I cannot load CityScape dataset as they did not validate my account

```
# transform = T.Compose([ T.Resize((256, 512)), T.ToTensor()])
# input transform = T.Compose([
     T.Resize((256, 256)),
     T.ToTensor(),
     T.Normalize(mean=[0.485, 0.456, 0.406], std=[0.229, 0.224, 0.225])
# 1)
# target_transform = T.Compose([
     T.Resize((256, 256)),
     T.ToTensor()
# 1)
# # Load the Cityscapes dataset
# dataset =Cityscapes('./data/cityscapes', split='train', mode='fine', target type=['instance', 'color', 'polygon'])
# train_loader = DataLoader(cityscapes_train, batch_size=8, shuffle=True)
# val_loader = DataLoader(cityscapes_val, batch_size=8, shuffle=False)
import os
import torch
import torch.nn as nn
import numpy as np
import torch.optim as optim
import torchvision.transforms as T
from torch.utils.data import DataLoader, random_split
from torchvision.datasets import Cityscapes
from torchvision.models.segmentation import fcn_resnet50
from torchvision.utils import make_grid
from torchvision.datasets import VOCSegmentation
from tgdm import tgdm
import matplotlib.pyplot as plt
device = torch.device('cuda' if torch.cuda.is_available() else 'cpu')
```

```
# Transforms
input transform = T.Compose([ T.Resize((256, 256)), T.ToTensor(), T.Normalize(mean=[0.485, 0.456, 0.406], std=[0.229, 0.224, 0.225]) ])
target_transform = T.Compose([ T.Resize((256, 256)), T.ToTensor() ])
# Load Pascal VOC dataset
# My initial plan was to use Cityscape Dataset but they took long time to validate my account
dataset = VOCSegmentation(root='./data', year='2012', image set='train', download=True, transform=input transform, target transform=target transform)
# Split dataset
train size = int(0.7 * len(dataset))
val\_size = int(0.15 * len(dataset))
test size = len(dataset) - train size - val size
train_dataset, val_dataset, test_dataset = random_split(dataset, [train size, val size, test size])
# DataLoader
batch size = 8
train loader = DataLoader(train dataset, batch size=batch size, shuffle=True)
val loader = DataLoader(val dataset, batch size=batch size, shuffle=False)
test loader = DataLoader(test dataset, batch size=batch size, shuffle=False)
→ Using downloaded and verified file: ./data/VOCtrainval_11-May-2012.tar
    Extracting ./data/VOCtrainval 11-May-2012.tar to ./data
# Model
model = fcn resnet50()
model.classifier[4] = nn.Conv2d(512, 21, kernel_size=1) # Pascal VOC has 21 classes (20 classes + background)
model = model.to(device)
# Loss and Optimizer
criterion = nn.CrossEntropyLoss()
optimizer = optim.Adam(model.parameters(), lr=0.001)
# Training function
def train_model(model, train_loader, val_loader, criterion, optimizer, num_epochs=25):
   train losses, val losses = [], []
   best val loss = float('inf')
   for epoch in range(num_epochs):
        model.train()
        running loss = 0.0
        for inputs, labels in tqdm(train_loader):
           inputs, labels = inputs.to(device), labels.to(device).long().squeeze(1)
           optimizer.zero_grad()
           outputs = model(inputs)['out']
           loss = criterion(outputs, labels)
           loss.backward()
           optimizer.step()
            running_loss += loss.item() * inputs.size(0)
        epoch_loss = running_loss / len(train_loader.dataset)
