

# PH 102, Electromagnetism,

Post Mid Semester

## Lecture 8.

### Electrodynamics

Maxwell's Equations:  
Problem Solving & Discussions

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# Maxwell's Equations

$$\nabla \cdot \mathbf{E} = \frac{1}{\epsilon_0} \rho$$

$$\nabla \times \mathbf{E} + \frac{\partial \mathbf{B}}{\partial t} = \mathbf{0},$$

$$\nabla \cdot \mathbf{B} = 0$$

$$\nabla \times \mathbf{B} - \mu_0 \epsilon_0 \frac{\partial \mathbf{E}}{\partial t} = \mu_0 \mathbf{J},$$

# Maxwell's Equations

Maxwell's Equations in Matter : Electric and Magnetic Polarization

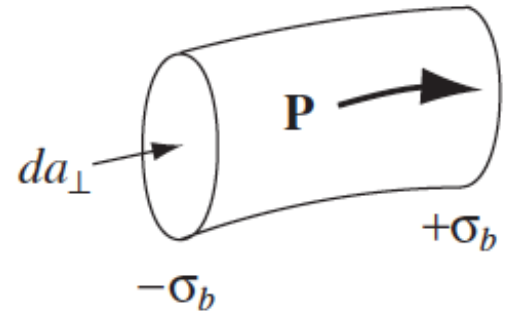
$$\rho_b = -\nabla \cdot \mathbf{P} \quad \mathbf{J}_b = \nabla \times \mathbf{M}$$

electric/magnetic polarization produces bound charge density/current

Polarization current:  $\mathbf{P}$  changes with time

$$dI = \frac{\partial \sigma_b}{\partial t} da_{\perp} = \frac{\partial P}{\partial t} da_{\perp}$$

$$\text{Polarization current, } \mathbf{J}_p = \frac{\partial \mathbf{P}}{\partial t}$$



$\mathbf{J}_b$  connected to magnetization but  $\mathbf{J}_p$  connected to change of electric polarization

$$\nabla \cdot \mathbf{J}_p = \nabla \cdot \frac{\partial \mathbf{P}}{\partial t} = \frac{\partial}{\partial t} (\nabla \cdot \mathbf{P}) = -\frac{\partial \rho_b}{\partial t}$$

Continuity  
Equation for  $\mathbf{J}_p$

# Maxwell's Equations

## Maxwell's Equations in Matter :

$$\nabla \cdot \mathbf{D} = \rho_f, \quad \nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t},$$

$$\nabla \cdot \mathbf{B} = 0, \quad \nabla \times \mathbf{H} = \mathbf{J}_f + \frac{\partial \mathbf{D}}{\partial t}.$$

$$\mathbf{J}_d \equiv \frac{\partial \mathbf{D}}{\partial t}$$

# Maxwell's Equations

## Boundary Conditions: General Conditions

$$\begin{aligned} D_1^\perp - D_2^\perp &= \sigma_f & \mathbf{E}_1^\parallel - \mathbf{E}_2^\parallel &= \mathbf{0} \\ B_1^\perp - B_2^\perp &= 0 & \mathbf{H}_1^\parallel - \mathbf{H}_2^\parallel &= \mathbf{K}_f \times \hat{\mathbf{n}} \end{aligned}$$

For linear media: Boundary conditions in terms of  $\mathbf{E}$  and  $\mathbf{B}$  alone,

$$\begin{aligned} \epsilon_1 E_1^\perp - \epsilon_2 E_2^\perp &= \sigma_f, & \mathbf{E}_1^\parallel - \mathbf{E}_2^\parallel &= \mathbf{0}, \\ B_1^\perp - B_2^\perp &= 0, & \frac{1}{\mu_1} \mathbf{B}_1^\parallel - \frac{1}{\mu_2} \mathbf{B}_2^\parallel &= \mathbf{K}_f \times \hat{\mathbf{n}}. \end{aligned}$$

Theory of reflection and refraction!

(1) An alternating current  $I = I_0 \cos(\omega t)$  flows down a long straight wire, and returns along a coaxial conducting tube of radius  $a$ . Assuming that the field goes to zero as  $s \rightarrow \infty$ ,

- Find  $E(s, t)$ .
- Find the displacement current density  $J_d$ .
- Integrate it to get the total displacement current,
- Compare  $I_d$  and  $I$ . If the outer cylinder were, say, 2 mm in diameter, how high would the frequency have to be, for  $I_d$  to be 1% of  $I$ ?

### Solution:

a) Using the “Amperian loop”

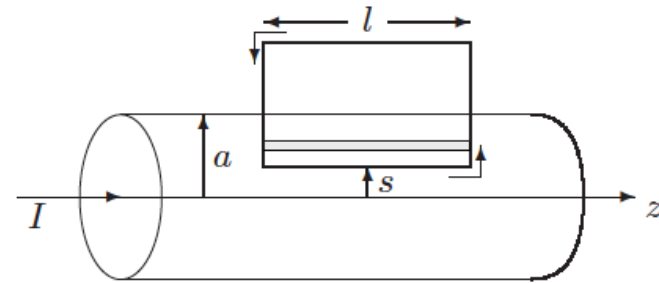
$$\oint \mathbf{E} \cdot d\mathbf{l} = El = -\frac{d\Phi}{dt} = -\frac{d}{dt} \int \mathbf{B} \cdot d\mathbf{a} = -\frac{d}{dt} \int_s^a \frac{\mu_0 I}{2\pi s'} l ds'$$

Outside,  $B = 0$ , so here  $E = 0$   
(like  $B$  outside a solenoid).

$$\therefore E = -\frac{\mu_0}{2\pi} \frac{dI}{dt} \ln\left(\frac{a}{s}\right).$$

$$\frac{dI}{dt} = -I_0 \omega \sin \omega t,$$

$$\mathbf{E} = \frac{\mu_0 I_0 \omega}{2\pi} \sin(\omega t) \ln\left(\frac{a}{s}\right) \hat{\mathbf{z}}.$$



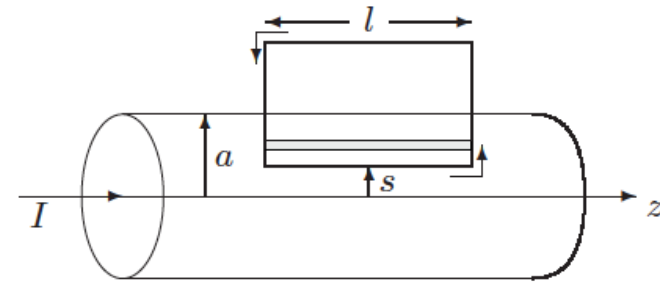
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**Solution:**

$$\mathbf{E} = \frac{\mu_0 I_0 \omega}{2\pi} \sin(\omega t) \ln\left(\frac{a}{s}\right) \hat{\mathbf{z}}.$$

