

# PH 101: Physics I

Module 2: Special Theory of Relativity-Basics

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# Recap from the last class

- Galilean Relativity:

- 1) While space coordinates change when seen from different inertial frames, Time is absolute, and is the same in all inertial frames.
- 2) Galilean relativity fails to accommodate the idea of the constancy of speed of light (in all inertial frame of references).

- Modification required in Galilean relativity:

- 1) Speed of light is constant in all frame of references (as required by Maxwell EM waves).
- 2) Consequently Time is not absolute and should be treated as a variable same as its space counterpart.
- 3) New ideas are required in order to compare the things in different frame of references.

# Need of Special Theory of Relativity (STR)

- 1879: Born in Ulm, Germany.
- 1901: Worked at **Swiss patent office**.
  - Unable to obtain an academic position.
- 1905: Published 4 famous papers.
  - Paper on **photoelectric effect** (Nobel prize).
  - Paper on **Brownian motion**.
  - 2 papers on **Special Relativity**.
  - Only 26 years old at the time!!
- 1915: General Theory of Relativity published.
- 1933: Einstein left Nazi-occupied Germany.
  - Spent remainder of time at **Institute of Advanced Study in Princeton, NJ**.
  - Attempted to develop unified theory of gravity and electromagnetism (unsuccessful).



## Postulates of STR

With the belief that Maxwell's equations must be valid in all inertial frames, Einstein proposes the following postulates:

**The principle of relativity:** The laws of physics are the same in all inertial systems. There is no way to detect absolute motion, and no preferred inertial system exists.

**The constancy of the speed of light:** Observers in all inertial systems measure the same value for the speed of light in a vacuum ( $c = 3 \times 10^8$  m/s)

# Relativity of Light

Consider Two frames,  $S$  and  $S'$ .

$S'$  is moving with speed  $v$  along  $x$ -axis

Consider Two events:            Event 1: Light pulse emitted            Event 2: This light pulse detected.

In frame  $S$ , let the coordinates of these events are:  $(0, 0, 0, 0)$  and  $(t, x, y, z)$

The same events as recorded in  $S'$ :             $(0, 0, 0, 0)$              $(t', x', y', z')$

The two frames are synchronised at the first event.

The second event correspond to detecting the light pulse =>  $x^2 + y^2 + z^2 = c^2 t^2$

$$x'^2 + y'^2 + z'^2 = c'^2 t'^2 = c^2 t'^2$$

# Lorentz transformation

Homogeneity of time and space: The properties of empty space are same everywhere and for all time.

In general,  $x'$  will be a function of  $x$  and  $t$ , i.e.  $x' = f(x, t)$  so that we would have  $dx' = f_x dx + f_t dt$

Homogeneity of space and time implies that

$$x' = a_1 x + a_2 ct$$

The origin of  $S'$  is moving with speed  $v \Rightarrow x' = 0 \Rightarrow x = vt$

$$ct' = b_1 ct + b_2 x$$

$$\Rightarrow 0 = a_1 vt + a_2 ct; \quad a_2 = -\frac{v}{c} a_1$$

$$y' = y$$

$$z' = z$$

Observation:

$y$  and  $z$  coordinates (of each event) are the same in both the frames, but  $x$  coordinate would be different.

From the point of view of  $S'$ , the frame  $S$  is moving with speed  $v$  in the -ve  $x$  direction.

The relation between  $x$  and  $x'$  should be **invertible**, and should look similar. **Should be a linear relation**

# Lorentz transformation

$$x' = a_1(x - vt)$$

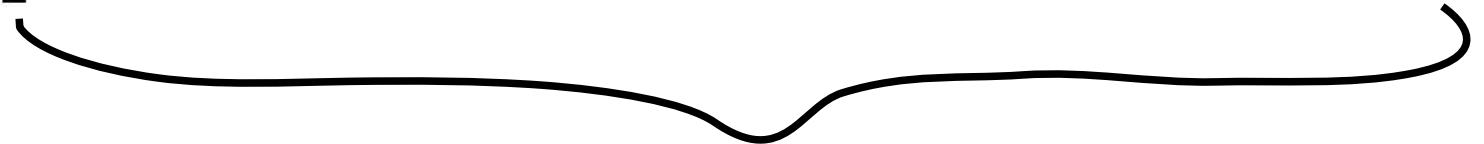
$$x^2 + y^2 + z^2 = c^2 t^2$$

$$t' = b_1 x + b_2 t$$

$$x'^2 + y'^2 + z'^2 = c'^2 t'^2 = c^2 t'^2$$

$$y' = y$$

$$z' = z$$


$$a_1^2(x - vt)^2 + y^2 + z^2 = c^2(b_1 x + b_2 t)^2$$

Rearranging the terms gives

$$(a_1^2 - c^2 b_1^2)x^2 + y^2 + z^2 - 2(va_1^2 + c^2 b_1 b_2)xt = (c^2 b_2^2 - v^2 a_1^2)t^2$$

