

# Computer Vision and Image Processing

## Homography and fundamental matrix estimation

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### **PART A: Homography estimation**

To run the code, send the image as:

```
image1 = imread(image1_path);
```

```
image2 = imread(image2_path);
```

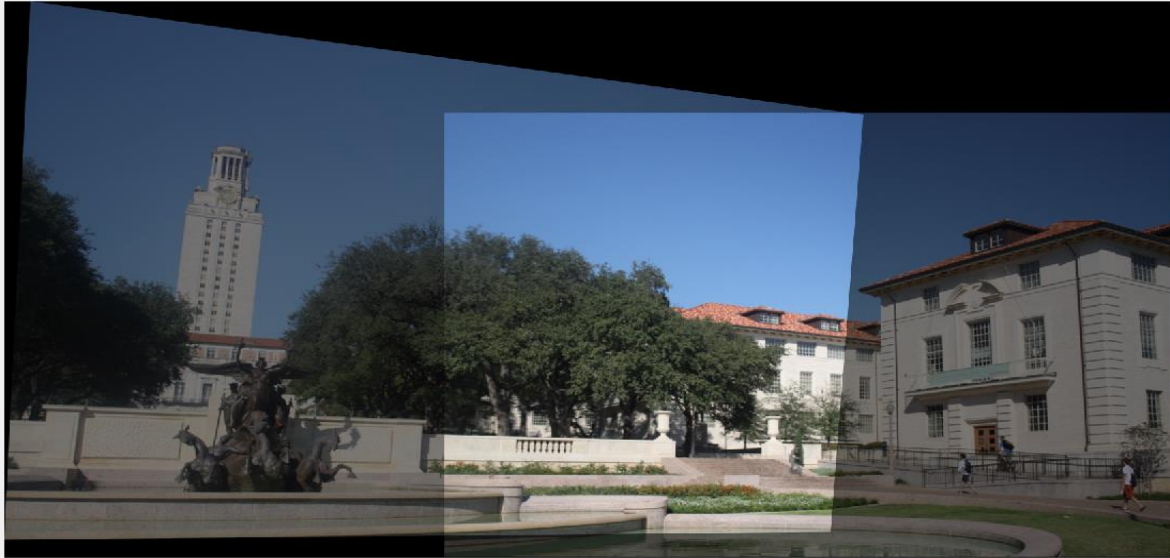
```
image_stitch(image1, image2);
```

#### 1) Uttower:

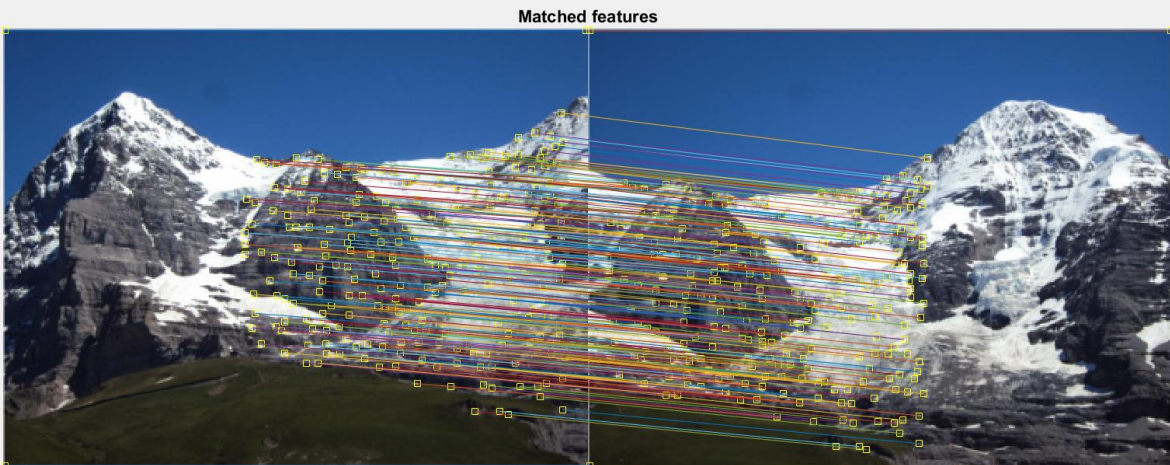
Number of inliers: 186

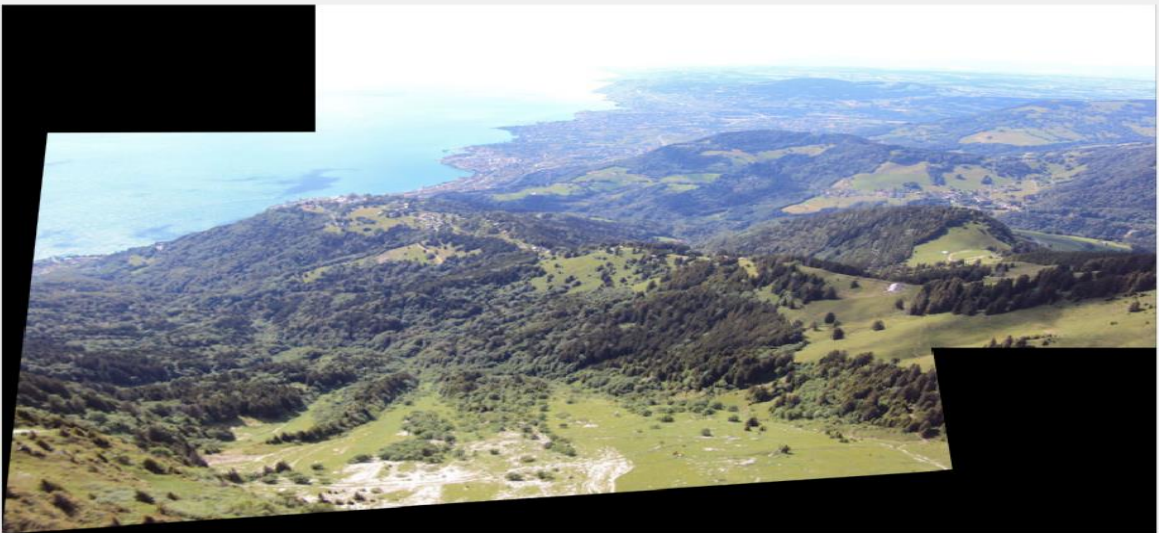
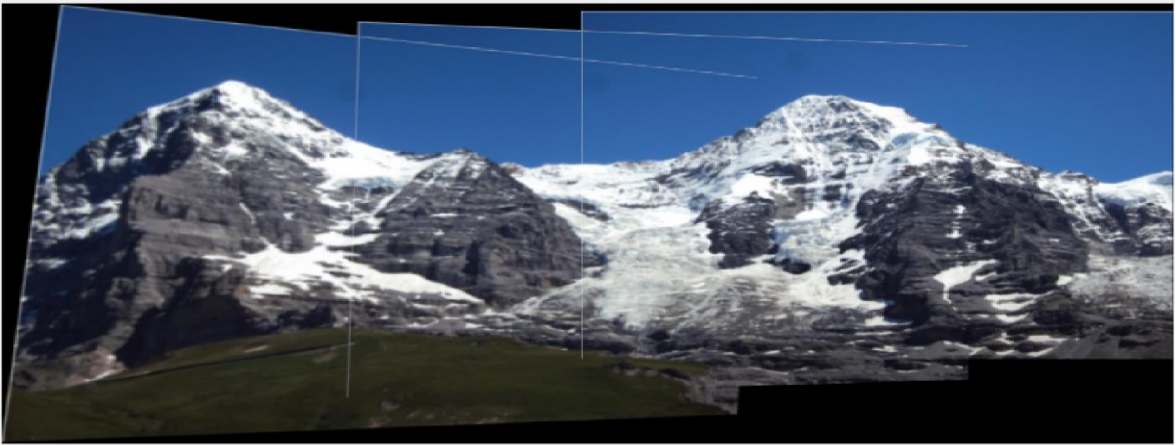
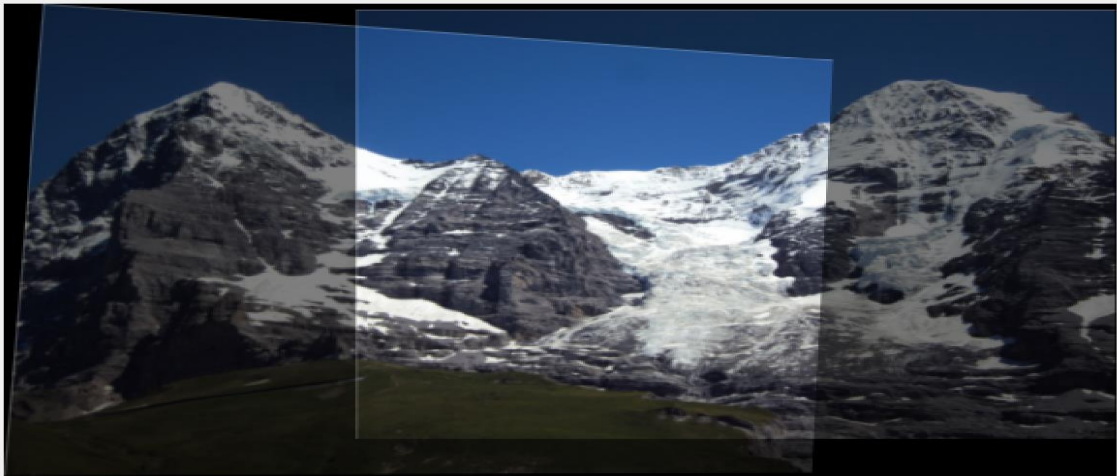
Average residual/error for inliers: 0.3632