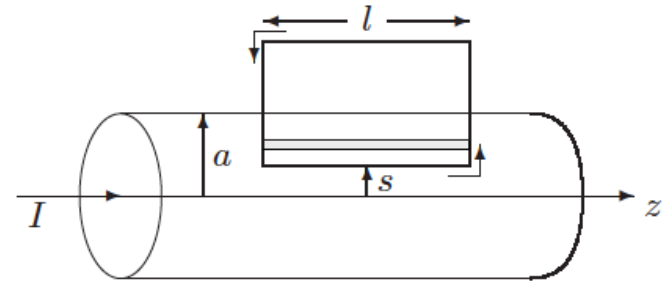
(b)

$$\begin{aligned}
 J_d &= \epsilon_0 \frac{\partial \mathbf{E}}{\partial t} \\
 &= \epsilon_0 \frac{\mu_0 I_0 \omega^2}{2\pi} \cos(\omega t) \ln(a/s) \hat{\mathbf{z}}. \\
 &= \frac{\mu_0 \epsilon_0}{2\pi} \omega^2 I \ln(a/s) \hat{\mathbf{z}}.
 \end{aligned}$$



(c)

$$\mathbf{J}_d = \epsilon_0 \frac{\partial \mathbf{E}}{\partial t} = \frac{\mu_0 \epsilon_0}{2\pi} \omega^2 I \ln(a/s) \hat{\mathbf{z}}.$$



$$\begin{aligned} I_d &= \int \mathbf{J}_d \cdot d\mathbf{a} = \frac{\mu_0 \epsilon_0 \omega^2 I}{2\pi} \int_0^a \ln(a/s) (2\pi s ds) = \mu_0 \epsilon_0 \omega^2 I \int_0^a (s \ln a - s \ln s) ds \\ &= \mu_0 \epsilon_0 \omega^2 I \left[ (\ln a) \frac{s^2}{2} - \frac{s^2}{2} \ln s + \frac{s^2}{4} \right] \bigg|_0^a = \mu_0 \epsilon_0 \omega^2 I \left[ \cancel{\frac{a^2}{2}} \ln a - \cancel{\frac{a^2}{2}} \ln a + \frac{a^2}{4} \right] \\ &= \frac{\mu_0 \epsilon_0 \omega^2 I a^2}{4}. \end{aligned}$$



(d) Compare  $I_d$  and  $I$ . If the outer cylinder were, say, 2 mm in diameter, how high would the frequency have to be, for  $I_d$  to be 1% of  $I$ ?

(d) 
$$I_d = \frac{\mu_0 \epsilon_0 \omega^2 I a^2}{4} \quad \longrightarrow \quad \frac{I_d}{I} = \frac{\mu_0 \epsilon_0 \omega^2 a^2}{4}$$

where,  $\mu_0 \epsilon_0 = 1/c^2$ ,  $I_d/I = (\omega a/2c)^2$ .

Given,  $a = 10^{-3} \text{ m}$ , and  $\frac{I_d}{I} = \frac{1}{100}$ ,  $\longrightarrow$   $\frac{\omega a}{2c} = \frac{1}{10}$ ,

$$\omega = \frac{2c}{10a} = \frac{3 \times 10^8 \text{ m/s}}{5 \times 10^{-3} \text{ m}}, \text{ or } \omega = 0.6 \times 10^{11} / \text{s}$$

$$\nu = \frac{\omega}{2\pi} \approx 10^{10} \text{ Hz},$$

Microwave, way above the  
radio frequencies

The frequency required so that the displacement current is comparable ( $\sim 1\%$ ) is very high @ microwave. Hence, in the early days of Faraday no experimental signal could appear giving clue for the displacement current!

**(2)** Consider the following fields,  $\mathbf{E}(\mathbf{r}, t) = \frac{1}{4\pi\epsilon_0} \frac{q}{r^2} \theta(vt - r) \hat{\mathbf{r}}; \quad \mathbf{B}(\mathbf{r}, t) = \mathbf{0}$

Show that these fields satisfy all of Maxwell's equations, and determine  $\rho$  and  $\mathbf{J}$ .  
Describe the physical situation that gives rise to these fields.

**Solution:**

Physically, this is the field of a point charge  $+q$  at the origin, out to an expanding spherical shell of radius  $vt$ . Outside the shell the field is zero. Evidently the shell carries the opposite charge,  $-q$ .

$$\mathbf{E}(\mathbf{r}, t) = \frac{1}{4\pi\epsilon_0} \frac{q}{r^2} \theta(vt - r) \hat{\mathbf{r}}; \quad \mathbf{B}(\mathbf{r}, t) = \mathbf{0}$$

Physically, this is the field of a point charge  $+q$  at the origin, out to an expanding spherical shell of radius  $vt$ . Outside the shell the field is zero. Evidently the shell carries the opposite charge,  $-q$ .

$$\mathbf{E}(\mathbf{r}, t) = \frac{1}{4\pi\epsilon_0} \frac{q}{r^2} \theta(vt - r) \hat{\mathbf{r}};$$

$$\nabla \cdot (f\mathbf{A}) = f(\nabla \cdot \mathbf{A}) + \mathbf{A} \cdot (\nabla f)$$

$$\nabla \cdot \mathbf{E} = \theta(vt - r) \nabla \cdot \left( \frac{1}{4\pi\epsilon_0} \frac{q}{r^2} \hat{\mathbf{r}} \right) + \frac{1}{4\pi\epsilon_0} \frac{q}{r^2} \hat{\mathbf{r}} \cdot \nabla [\theta(vt - r)]$$

$$\nabla \cdot \left( \frac{\hat{\mathbf{r}}}{r^2} \right) = 4\pi \delta^3(\mathbf{r}).$$

$$= \frac{q}{\epsilon_0} \delta^3(\mathbf{r}) \theta(vt - r) + \frac{1}{4\pi\epsilon_0} \frac{q}{r^2} (\hat{\mathbf{r}} \cdot \hat{\mathbf{r}}) \frac{\partial}{\partial r} \theta(vt - r).$$

$$\delta^3(\mathbf{r}) \theta(vt - r) = \delta^3(\mathbf{r}) \theta(t), \text{ and } \frac{\partial}{\partial r} \theta(vt - r) = -\delta(vt - r)$$

$$\rho = \epsilon_0 \nabla \cdot \mathbf{E} = q \delta^3(\mathbf{r}) \theta(t) - \frac{q}{4\pi r^2} \delta(vt - r).$$

$$\rho = \epsilon_0 \nabla \cdot \mathbf{E} = q \delta^3(\mathbf{r}) \theta(t) - \frac{q}{4\pi r^2} \delta(vt - r).$$

