



Car-eful Consideration

An ML approach to pricing cars

Team 10

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Have you bought a resale car?

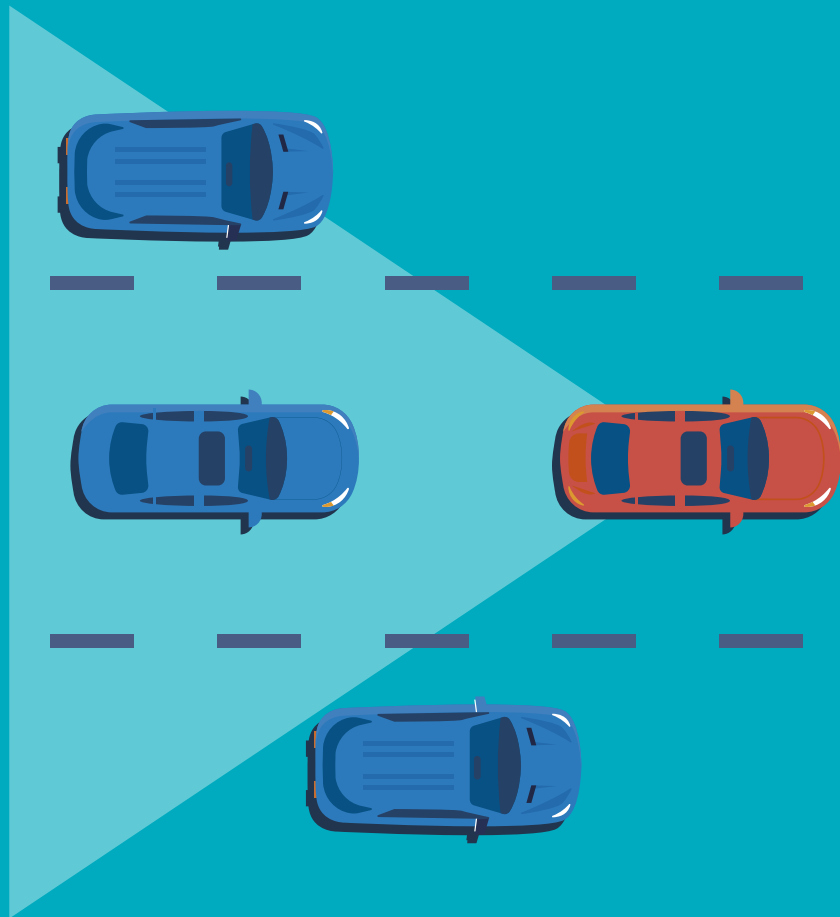
Used car pricing is often
ambiguous - it can depend
on multiple factors.

However, how these affect
the price of the car is often
unclear to most potential
buyers.

Our Objective

We seek to build an online platform to bring clarity to buyers in their decision-making process and put them in a better position to negotiate a better price

Let us show you



DEMO

01

DATA

EDA & Processing



02

COMPUTER VISION

Feature Selection
Model Build & Analysis



03

PRICE PREDICTION

Feature Selection
Model Builds & Analysis



04

CONCLUSION

Learnings



About the data

Car Images Dataset

- **Purpose:** Used for computer vision model
- **Source:** Stanford
- **Sample Size:** 16,185
- **Feature Size:** N/A

