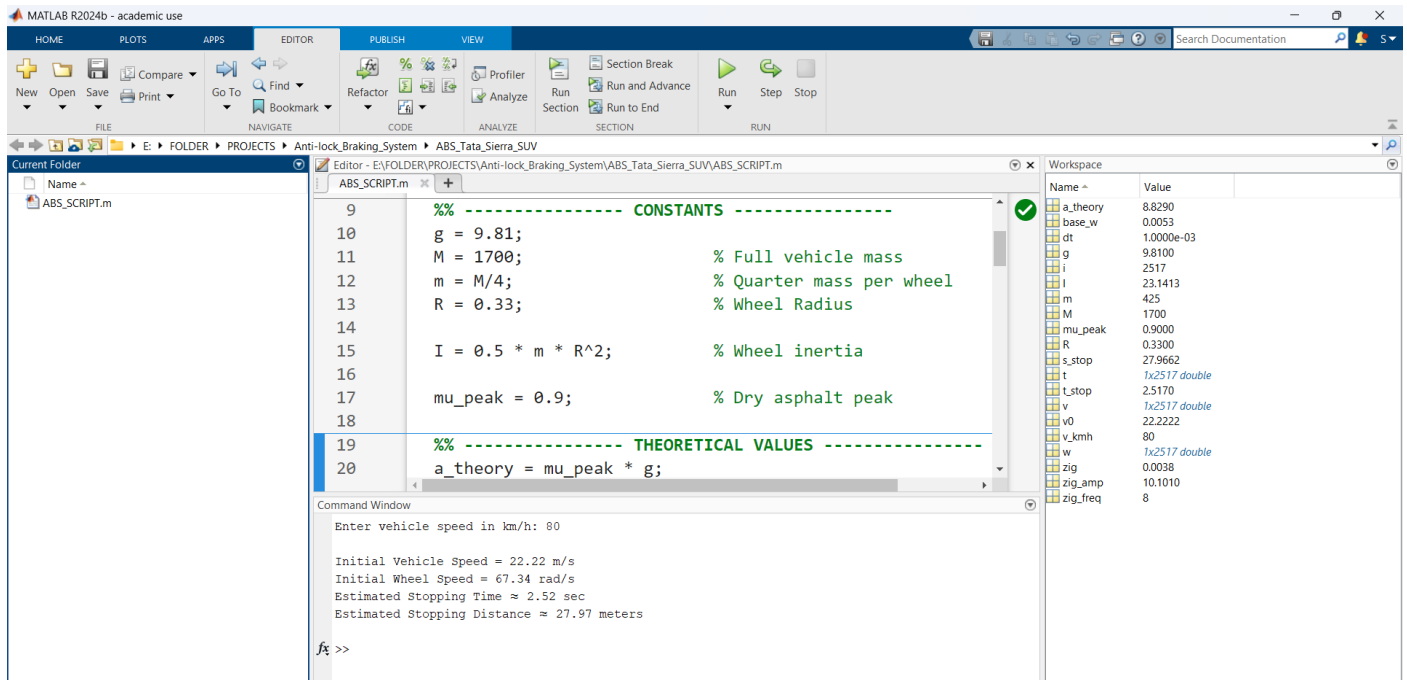


FIG.1.1: Displays user-entered vehicle speed and the computed theoretical values such as initial speeds, stopping time, and stopping distance using ABS braking equations.