For  $t < 0$  the field and the charge density are zero everywhere.

$$\nabla \cdot \mathbf{B} = 0, \text{ and } \nabla \times \mathbf{E} = 0$$

(since  $\mathbf{E}$  has only an  $r$  component and it is independent of  $\theta$  and  $\phi$ )

$$\nabla \times \mathbf{B} = 0 = \mu_0 \mathbf{J} + \mu_0 \epsilon_0 \partial \mathbf{E} / \partial t.$$

$$\mathbf{J} = -\epsilon_0 \frac{\partial \mathbf{E}}{\partial t} = -\epsilon_0 \left\{ \frac{q}{4\pi \epsilon_0 r^2} \frac{\partial}{\partial t} [\theta(vt - r)] \right\} \hat{\mathbf{r}} = -\frac{q}{4\pi r^2} v \delta(vt - r) \hat{\mathbf{r}}.$$

The stationary charge at the origin doesn't contribute to  $\mathbf{J}$ ,  
of course; for the expanding shell we have  $\mathbf{J} = \rho \mathbf{v}$ .

3. (a)

Show that Maxwell's equations with magnetic charge are invariant under the duality transformation,

$$\begin{aligned}\mathbf{E}' &= \mathbf{E} \cos \alpha + c \mathbf{B} \sin \alpha, \\ c \mathbf{B}' &= c \mathbf{B} \cos \alpha - \mathbf{E} \sin \alpha, \\ c q_e' &= c q_e \cos \alpha + q_m \sin \alpha, \\ q_m' &= q_m \cos \alpha - c q_e \sin \alpha,\end{aligned}$$

where  $c = 1/\sqrt{\epsilon_0 \mu_0}$  and  $\alpha$  is an arbitrary rotation angle in “ $\mathbf{E}/\mathbf{B}$ -space.” Charge and current densities transform in the same way as  $q_e$  and  $q_m$ .

3. (b)

Show that the force law,  $\mathbf{F} = q_e(\mathbf{E} + \mathbf{v} \times \mathbf{B}) + q_m \left( \mathbf{B} - \frac{1}{c^2} \mathbf{v} \times \mathbf{E} \right)$ , is also invariant under the duality transformation.

(i) $\nabla \cdot \mathbf{E} = \frac{1}{\epsilon_0} \rho_e,$	(iii) $\nabla \times \mathbf{E} = -\mu_0 \mathbf{J}_m - \frac{\partial \mathbf{B}}{\partial t},$
(ii) $\nabla \cdot \mathbf{B} = \mu_0 \rho_m,$	(iv) $\nabla \times \mathbf{B} = \mu_0 \mathbf{J}_e + \mu_0 \epsilon_0 \frac{\partial \mathbf{E}}{\partial t}.$

$$\begin{aligned}
\mathbf{E}' &= \mathbf{E} \cos \alpha + c \mathbf{B} \sin \alpha, \\
c \mathbf{B}' &= c \mathbf{B} \cos \alpha - \mathbf{E} \sin \alpha, \\
c q'_e &= c q_e \cos \alpha + q_m \sin \alpha, \\
q'_m &= q_m \cos \alpha - c q_e \sin \alpha,
\end{aligned}$$

3. (a)

$$\begin{aligned}
\nabla \cdot \mathbf{E}' &= (\nabla \cdot \mathbf{E}) \cos \alpha + c(\nabla \cdot \mathbf{B}) \sin \alpha = \frac{1}{\epsilon_0} \rho_e \cos \alpha + c \mu_0 \rho_m \sin \alpha \\
&= \frac{1}{\epsilon_0} (\rho_e \cos \alpha + c \mu_0 \epsilon_0 \rho_m \sin \alpha) = \frac{1}{\epsilon_0} (\rho_e \cos \alpha + \frac{1}{c} \rho_m \sin \alpha) = \frac{1}{\epsilon_0} \rho'_e.
\end{aligned}$$

$$\begin{aligned}
\nabla \cdot \mathbf{B}' &= (\nabla \cdot \mathbf{B}) \cos \alpha - \frac{1}{c} (\nabla \cdot \mathbf{E}) \sin \alpha = \mu_0 \rho_m \cos \alpha - \frac{1}{c \epsilon_0} \rho_e \sin \alpha \\
&= \mu_0 (\rho_m \cos \alpha - \frac{1}{c \mu_0 \epsilon_0} \rho_e \sin \alpha) = \mu_0 (\rho_m \cos \alpha - c \rho_e \sin \alpha) = \mu_0 \rho'_m.
\end{aligned}$$

$$\begin{aligned}
\nabla \times \mathbf{E}' &= (\nabla \times \mathbf{E}) \cos \alpha + c(\nabla \times \mathbf{B}) \sin \alpha = \left( -\mu_0 \mathbf{J}_m - \frac{\partial \mathbf{B}}{\partial t} \right) \cos \alpha + c \left( \mu_0 \mathbf{J}_e + \mu_0 \epsilon_0 \frac{\partial \mathbf{E}}{\partial t} \right) \sin \alpha \\
&= -\mu_0 (\mathbf{J}_m \cos \alpha - c \mathbf{J}_e \sin \alpha) - \frac{\partial}{\partial t} \left( \mathbf{B} \cos \alpha - \frac{1}{c} \mathbf{E} \sin \alpha \right) = -\mu_0 \mathbf{J}'_m - \frac{\partial \mathbf{B}'}{\partial t}. \checkmark
\end{aligned}$$

$$\begin{aligned}
\nabla \times \mathbf{B}' &= (\nabla \times \mathbf{B}) \cos \alpha - \frac{1}{c} (\nabla \times \mathbf{E}) \sin \alpha = \left( \mu_0 \mathbf{J}_e + \mu_0 \epsilon_0 \frac{\partial \mathbf{E}}{\partial t} \right) \cos \alpha - \frac{1}{c} \left( -\mu_0 \mathbf{J}_m - \frac{\partial \mathbf{B}}{\partial t} \right) \sin \alpha \\
&= \mu_0 (\mathbf{J}_e \cos \alpha + \frac{1}{c} \mathbf{J}_m \sin \alpha) + \mu_0 \epsilon_0 \frac{\partial}{\partial t} (\mathbf{E} \cos \alpha + c \mathbf{B} \sin \alpha) = \mu_0 \mathbf{J}'_e + \mu_0 \epsilon_0 \frac{\partial \mathbf{E}'}{\partial t}. \checkmark
\end{aligned}$$