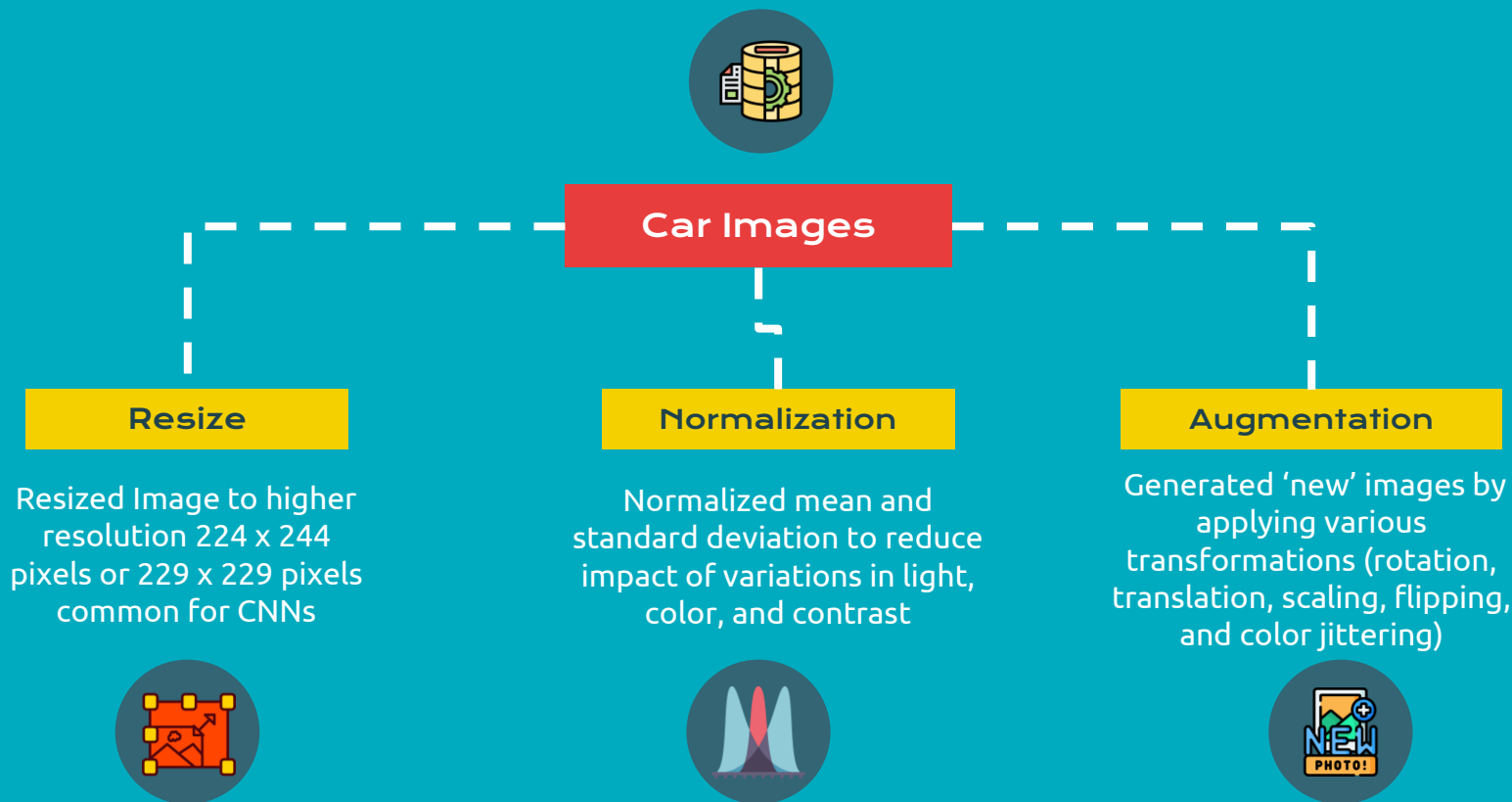


USA Used Cars Dataset

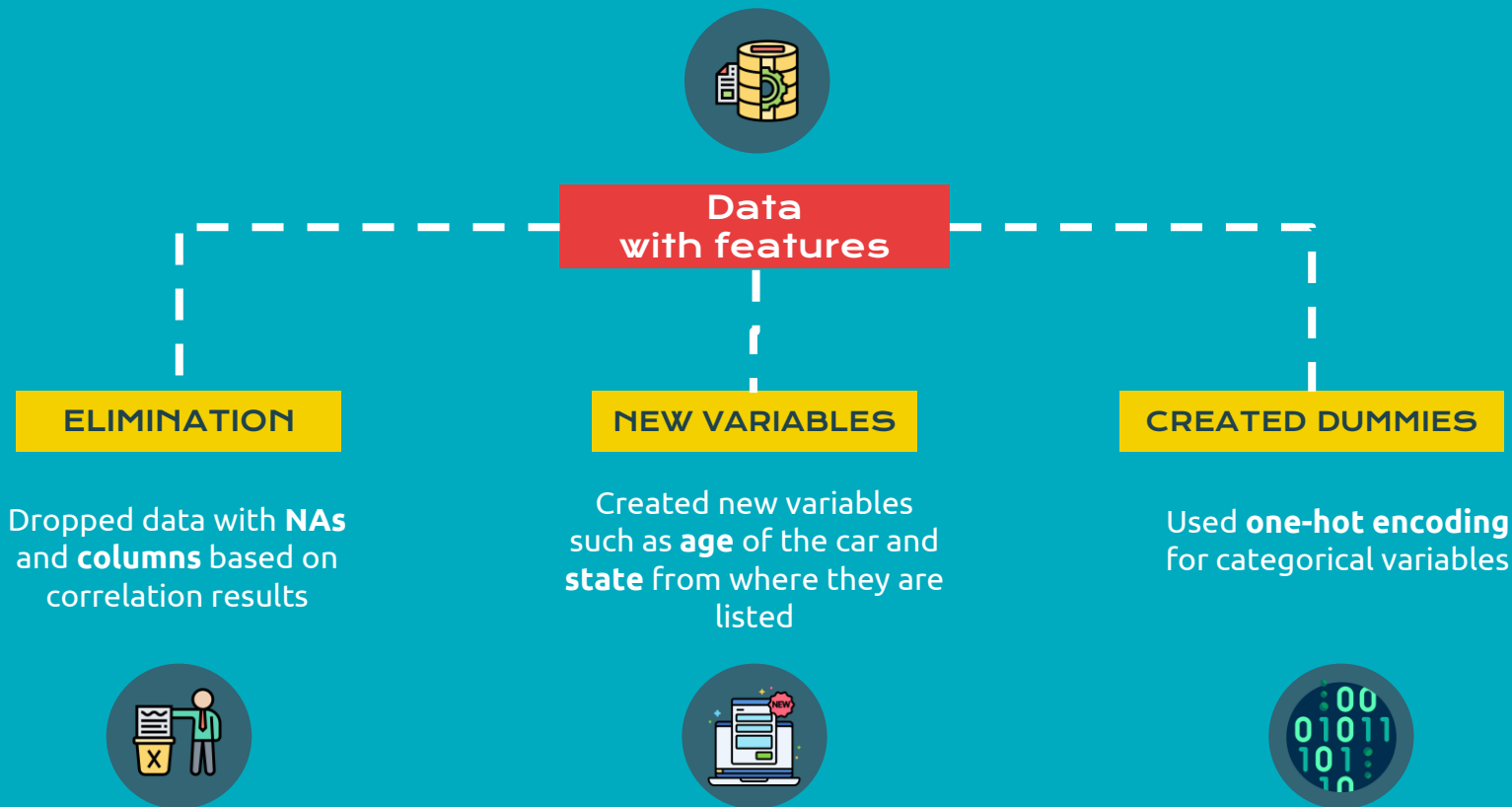
- **Purpose:** Used for price prediction model
- **Source:** Kaggle
- **Sample Size:** 3,000,040
- **Feature Size:** 166 features



CV Multiclass Model data processing



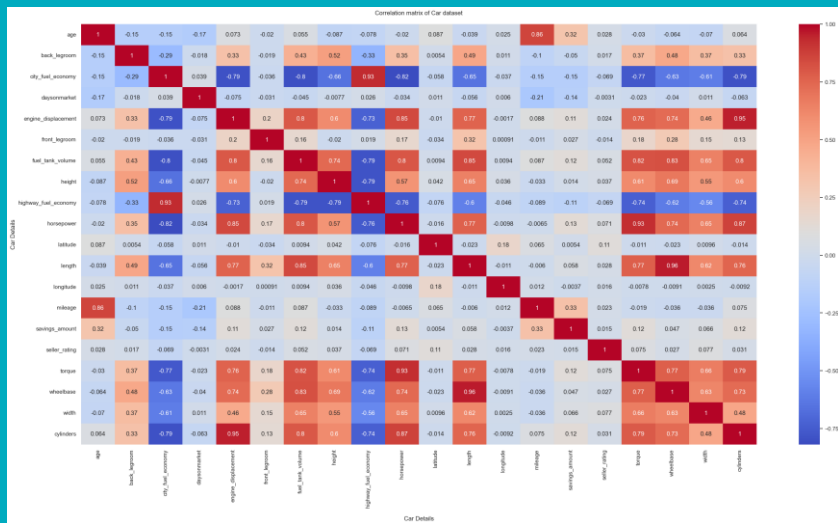
Data processing for prediction models



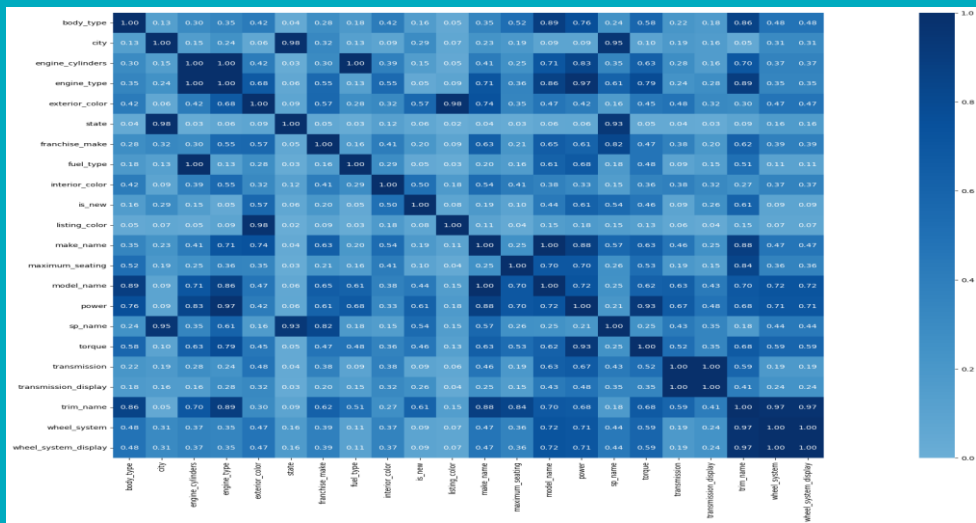
EDA: CORRELATION ANALYSIS (1/4)

We check correlation between variables to avoid inputting highly correlated variables into the model

