

Name	Pradnosh	Proller	Roll No	190123016	
Name	radnesh	r. Kalkas	ROII INO	190123046	

- 3. The ground state of a particle in one dimensional harmonic oscillator potential is given as $\psi_0(x) = Ae^{-\alpha x^2/2}$ with energy $E_0 = \frac{1}{2}\hbar\omega$, where $A = (m\omega/\pi\hbar)^{1/4}$, $\alpha = m\omega/\hbar$ and ω is the angular frequency of oscillation. [4+6]
 - (a) Compute the uncertainty relation $(\Delta x \Delta p)$ of the particle in the state $\psi_0(x)$.
 - (b) Compute the expectation values of the kinetic energy $(\langle \hat{T} \rangle)$ and the potential energy $(\langle \hat{V} \rangle)$ of the particle in the state $\psi_0(x)$.

Note: You may consider using the Gaussian integrals given as $\int_{-\infty}^{\infty} e^{-ax^2} dx = \sqrt{\frac{\pi}{a}}$.

$$\begin{array}{lll}
\langle x \rangle &=& \left(\begin{array}{c} \varphi_{0}^{*}(x) \times \psi_{0}(x) \, dx \\ =& \left(\begin{array}{c} \infty \\ A^{2} = -\alpha x^{2} \end{array} \right) \, dx \\ =& \left(\begin{array}{c} \infty \\ A^{2} = -\alpha x^{2} \end{array} \right) \, dx \\ =& \left(\begin{array}{c} \infty \\ A^{2} = -\alpha x^{2} \end{array} \right) \, dx \\ =& \left(\begin{array}{c} -\alpha x \\ -\alpha x \end{array} \right) \\ =& \left(\begin{array}{c} -\alpha x \\ -\alpha x \end{array} \right) \\ =& \left(\begin{array}{c} -\alpha x \\ -\alpha x \end{array} \right) \\ =& \left(\begin{array}{c} -\alpha x \\ -\alpha x \end{array} \right) \\ =& \left(\begin{array}{c} -\alpha x \\ -\alpha x \end{array} \right) \\ =& \left(\begin{array}{c} -\alpha x \\ -\alpha x \end{array} \right) \\ =& \left(\begin{array}{c} -\alpha x \\ -\alpha x \end{array} \right) \\ =& \left(\begin{array}{c} -\alpha x \\ -\alpha x \end{array} \right) \\ =& \left(\begin{array}{c} -\alpha x \\ -\alpha x \end{array} \right) \\ =& \left(\begin{array}{c} -\alpha x \\ -\alpha x \end{array} \right) \\ =& \left(\begin{array}{c} -\alpha x \\ -\alpha x \end{array} \right) \\ =& \left(\begin{array}{c} -\alpha x \\ -\alpha x \end{array} \right) \\ =& \left(\begin{array}{c} -\alpha x \\ -\alpha x \end{array} \right) \\ =& \left(\begin{array}{c} -\alpha x \\ -\alpha x \end{array} \right) \\ =& \left(\begin{array}{c} -\alpha x \\ -\alpha x \end{array} \right) \\ =& \left(\begin{array}{c} -\alpha x \\ -\alpha x \end{array} \right) \\ =& \left(\begin{array}{c} -\alpha x \\ -\alpha x \end{array} \right) \\ =& \left(\begin{array}{c} -\alpha x \\ -\alpha x \end{array} \right) \\ =& \left(\begin{array}{c} -\alpha x \\ -\alpha x \end{array} \right) \\ =& \left(\begin{array}{c} -\alpha x \\ -\alpha x \end{array} \right) \\ =& \left(\begin{array}{c} -\alpha x \\ -\alpha x \end{array} \right) \\ =& \left(\begin{array}{c} -\alpha x \\ -\alpha x \end{array} \right) \\ =& \left(\begin{array}{c} -\alpha x \\ -\alpha x \end{array} \right) \\ =& \left(\begin{array}{c} -\alpha x \\ -\alpha x \end{array} \right) \\ =& \left(\begin{array}{c} -\alpha x \\ -\alpha x \end{array} \right) \\ =& \left(\begin{array}{c} -\alpha x \\ -\alpha x \end{array} \right) \\ =& \left(\begin{array}{c} -\alpha x \\ -\alpha x \end{array} \right) \\ =& \left(\begin{array}{c} -\alpha x \\ -\alpha x \end{array} \right) \\ =& \left(\begin{array}{c} -\alpha x \\ -\alpha x \end{array} \right) \\ =& \left(\begin{array}{c} -\alpha x \\ -\alpha x \end{array} \right) \\ =& \left(\begin{array}{c} -\alpha x \\ -\alpha x \end{array} \right) \\ =& \left(\begin{array}{c} -\alpha x \\ -\alpha x \end{array} \right) \\ =& \left(\begin{array}{c} -\alpha x \\ -\alpha x \end{array} \right) \\ =& \left(\begin{array}{c} -\alpha x \\ -\alpha x \end{array} \right) \\ =& \left(\begin{array}{c} -\alpha x \\ -\alpha x \end{array} \right) \\ =& \left(\begin{array}{c} -\alpha x \\ -\alpha x \end{array} \right) \\ =& \left(\begin{array}{c} -\alpha x \\ -\alpha x \end{array} \right) \\ =& \left(\begin{array}{c} -\alpha x \\ -\alpha x \end{array} \right) \\ =& \left(\begin{array}{c} -\alpha x \\ -\alpha x \end{array} \right) \\ =& \left(\begin{array}{c} -\alpha x \\ -\alpha x \end{array} \right) \\ =& \left(\begin{array}{c} -\alpha x \\ -\alpha x \end{array} \right) \\ =& \left(\begin{array}{c} -\alpha x \\ -\alpha x \end{array} \right) \\ =& \left(\begin{array}{c} -\alpha x \\ -\alpha x \end{array} \right) \\ =& \left(\begin{array}{c} -\alpha x \\ -\alpha x \end{array} \right) \\ =& \left(\begin{array}{c} -\alpha x \\ -\alpha x \end{array} \right) \\ =& \left(\begin{array}{c} -\alpha x \\ -\alpha x \end{array} \right) \\ =& \left(\begin{array}{c} -\alpha x \\ -\alpha x \end{array} \right) \\ =& \left(\begin{array}{c} -\alpha x \\ -\alpha x \end{array} \right) \\ =& \left(\begin{array}{c} -\alpha x \\ -\alpha x \end{array} \right) \\ =& \left(\begin{array}{c} -\alpha x \\ -\alpha x \end{array} \right) \\ =& \left(\begin{array}{c} -\alpha x \\ -\alpha x \end{array} \right) \\ =& \left(\begin{array}{c} -\alpha x \\ -\alpha x \end{array} \right) \\ =& \left(\begin{array}{c} -\alpha x \\ -\alpha x \end{array} \right) \\ =& \left(\begin{array}{c} -\alpha x \\ -\alpha x \end{array} \right) \\ =& \left(\begin{array}{c} -\alpha x \\ -\alpha x \end{array} \right) \\ =& \left(\begin{array}{c} -\alpha x \\ -\alpha x \end{array} \right) \\ =& \left(\begin{array}{c} -\alpha x \\ -\alpha x \end{array} \right) \\ =& \left(\begin{array}{c} -\alpha x \\ -\alpha x \end{array} \right) \\ =& \left(\begin{array}{c} -\alpha x \\ -\alpha x \end{array} \right) \\ =& \left(\begin{array}{c} -\alpha x \\ -\alpha x \end{array} \right) \\ =& \left(\begin{array}{c} -\alpha x \\ -\alpha x \end{array} \right) \\ =& \left(\begin{array}{c} -\alpha x \\ -\alpha x \end{array}$$

