Exercise 9, pp. 123-124: multiple linear regression using automobile data.

Importing libraries

```
In [ ]: import matplotlib.pyplot as plt
import numpy as np
import pandas as pd
import seaborn as sns
from statsmodels.api import OLS, add_constant
from statsmodels.graphics.gofplots import ProbPlot
from sklearn.preprocessing import PolynomialFeatures
from statsmodels.regression import linear_model
In [ ]: auto = pd.read_csv(
    "https://static1.squarespace.com/static/5ff2adbe3fe4fe33db902812/t/5fffeauto.head()
Out[ ]: mpg cylinders displacement horsepower weight acceleration year origin name
```

:		mpg	cylinders	displacement	horsepower	weight	acceleration	year	origin	name
	0	18.0	8	307.0	130	3504	12.0	70	1	chevrolet chevelle malibu
	1	15.0	8	350.0	165	3693	11.5	70	1	buick skylark 320
	2	18.0	8	318.0	150	3436	11.0	70	1	plymouth satellite
	3	16.0	8	304.0	150	3433	12.0	70	1	amc rebel sst
	4	17.0	8	302.0	140	3449	10.5	70	1	ford torino

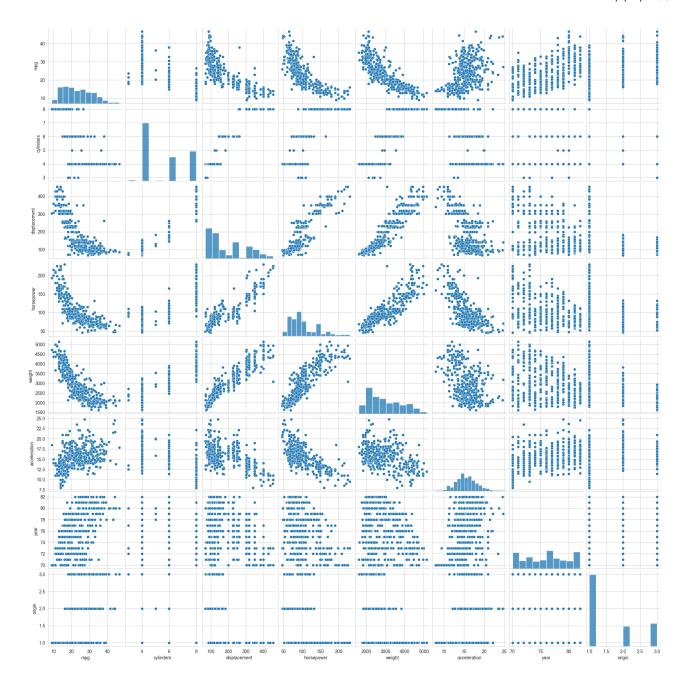
Removing '?' from the dataset and converting data-type 'object' to 'int64'

```
In [ ]: #As we are having '?' in column we need to drop this
        auto=auto.drop(auto.loc[auto['horsepower']=='?'].index,axis=0).reset_index(c
        auto['horsepower']=auto['horsepower'].astype(int)
        auto_2 = auto.copy()
        auto_3 = auto.copy()
        auto.dtypes
Out[]: mpg
                         float64
        cylinders
                           int64
        displacement
                         float64
        horsepower
                           int64
        weight
                           int64
        acceleration
                         float64
        year
                           int64
                           int64
        origin
                          object
        name
```

(a) Produce a scatterplot matrix which includes all of the variables in the data set.

```
In []: plt.close()
    sns.set_style("whitegrid")
    sns.pairplot(auto)
    plt.show()
```

dtype: object



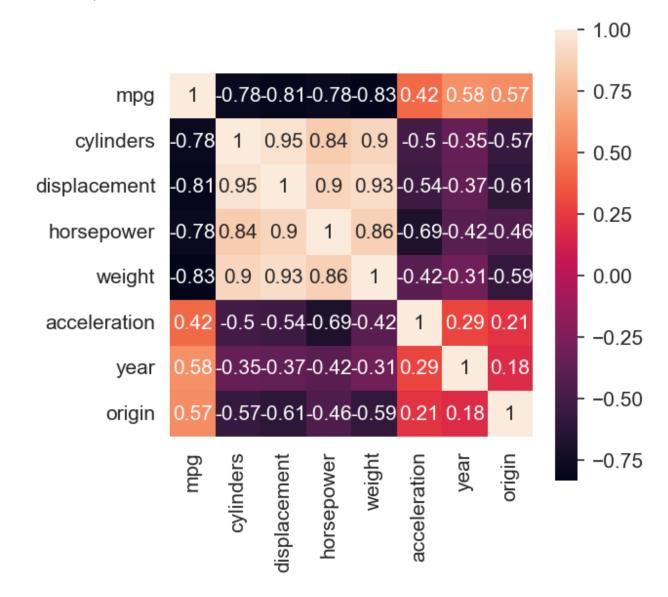
(b) Compute the matrix of correlations between the variables using the function cor(). You will need to exclude the name variable, which is qualitative.

```
In []: plt.rcParams['figure.dpi'] = 150

corr_mat = auto.corr()
fig = plt.gcf()
fig.set_size_inches(4, 4)
sns.heatmap(data=corr_mat, square=True, annot=True, cbar=True)
```