CorrPlot for continuous variables

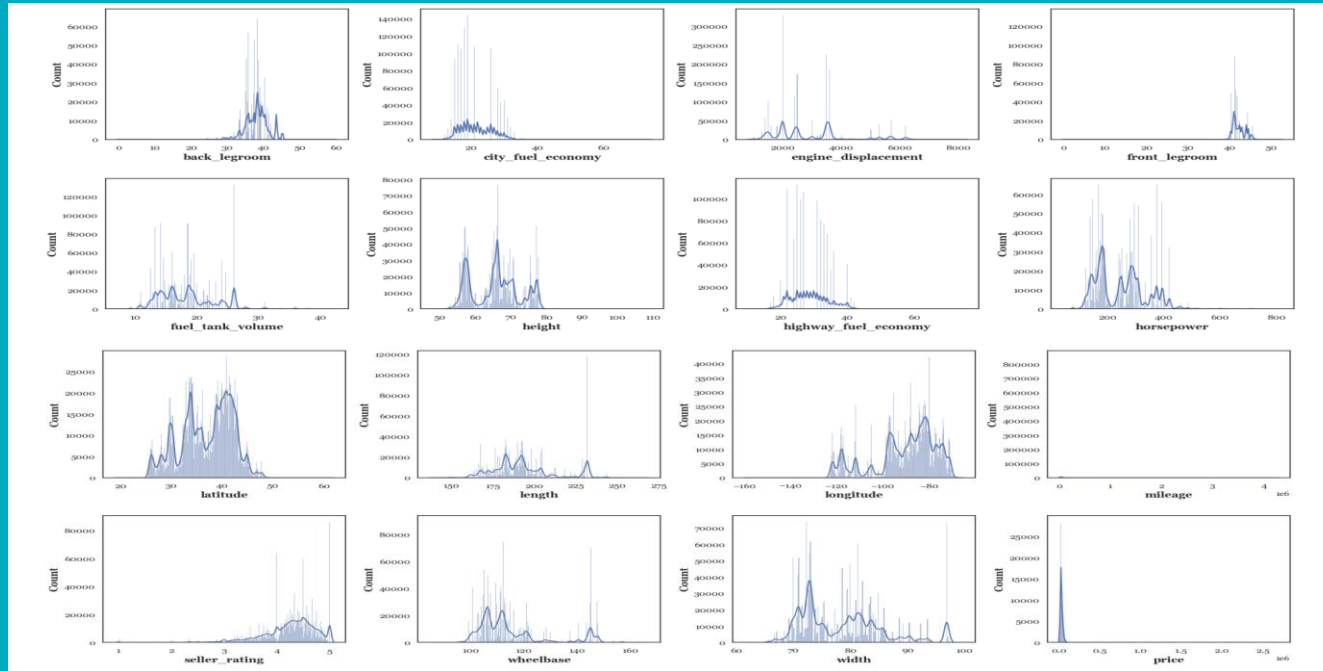


Cramer's V for categorical variables



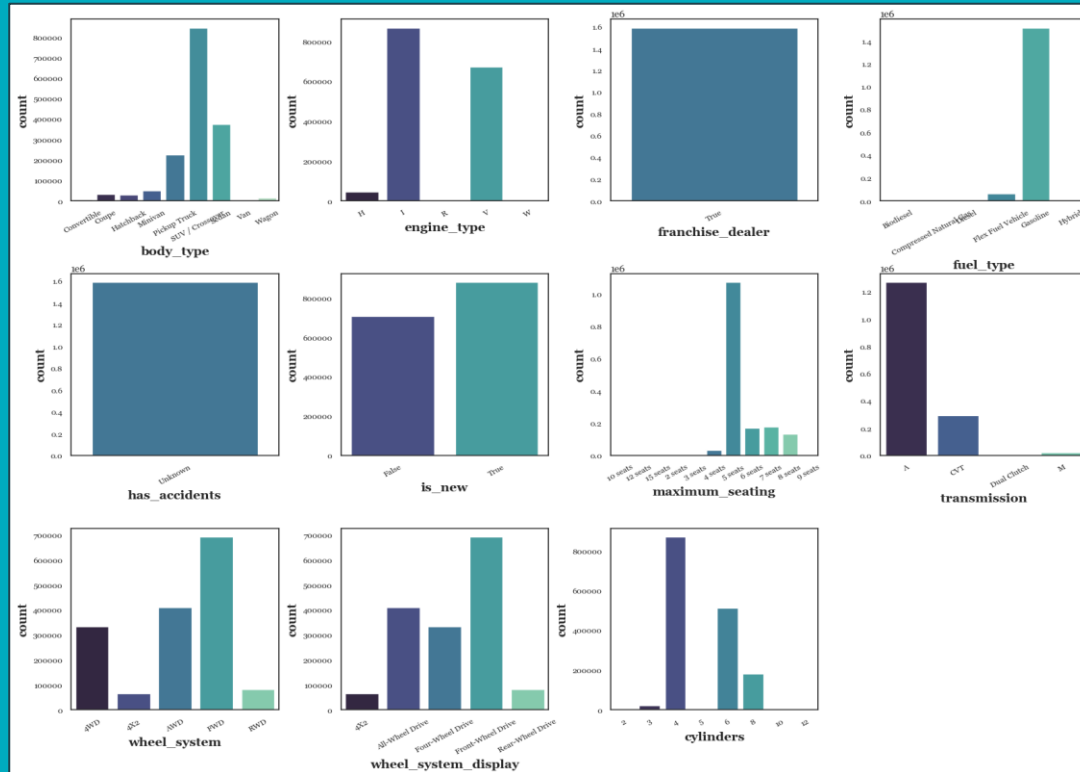
EDA: CHECKING THE DATA DISTRIBUTION (2/4)

Since the input variables are not normally distributed, data normalization will be required prior to developing the machine learning models



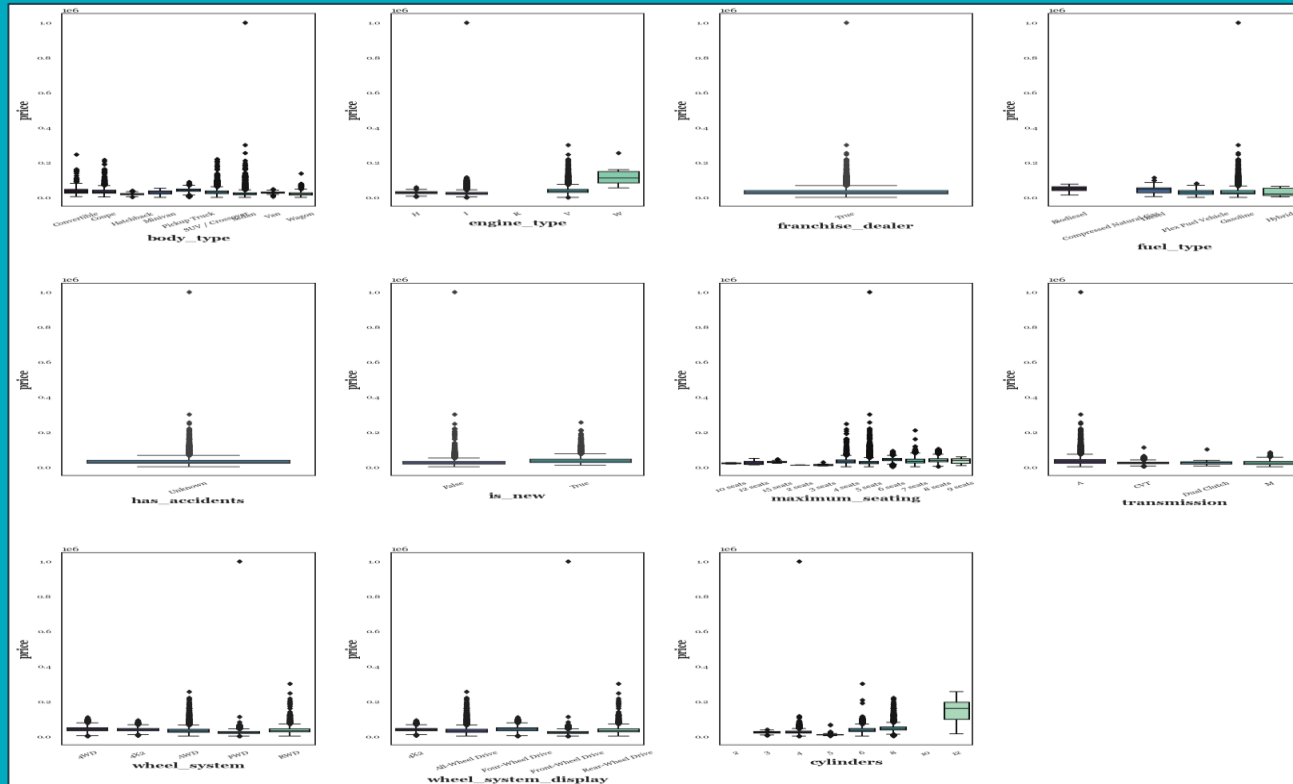
EDA: CHECKING THE DATA DISTRIBUTION (3/4)

Since the input variables are not normally distributed, data normalization will be required prior to developing the machine learning models



EDA: CHECKING FOR OUTLIERS (4/4)

We check for the presence of outliers in categorical variables, data normalization will be required prior to developing the machine learning models



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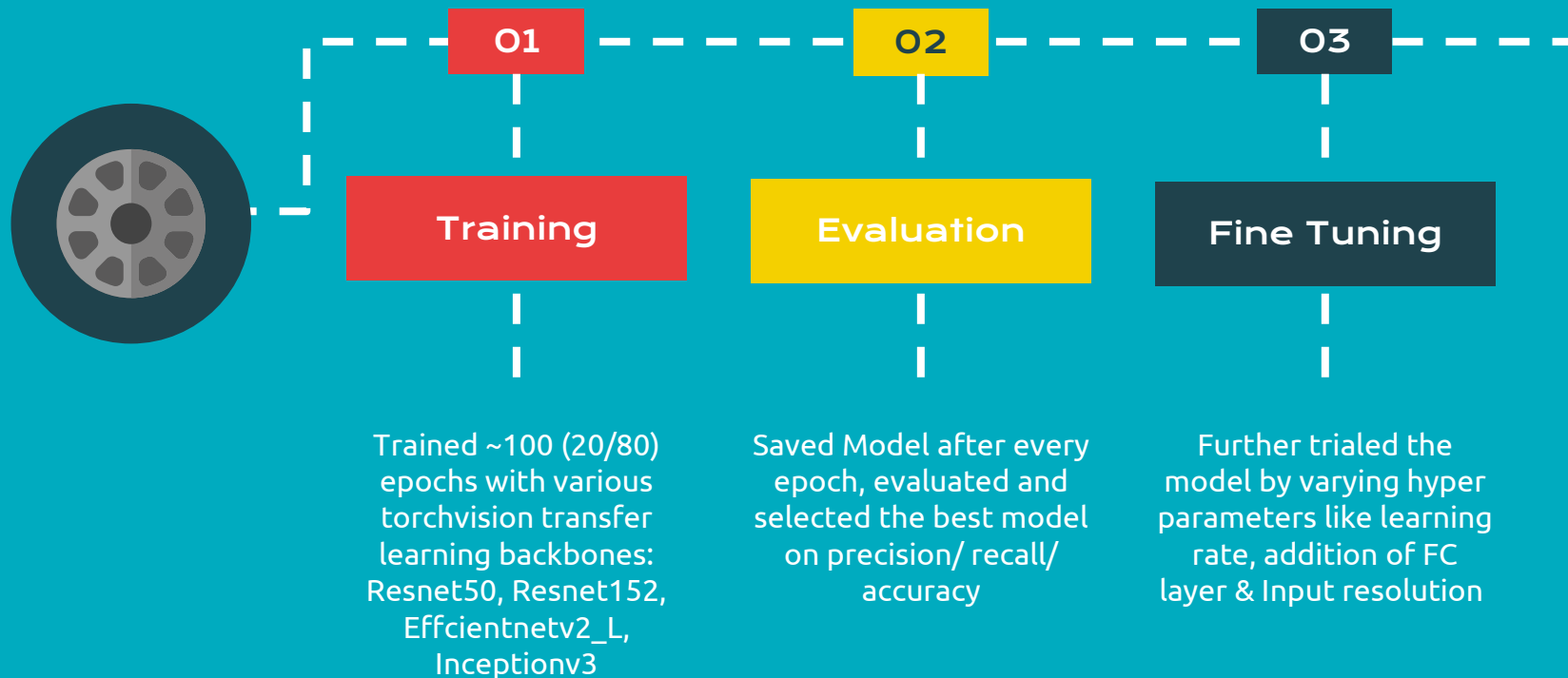
04