$$\begin{aligned}
\mathbf{E}' &= \mathbf{E} \cos \alpha + c\mathbf{B} \sin \alpha, \\
c\mathbf{B}' &= c\mathbf{B} \cos \alpha - \mathbf{E} \sin \alpha, \\
cq'_e &= cq_e \cos \alpha + q_m \sin \alpha, \\
q'_m &= q_m \cos \alpha - cq_e \sin \alpha,
\end{aligned}$$

$$\begin{aligned}
3. (b) \quad \mathbf{F}' &= q'_e(\mathbf{E}' + \mathbf{v} \times \mathbf{B}') + q'_m(\mathbf{B}' - \frac{1}{c^2}\mathbf{v} \times \mathbf{E}') \\
&= \left( q_e \cos \alpha + \frac{1}{c}q_m \sin \alpha \right) \left[ (\mathbf{E} \cos \alpha + c\mathbf{B} \sin \alpha) + \mathbf{v} \times \left( \mathbf{B} \cos \alpha - \frac{1}{c}\mathbf{E} \sin \alpha \right) \right] \\
&\quad + (q_m \cos \alpha - cq_e \sin \alpha) \left[ \left( \mathbf{B} \cos \alpha - \frac{1}{c}\mathbf{E} \sin \alpha \right) - \frac{1}{c^2}\mathbf{v} \times (\mathbf{E} \cos \alpha + c\mathbf{B} \sin \alpha) \right] \\
&= q_e \left[ (\mathbf{E} \cos^2 \alpha + c\mathbf{B} \sin \alpha \cos \alpha - c\mathbf{B} \sin \alpha \cos \alpha + \mathbf{E} \sin^2 \alpha) \right. \\
&\quad \left. + \mathbf{v} \times \left( \mathbf{B} \cos^2 \alpha - \frac{1}{c}\mathbf{E} \sin \alpha \cos \alpha + \frac{1}{c}\mathbf{E} \sin \alpha \cos \alpha + \mathbf{B} \sin^2 \alpha \right) \right] \\
&\quad + q_m \left[ \left( \frac{1}{c}\mathbf{E} \sin \alpha \cos \alpha + \mathbf{B} \sin^2 \alpha + \mathbf{B} \cos^2 \alpha - \frac{1}{c}\mathbf{E} \sin \alpha \cos \alpha \right) \right. \\
&\quad \left. + \mathbf{v} \times \left( \frac{1}{c}\mathbf{B} \sin \alpha \cos \alpha - \frac{1}{c^2}\mathbf{E} \sin^2 \alpha - \frac{1}{c^2}\mathbf{E} \cos^2 \alpha - \frac{1}{c}\mathbf{B} \sin \alpha \cos \alpha \right) \right] \\
&= q_e (\mathbf{E} + \mathbf{v} \times \mathbf{B}) + q_m \left( \mathbf{B} - \frac{1}{c^2}\mathbf{v} \times \mathbf{E} \right) = \mathbf{F}. \quad \text{qed}
\end{aligned}$$

LT can transform  $\mathbf{E} \longleftrightarrow \mathbf{B}$

**RECAP**



# Magnetostatics:

Lorentz force law

$$\mathbf{F} = Q[\mathbf{E} + (\mathbf{v} \times \mathbf{B})].$$

Magnetic forces do no work.

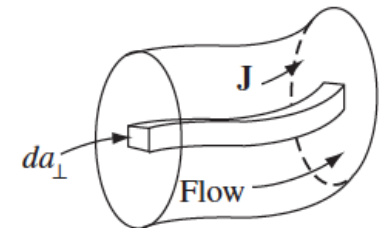
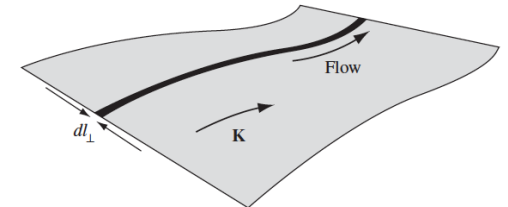
$$dW_{\text{mag}} = \mathbf{F}_{\text{mag}} \cdot d\mathbf{l} = Q(\mathbf{v} \times \mathbf{B}) \cdot \mathbf{v} dt = 0.$$

Current

$$\mathbf{I} = \lambda \mathbf{v}. \quad \mathbf{K} = \sigma \mathbf{v}. \quad \mathbf{J} = \rho \mathbf{v}.$$

Continuity Equation

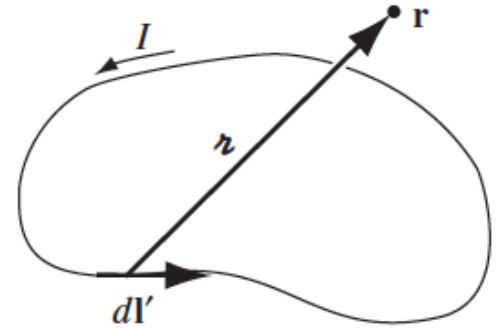
$$\nabla \cdot \mathbf{J} = -\frac{\partial \rho}{\partial t} = 0.$$



# Magnetostatics:

## Biot-Savart Law

$$\mathbf{B}(\mathbf{r}) = \frac{\mu_0}{4\pi} \int \frac{\mathbf{I} \times \hat{\mathbf{r}}}{r^2} dl' = \frac{\mu_0}{4\pi} I \int \frac{d\mathbf{l}' \times \hat{\mathbf{r}}}{r^2}.$$



## Ampere's Law

$$\oint \mathbf{B} \cdot d\mathbf{l} = \mu_0 I_{\text{enc}}, \quad \nabla \times \mathbf{B} = \mu_0 \mathbf{J}.$$

Ampere's Law is useful, only when symmetry enables pulling  $\mathbf{B}$  outside integral

## Magnetic vector potential :

$$\begin{cases} \nabla \cdot \mathbf{B} = 0, & \text{(no name);} \\ \nabla \times \mathbf{B} = \mu_0 \mathbf{J}, & \text{(Ampère's law).} \end{cases}$$

The Vector Potential ( $\mathbf{A}$ )

$$\mathbf{B} = \nabla \times \mathbf{A}.$$

Freedom in choosing  $\mathbf{A}$

As,  $\nabla \times (\nabla \lambda) = 0$ , we can transform  $\mathbf{A}_0$  to,  $\mathbf{A} = \mathbf{A}_0 + \nabla \lambda$

$$\nabla \times \mathbf{B} = \nabla \times (\nabla \times \mathbf{A}) = \nabla(\nabla \cdot \mathbf{A}) - \nabla^2 \mathbf{A} = \mu_0 \mathbf{J}.$$

Freedom in choosing  $\mathbf{A}$  to eliminate  $\text{Div. } \mathbf{A} = 0$

$$\nabla \cdot \mathbf{A} = \nabla \cdot \mathbf{A}_0 + \nabla^2 \lambda.$$

Choose,  $\lambda$  is such that,  $\nabla^2 \lambda = -\nabla \cdot \mathbf{A}_0$ .