/var/folders/qd/78cm3bf52xs_khrj7wkd_myc0000gn/T/ipykernel_33252/3367786091
.py:3: FutureWarning: The default value of numeric_only in DataFrame.corr i s deprecated. In a future version, it will default to False. Select only va lid columns or specify the value of numeric_only to silence this warning. corr_mat = auto.corr()

Out[]: <AxesSubplot: >



(c) Use the Im() function to perform a multiple linear regression with mpg as the response and all other variables except name as the predictors. Use the summary() function to print the results. Comment on the output. For instance:

```
In [ ]: def run_model(x, y, model_fit=OLS):
          accepts x and y and returns fitted model
          return model_fit(y, add_constant(x)).fit()
In [ ]: X = auto[['cylinders', 'displacement', 'horsepower',
               'weight', 'acceleration', 'year', 'origin']]
       y = auto['mpg']
       model_fit = run_model(x=X, y=y)
       print(model_fit.summary())
                               OLS Regression Results
       ===
       Dep. Variable:
                                         R-squared:
                                                                     0.
                                    mpg
       821
                                    0LS
       Model:
                                        Adj. R-squared:
                                                                     0.
       818
                                                                     25
       Method:
                          Least Squares F-statistic:
       2.4
                        Sun, 02 Oct 2022 Prob (F-statistic): 2.04e-
       Date:
       139
       Time:
                               23:06:55 Log-Likelihood:
                                                                   -102
       3.5
       No. Observations:
                                    392
                                       AIC:
                                                                     20
       63.
       Df Residuals:
                                    384
                                         BIC:
                                                                     20
       95.
       Df Model:
       Covariance Type:
                              nonrobust
       ______
                       coef std err t
                                                  P>|t| [0.025
       .975]
                                        -3.707
                 -17.2184 4.644
                                                  0.000
                                                           -26.350
       const
       8.087
                               0.323
       cylinders
                   -0.4934
                                        -1.526
                                                  0.128
                                                           -1.129
       0.142
       displacement 0.0199
                               0.008
                                        2.647
                                                  0.008
                                                           0.005
       0.035
       horsepower
                   -0.0170
                               0.014
                                        -1.230
                                                  0.220
                                                            -0.044
       0.010
       weiaht
                  -0.0065
                               0.001
                                        -9,929
                                                  0.000
                                                            -0.008
       0.005
       acceleration 0.0806
                               0.099
                                     0.815
                                                  0.415
                                                            -0.114
```

0.275						
year 0.851	0.7508	0.051	14.729	0.000	0.651	
origin 1.973	1.4261	0.278	5.127	0.000	0.879	
===						
Omnibus:		31.906	Durbin-Wat	son:		1.
Prob(Omnibus): 100		0.000	Jarque-Ber	a (JB):		53.
Skew: -12		0.529	Prob(JB):			2.95e
Kurtosis: +04		4.460	Cond. No.			8.59e
==========	========	=======	========	========	======	
===						

Notes:

- [1] Standard Errors assume that the covariance matrix of the errors is correctly specified.
- [2] The condition number is large, 8.59e+04. This might indicate that there are

strong multicollinearity or other numerical problems.

i. Is there a relationship between the predictors and the response?

- Yes, the relationship between the predictor variables and the response variable was statistically significant, because the F-statistic: 252.4 which is larger than 1 and pvalue: < 2.2e-16 which is much lower, confirmed that the null hypothesis was false, and that there was a statistically significant relationship between mpg and other variables.
- 2. Also we can see from the table above,
 - A. For every unit increase in cylinders, mileage decreased by ~ 0.5 .
 - B. For every unit increase in displacement, mileage increase by ~0.02.
 - C. For every unit increase in horsepower, mileage decreased by ~ 0.02 .
 - D. For every unit increase in weight, mileage decreased by ~0.065.
 - E. For every unit increase in acceleration, mileage increase by ~0.08.
 - F. For every unit increase in year, mileage increase by ~ 0.75 .
 - G. For every unit increase in origin, mileage increase by \sim 1.43.
 - So, we can see that the 'mpg' is very much depended on other variables.

ii. Which predictors appear to have a statistically significant relationship to the response?