CONCLUSION

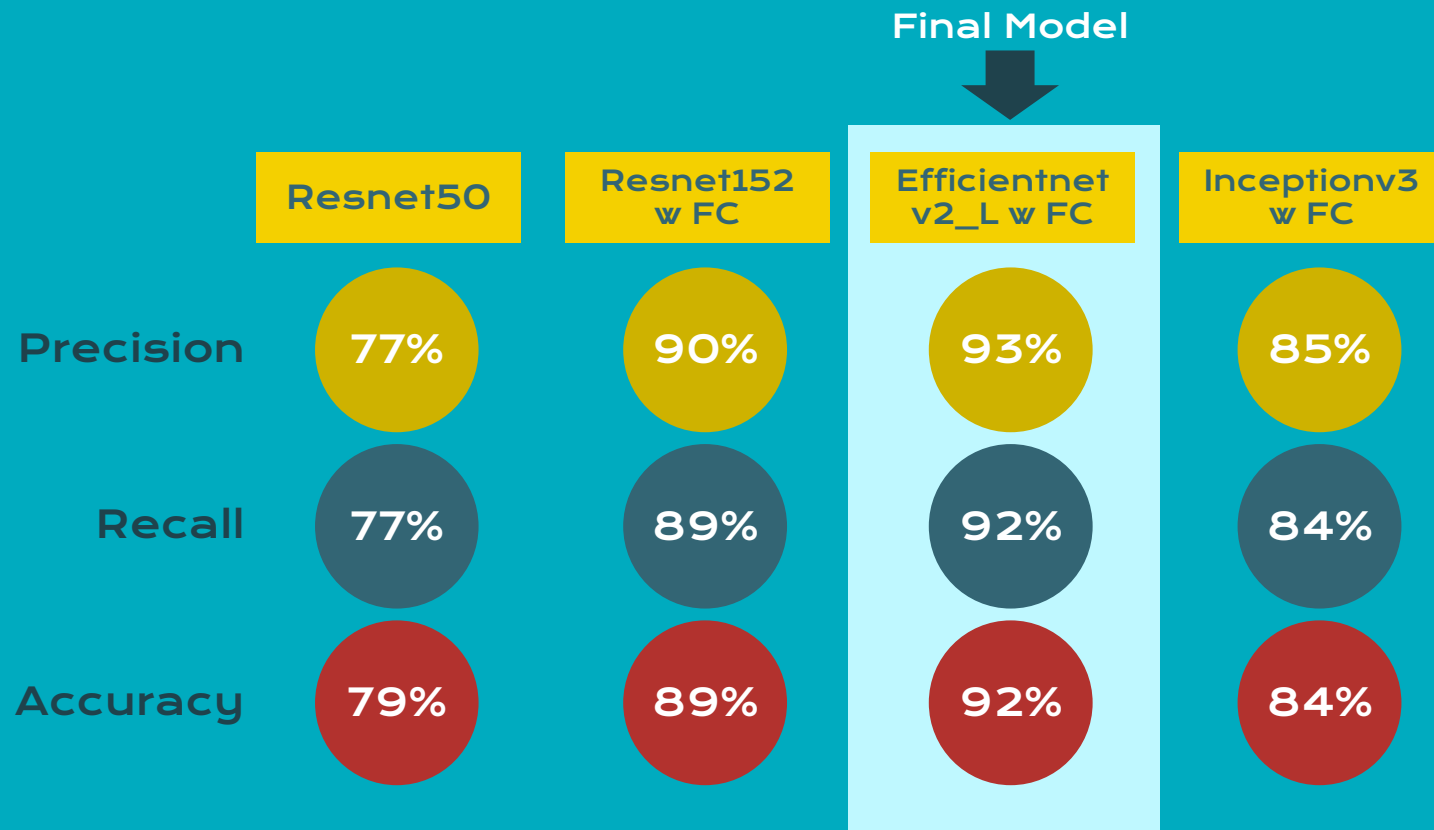
Learnings



Process for CV multi-class model selection



Trials best model summary



Final Selected Model

Parameters

Model Parameters	EfficientnetV2	FC Layer
	Depth: 23 layers	Depth: 2 layers
	Width: 4.0	Activation F: Relu
	Activation F: Swish	598k parameters
	Pooling: Adaptive	
Training Parameters	Average Pooling	
	307 mil parameters	
	Optimizer	Adam
	Learning R	0.001,0.0001
	LR Scheduler	Cosine Annealing
	Dropout	0.3
	Batch size	32

Classification Report

	precision	recall	f1-score	support
AM General Hummer SUV 2000	0.98	0.98	0.98	44
Acura Integra Type R 2001	0.98	0.93	0.95	44
Acura RL Sedan 2012	0.82	0.88	0.85	32
Acura TL Sedan 2012	0.79	0.98	0.88	43
Acura TL Type-S 2008	1.00	1.00	1.00	42
Acura TSX Sedan 2012	1.00	0.78	0.87	40
Acura ZDX Hatchback 2012	1.00	0.87	0.93	39
Aston Martin V8 Vantage Convertible 2012	0.90	0.78	0.83	45
Aston Martin V8 Vantage Coupe 2012	0.82	0.78	0.80	41
Aston Martin Virage Convertible 2012	1.00	0.82	0.90	33
Aston Martin Virage Coupe 2012	0.77	0.97	0.86	38
Audi 100 Sedan 1994	0.71	0.90	0.79	40
Audi 100 Wagon 1994	1.00	0.83	0.91	42
Audi A5 Coupe 2012	0.71	0.90	0.80	41
Audi R8 Coupe 2012	0.98	0.95	0.96	43
Audi RS 4 Convertible 2008	0.89	0.92	0.90	36
Audi S4 Sedan 2007	0.96	0.96	0.96	45
Audi S4 Sedan 2012	0.97	0.74	0.84	39
Audi S5 Convertible 2012	0.84	0.76	0.80	42
...				
Tesla Model S Sedan 2012	1.00	0.97	0.99	38
Toyota 4Runner SUV 2012	0.98	1.00	0.99	40
Toyota Camry Sedan 2012	0.95	0.95	0.95	43
Toyota Corolla Sedan 2012	0.97	0.91	0.94	43
Toyota Sequoia SUV 2012	0.97	0.89	0.93	38
Volkswagen Beetle Hatchback 2012	1.00	1.00	1.00	42
Volkswagen Golf Hatchback 1991	1.00	0.98	0.99	46
Volkswagen Golf Hatchback 2012	0.95	0.93	0.94	43
Volvo 240 Sedan 1993	0.96	0.96	0.96	45
Volvo C30 Hatchback 2012	1.00	0.95	0.97	41
Volvo XC90 SUV 2007	0.95	0.98	0.97	43
smart fortwo Convertible 2012	0.95	1.00	0.98	40
accuracy			0.92	8041
macro avg	0.93	0.92	0.92	8041
weighted avg	0.93	0.92	0.92	8041

Visualizing class activation maps

Front View

Acura RL Sedan 2006



Chevrolet Camaro Convertible 2012



Diagonal View

Lexus LS460 2012



Side View

Dodge Dakota Club Cab 2006



Dodge Caravan Minivan 1997



Back View

Acura Integra Type R 2001



Dodge Challenger SRT8 2008



Limitations and Future Considerations

Limitations



Insufficient computing power



Realistically, number of brand, model and make is very high



Resolution of input images need to be high

Future Work



Add more data and add more classes, split models up by classes



Try more transfer-learning backbone



Optimizing NN hyperparameters further (batch-size, epochs, optimizers,)