        train losses.append(epoch loss)
```

```
IIIUUE L. EVA L()
       running_loss = 0.0
       with torch.no_grad():
           for inputs, labels in val_loader:
               inputs, labels = inputs.to(device), labels.to(device).long().squeeze(1)
               outputs = model(inputs)['out']
               loss = criterion(outputs, labels)
               running loss += loss.item() * inputs.size(0)
       epoch loss = running loss / len(val loader.dataset)
       val losses.append(epoch loss)
       print(f'Epoch {epoch+1}/{num_epochs}, Train Loss: {train_losses[-1]:.4f}, Val Loss: {val_losses[-1]:.4f}')
       if epoch loss < best val loss:
           best val loss = epoch loss
           torch.save(model.state dict(), 'best model.pth')
   return train losses, val losses
# Train the model
num epochs = 25
train losses, val losses = train model(model, train loader, val loader, criterion, optimizer, num epochs)
→ 100% 128/128 [01:03<00:00, 2.03it/s]
    Epoch 1/25, Train Loss: 0.3621, Val Loss: 0.1859
    100%| 128/128 [01:02<00:00, 2.05it/s]
    Epoch 2/25. Train Loss: 0.2008. Val Loss: 0.1823
    100%| 128/128 [01:01<00:00, 2.07it/s]
    Epoch 3/25, Train Loss: 0.1941, Val Loss: 0.1824
    100% | 128/128 [01:02<00:00, 2.06it/s]
    Epoch 4/25, Train Loss: 0.1916, Val Loss: 0.1710
    100%| 128/128 [01:02<00:00, 2.06it/s]
    Epoch 5/25, Train Loss: 0.1869, Val Loss: 0.1767
    100%| 128/128 [01:02<00:00, 2.06it/s]
    Epoch 6/25, Train Loss: 0.1853, Val Loss: 0.1728
    100% | 128/128 [01:02<00:00, 2.06it/s]
    Epoch 7/25, Train Loss: 0.1831, Val Loss: 0.1690
           128/128 [01:02<00:00, 2.06it/s]
```

Epoch 8/25, Train Loss: 0.1791, Val Loss: 0.1826 100% | 128/128 [01:02<00:00, 2.06it/s] Epoch 9/25, Train Loss: 0.1835, Val Loss: 0.1761 100% | 128/128 [01:01<00:00, 2.06it/s] Epoch 10/25, Train Loss: 0.1778, Val Loss: 0.1737 100% | 128/128 [01:01<00:00, 2.07it/s] Epoch 11/25, Train Loss: 0.1757, Val Loss: 0.1810 100% | 128/128 [01:02<00:00, 2.06it/s] Epoch 12/25, Train Loss: 0.1769, Val Loss: 0.1838 100% | 128/128 [01:02<00:00, 2.06it/s] Epoch 13/25, Train Loss: 0.1679, Val Loss: 0.1841 100% | 128/128 [01:01<00:00, 2.07it/s] Epoch 14/25, Train Loss: 0.1701, Val Loss: 0.1744 128/128 [01:02<00:00. 2.06it/s] Epoch 15/25, Train Loss: 0.1586, Val Loss: 0.1731 100% | 128/128 [01:01<00:00, 2.07it/s] Epoch 16/25, Train Loss: 0.1621, Val Loss: 0.1757

```
100%| 128/128 [01:01<00:00, 2.07it/s]
    Epoch 17/25, Train Loss: 0.1570, Val Loss: 0.1753
    100%| 128/128 [01:02<00:00, 2.06it/s]
    Epoch 18/25, Train Loss: 0.1575, Val Loss: 0.1718
    100% | 128/128 [01:02<00:00, 2.06it/s]
    Epoch 19/25, Train Loss: 0.1525, Val Loss: 0.1841
    100%| 128/128 [01:01<00:00, 2.06it/s]
    Epoch 20/25, Train Loss: 0.1479, Val Loss: 0.1762
    100%| 128/128 [01:01<00:00, 2.07it/s]
    Epoch 21/25, Train Loss: 0.1392, Val Loss: 0.1838
    100%| 128/128 [01:02<00:00, 2.06it/s]
    Epoch 22/25. Train Loss: 0.1274. Val Loss: 0.1777
    100%| 128/128 [01:02<00:00. 2.06it/s]
    Epoch 23/25, Train Loss: 0.1231, Val Loss: 0.1929
    100%| 128/128 [01:01<00:00, 2.07it/s]
    Epoch 24/25, Train Loss: 0.1380, Val Loss: 0.2865
    100%| 128/128 [01:01<00:00, 2.07it/s]
