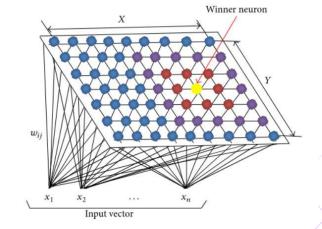
Self Organizing Map



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MACHINE LEARNING

A branch of artificial intelligence based on the idea that systems can learn from data, identify patterns and make decisions with minimal human intervention.

Types Of Machine Learning

- **Supervised Learning**: Training machines on a labelled dataset for output prediction
- **Unsupervised Learning:** Training machine on an unlabelled dataset and predicts output without any supervision.
- Reinforcement Learning: Works on feedback process.

Unsupervised Learning

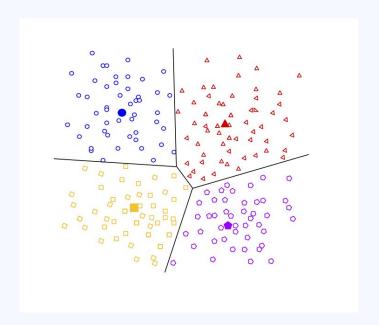
Main aim of grouping or categorizing the unsorted dataset according to the similarities, patterns, and differences.

- Clustering
- Association

CLUSTERING

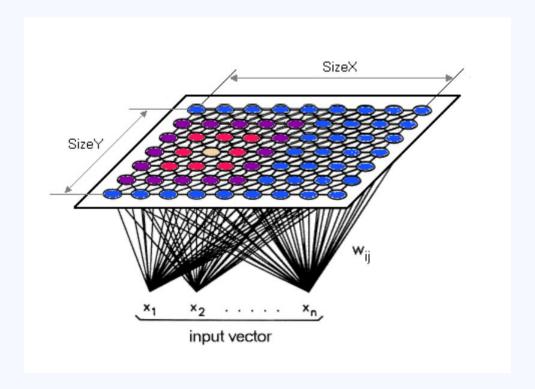
Clustering is the process of grouping a set of objects in such a way that objects in the same group (called a cluster) are more similar to each other than to those in other groups.

- Self Organized Maps
- K Means Clustering
- Singular Value Decomposition
- Principal Component Analysis



SELF ORGANIZING MAPS

Data visualization machine learning technique



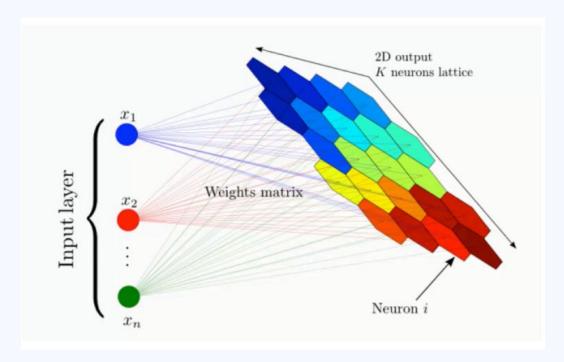
TYPES OF SELF ORGANIZING MAPS

Von-Der Malsburg model

Kohonen Model

Kohonen Model

is particularly useful for visualizing and understanding the structure of high-dimensional data by mapping it onto a lower-dimensional grid.



Application

Traveling Salesman Problem

is a problem of finding the shortest possible route that visits each city in a given list exactly once and returns to the original city.



1. Initialization

- 2. Normalization of Input Data
- 3. Iterative Training
- 4. Weight Update
- 5. Animation Update
- 6. Shortest Path Calculation
- 7. Stopping Criterion
- 8. Animation Termination
- 9. Visualization

Initialize the SOM with random weights for each neuron. These weights typically have the same dimensionality as the input data (in this case, 2D for x and y coordinates).

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Normalize the input data to a common range, typically [0, 1], to ensure uniformity. This step is important as it prevents any particular dimension from dominating the training process.

```
x_n = (x - np.amin(x)) / (np.amax(x) - np.amin(x))

y_n = (y - np.amin(y)) / (np.amax(y) - np.amin(y))
```

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The training process iterates over a fixed number of epochs. Each epoch represents a complete pass through the entire dataset.

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Update the weights of the BMU and its neighboring neurons. The update is done based on a learning rate and a neighborhood function. Neurons closer to the BMU have their weights adjusted more than those farther away.

$$w_{ji}(t+1) = w_{ji}(t) + \eta(t) \cdot h_{ji}(t) \cdot (x(t)-w_{ji}(t))$$

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Update the visualization of the SOM after each epoch to observe how the solution evolves over time.

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Calculate the distance of the current path formed by the neuron weights.

Keep track of the shortest path found during the training process.

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The training process continues for a fixed number of epochs. Alternatively, it can stop when certain conditions are met, such as convergence of the solution or reaching a predefined number of epochs.

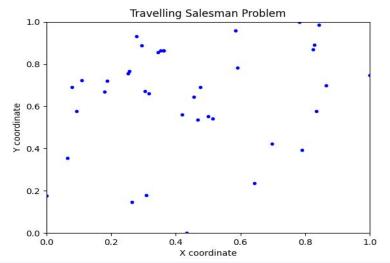
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Once the training process is complete, stop the animation and display the final solution.

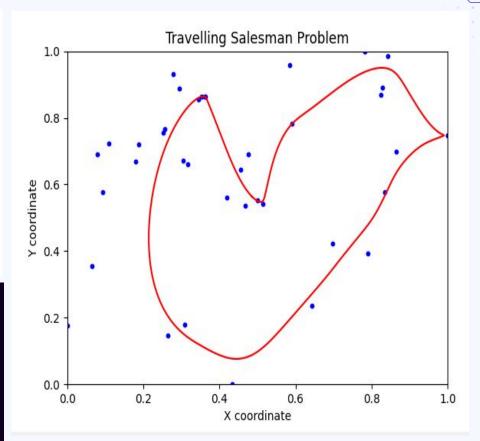
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Visualize the final solution, which represents the shortest path found through the dataset.

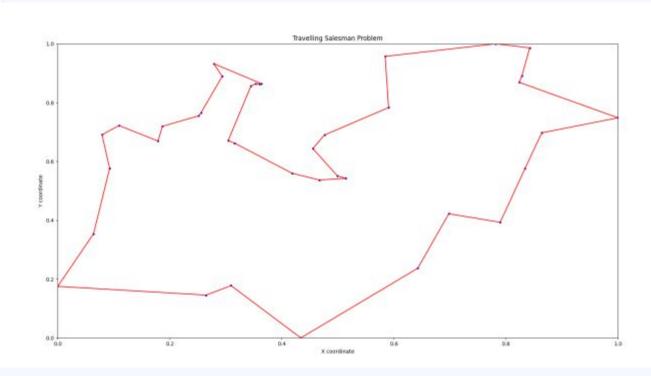
Results



```
Shortest Path: [[0.95817884 0.76096147]
[0.95831318 0.76101076]
[0.95844734 0.76105949]
...
[0.95777476 0.76081028]
[0.95790963 0.76086123]
[0.95804433 0.76091163]]
```



Results



Thank You