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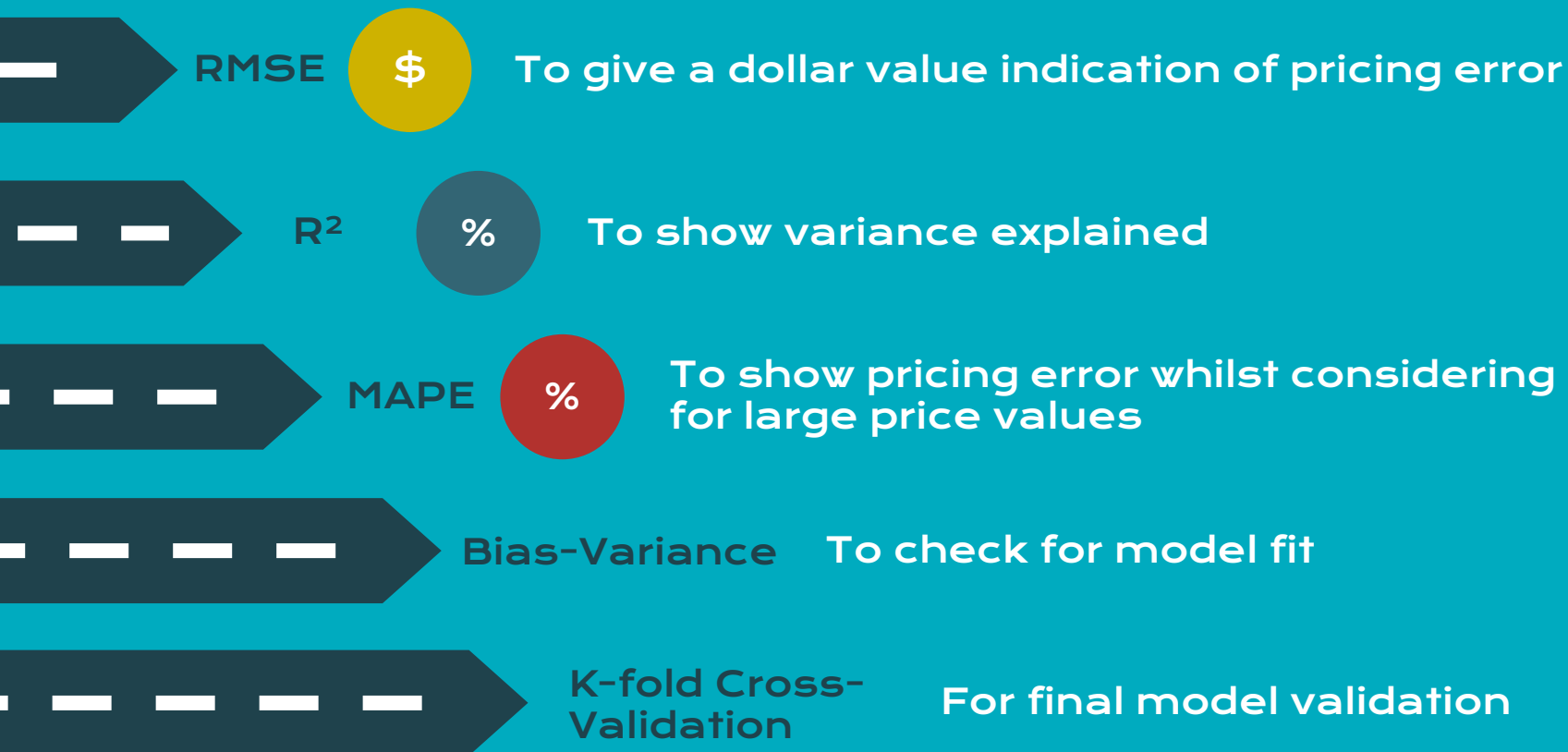
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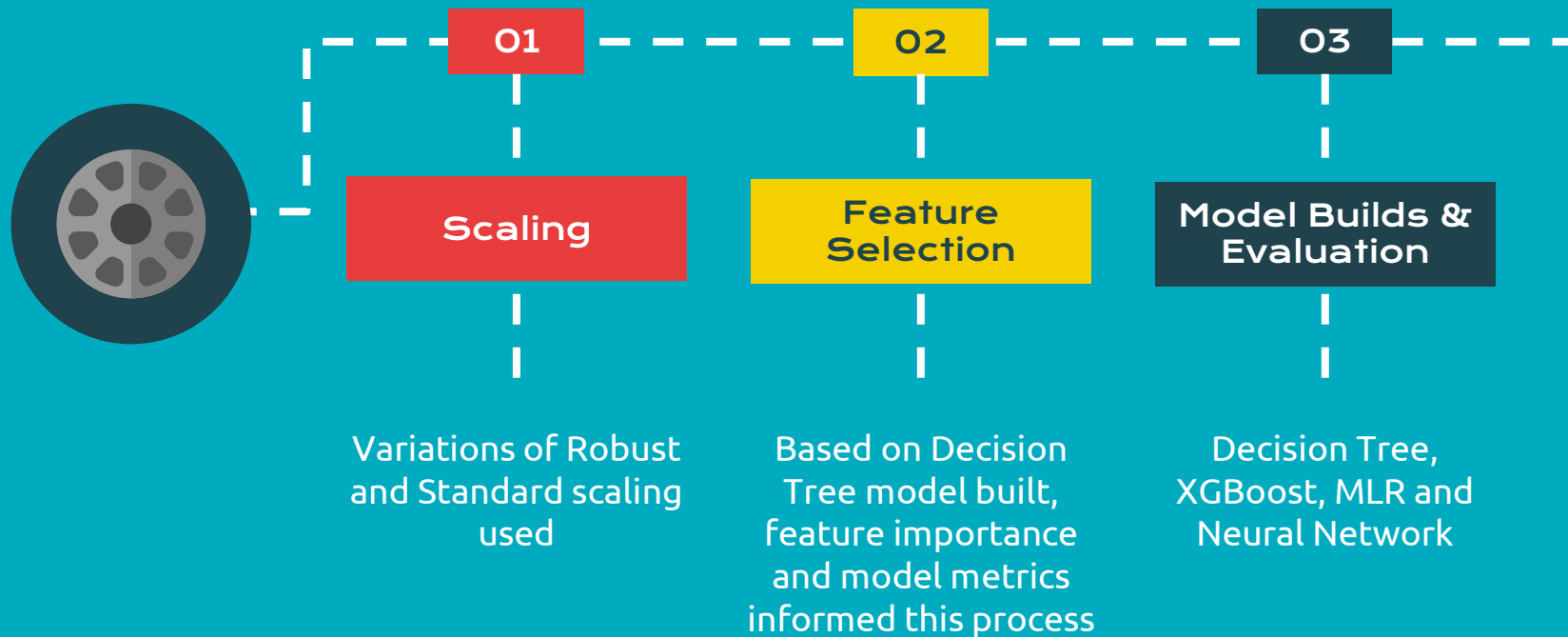
Our model evaluation metrics



In any price negotiation...



Overview of our process for price prediction



Models were built on scaled data after each feature was omitted in feature selection

Train-Test-Val Split: 60-20-20

Scaling

By Sci-kit Learn



Robust

Addresses outliers



Standard

Centers data around the mean

Feature selection - variables omitted

Based on Decision Tree model



01

SAVINGS AMOUNT

Definition unclear



03

FUEL TYPE

Low feature importance



05

ENGINE TYPE

Low feature importance



07

LISTING COLOUR

Low feature importance



02

TRANSMISSION TYPE

Low feature importance



04

MAX. SEATING

Low feature importance for some values



06

BODY TYPE

Low feature importance



08

STATE

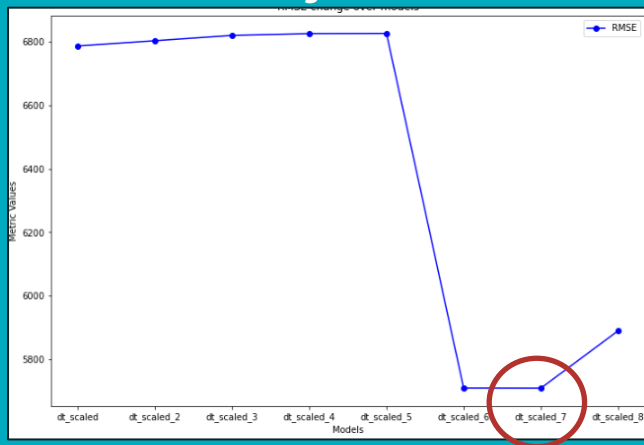
Low feature importance

Feature Selection Justification

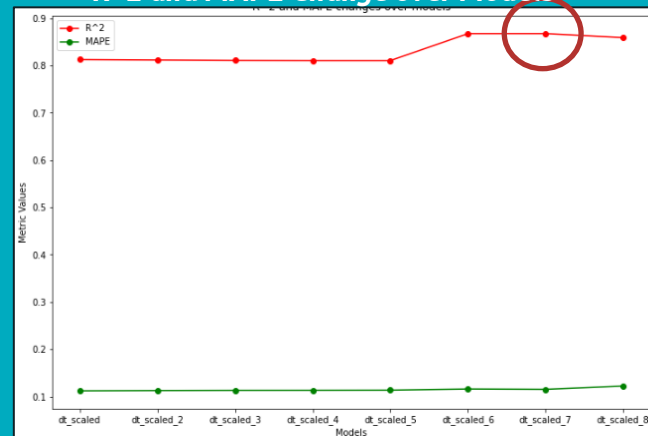
Models

● O1	● O5
SAVINGS AMOUNT	ENGINE TYPE
● O2	● O6
TRANSMISSION TYPE	BODY TYPE
● O3	● O7
FUEL TYPE	LISTING COLOUR
● O4	● O8
MAX. SEATING	STATE