# Magnetic vector potential :

$$\begin{cases} \nabla \cdot \mathbf{B} = 0, & \text{(no name);} \\ \nabla \times \mathbf{B} = \mu_0 \mathbf{J}, & \text{(Ampère's law).} \end{cases}$$

The Vector Potential (  $\mathbf{A}$  )

$$\mathbf{B} = \nabla \times \mathbf{A}.$$

$$\nabla \times \mathbf{B} = \nabla \times (\nabla \times \mathbf{A}) = \nabla(\nabla \cdot \mathbf{A}) - \nabla^2 \mathbf{A} = \mu_0 \mathbf{J}.$$

Freedom in choosing  $\mathbf{A}$  to eliminate  $\text{Div. } \mathbf{A} = 0$

3 Poisson's eqs.

$$\nabla^2 \mathbf{A} = -\mu_0 \mathbf{J}. \quad \text{and} \quad \mathbf{A}(\mathbf{r}) = \frac{\mu_0}{4\pi} \int \frac{\mathbf{J}(\mathbf{r}')}{r} d\tau'.$$

# Magnetic vector potential :

## Magnetostatic Boundary Conditions

$$\mathbf{B}_{\text{above}} - \mathbf{B}_{\text{below}} = \mu_0(\mathbf{K} \times \hat{\mathbf{n}}),$$

$$\frac{\partial \mathbf{A}_{\text{above}}}{\partial n} - \frac{\partial \mathbf{A}_{\text{below}}}{\partial n} = -\mu_0 \mathbf{K}.$$

$$(\nabla \times \vec{A})_{\text{above}} - (\nabla \times \vec{A})_{\text{below}} = \mu_0(\vec{K} \times \hat{n})$$

# Multipole expansion of vector potential

Magnetic Dipole : In absence of monopoles dipole is the dominant term

$$\begin{aligned} \mathbf{A}_{\text{dip}}(\mathbf{r}) &= \frac{\mu_0 I}{4\pi r^2} \oint r' \cos \alpha \, d\mathbf{l}' = \frac{\mu_0 I}{4\pi r^2} \oint (\hat{\mathbf{r}} \cdot \mathbf{r}') \, d\mathbf{l}'. & \oint (\vec{c} \cdot \vec{r}) d\vec{l} &= \vec{a} \times \vec{c} \\ &= \frac{\mu_0}{4\pi} \frac{\mathbf{m} \times \hat{\mathbf{r}}}{r^2}, & \vec{a} &= \frac{1}{2} \oint \vec{r} \times d\vec{l} \\ & & & \text{with } \mathbf{c} = \hat{\mathbf{r}} \\ & & & \oint (\hat{\mathbf{r}} \cdot \mathbf{r}') \, d\mathbf{l}' = -\hat{\mathbf{r}} \times \int d\mathbf{a}'. \end{aligned}$$

Here  $\mathbf{m}$  is the magnetic dipole moment

$$\mathbf{m} \equiv I \int d\mathbf{a} = I \mathbf{a}.$$

$$\begin{aligned} \hat{r} \times \oint (\vec{r}' \times d\vec{r}') &= \oint \vec{r}' (\hat{r} \cdot d\vec{r}') - \oint d\vec{r}' (\hat{r} \cdot \vec{r}') \\ &= \oint d[(\vec{r}' (\hat{r} \cdot \vec{r}'))] - \oint (\hat{r} \cdot \vec{r}') d\vec{r}' - \oint d\vec{r}' (\hat{r} \cdot \vec{r}') \\ &= -2 \oint (\hat{r} \cdot \vec{r}') d\vec{r}' \end{aligned}$$

Magnetic dipole moment is independent of choice of origin!

No Magnetic monopole

Remember,

Electric dipole moment was independent of origin only  
when the total charge vanished

# Torque and forces on magnetic dipole

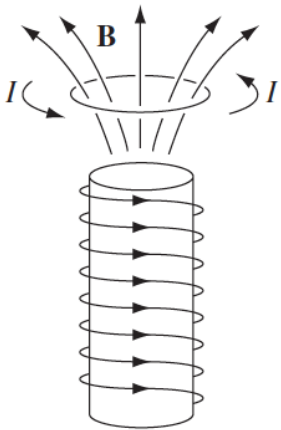
In the uniform field the net force on a current loop is zero!

$$\mathbf{F} = I \oint (d\mathbf{l} \times \mathbf{B}) = I \left( \oint d\mathbf{l} \right) \times \mathbf{B} = \mathbf{0};$$

$\mathbf{B}$  being constant comes outside integral and the net displacement around a closed loop also vanishes,

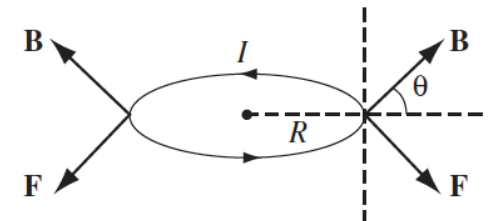
Not true for non uniform field,

Circular wire ( $R$ ) carrying current  $I$  is suspended over a short solenoid over the fringing region.



