## Sec 2.3 LU Factorization

Good: 1. Motivation: why LU factorization?

- 2. LU factorization and Gaussian Elimination (GE) without pivoting
- 3. PA = LU fectorization and GE with pivoting

Motivation: 1.

If 
$$A = LU$$
 upper trangular then  $A\vec{\lambda} = \vec{b} \iff LU\vec{\lambda} = \vec{b}$  [lower trangular]

step 1: Solve  $L\vec{y} = \vec{b}$  for  $\vec{y}$ , forward substitution,  $O(n^2)$  operations step z: Solve  $U\vec{\lambda} = \vec{y}$  for  $\vec{\lambda}$ , backward substitution,  $O(n^2)$  operations Determine the factorisation A = LU requires  $O(\frac{2}{3}n^3)$  operations (only once)

But it can be used to solve  $A\vec{x} = \vec{b}$  for different  $\vec{b}$ 

2. A=LU factorization and Gaussian Elimination without pivoting:

$$A = A_{1} \longrightarrow A_{2} :$$

$$(E_{i} - m_{i,1} E_{1}) \longrightarrow (E_{i}) \quad \text{where} \quad m_{i,1} = \frac{\alpha_{i} i^{(i)}}{\alpha_{i}^{(i)}}, \quad i = 2, \dots, n$$

$$A_{2} = M_{1} \cdot A_{1} \quad \text{where} \quad M_{1} = \begin{pmatrix} 1 & 0 & \cdots & 0 \\ -m_{21} & 1 & \cdots & \cdots \\ \vdots & 0 & \cdots & 0 \\ -m_{n_{1}} & 0 & \cdots & 0 \end{pmatrix}$$

$$A\vec{x} = \vec{b} \iff M_1 \cdot A\vec{x} = M_1 \cdot \vec{b}$$

$$A_2 \vec{x} = \vec{b}_2$$

Similarly, 
$$m_{i,2} = \frac{\alpha_{iz}^{(2)}}{\alpha_{2z}^{(2)}}$$
,  $i = 3, \dots, n$ ,  $M_2 = \begin{pmatrix} 1 & 1 & 1 \\ -m_{3z} & 1 & 1 \\ -m_{nz} & 1 \end{pmatrix}$   
 $M_2 A_2 \vec{\lambda} = M_2 \vec{b}_2$ , where  $A_3 = M_2 \cdot A_2 = M_2 \cdot M_1 \cdot A_2$   
 $\vec{b}_3 = M_2 \cdot \vec{b}_2 = M_2 \cdot M_1 \cdot \vec{b}$ 

$$M_2 A_2 \vec{\lambda} = M_2 \vec{b}_2$$
, where  $A_3 = M_2 \cdot A_2 = M_2 \cdot M_1 \cdot A_2$ 

$$\vec{b}_3 = M_2 \cdot \vec{b}_2 = M_2 \cdot M_1 \cdot \vec{b}_2$$

Alt if 
$$\vec{x} = \vec{b}_{k+1}$$
, where  $\vec{A}_{k+1} = M_k \cdots M_1$  is

At the end,  $\vec{A}_n \cdot \vec{x} = \vec{b}_n$ ,  $\vec{a}_n \cdot \vec{a}_n \cdot$ 

· If in addition det (A) \$0. then the LU factorisation is unique.

$$\begin{pmatrix}
2 & 4 & 4 \\
1 & 5 & 6
\end{pmatrix}
\xrightarrow{(E_2 - \frac{1}{2}E_1) \to (E_2)}
\begin{pmatrix}
2 & 4 & 4 \\
0 & 3 & 4
\end{pmatrix}
\xrightarrow{(E_3 - \frac{1}{3}E_2) \to E_3}
\begin{pmatrix}
2 & 4 & 4 \\
0 & 3 & 4
\end{pmatrix}$$

$$\begin{pmatrix}
0 & 3 & 4 \\
0 & 1 & -1
\end{pmatrix}$$

$$S_{0} \quad A = L \cup = \begin{pmatrix} 1 & 0 & 0 \\ \frac{1}{2} & 1 & 0 \\ \frac{1}{2} & \frac{1}{3} & 1 \end{pmatrix} \begin{pmatrix} 2 & 4 & 4 \\ 0 & 3 & 4 \\ 0 & 0 & -\frac{1}{3} \end{pmatrix}$$