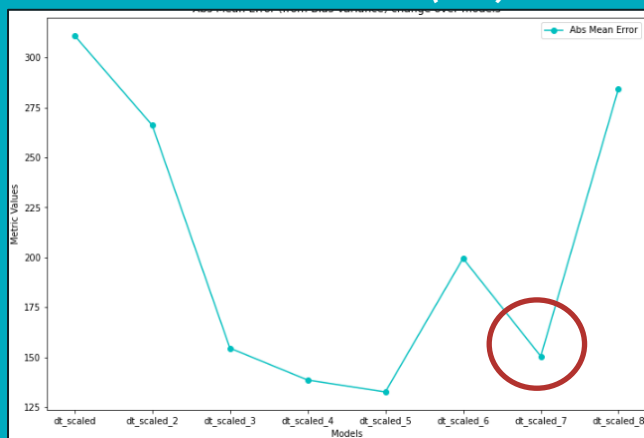
RMSE Change over Models



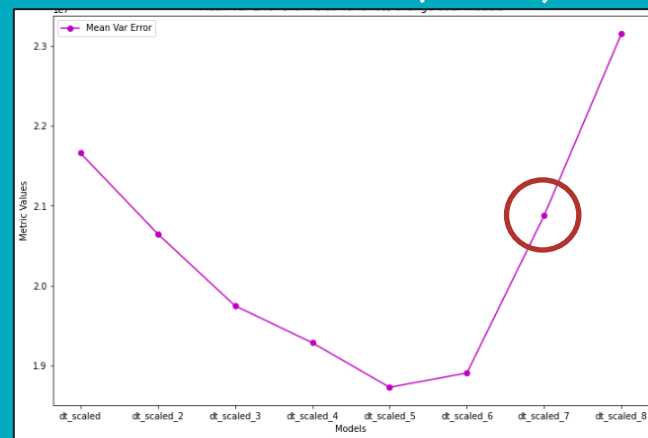
R² and MAPE Change over Models



Absolute Mean Error (Bias)



Mean Variance Error (Variance)



Model 7 Analysis

- Among the **Lowest RMSE**
- **R²** goes up to **~0.86**
- **Abs. Mean Error** drops to **~150**
- **Variance** increases quite significantly to **~2.1**
- **Bias-Variance tradeoff** – prioritize lower bias since test data shows model is less overfit

Final Model Variables



Is New

1st hand car



Make Name

Brand of Car



Max. Seating

Seats in the car: 4,5,6,7,8



Wheel system

*4x2, All Wheel, Forward,
Rear drive*



State

US state



Horsepower

Vroom, vroom



Days on market

Duration car has been for sale



Mileage

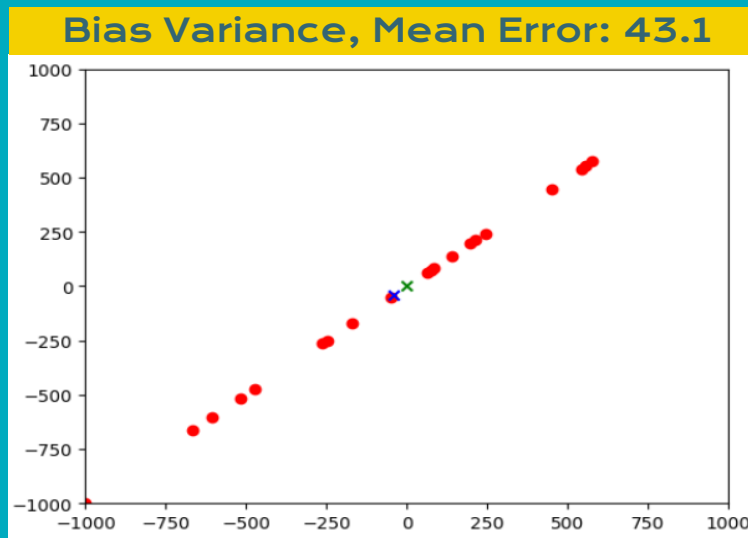
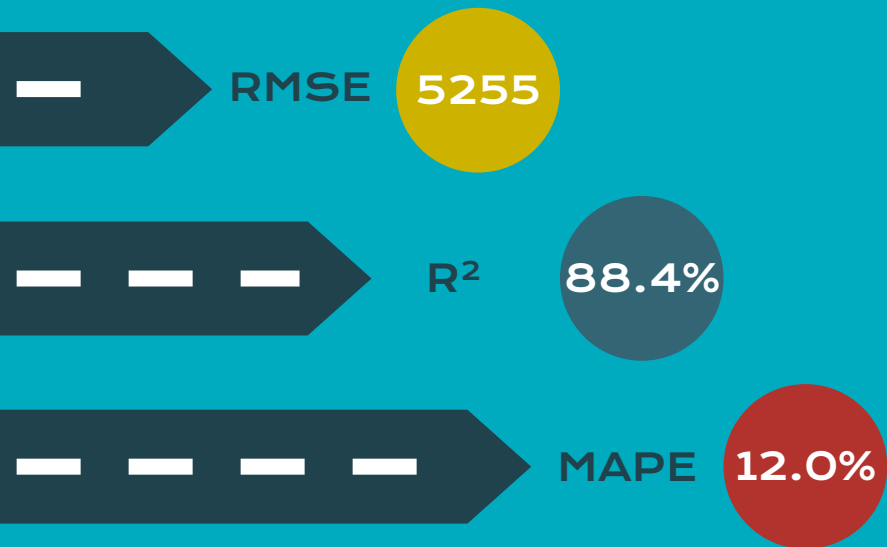
Distance travelled



Seller rating

Proxy for trustworthiness

Final Decision Tree – Results on Test data



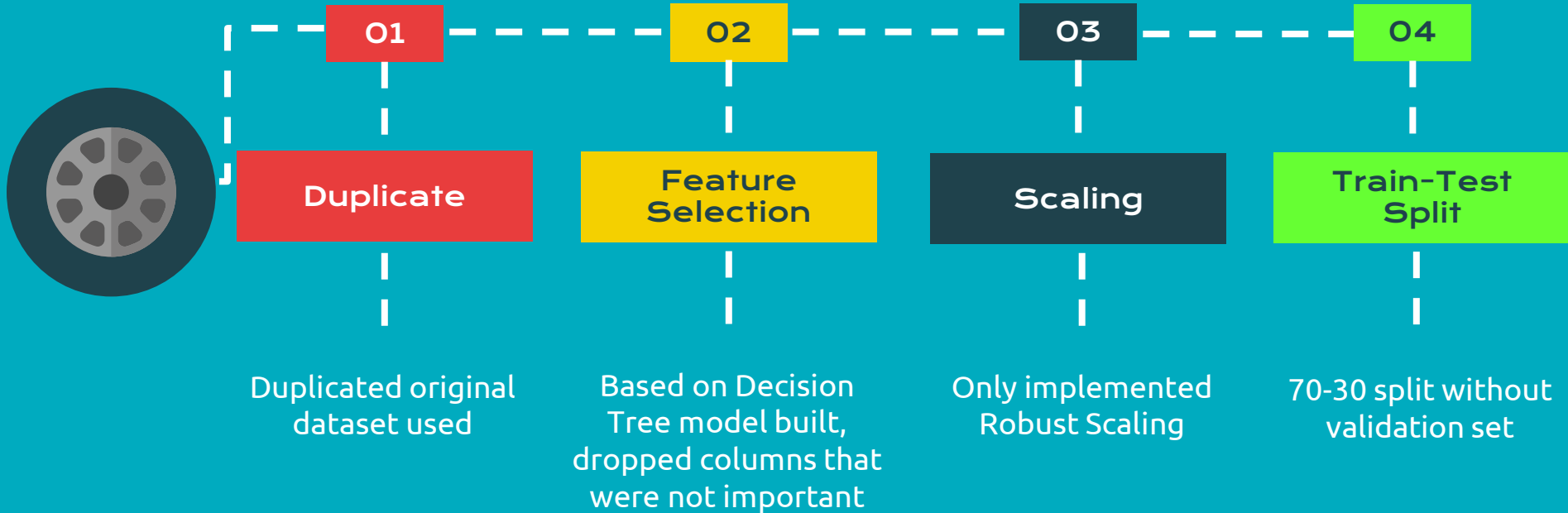
K-fold Cross-Validation (10 splits)

Average R^2 84.5%

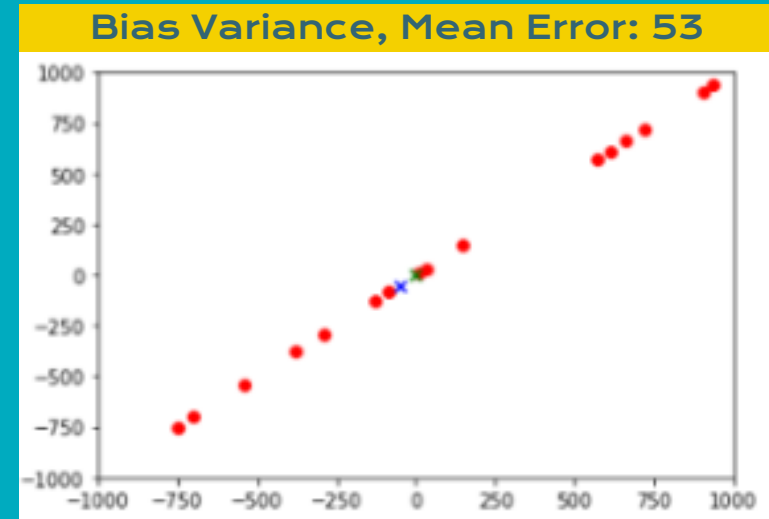
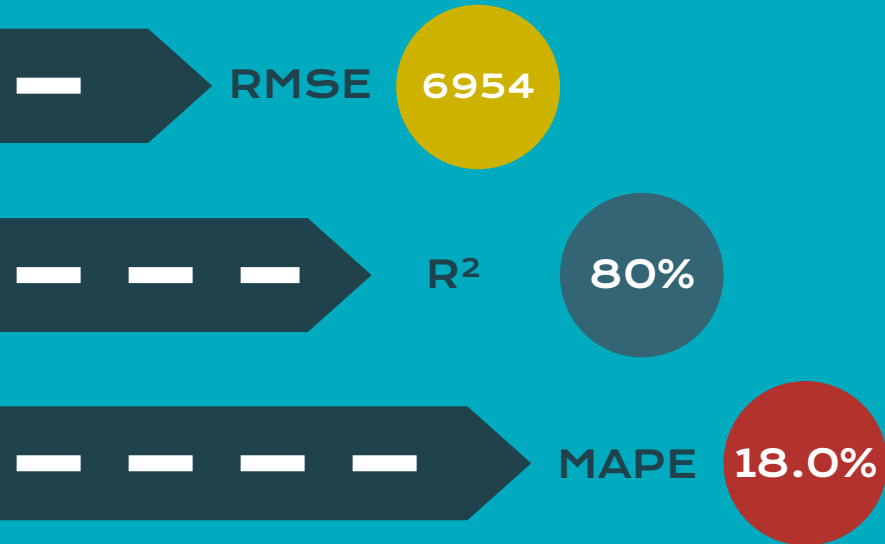
Average MAPE 10.0%