Here  $\mathbf{B}$  has a radial component, hence net downward force on loop.

$$F = 2\pi I R B \cos \theta.$$



$$\mathbf{F} = \nabla(\mathbf{m} \cdot \mathbf{B})$$

# Multipole expansion of vector potential

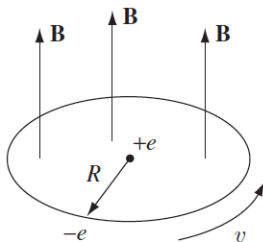
$$\nabla \cdot \mathbf{B} = 0.$$

No magnetic  
Monopole

$$\mathbf{A}_{\text{dip}}(\mathbf{r}) = \frac{\mu_0}{4\pi} \frac{\mathbf{m} \times \hat{\mathbf{r}}}{r^2}, \quad \mathbf{m} \equiv I \int d\mathbf{a} = I\mathbf{a}.$$

## Torque and forces on magnetic dipole

$$\overline{\mathbf{T}} = \overline{\mathbf{m}} \times \overline{\mathbf{B}}.$$



$$\Delta \mathbf{m} = -\frac{1}{2}e(\Delta v)R\hat{\mathbf{z}} = -\frac{e^2 R^2}{4m_e}\mathbf{B}.$$



## The Field of Magnetized Object

$$\mathbf{A}(\mathbf{r}) = \frac{\mu_0}{4\pi} \int_V \frac{\mathbf{J}_b(\mathbf{r}')}{r} d\tau' + \frac{\mu_0}{4\pi} \oint_S \frac{\mathbf{K}_b(\mathbf{r}')}{r} da'$$

$$\mathbf{J}_b = \nabla \times \mathbf{M},$$

$$\mathbf{K}_b = \mathbf{M} \times \hat{\mathbf{n}}$$

Potential of a  
volume current

Potential of a  
surface current

Potential of a magnetized object = Potential from a volume current  $\mathbf{J}_b$  + Potential from a surface current  $\mathbf{K}_b$  on boundary

## Ampere's law in Magnetized Materials

The total current in a medium is the summation of free and bound currents

$$\vec{J} = \vec{J}_b + \vec{J}_f$$

Ampere's law can therefore, be written as

$$\frac{1}{\mu_0}(\vec{\nabla} \times \vec{B}) = \vec{J} = \vec{J}_f + \vec{J}_b = \vec{J}_f + (\vec{\nabla} \times \vec{M})$$

$$\implies \vec{\nabla} \times \left( \frac{1}{\mu_0} \vec{B} - \vec{M} \right) = \vec{\nabla} \times \vec{H} = \vec{J}_f$$

where  $\vec{H} = \frac{1}{\mu_0} \vec{B} - \vec{M}$  plays a role in magnetostatics analogous to  $\vec{D} = \epsilon_0 \vec{E} + \vec{P}$  in electrostatics.

Ampere's law in integral form for magnetised materials can therefore be written as

$$\oint \vec{H} \cdot d\vec{l} = I_{f_{\text{enc}}}$$

$$\oint \vec{D} \cdot d\vec{a} = Q_{f_{\text{enc}}}$$

## Boundary Conditions

Using  $\vec{\nabla} \cdot (\vec{H} + \vec{M}) = 0 \implies \oint (\vec{H} + \vec{M}) \cdot d\vec{a} = 0$

we have,  $H_{\text{above}}^{\perp} - H_{\text{below}}^{\perp} = -(M_{\text{above}}^{\perp} - M_{\text{below}}^{\perp})$

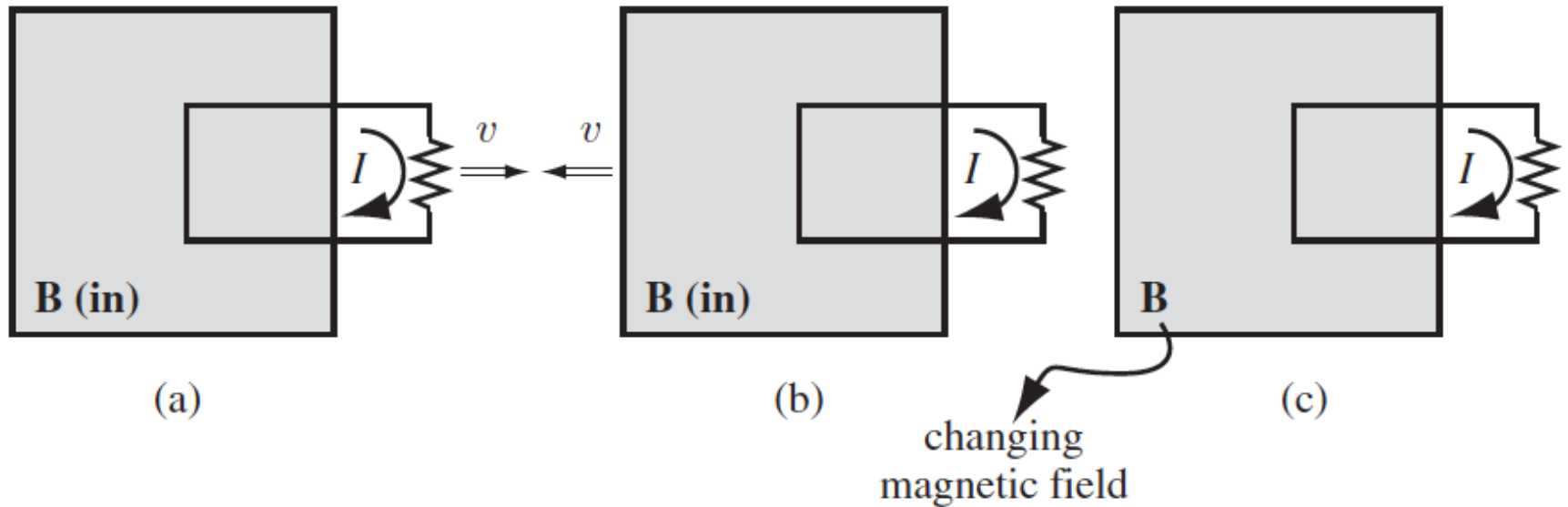
Using Ampere's law  $\oint \vec{H} \cdot d\vec{l} = I_{f_{\text{enc}}}$  we have

$$\vec{H}_{\text{above}}^{\parallel} - \vec{H}_{\text{below}}^{\parallel} = \vec{K}_f \times \hat{n}$$

Which, in the absence of materials, become

$$B_{\text{above}}^{\perp} - B_{\text{below}}^{\perp} = 0 \quad \vec{B}_{\text{above}}^{\parallel} - \vec{B}_{\text{below}}^{\parallel} = \mu_0(\vec{K}_f \times \hat{n})$$

# Faraday's Law



(a) Case of motional emf;

(b) 2<sup>nd</sup> Experiment has the same emf, relative motion of loop and the magnet.