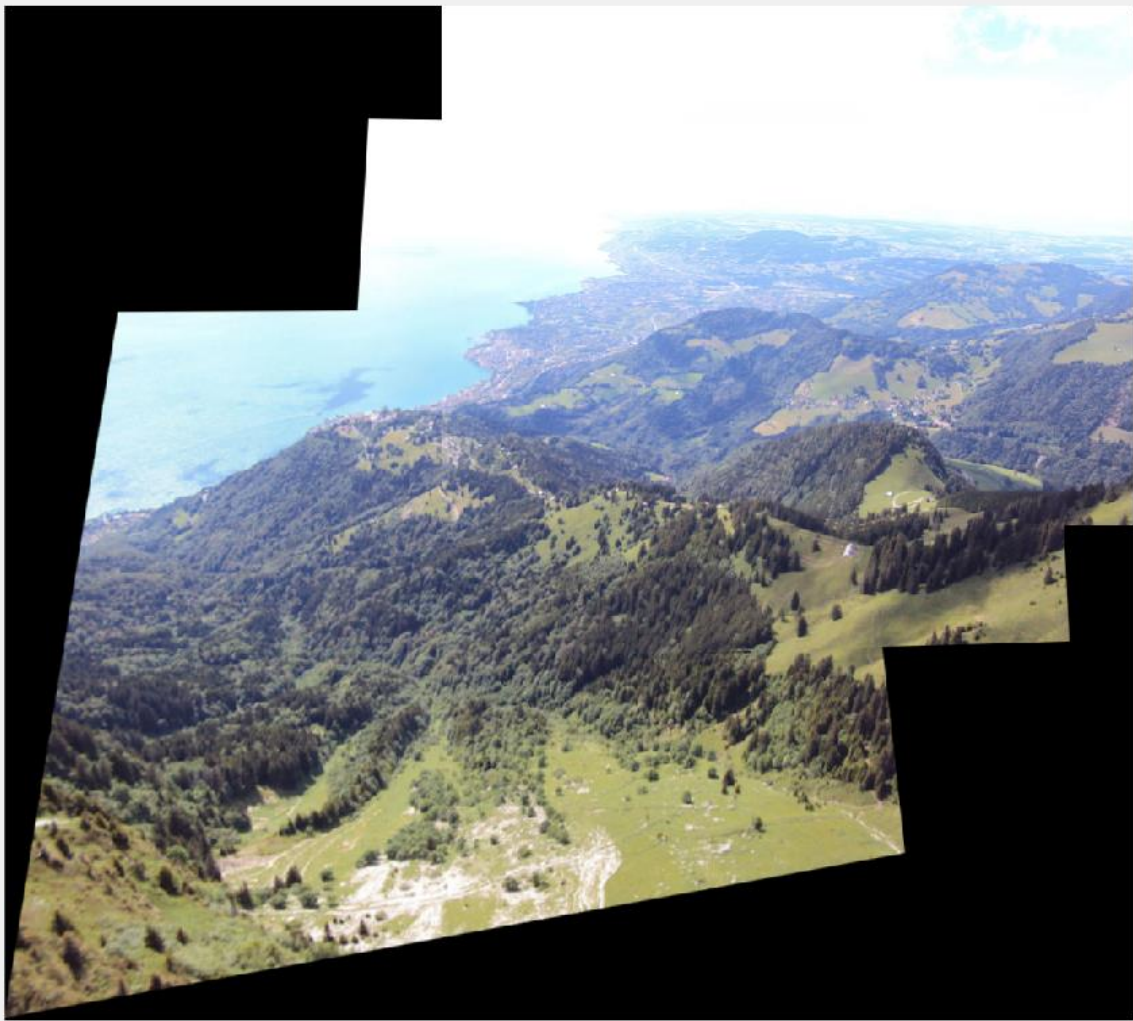


2) Hills:



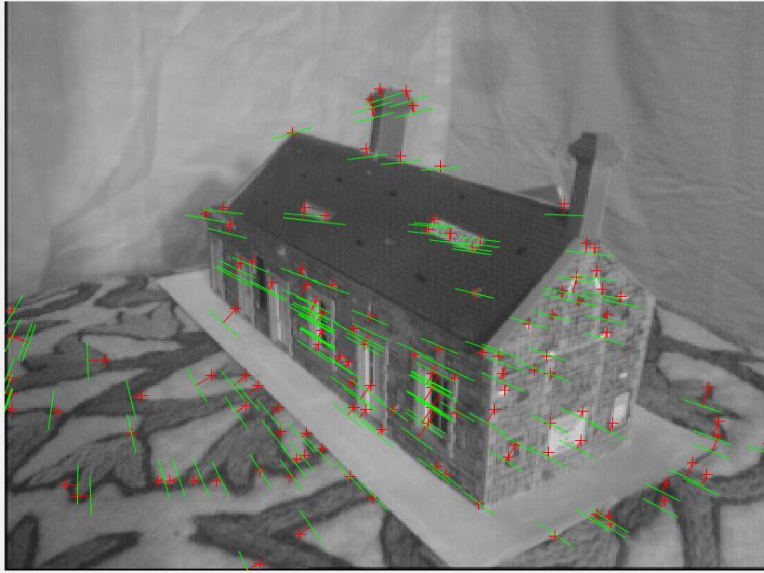




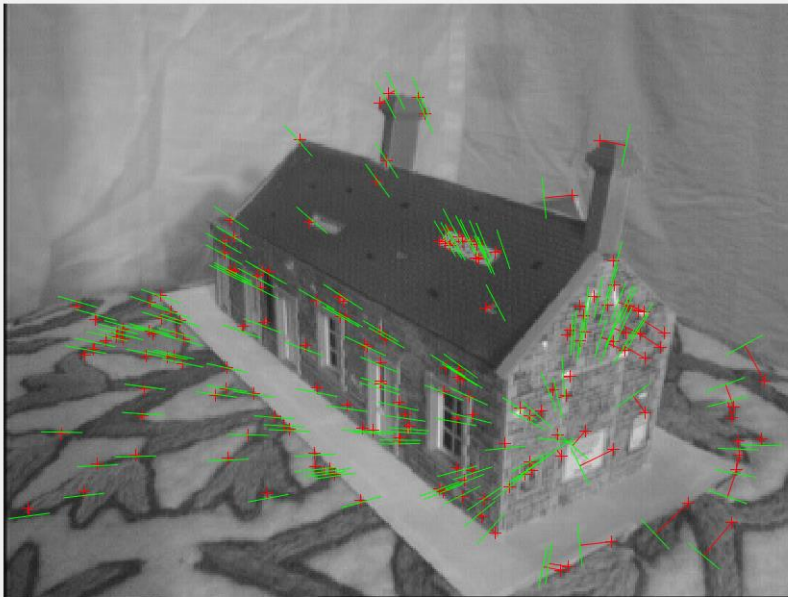


## **Part2:Fundamental Matrix Estimation and Triangulation**

- 1) House:
  - a) With Ground truth Matches:



normalised



Unnormalized

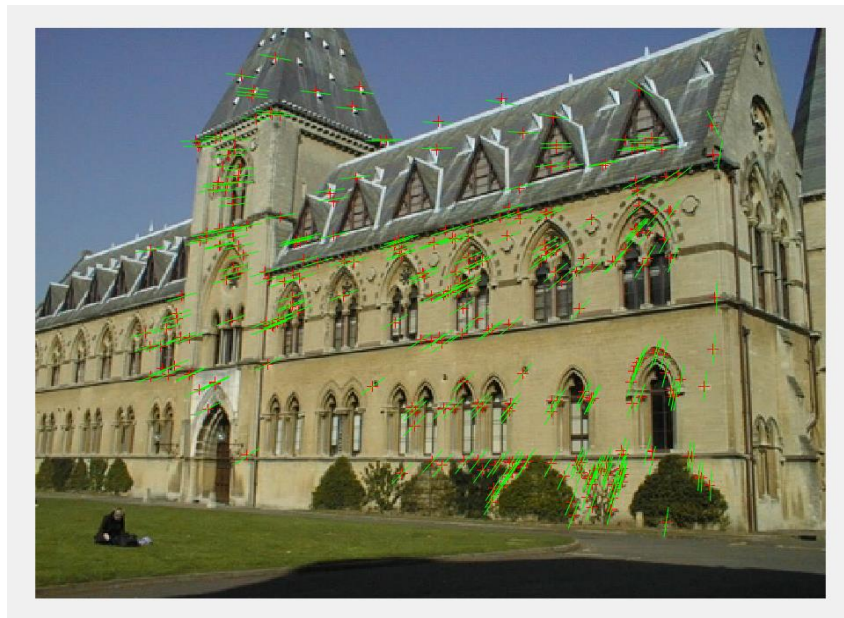
b) Without ground truth Matches:



normalised

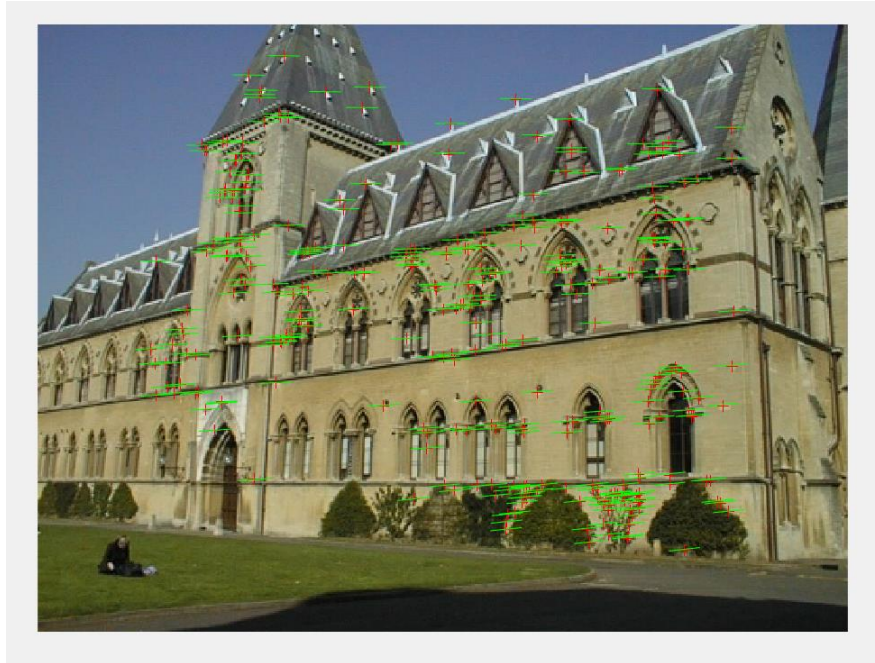
2) Library:

a) With ground truth Matches:



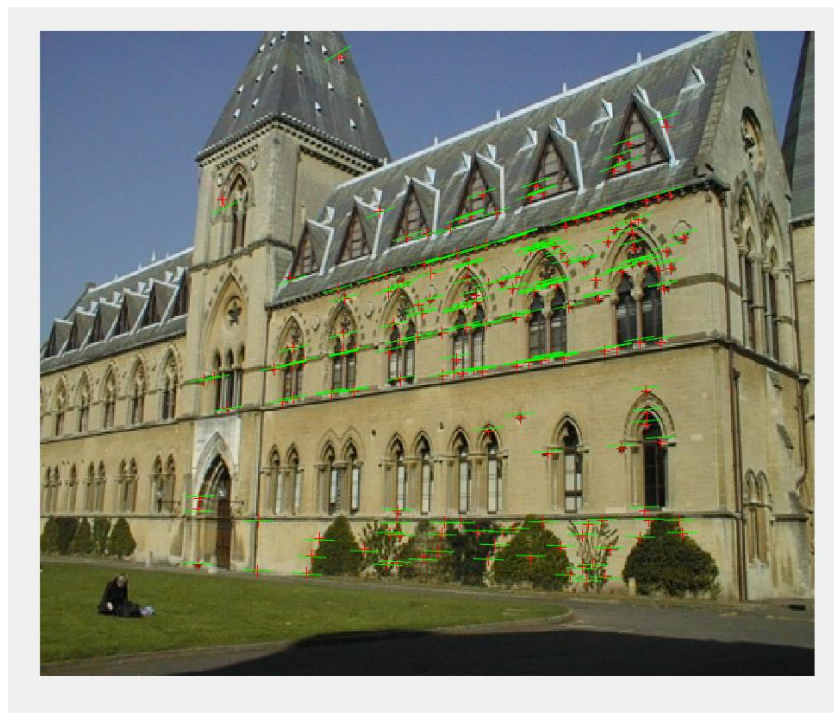
Normalized





Unnormalised

3) Without ground truth matches:



Normalized

With ground truth Matches:

Residual for Unnormalized:

House: 3.0342

Library: 0.5236

Residual for Normalized:

House: 2.8905

Library: 0.3385

Without ground truth matches:

Images	Normalized Residual	Inliers
House	4.6166	156
Library	3.5288	247

Without the ground truth matches, the normalized residual is higher than with the ground truth matches.

### Triangulation:

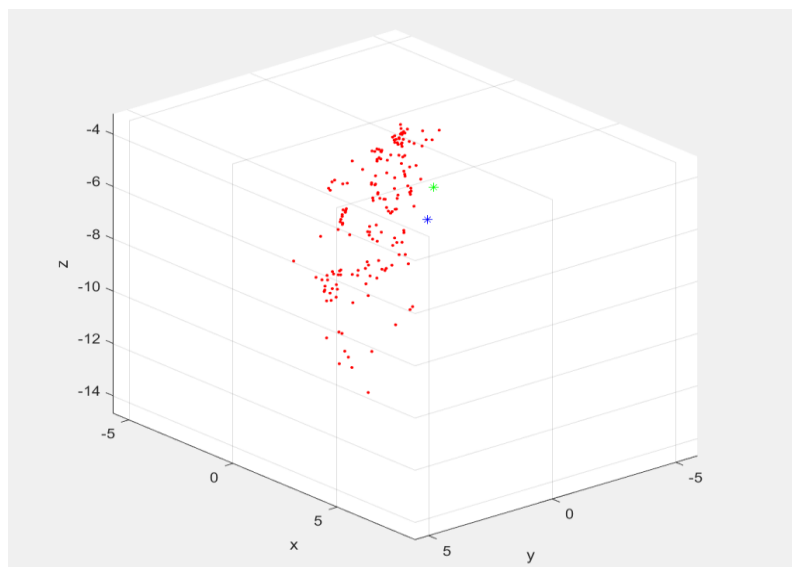
a) Library:

mean residual for left image

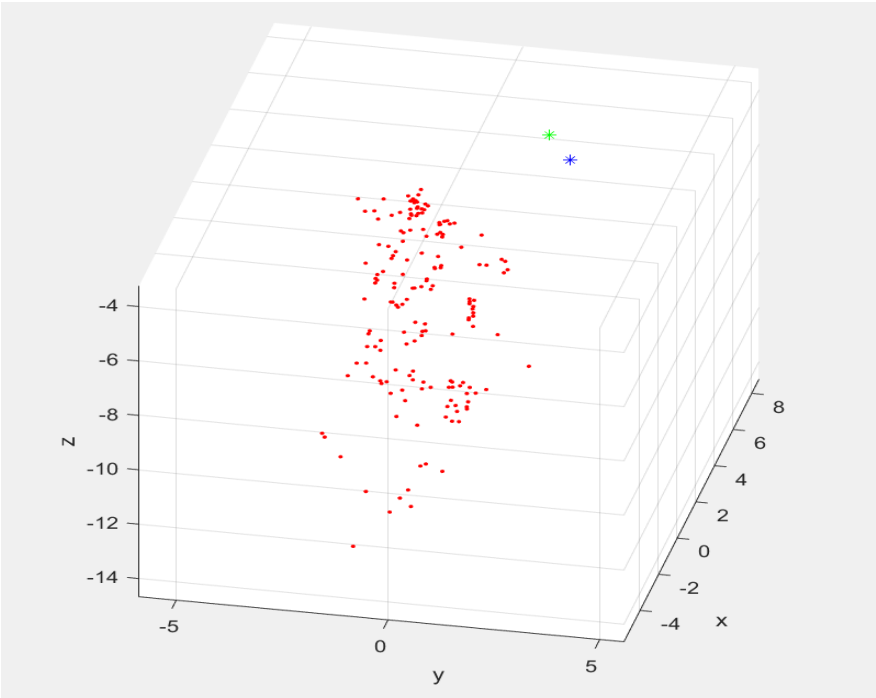
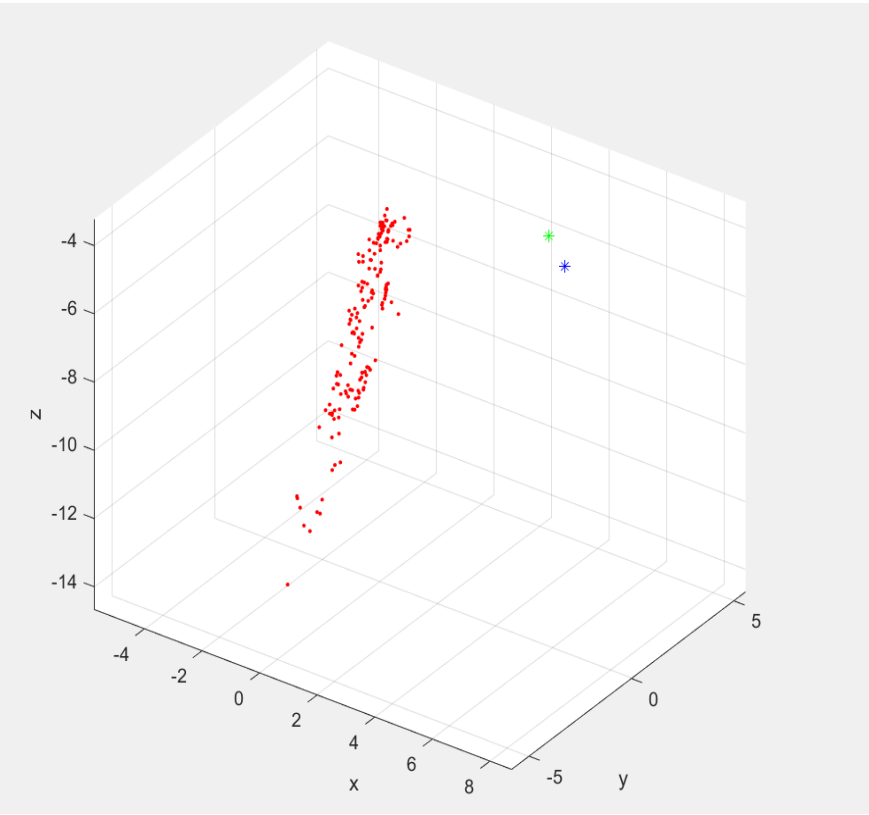
347.6150