XGBoost model tried – results were not comparable

Preprocessing for multilinear regression



Final Multilinear Regression – Results on Test data

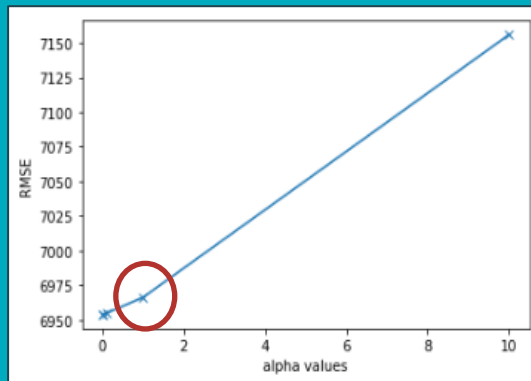


Optimal Alpha = 1

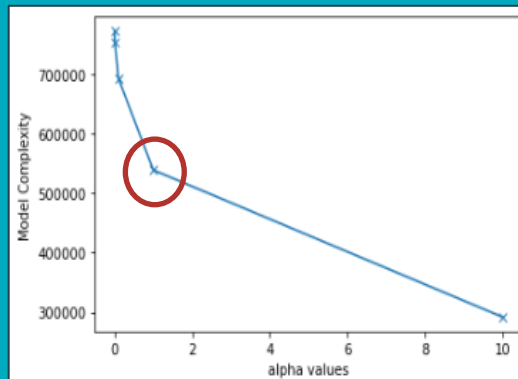
Regularization

Lasso Metrics by Alpha

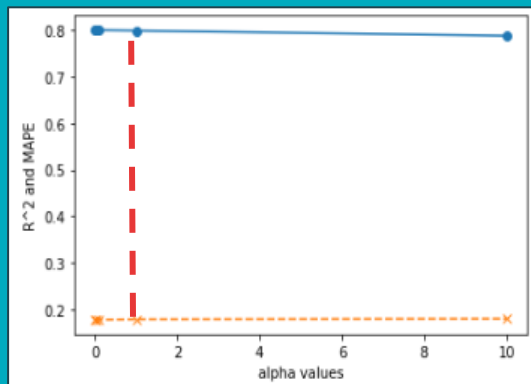
RMSE



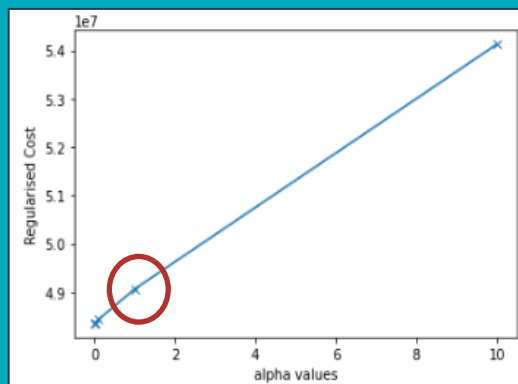
Model Complexity



R² and MAPE



Regularized Cost

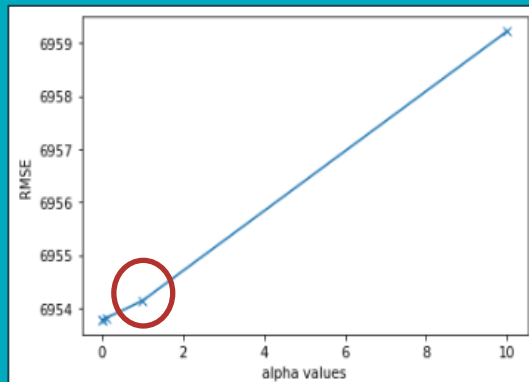


Optimal Alpha = 1

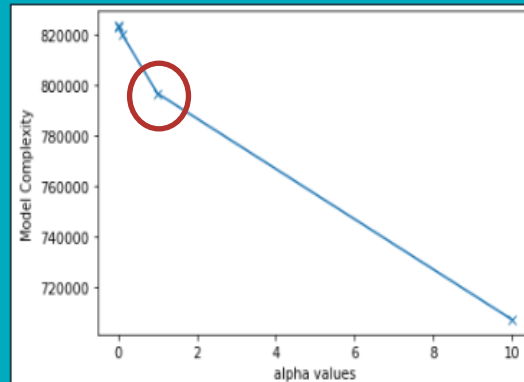
Regularization

Ridge Metrics by Alpha

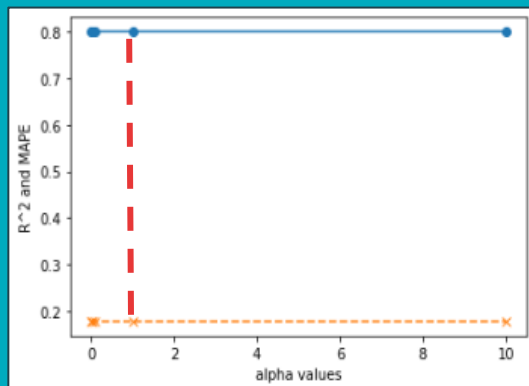
RMSE



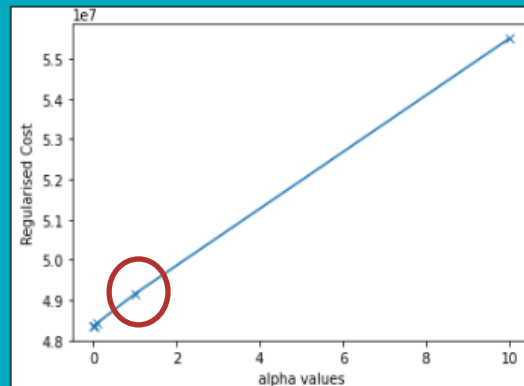
Model Complexity



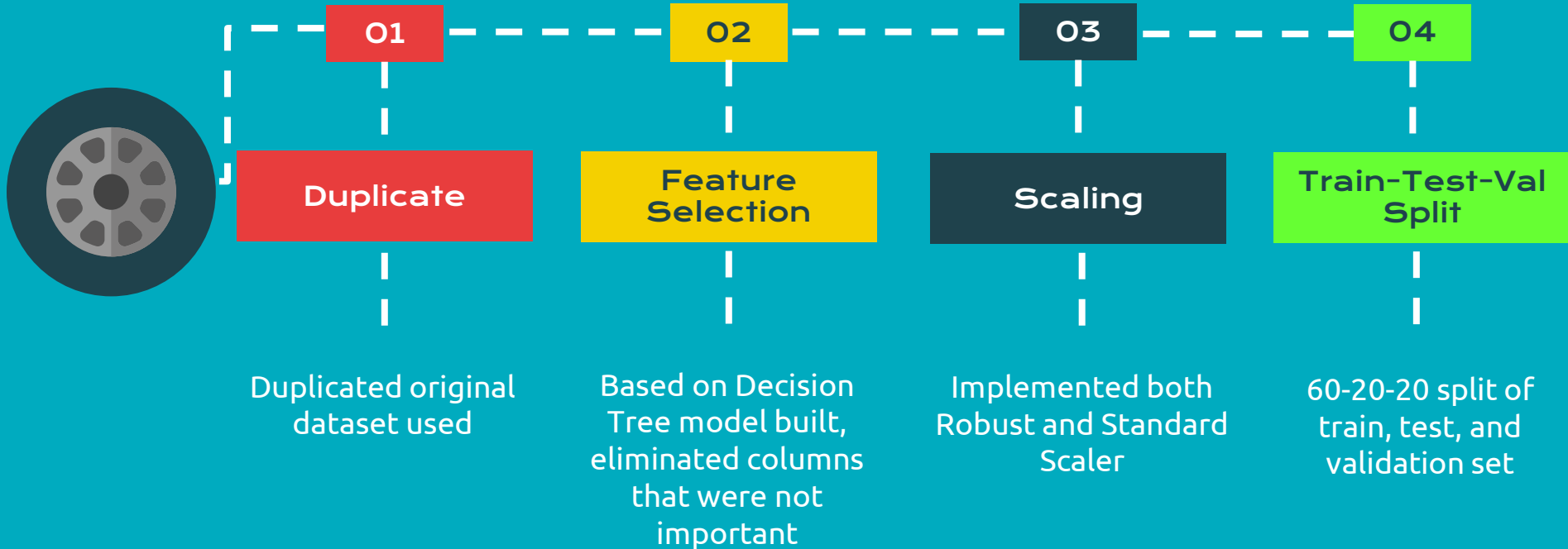
R² and MAPE



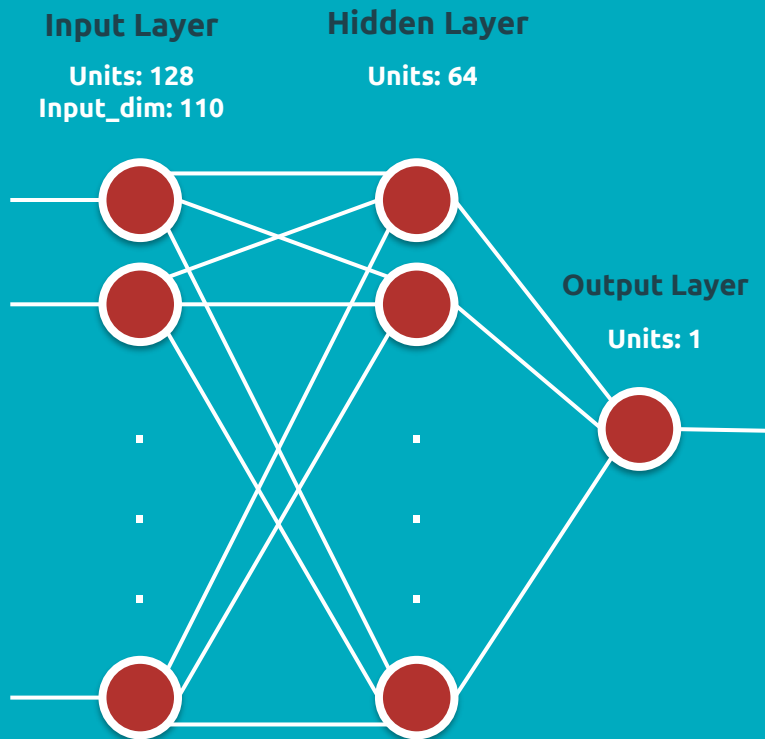
Regularized Cost



Preprocessing for neural network



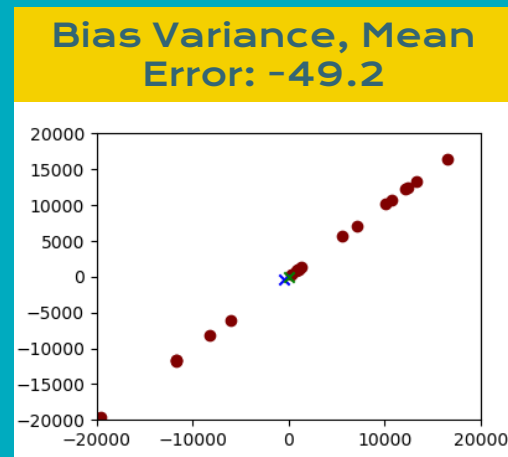
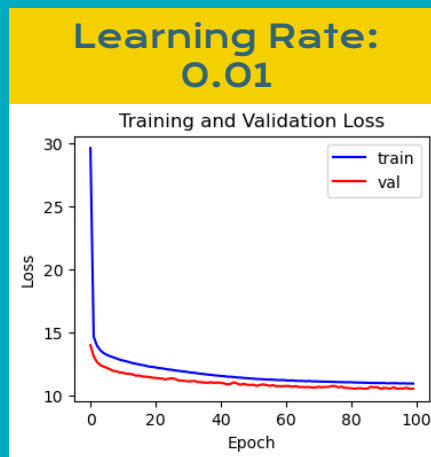
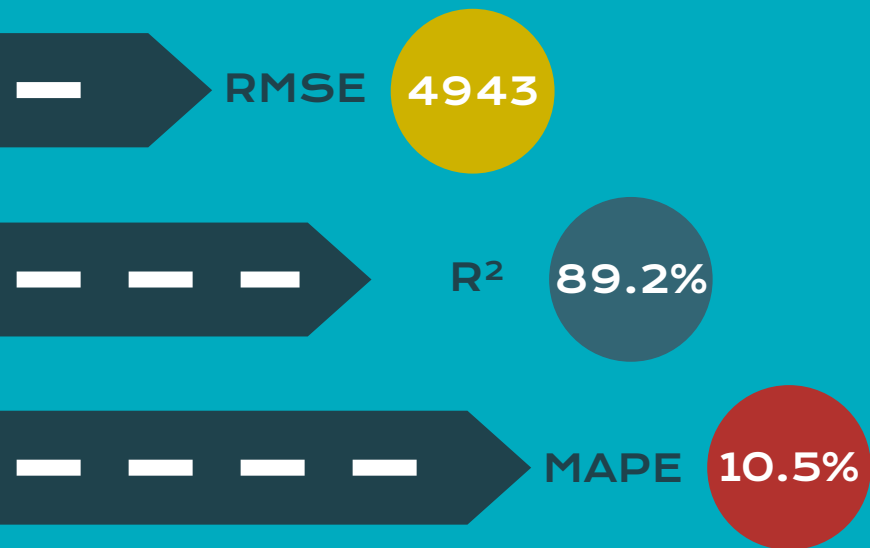
Model of the neural network



Parameters

- **Sample size:** 750k
- **Package used:** Tensorflow, Keras
- **Learning rates:** 0.001, 0.01, 0.025, 0.05, 0.1