(c) 3<sup>rd</sup> scenario also an electric field gets generated and gives the same emf

$$\mathcal{E} = -\frac{d\Phi}{dt}$$

Changing magnetic field generates an electric field

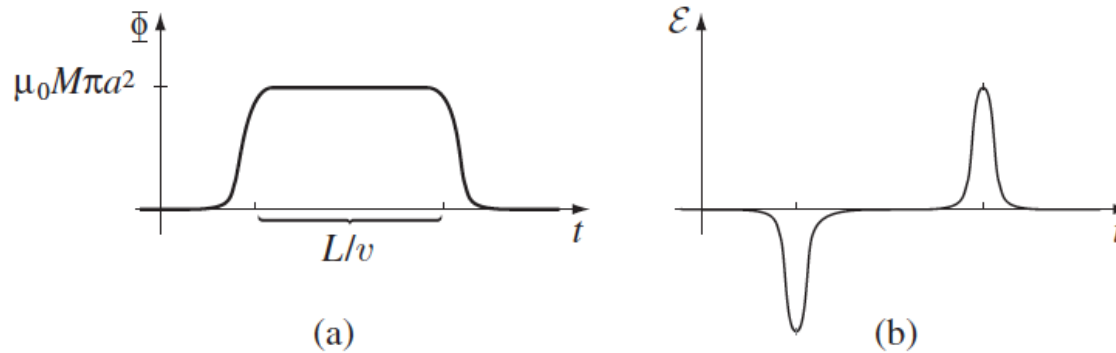
Note: In (a),  $\mathbf{v} \times \mathbf{B}$  drives the current  $\mathbf{I}$  not  $\mathbf{E}$

In (b) & (c), induced  $\mathbf{E}$  drives the current  $\mathbf{I}$

# Lenz's Law

The induced current flows in such a direction that the flux it produces tends to cancel the change. We can not quantify the current but can get the directions right.

**Nature abhors a change in flux.**



The magnet enters the ring, flux increases. The current is clockwise to generate field to the right.

Change in the flux is prevented, not flux

The magnet exits ring, flux drops, counterclockwise current to restore the field.

# Inductance

$\mathbf{B}_1$  is proportional to  $\mathbf{I}_1$   
 hence flux through loop2  
 is also proportional to  $\mathbf{I}_1$

$$\Phi_2 = \int \mathbf{B}_1 \cdot d\mathbf{a}_2.$$

$$\Phi_2 = M_{21} I_1,$$

here  $\mathbf{M}_{21}$  is the Mutual Inductance

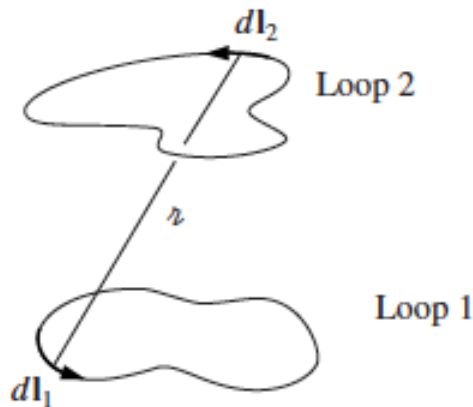
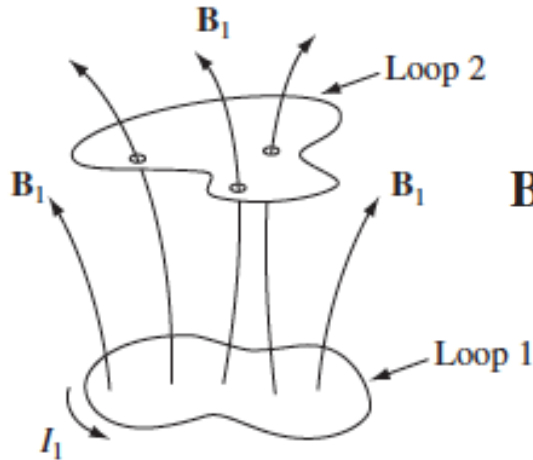
$$\Phi_2 = \int \mathbf{B}_1 \cdot d\mathbf{a}_2 = \int (\nabla \times \mathbf{A}_1) \cdot d\mathbf{a}_2 = \oint \mathbf{A}_1 \cdot d\mathbf{l}_2.$$

$$= \frac{\mu_0 I_1}{4\pi} \oint \left( \oint \frac{d\mathbf{l}_1}{r} \right) \cdot d\mathbf{l}_2.$$

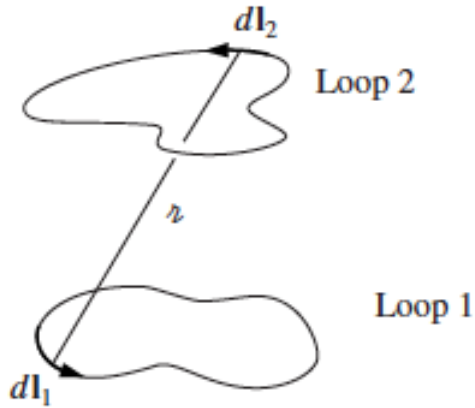
$$\mathbf{A}_1 = \frac{\mu_0 I_1}{4\pi} \oint \frac{d\mathbf{l}_1}{r},$$

$$M_{21} = \frac{\mu_0}{4\pi} \oint \oint \frac{d\mathbf{l}_1 \cdot d\mathbf{l}_2}{r}.$$

Neumann formula  
 for mutual inductance

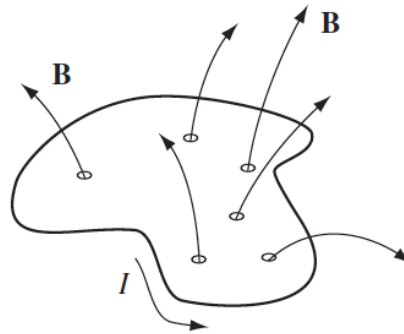


# Inductance



emf in loop2 due to change of current in loop1

$$\mathcal{E}_2 = -\frac{d\Phi_2}{dt} = -M\frac{dI_1}{dt}.$$



Changing current will induce an emf in the source loop as well

$$\Phi = LI.$$

self inductance  $L$  also depends on the geometry of the loop!

unit is henries (H), volt-second per ampere

$$\mathcal{E} = -L\frac{dI}{dt}.$$

Back emf, Lenz's Law

## Energy in Magnetic field

$$W = \frac{1}{2\mu_0} \int_{\text{all space}} B^2 d\tau.$$

In view of this result, we say the energy is "stored in the magnetic field," in the amount  $(B^2/2\mu_0)$  per unit volume.