    Epoch 25/25, Train Loss: 0.1331, Val Loss: 0.1834
def evaluate_model(model, test_loader, criterion):
   model.eval()
   running loss = 0.0
   correct predictions = 0
   total pixels = 0
   with torch.no grad():
       for inputs, labels in test_loader:
           inputs, labels = inputs.to(device), labels.to(device).long().squeeze(1)
           outputs = model(inputs)['out']
           loss = criterion(outputs, labels)
           running loss += loss.item() * inputs.size(0)
           _, preds = torch.max(outputs, 1)
           correct_predictions += torch.sum(preds == labels.data)
           total pixels += labels.numel()
   avg_loss = running_loss / len(test_loader.dataset)
   accuracy = correct predictions.double() / total pixels
   return avg_loss, accuracy
# Load best model
model.load state dict(torch.load('best model.pth'))
# Evaluate the model
test_loss, test_accuracy = evaluate_model(model, test_loader, criterion)
print(f'Test Loss: {test_loss:.4f}, Test Accuracy: {test_accuracy*100:.2f}%')
→ Test Loss: 0.1571, Test Accuracy: 95.17%
# Visualize predictions
def visualize_predictions(model, dataset, num_images=5):
   model.eval()
   fig, axes = plt.subplots(num_images, 3, figsize=(15, num_images * 5))
   for i in range(num images):
       idx = np.random.randint(0, len(dataset))
       image, label = dataset[idx]
```

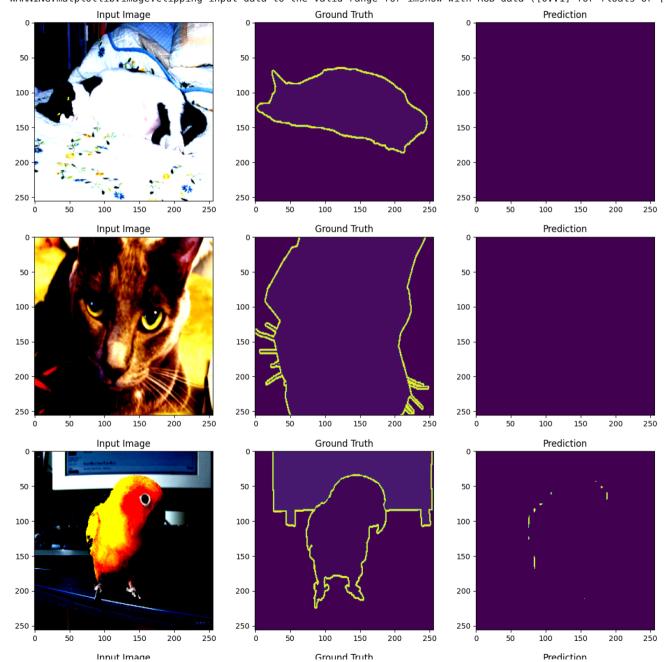
```
image = image.to(device).unsqueeze(0)
  outputs = model(image)['out']
  image = image.squeeze().cpu().permute(1, 2, 0).numpy()
  label = label.squeeze().cpu().numpy()
  pred_mask = torch.argmax(outputs, dim=1).cpu().squeeze().numpy()

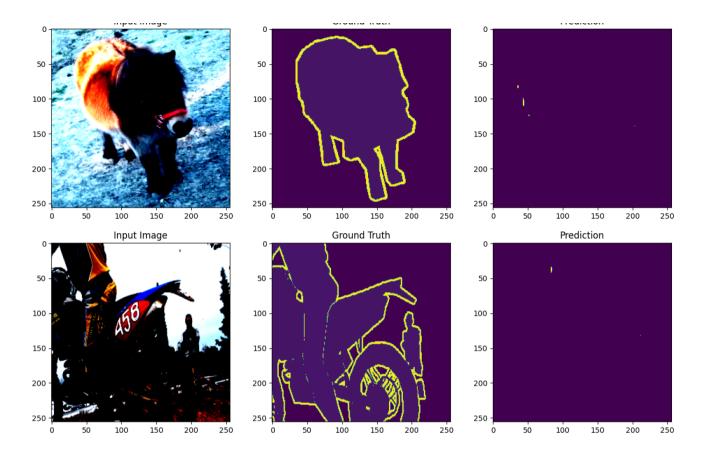
  axes[i, 0].imshow(image)
  axes[i, 0].set_title('Input Image')
  axes[i, 1].imshow(label)
  axes[i, 1].set_title('Ground Truth')
  axes[i, 2].imshow(pred_mask)
  axes[i, 2].set_title('Prediction')

plt.show()

# Visualize predictions
visualize_predictions(model, dataset)
```

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```
class UNet(nn.Module):
   def __init__(self, n_classes):
       super(UNet, self).__init__()
       self.encoder = fcn_resnet50().backbone
       self.decoder = nn.Sequential(
           nn.Conv2d(2048, 1024, kernel_size=3, padding=1),
           nn.ReLU(inplace=True),
           nn.Conv2d(1024, 512, kernel_size=3, padding=1),
           nn.ReLU(inplace=True),
           # Upsample to match target size
           nn.Upsample(scale factor=8, mode='bilinear', align corners=True), # Add upsampling layer
           nn.Conv2d(512, n_classes, kernel_size=1)
   def forward(self, x):
       x = self.encoder(x)['out']
       x = self.decoder(x)
        return x
n_classes = 21 # Number of classes in the Cityscapes dataset
model = UNet(n classes).to(device)
Downloading: "https://download.pytorch.org/models/resnet50-0676ba61.pth" to /root/.cache/torch/hub/checkpoints/resnet50-0676ba61.pth
    100%| 97.8M/97.8M [00:00<00:00, 178MB/s]
# # Define loss function and optimizer
criterion = nn.CrossEntropyLoss()
optimizer = optim.Adam(model.parameters(), lr=0.001)
```

```
# # Training loop
def train(model, loader, optimizer, criterion, device):
   model.train()
   epoch_loss = 0
   for images, targets in loader:
        images = images.to(device)