- **Activation function:** Leaky ReLU
- **Epochs:** 100
- **Batch_size:** 1024
- **Evaluation metrics:** MAPE, R^2 , RMSE

Final Neural Network – Results on Test data



K-fold Cross-Validation (10 splits)

Average R² **85.7%**

Average MAPE **10.4%**

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Overall results

	Decision Tree	MLR	Final Model ↓ Neural Network
RMSE	5255	5255	4943
R ²	88.4%	88.4%	89.2%
MAPE	12.0%	12.0%	10.4%

Limitations and Future Considerations

Limitations



Insufficient computing power



Transferability of model limited for SG, etc



Additional variables that are difficult to quantify (e.g. condition of car, market conditions)

Future Work



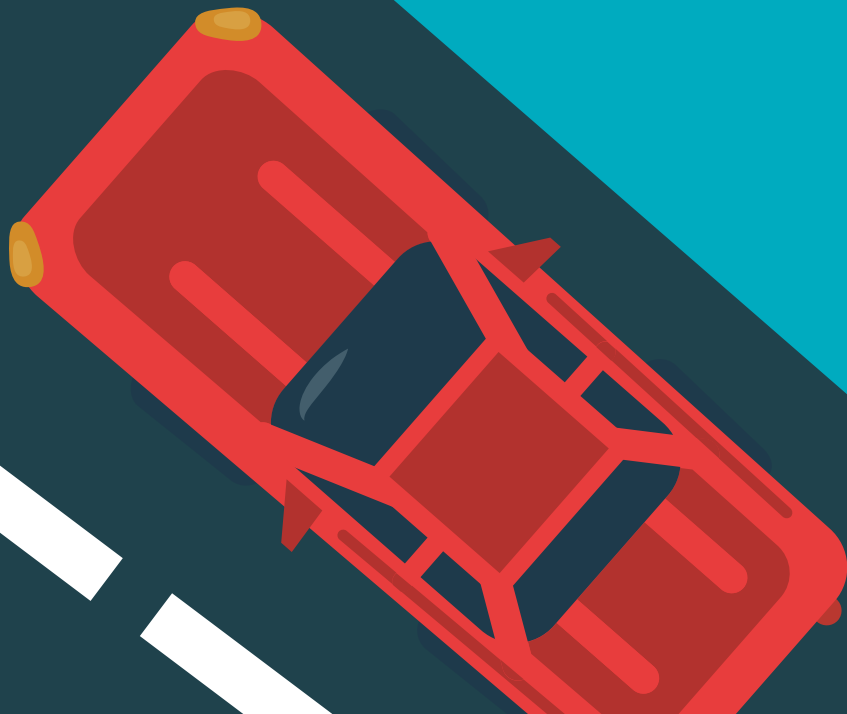
Performing Polynomial Regression



Regularization for Decision Tree



Optimizing NN (pruning, batch-size, epochs, optimizers)



Be Car-eful now

Thank you





APPENDIX

XGBoost with GridSearchCV and K-fold

Parameters	
TUNED	n_estimators 200, 300, 400, 500
	learning_rate 0.001, 0.01, 0.1, 0.2
FIXED	lambda 2
	objective squared error
	eval_metric MAPE
OTHERS	K-fold 10 splits, random shuffle
	GridSearchCV MAPE