In the light of this, it is extraordinary how similar the magnetic energy formulas are to their electrostatic counterparts:

$$W_{\text{elec}} = \frac{1}{2} \int (V\rho) d\tau = \frac{\epsilon_0}{2} \int E^2 d\tau,$$

$$W_{\text{mag}} = \frac{1}{2} \int (\mathbf{A} \cdot \mathbf{J}) d\tau = \frac{1}{2\mu_0} \int B^2 d\tau.$$



# Summary: Formulae

Lorentz force law:

$$\mathbf{F} = Q[\mathbf{E} + (\mathbf{v} \times \mathbf{B})].$$

Current:

$$\mathbf{I} = \lambda \mathbf{v}. \quad \mathbf{K} = \sigma \mathbf{v}. \quad \mathbf{J} = \rho \mathbf{v}.$$

Continuity Equation:

$$\nabla \cdot \mathbf{J} = -\frac{\partial \rho}{\partial t} = 0.$$

The Biot-Savart Law :

$$\mathbf{B}(\mathbf{r}) = \frac{\mu_0}{4\pi} \int \frac{\mathbf{I} \times \hat{\mathbf{r}}}{r^2} dl' = \frac{\mu_0}{4\pi} I \int \frac{d\mathbf{l}' \times \hat{\mathbf{r}}}{r^2}.$$

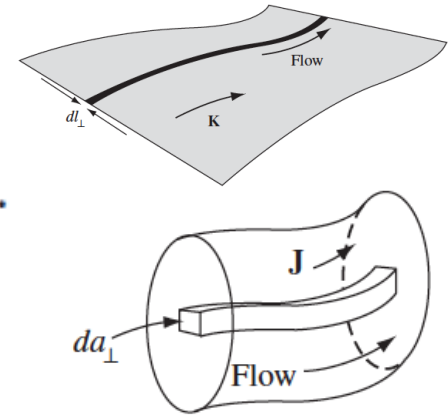
surface currents:  $\mathbf{B}(\mathbf{r}) = \frac{\mu_0}{4\pi} \int \frac{\mathbf{K}(\mathbf{r}') \times \hat{\mathbf{r}}}{r^2} da'$  ; volume currents:  $\mathbf{B}(\mathbf{r}) = \frac{\mu_0}{4\pi} \int \frac{\mathbf{J}(\mathbf{r}') \times \hat{\mathbf{r}}}{r^2} d\tau'$

Ampere's law in integral and in Differential form

$$\oint \mathbf{B} \cdot d\mathbf{l} = \mu_0 I_{\text{enc}}, \quad \nabla \times \mathbf{B} = \mu_0 \mathbf{J}.$$

Absence of Magnetic Monopole:

$$\nabla \cdot \mathbf{B} = 0$$



## Summary: Formulae

### Magnetic Vector Potential

$$\vec{B} = \vec{\nabla} \times \vec{A}$$

$$\vec{\nabla} \cdot \vec{A} = 0$$

$$\nabla^2 \vec{A} = -\mu_0 \vec{J}$$

$$\vec{A}(\vec{r}) = \frac{\mu_0}{4\pi} \int \frac{\vec{J}(\vec{r}')}{r} d\tau'$$

### Magnetostatic Boundary Condition

$$\vec{B}_{\text{above}} - \vec{B}_{\text{below}} = \mu_0 (\vec{K} \times \hat{n})$$

### Magnetic Dipole

$$\vec{m} = \frac{1}{2} \oint I(\vec{r} \times d\vec{l}) = \frac{1}{2} \int (\vec{r} \times \vec{J}) d\tau$$

$$\vec{A}_{\text{dipole}}(\vec{r}) = \frac{\mu_0}{4\pi} \frac{\vec{m} \times \hat{r}}{r^2},$$

$$\vec{B}_{\text{dipole}}(\vec{r}) = \frac{\mu_0}{4\pi} \frac{1}{r^3} [3(\vec{m} \cdot \hat{r})\hat{r} - \vec{m}]$$

### Force & Torque on Magnetic Dipole

$$\vec{F} = \vec{\nabla}(\vec{m} \cdot \vec{B})$$

$$\vec{N} = \vec{m} \times \vec{B}$$

## Summary: Formulae

$$\vec{A}(\vec{r}) = \frac{\mu_0}{4\pi} \int \frac{\vec{M}(\vec{r}') \times \hat{\mathbf{r}}}{r^2} d\tau'$$

$$\vec{A}(\vec{r}) = \frac{\mu_0}{4\pi} \int_V \frac{\vec{J}_b(\vec{r}')}{r} d\tau' + \frac{\mu_0}{4\pi} \oint_S \frac{\vec{K}_b(\vec{r}')}{r} da'$$

$$\vec{J}_b = \vec{\nabla} \times \vec{M} \quad \vec{K}_b = \vec{M} \times \hat{n}$$

$$\vec{\nabla} \times \left( \frac{1}{\mu_0} \vec{B} - \vec{M} \right) = \vec{\nabla} \times \vec{H} = \vec{J}_f$$

$$H_{\text{above}}^{\perp} - H_{\text{below}}^{\perp} = -(M_{\text{above}}^{\perp} - M_{\text{below}}^{\perp})$$

$$\vec{H}_{\text{above}}^{\parallel} - \vec{H}_{\text{below}}^{\parallel} = \vec{K}_f \times \hat{n}$$

$$\vec{B} = \mu_0(\vec{H} + \vec{M}) = \mu_0(1 + \chi_m)\vec{H}$$

$$\mu = \mu_0(1 + \chi_m) \quad \vec{J}_b = \vec{\nabla} \times \vec{M} = \vec{\nabla} \times (\chi_m \vec{H}) = \chi_m \vec{J}_f$$

# Summary: Formulae

The analog to Bio-savart's law

$$\mathbf{E} = -\frac{1}{4\pi} \int \frac{(\partial \mathbf{B} / \partial t) \times \hat{\mathbf{r}}}{r^2} d\tau = -\frac{1}{4\pi} \frac{\partial}{\partial t} \int \frac{\mathbf{B} \times \hat{\mathbf{r}}}{r^2} d\tau,$$

If symmetry permits,.

$$\oint \mathbf{E} \cdot d\mathbf{l} = -\frac{d\Phi}{dt}.$$

Neumann formula  
for mutual inductance

$$M_{21} = \frac{\mu_0}{4\pi} \oint \oint \frac{d\mathbf{l}_1 \cdot d\mathbf{l}_2}{r}.$$

Work against the *back emf* to get the current going. It is fixed and *recoverable*!

$$W = \frac{1}{2} L I^2. \quad \begin{array}{l} \text{(only geometry of the loop 'L' \\ \text{and} \\ \text{final current I) } \end{array}$$

Energy is "stored in the magnetic field,"  
in the amount  $(B^2/2\mu_0)$  per unit volume.

$$W_{\text{mag}} = \frac{1}{2} \int (\mathbf{A} \cdot \mathbf{J}) d\tau = \frac{1}{2\mu_0} \int B^2 d\tau.$$