mean residual for right image

1.9196e+03

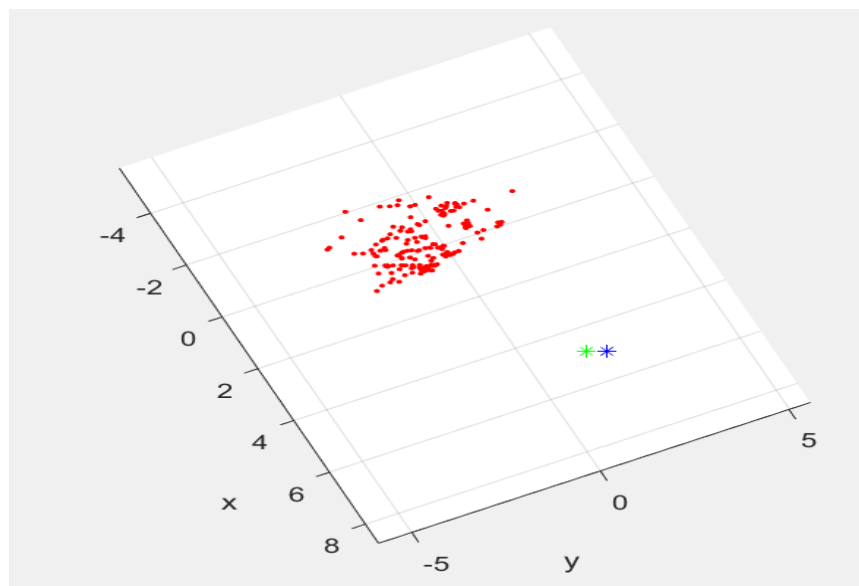
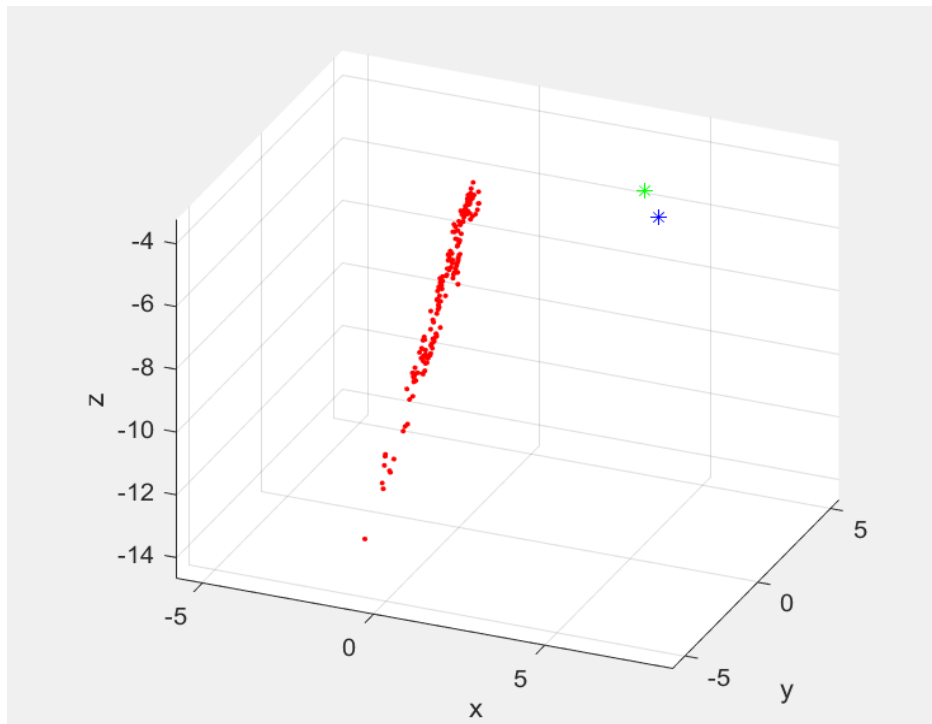


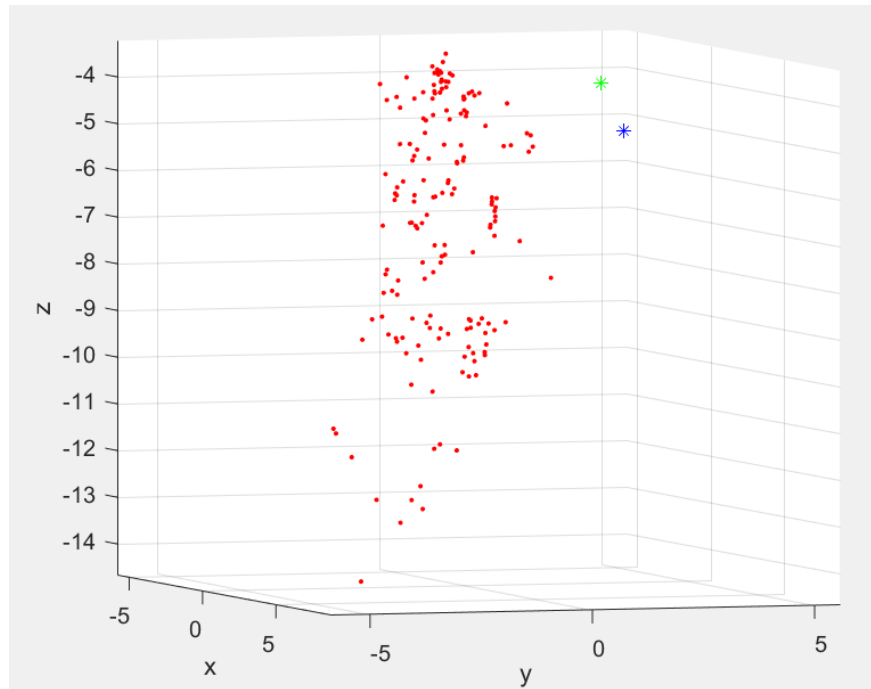




b) House:  
mean residual for left image  
3.6626

mean residual for right image  
873.0394





**Extra Credit:**

Run the `stitch_multiple_images(img1, img2, img3)`

This code will stitch 3 images.

**Reference:**

- 1) <http://dcyoung.weebly.com/computer-vision.html>