Equating this with  $x^2 + y^2 + z^2 = c^2 t^2$  gives

$$c^2 b_2^2 - v^2 a_1^2 = c^2$$

$$a_1^2 - c^2 b_1^2 = 1$$

$$va_1^2 + c^2 b_1 b_2 = 0$$

$$\Rightarrow a_1 = b_2 = 1/\sqrt{1 - v^2/c^2} = \gamma \text{ and } b_1 = -\frac{v}{c^2}/\sqrt{1 - v^2/c^2} = -\gamma\beta/c \text{ with } \beta = v/c$$

# Lorentz transformation

Lorentz transformation: relating the coordinates and time in two different coordinates.

$$x' = \gamma(x - \beta x_0); \quad y' = y; \quad z' = z$$

We introduce  $x_0 = ct$

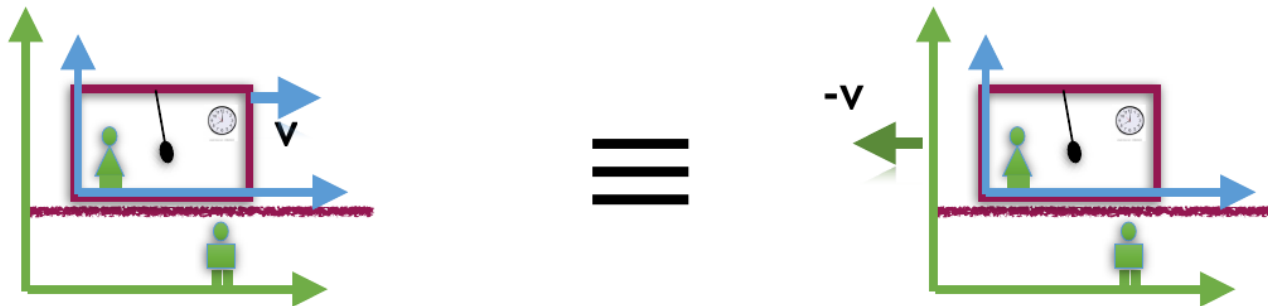
$$x'_0 = \gamma(x_0 - \beta x)$$

Inverting the relation:

$$x = \gamma(x' + \beta x'_0); \quad y' = y; \quad z' = z$$

$$x_0 = \gamma(x'_0 + \beta x')$$

**Exercise**



# Variation of relativistic factor $\gamma$ with speed

Recall  $\beta = v/c < 1$  for all observers.

$\gamma \geq 1$  : equals 1 only when  $v = 0$ .

$$\beta = \frac{v}{c}$$
$$\gamma = \frac{1}{\sqrt{1 - v^2/c^2}}$$

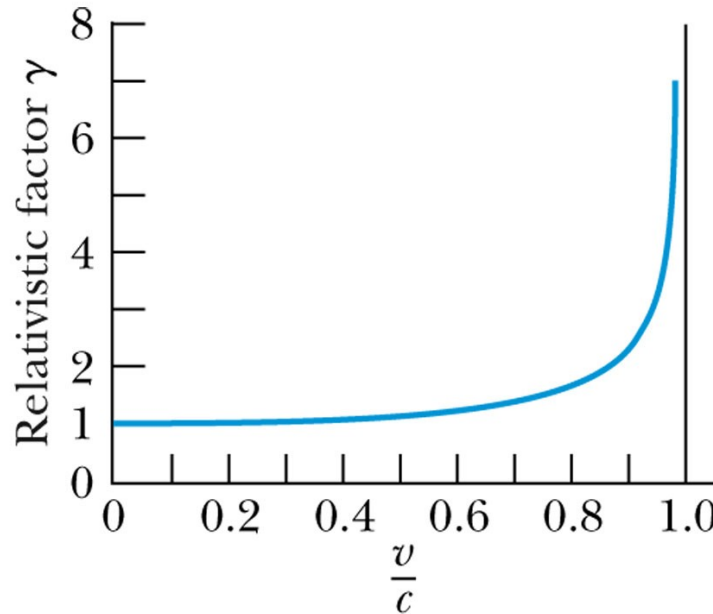
$$x' = \gamma(x - \beta ct)$$

$$y' = y$$

$$z' = z$$

$$t' = \gamma(t - \beta x/c)$$

Graph of  $\gamma$ :  
(note  $v \neq c$ )



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1) If  $v \ll c$ , i.e.,  $\beta \approx 0$  and  $\gamma \approx 1$ , we see these equations reduce to the familiar Galilean transformation.

2) Space and time are now not separated.



# Examples (Home work)

Consider frame S and another frame S'.

Their origins coincide at  $t = t' = 0$ . Their axes are parallel to each other. The origin of S' moves with a constant speed  $v = 10 \text{ km/s}$  along the x-axis.

An event occurs at  $x = 1 \text{ m}$ ,  $y = 2 \text{ m}$ ,  $z = 10 \text{ m}$  at  $t = 8 \text{ s}$  in S.