Algorithm: (LU Factorization)

Inputs: A= (aij) & Rnxn

Outputs:  $L = (L_{ij})$ ,  $(L = (u_{ij}))$ 

step 1: Set U=A, L=I

step 2: For k=1, ---, n-1

for 
$$j = h+1, ..., n$$

$$\begin{cases}
set & l_{jk} = a_{jk}/a_{kk} \\
a_{j,k:m} = a_{j,k:m} - l_{jk} \cdot a_{k,k:m}
\end{cases}$$

U = triu(A) % taking the upper triangular part of A

2. PA = LU factorization and Gaussian Elimination with partial pivoting

Def: Permutation matrix is a matrix obtained by rearranging—the rows of In

eg. 
$$P = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} = \begin{pmatrix} e_1 \\ e_3 \\ e_2 \end{pmatrix}$$
 is a permutation matrix.

Suppose  $A = (a_{ij})$   $PA = \begin{pmatrix} A(1,:) \\ A(3,:) \\ A(2,:) \end{pmatrix}$   $AP = \begin{pmatrix} A(:,i) \\ A(:,3) \end{pmatrix}$   $A(:,2)$ 

Remark: 
$$PP^T = P^TP = I$$
, i.e.,  $P^T = P^{-1}$ 

$$\Rightarrow \underbrace{\widetilde{M_{n-1}} \cdots \widetilde{M_{z}} \, \widetilde{M_{i}}}_{P_{i-1}} \cdot \underbrace{P_{n-1} \cdots P_{z} \cdot P_{1} \cdot A}_{P} = U$$
, where  $\widetilde{M_{k}}$  has the same structure as  $M_{k}$ 

To solve 
$$A\vec{x} = \vec{b}$$
:  $PA\vec{x} = P\vec{b}$   $\Rightarrow$   $LU\vec{x} = \vec{b}$   $\Leftrightarrow$  solve  $L\vec{y} = \vec{b}$  for  $\vec{y}$  solve  $U\vec{x} = \vec{y}$  for  $\vec{x}$ 

Remark: PA = LU = P'LU = (PTL)·U, PTL is not lower triangular runless P=In

eg. Determine a factorisatrin of the form 
$$A = (P^TL)U$$
 for  $A = \begin{pmatrix} 0 & 0 & 1 & 1 \\ 1 & 1 & -1 & 2 \\ -1 & -1 & 2 & 0 \\ 1 & 2 & 0 & 2 \end{pmatrix}$ 

$$A \xrightarrow{(E_{1}) \longleftrightarrow (E_{2})} \begin{pmatrix} 1 & 1 & -1 & 2 \\ 0 & 0 & -1 & 1 \\ -1 & -1 & 2 & 0 \\ 1 & 2 & 0 & 2 \end{pmatrix} \xrightarrow{(E_{3} - (-1)E_{1}) \to (E_{4})} \begin{pmatrix} 1 & 1 & -1 & 2 \\ 0 & 0 & -1 & 1 \\ 0 & 0 & 1 & 2 \\ 0 & 1 & 1 & 0 \end{pmatrix}$$

So 
$$E_1 \longleftrightarrow E_2$$
,  $E_2 \longleftrightarrow E_4$   $\Rightarrow$   $P = \begin{pmatrix} e_2 \\ e_4 \\ e_3 \\ e_1 \end{pmatrix} = \begin{pmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix}$ 

$$PA = \begin{pmatrix} 1 & 1 & -1 & 2 \\ 1 & 2 & 0 & 2 \\ -1 & -1 & 2 & 0 \\ 0 & 0 & -1 & 1 \end{pmatrix} \xrightarrow{(E_2 - E_1) \to (E_2)} \begin{pmatrix} 1 & 1 & -1 & 2 \\ 0 & 1 & 1 & 0 \\ -1 & 0 & 0 & -1 & 1 \end{pmatrix} \xrightarrow{(E_4 - (-1)E_3) \to E_3} \begin{pmatrix} 1 & 1 & -1 & 2 \\ 0 & 1 & 1 & 0 \\ -1 & 0 & 0 & -1 & 1 \end{pmatrix}$$