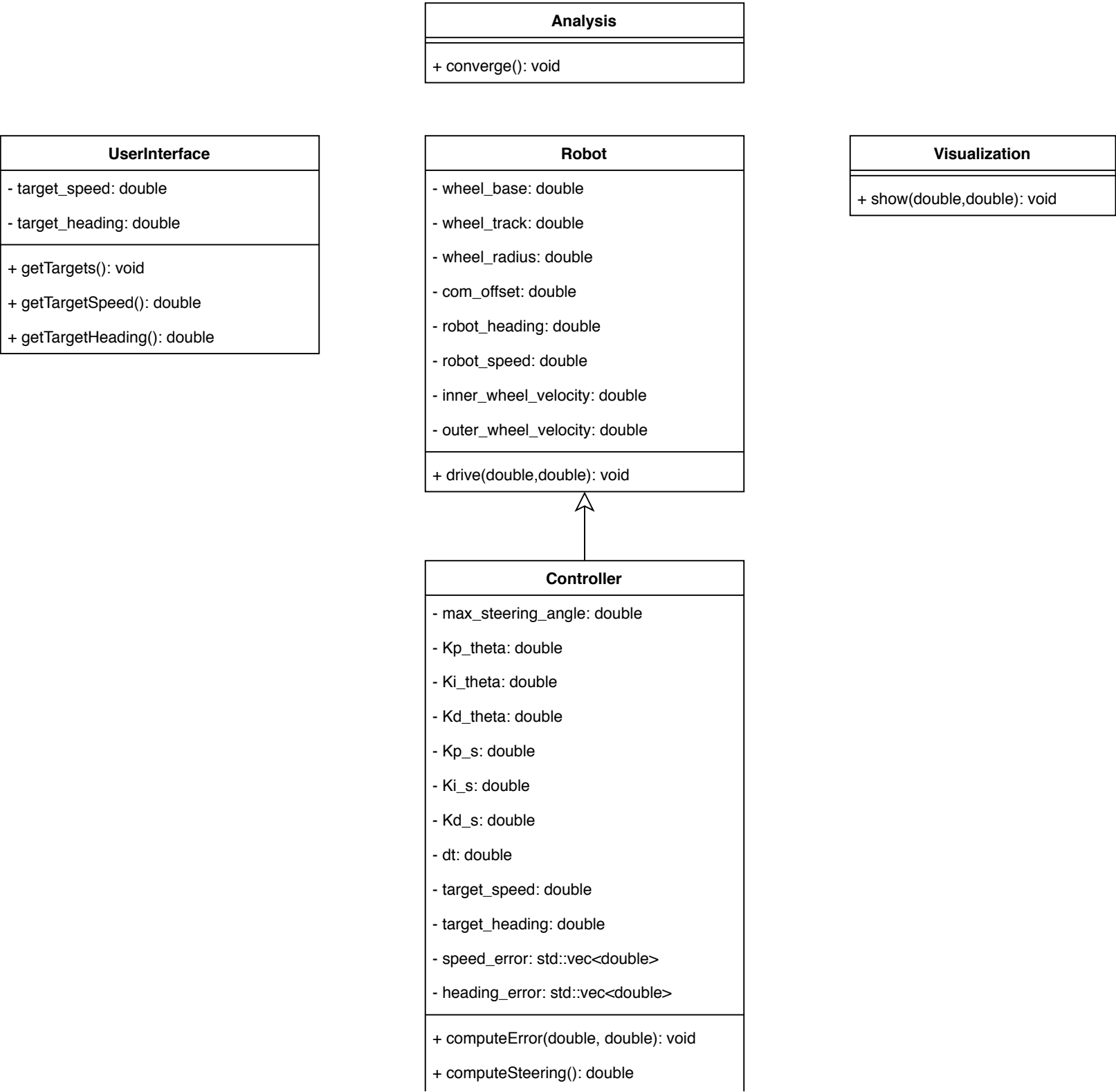


Ackermann Steering Controller

Pradeep Gopal  
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Justin Albrecht



+ computeThrottle(): double

+ setTargets(): void