        #this step was suggested by collab fix error AI
        targets = targets.to(device).long().squeeze(1) # squeeze the target to remove the extra dimension
        optimizer.zero_grad()
        outputs = model(images)
        loss = criterion(outputs, targets)
        loss.backward()
        optimizer.step()
        epoch_loss += loss.item()
   return epoch_loss / len(loader)
# # Validation loop
def validate(model, loader, criterion, device):
   model.eval()
   epoch_loss = 0
   with torch.no grad():
        for images, targets in loader:
            images = images.to(device)
            targets = targets.to(device).long().squeeze(1) # squeeze the target to remove the extra dimension
            outputs = model(images)
            loss = criterion(outputs, targets)
            epoch_loss += loss.item()
   return epoch_loss / len(loader)
num_epochs = 25
for epoch in range(num_epochs):
   train_loss = train(model, train_loader, optimizer, criterion, device)
   val loss = validate(model, val loader, criterion, device)
   print(f"Epoch {epoch+1}/{num_epochs}, Train Loss: {train_loss:.4f}, Val Loss: {val_loss:.4f}")
Froch 1/25, Train Loss: 0.7775, Val Loss: 0.2063
    Epoch 2/25, Train Loss: 0.2062, Val Loss: 0.2029
    Epoch 3/25, Train Loss: 0.1977, Val Loss: 0.1929
    Epoch 4/25, Train Loss: 0.1948, Val Loss: 0.1957
    Epoch 5/25, Train Loss: 0.1878, Val Loss: 0.1931
    Epoch 6/25, Train Loss: 0.1866, Val Loss: 0.1905
    Epoch 7/25, Train Loss: 0.1846, Val Loss: 0.1960
    Epoch 8/25, Train Loss: 0.1921, Val Loss: 0.1988
    Epoch 9/25, Train Loss: 0.1878, Val Loss: 0.1969
```

```
Epoch 10/25, Train Loss: 0.1914, Val Loss: 0.2241
    Epoch 11/25, Train Loss: 0.1944, Val Loss: 0.1954
    Epoch 12/25, Train Loss: 0.1906, Val Loss: 0.1965
    Epoch 13/25, Train Loss: 0.1833, Val Loss: 0.2037
    Epoch 14/25, Train Loss: 0.1881, Val Loss: 0.1931
    Epoch 15/25, Train Loss: 0.1875, Val Loss: 0.1849
    Epoch 16/25, Train Loss: 0.1874, Val Loss: 0.1896
    Epoch 17/25, Train Loss: 0.1857, Val Loss: 0.1904
    Epoch 18/25, Train Loss: 0.1796, Val Loss: 0.1853
    Epoch 19/25, Train Loss: 0.1773, Val Loss: 0.1826
    Epoch 20/25, Train Loss: 0.1756, Val Loss: 0.1830
    Epoch 21/25, Train Loss: 0.1698, Val Loss: 0.1998
    Epoch 22/25, Train Loss: 0.1706, Val Loss: 0.1944
    Epoch 23/25, Train Loss: 0.1664, Val Loss: 0.1861
    Epoch 24/25, Train Loss: 0.1603, Val Loss: 0.1922
    Epoch 25/25, Train Loss: 0.1531, Val Loss: 0.2427
def evaluate(model, loader, device):
   model.eval()
   correct = 0
   total = 0
   with torch.no_grad():
        for images, targets in loader:
            images = images.to(device)
            targets = targets.to(device).long().squeeze(1) # squeeze the target to remove the extra dimension
            outputs = model(images)
            _, predicted = torch.max(outputs.data, 1)
            total += targets.nelement()
            correct += (predicted == targets).sum().item()
   return correct / total
pixel_accuracy = evaluate(model, val_loader, device)
print(f"Pixel Accuracy: {pixel_accuracy * 100:.2f}%")
→ Pixel Accuracy: 94.43%
```

Visualize predictions

visualize_predictions(model, dataset)

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