Based the above table, these variables have significant effect on 'mpg':

- 1. weight
- 2. year
- 3. origin
- 4. displacement

iii. What does the coefficient for the year variable suggest?

According to the above table, regression co-efficient of year is \sim 0.75. So according to this, every year mileage increases by \sim 0.75. So automobiles are becoming more efficient every year.

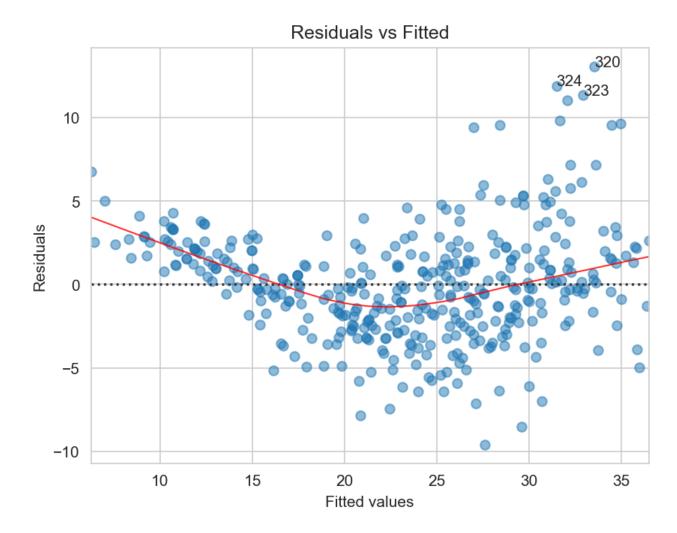
(d) Use the plot() function to produce diagnostic plots of the linear regression fit. Comment on any problems you see with the fit. Do the residual plots suggest any unusually large outliers? Does the leverage plot identify any observations with unusually high leverage?

Reference: https://robert-alvarez.github.io/2018-06-04-diagnostic_plots/

```
In [ ]: # create dataframe from X, y for easier plot handling
        dataframe = pd.concat([X, y], axis=1)
        # model values
        model_fitted_y = model_fit.fittedvalues
        # model residuals
        model_residuals = model_fit.resid
        # normalized residuals
        model_norm_residuals = model_fit.get_influence().resid_studentized_internal
        # absolute squared normalized residuals
        model_norm_residuals_abs_sqrt = np.sqrt(np.abs(model_norm_residuals))
        # absolute residuals
        model_abs_resid = np.abs(model_residuals)
        # leverage, from statsmodels internals
        model_leverage = model_fit.get_influence().hat_matrix_diag
        # cook's distance, from statsmodels internals
        model_cooks = model_fit.get_influence().cooks_distance[0]
```

```
In [ ]: def _residplot(x, y, model_fitted_y):
            plot = plt.figure()
            plot.axes[0] = sns.residplot(x=model_fitted_y, y=y,
                                               lowess=True,
                                               scatter_kws={'alpha': 0.5},
                                               line_kws={'color': 'red', 'lw': 1, 'al
            plot.axes[0].set_title('Residuals vs Fitted')
            plot.axes[0].set_xlabel('Fitted values')
            plot.axes[0].set_ylabel('Residuals')
            # annotations
            abs_resid = model_abs_resid.sort_values(ascending=False)
            abs_resid_top_3 = abs_resid[:3]
            for i in abs resid top 3.index:
                plot.axes[0].annotate(i,
                                            xy=(model fitted y[i],
                                                model residuals[i]))
            return True
        _ = _residplot(X, y, model_fitted_y)
```