What are its coordinates in S'?

# Examples (Home work)

Consider frame S and another frame S'.

Their origins coincide at  $t = t' = 0$ . Their axes are parallel to each other. The origin of S' moves with a constant speed  $v = 0.2c$  along the x-axis.

An event occurs at  $x = 1\text{ m}$ ,  $y = 2\text{ m}$ ,  $z = 10\text{ m}$  at  $t = 8\text{ s}$  in S.

What are its coordinates in S'?

# Examples (Home work)

Consider frame  $S$  and another frame  $S'$ .

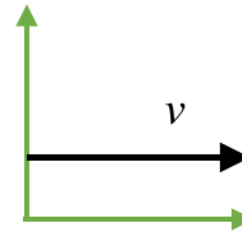
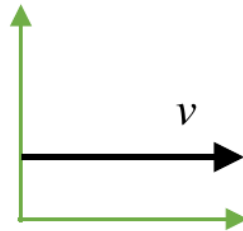
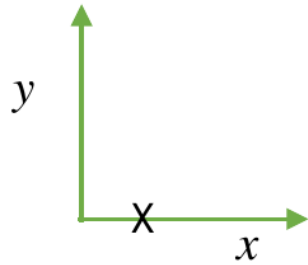
Their origins coincide at  $t = t' = 0$ . Their axes are parallel to each other. The origin of  $S'$  moves with a constant speed  $v = 0.7c$  along the  $x$ -axis.

An event occurs at  $x = 1\text{ m}$ ,  $y = 2\text{ m}$ ,  $z = 10\text{ m}$  at  $t = 8\text{ s}$  in  $S$ .

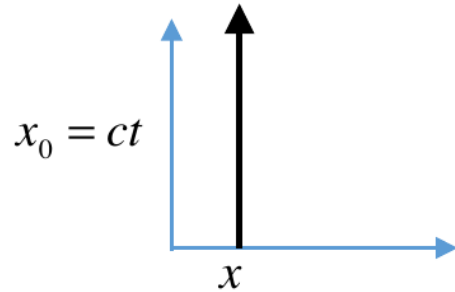
What are its coordinates in  $S'$ ?

# World Line

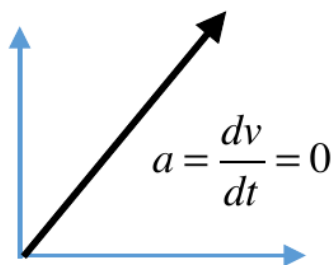
Meaning of trajectory in the usual sense is lost in STR, as the space and time are interlinked.  
The concept of **world line** is introduced instead.



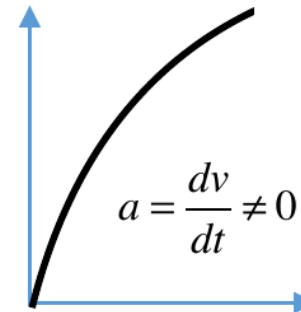
Path of particles  
in the usual sense.



Object at rest



Moving with const  
speed along x



Accelerating  
object

World lines in STR

# Characetrization of events

Consider the invariant interval (between two events, E1 and E2):  $ds^2 = c^2 dt^2 - dx^2 - dy^2 - dz^2$

Three possibilities:

$ds^2 = 0$  Events are called light-like events.

For example, E1 is the flashing of light at  $(0, 0, 0, 0)$   
and E2 is detecting it at  $(t, x, y, z)$

Distance covered by the light pulse in time  $t = ct$

This is equal to the spatial distance between the points.

$ds^2 > 0$

Events are called time-like events.

For example, E1 is firing a bullet at  $(0, 0, 0, 0)$   
and E2 is it hitting a target at  $(t, x, y, z)$

Distance covered by the bullet in time  $t = vt < ct$

The spatial distance between the points  $vt = \sqrt{x^2 + y^2 + z^2}$

$ds^2 < 0$

Events are called space-like

This cannot be the case with normal events.  
Possible for particles moving faster than  $c$

Such particles with  $v > c$  are called Tachyons

# Examples

Consider two time-like events

$$E1: (t_1, x_1, y_1, z_1)$$

$$E2: (t_2, x_2, y_2, z_2)$$

with

$$dt = t_2 - t_1, \quad dx = x_2 - x_1, \quad dy = y_2 - y_1, \quad dz = z_2 - z_1$$

Since the interval is the same  
when seen from different inertial frames,

$$\begin{aligned} ds^2 &= c^2 dt^2 - dx^2 - dy^2 - dz^2 \\ &= c^2 dt'^2 - dx'^2 - dy'^2 - dz'^2 = ds'^2 \end{aligned}$$

The events will remain time-like in all inertial frames.

Similarly, light-like and space-like events also would remain so when seen from any inertial frame.

Similarly, light-like and space-like events also would remain so when seen from any inertial frame.

Show explicitly that  $ds^2 = ds'^2$

# Illustration of World line

