### LAB 1: Revision

Date: 19-12-2023

```
In [3]: import numpy as np
```

```
WAP to solve the following system of linear equations: 2x-y+3z=8 x+2y+z=7 3x+y-2x=9
```

WAP to find the roots of the given quadratic equation:  $x^2+x+1=0$ 

```
In [25]: P = np.array([1,1,1])
    print(np.roots(P))

[-0.5+0.8660254j -0.5-0.8660254j]
```

WAP to display 10 values between 0 and 10 including 10.

WAP to display 10 values between 0 and 10 excluding 10.

WAP to add and multiply two matrices.

WAP to find the invese of a matrix

```
In [22]: A = np.matrix(eval(input("Enter First Matrix:")))
    print("Invese = ")
    print(A.I)

Enter First Matrix:[[1,4],[5,9]]
    Invese =
    [[-0.81818182    0.36363636]
        [ 0.45454545    -0.09090909]]
```

# LAB 2: Algebraic and Transcedental Equations

Date: 02-01-2024

```
In [1]: import numpy as np
from scipy.misc import derivative
import scipy.optimize as opt
```

### **BISECTION METHOD**

```
In [2]: def bisect(f:'function',a = -1,b = 1):
                Bisect the interval with respect to given function
                Parameters
                 -----
                a : int
                    Lower Limit
                b : int
                    Upper Limit
                f: function
                    Function to be evaluated
                Returns
                 _____
                New interval after single bisection.
            if(f(a)>f(b)):
                a,b = b,a;
            if(f(a)*f(b)>0):
                raise Exception("INVALID INTERVAL",(a,b))
            mid = (a+b)/2
            a,b = [mid,b] if f(mid)<0 else [a,mid]
            return [a,b]
        def bisectionMethod(a,b,f:'function' = lambda x:0,error = 1e-10):
                Find roots using Bisection Method
                Parameters
                 ______
                a: int
                    Lower Limit
                b: int
                    Upper Limit
                error : float
                    Approximation required
                f: function
                    Function to be evaluated
                Returns
                Approximate root, number of iterations
            n = 0;
            while((abs(a-b) > error) and (n<100)):</pre>
                a,b = bisect(f,a,b)
                n += 1;
            return [(a+b)/2,n]
```

WAP to find the roots of the following equations

```
• f(x) = x^3 - x - 1
• f(x) = x^2 - 3x - 1
• f(x) = x^2 - 3e^x
```

### **REGULA FALSI METHOD or METHOD OF FALSE POSITION**

```
In [7]:

def regula(f:'function',a = -1,b = 1):
    if(a>b):
        a,b = b,a;
    if(f(a)*f(b) > 0):
        raise Exception("INVALID INTERVAL",(a,b))
    return [b,b - ((b-a)*f(b)/(f(b)-f(a)))]

def regulaFalsiMethod(a,b,f:'function' = lambda x:0,error = 1e-10):
    n = 0;
    while((abs(f(b)) > error) and (n<100)):
        a,b = regula(f,a,b)
        n += 1;
    return [b,n]</pre>
```

```
In [8]: f = lambda x: x**3 - 2*x - 5
regulaFalsiMethod(-1,5,f)
```

Out[8]: [2.094551481535422, 85]

WAP to find the roots of the following equations

```
egin{aligned} ullet f(x) &= x^4 - 3 \ ullet f(x) &= 2\cos x - x \ ullet f(x) &= xe^x - 1 \end{aligned}
```

#### **FIXED POINT METHOD**

```
In [13]: def fixedPointMethod(a,f:'function' = lambda x:0, g:'function' = lambda x:
0, error = 1e-10,thresh = 500):
    n = 0;
    while((abs(f(a)) > error) and (n<thresh)):
        a = g(a)
        n += 1;
    return [a,False if n == thresh else True,n]</pre>
```

```
In [14]: f = lambda x: x^{**3} + x^{**2} - 2

g = lambda x: (2-x^{**2})^{**}(1/3)

fixedPointMethod(2,f,g)
```