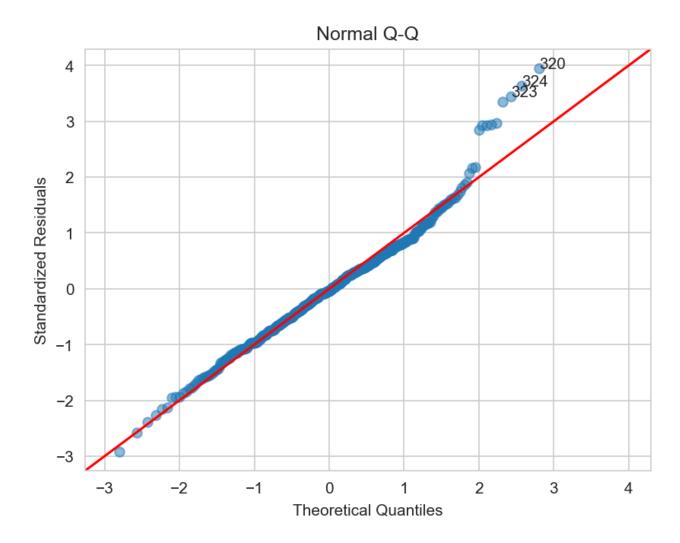
/var/folders/qd/78cm3bf52xs_khrj7wkd_myc0000gn/T/ipykernel_33252/4147608053
.py:14: FutureWarning: The behavior of `series[i:j]` with an integer-dtype
index is deprecated. In a future version, this will be treated as *label-ba
sed* indexing, consistent with e.g. `series[i]` lookups. To retain the old
behavior, use `series.iloc[i:j]`. To get the future behavior, use `series.l
oc[i:j]`.
 abs_resid_top_3 = abs_resid[:3]



Observations: In the above plot, residuals shows a U-shaped pattern, so data might be non-linear.

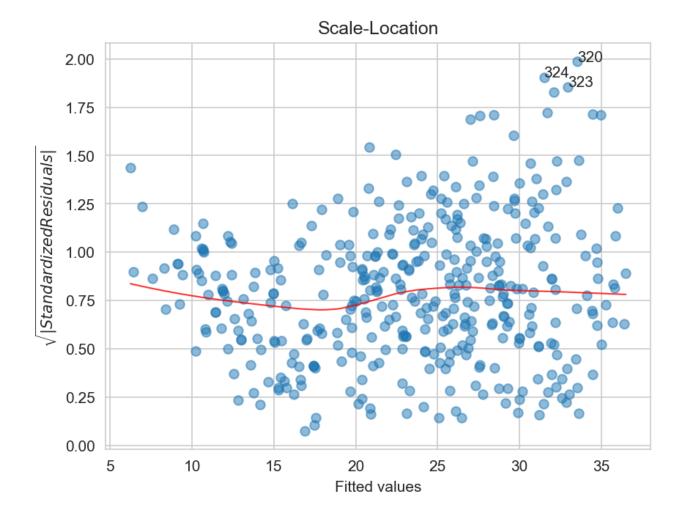
```
In [ ]: def _normal_qq_plot(model_norm_residuals):
            QQ = ProbPlot(model norm residuals)
            plot = QQ.qqplot(line='45', alpha=0.5, color='#4C72B0', lw=1)
            plot.axes[0].set_title('Normal Q-Q')
            plot.axes[0].set_xlabel('Theoretical Quantiles')
            plot.axes[0].set_ylabel('Standardized Residuals')
            # annotations
            abs_norm_resid = np.flip(np.argsort(np.abs(model_norm_residuals)), 0)
            abs_norm_resid_top_3 = abs_norm_resid[:3]
            for r, i in enumerate(abs_norm_resid_top_3):
                plot.axes[0].annotate(
                    i,
                    xy=(np.flip(QQ.theoretical quantiles, 0)[r],
                        model_norm_residuals[i])
            return True, abs_norm_resid_top_3
        _, abs_norm_resid_top_3 = _normal_qq_plot(model_norm_residuals)
```

/Volumes/work/MTH522/project/block_2/.venv/lib/python3.9/site-packages/stat smodels/graphics/gofplots.py:1045: UserWarning: color is redundantly define d by the 'color' keyword argument and the fmt string "b" (-> color=(0.0, 0.0, 1.0, 1)). The keyword argument will take precedence. ax.plot(x, y, fmt, **plot_style)



Observation: The above plot that residual plot is not normally distributed as all othe data points do not lie on the red color line

```
In [ ]: def _scale_location_plot(abs_norm_resid_top_3):
            plot = plt.figure()
            plt.scatter(model_fitted_y, model_norm_residuals_abs_sqrt, alpha=0.5)
            sns.regplot(x=model_fitted_y, y=model_norm_residuals_abs_sqrt,
                        scatter=False,
                        ci=False,
                        lowess=True,
                        line_kws={'color': 'red', 'lw': 1, 'alpha': 0.8})
            plot.axes[0].set_title('Scale-Location')
            plot.axes[0].set_xlabel('Fitted values')
            plot.axes[0].set_ylabel('$\sqrt{|Standardized Residuals|}$')
            # annotations
            abs_sq_norm_resid = np.flip(np.argsort(model_norm_residuals_abs_sqrt), @
            abs_sq_norm_resid_top_3 = abs_sq_norm_resid[:3]
            for i in abs norm resid top 3:
                plot.axes[0].annotate(i,
                                            xy=(model_fitted_y[i],
                                                model_norm_residuals_abs_sqrt[i]))
            return True
        _ = _scale_location_plot(abs_norm_resid_top_3)
```