Δx = /(x²> - (x)² = /x²> = /xw V = 1 kg = 1 mw sz .. < \(\sigma\) = \(\frac{7}{2} \times = \frac{2m\omega}{4} \frac{1m\omega}{2} \frac{5m\omega}{4} $\langle \hat{v} \rangle = \pm \hbar \omega$ < p² > = (40/2) p² 40/2) dx ρ2 ψο(x) = - +2 22 ψο(x) = Aα +2 - αχε/2 (1-αχε) : <p2> = \(\rho^2 > = \int^2 \rho^2 \rangle \rangle \(\rho^2 \rangle \rangle \rangle \rangle \rangle \(\rho^2 \rangle \rang = A2 x t2 se dx - A2x2 t2 se dx $= A^{2} \cdot \alpha \cdot t^{2} \cdot \sqrt{\pi/\alpha} - A^{2} \cdot \alpha^{2} t^{2} \cdot \sqrt{\alpha}$ $= A^{2} \cdot \alpha \cdot t^{2} \cdot \sqrt{\pi/\alpha}$ $= A^2 \propto t^2 / T/\alpha = m \omega t$ · · < p2 > = mwt $kE = \frac{p^2}{2m} \cdot (\sqrt{+}) = \frac{\sqrt{p^2}}{2m} = \frac{1}{4} t\omega$ $\Delta p = \sqrt{\langle p^2 \rangle - \langle p \rangle^2} = \sqrt{\langle p^2 \rangle} = \sqrt{\frac{m \omega t}{m \omega t}}$ From (2) and (4), Ax-Ap = It I mwth - It which clearly satisfies uncertainty principles

Ans: (9) Ax. Ap = to 2 b) < +> = < \(\hat{V} > = \pm \tau \)