Out[14]: [(1.000000000012568-1.254483651600653e-11j), True, 62]

```
In [15]: opt.root(f,2)
Out[15]:
              fjac: array([[-1.]])
               fun: array([0.])
          message: 'The solution converged.'
              nfev: 10
               qtf: array([-2.91384694e-10])
                 r: array([-5.00000208])
            status: 1
           success: True
                 x: array([1.])
   WAP to find the roots of the following equations
     • f(x) = x^3 - 2x - 5
     • f(x) = 2x - 3 - \cos x
     • f(x) = \sin x - 10(x-1)
In [16]: f = lambda x: x^{**}3 - 2^*x - 5
          g = lambda x: (5+2*x)**(1/3)
          fixedPointMethod(2,f,g),opt.root(f,2).x
Out[16]: ([2.0945514815401305, True, 13], array([2.09455148]))
In [17]: f = lambda x: 2*x - 3 - np.cos(x)
```

```
Out[17]: ([1.5235929331230837, True, 34], array([1.52359293]))
```

fixedPointMethod(2,f,g),opt.root(f,2).x

g = lambda x: (np.cos(x) + 3)/2

```
In [18]:  f = lambda x: np.sin(x) - 10*(x-1) 
 g = lambda x: np.sin(x)/10 + 1 
 fixedPointMethod(2,f,g),opt.root(f,2).x
```

```
Out[18]: ([1.0885977523989665, True, 8], array([1.08859775]))
```

#### **NEWTON RAPHSON METHOD**

```
In [19]: def getRaphson(a,f,error):
    if(derivative(f,a,dx=error) == 0):
        raise Exception("DERIVATIVE IS ZERO",(a))
    return a-(f(a)/derivative(f,a,error))

def newtonRaphsonMethod(a,f:'function' = lambda x:0, error = 1e-10,thresh = 500):
    n = 0;
    while((abs(f(a)) > error) and (n<thresh)):
        a = getRaphson(a,f,error)
        n += 1
    return [a,False if n == thresh else True,n]</pre>
```

```
WAP to find the roots of the following equations
```

•  $f(x) = x^3 - 5x^2$ •  $f(x) = x^3 - 3x - 1$ 

```
• f(x) = x^3 + 2x^2 + x - 1

• f(x) = 3\cos(x) + x

In [29]: f = lambda x: x**3 - 5*x**2

newtonRaphsonMethod(6,f),opt.root(f,6).x
```

```
Out[29]: ([5.00000000000000115, True, 5], array([5.]))
In [30]: f = lambda x: x**3 - 3*x - 1
    newtonRaphsonMethod(2,f),opt.root(f,2).x

Out[30]: ([1.8793852415718182, True, 4], array([1.87938524]))
In [32]: f = lambda x: x**3 + 2*x**2 + x - 1
    newtonRaphsonMethod(0,f),opt.root(f,0).x

Out[32]: ([0.4655712318767954, True, 6], array([0.46557123]))
In [35]: f = lambda x: 3*pn cos(x) + x
```

```
In [35]: f = lambda x: 3*np.cos(x) + x
newtonRaphsonMethod(1,f),opt.root(f,1).x
```

Out[35]: ([2.663178883323163, True, 5], array([2.66317888]))

## LAB 3: System of Equation

Date: 13-01-2024

```
In [1]: import numpy as np
```

WAP to find the inverse of the following matrix and solve the system of equations.

```
In [2]: A = np.matrix([[4,-2,1],[-2,4,-2],[1,-2,4]])
Out[2]: matrix([[ 4, -2, 1],
                 [-2, 4, -2],
[ 1, -2, 4]])
In [3]: B = np.matrix([11, -16, 17]).T
Out[3]: matrix([[ 11],
                 [-16],
                 [ 17]])
In [4]: #Inverse
        A.I
Out[4]: matrix([[0.33333333, 0.16666667, 0.
                 [0.16666667, 0.41666667, 0.16666667],
                         , 0.16666667, 0.33333333]])
In [5]: #Solution
        np.linalg.solve(A,B)
Out[5]: matrix([[ 1.],
                 [-2.],
                 [ 3.]])
In [6]: |#Solution
        A.I @ B
Out[6]: matrix([[ 1.],
                 [-2.],
                 [ 3.]])
```

WAP to print the  $2^{nd}$  row of the given matrix.

```
In [7]: A[1]
Out[7]: matrix([[-2, 4, -2]])
```

```
WAP to print col[4 - 2]
```

```
In [19]:
    A[0,0:2].T
```

```
CRAMERS RULE
     X = rac{A \ with \ X \ replaced \ with \ B}{}
```

|A|

```
In [23]: def cramersRule(A,B):
             X = np.ones(len(A))
             for i in range(len(A)):
                 X[i] = A.T[0:i];
```