2. WHEEL SPEED AND VEHICLE SPEED :

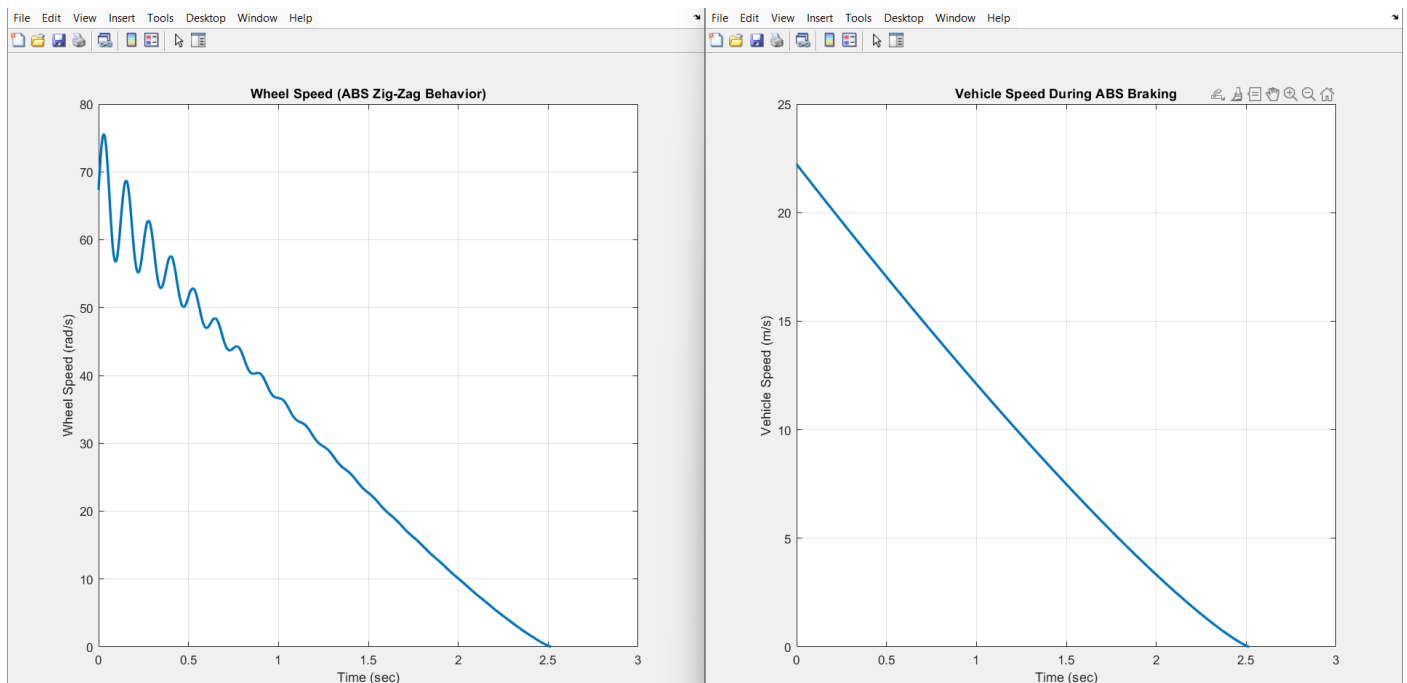


FIG1.2: WHEEL SPEED: Illustrates oscillatory wheel speed caused by ABS modulation, gradually decreasing to zero while preventing wheel lock.

VEHICLE SPEED: Represents smooth nonlinear reduction of vehicle speed from initial velocity to zero within the estimated stopping time.

DESIGN AND CALCULATIONS - ABS

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Date _____

Page _____

* STEP 1: Convert Vehicle Speed

$$V_0 = \frac{80 \times 1000}{3600}$$

$$V_0 = 22.22 \text{ m/s}$$

* STEP 2: Wheel Angular Speed

Given, $R = 0.33 \text{ m}$

$$\omega_0 = \frac{V_0}{R} = \frac{22.22}{0.33}$$

$$\omega_0 = 67.34 \text{ rad/s}$$

* STEP 3: Vehicle Mass Data

Total Vehicle Mass : $M = 1700 \text{ kg}$

$$m = \frac{1700}{4} = 425 \text{ kg (one wheel)}$$

* STEP 4: Normal Force on One Wheel

$$N = \frac{Mg}{4} = \frac{1700 \times 9.81}{4} = 4169.25 \text{ N}$$

* STEP 5: Friction Force (Dry Asphalt)

For Dry road, $\mu \approx 0.9$

$$F = \mu N$$

$$F = 0.9 \times 4169.25 = \boxed{3752.3 \text{ N}}$$

* STEP 6: Vehicle Deceleration

$$a = \frac{F_{\text{total}}}{M} \quad (\text{Total Force from 4 wheel})$$

$$F_{\text{total}} = 4F = 4 \times 3752.3$$

$$F_{\text{total}} = 15009.2 \text{ N}$$

$$\rightarrow a = \frac{F_{\text{total}}}{M} = \frac{15009.2}{1700}$$

$$\boxed{a = 8.83 \text{ m/s}^2}$$

* STEP 7: Stopping Time

$$t = \frac{V_0}{a} = \frac{22.22}{8.83}$$

$$\boxed{t = 2.52 \text{ sec}}$$

* STEP 8: Stopping Distance

$$S = \frac{V_0^2}{2a} = \frac{(22.22)^2}{2 \times 8.83}$$

$$S = \frac{493.8}{17.66} = \boxed{27.97 \text{ meters}}$$

* STEP 9: Wheel Rotational Inertia

$$I = 0.5 \times M_{\text{wheel}} \times R^2$$

$$I = 0.5 \times 20 \times (0.33)^2 = 1.089 \text{ kg.m}^2$$

→ $\boxed{I = 1.5 \text{ kg.m}^2}$ is reasonable including tire + brake disc.

* STEP 10: ABS Theory

$$\text{Slip ratio: } \lambda = \frac{V - \omega R}{V}$$

ABS keeps slip near 0.15 - $\boxed{0.2}$

This produces:

- * Zig-zag oscillation
- * Average deceleration $\approx 8.8 \text{ m/s}^2$
- * Stopping time $\approx 2.5 \text{ sec}$