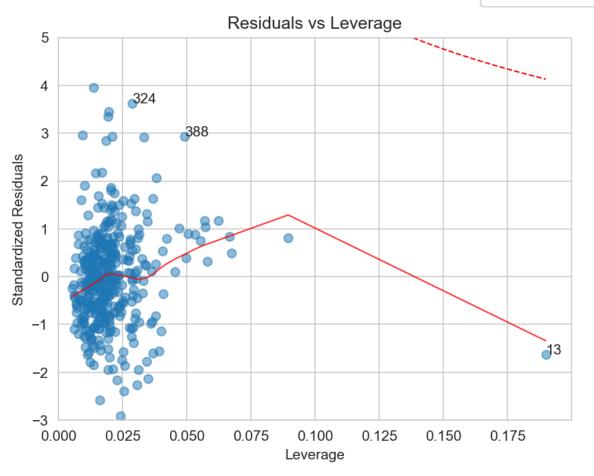


Observation:

1. We can come to the conclusion that there are no outliers. As the data is standardized values should be between[-3,3]. The above data is between 0 to 2 which is accetable.

```
In [ ]: def graph(formula, x_range, label=None):
            Helper function for plotting cook's distance lines
            x = x_range
            y = formula(x)
            plt.plot(x, y, label=label, lw=1, ls='--', color='red')
        def _residuals_vs_leverage_plot():
            plot = plt.figure()
            plt.scatter(model_leverage, model_norm_residuals, alpha=0.5)
            sns.regplot(x=model_leverage, y=model_norm_residuals,
                        scatter=False,
                        ci=False,
                        lowess=True,
                        line_kws={'color': 'red', 'lw': 1, 'alpha': 0.8})
            plot.axes[0].set_xlim(0, max(model_leverage)+0.01)
            plot.axes[0].set vlim(-3, 5)
            plot.axes[0].set_title('Residuals vs Leverage')
            plot.axes[0].set_xlabel('Leverage')
            plot.axes[0].set_ylabel('Standardized Residuals')
            # annotations
            leverage_top_3 = np.flip(np.argsort(model_cooks), 0)[:3]
            for i in leverage_top_3:
                plot.axes[0].annotate(i,
                                            xy=(model_leverage[i],
                                                model_norm_residuals[i])
            p = len(model_fit.params) # number of model parameters
            graph(lambda x: np.sqrt((0.5 * p * (1 - x)) / x),
                  np.linspace(0.001, max(model_leverage), 50),
                  'Cook\'s distance') # 0.5 line
            graph(lambda x: np.sqrt((1 * p * (1 - x)) / x),
                  np.linspace(0.001, max(model_leverage), 50)) # 1 line
            plot.legend(loc='upper right')
            return True
         _ = _residuals_vs_leverage_plot()
```





Observation:

1. From above graph, we can say that there is no leverage points. The points above 'cooks distance' are conidered high leverage points.

(e)Use the * and : symbols to fit linear regression models with interaction effects. Do any interactions appear to be statistically significant?

Out []: OLS Regression Results

Dep. Variable: mpg R-squared (uncentered): 0.989 Model: OLS Adj. R-squared (uncentered): 0.988 Method: F-statistic: 1166. Least Squares Prob (F-statistic): 0.00 Date: Sun, 02 Oct 2022 Time: 23:06:58 Log-Likelihood: -929.96 No. Observations: 392 AIC: 1916. **Df Residuals:** 364 BIC: 2027. **Df Model:** 28

Covariance Type: nonrobust

	coef	std err	t	P> t	[0.025	0.975]
cylinders	9.2200	7.535	1.224	0.222	-5.597	24.037
displacement	-0.5238	0.177	-2.964	0.003	-0.871	-0.176
horsepower	0.6393	0.281	2.276	0.023	0.087	1.192
weight	0.0052	0.018	0.298	0.766	-0.029	0.040
acceleration	-4.7217	1.349	-3.500	0.001	-7.374	-2.069
year	1.0925	0.147	7.448	0.000	0.804	1.381
origin	-19.1539	6.595	-2.904	0.004	-32.124	-6.184
cylinders:displacement	-0.0030	0.006	-0.460	0.646	-0.016	0.010
cylinders:horsepower	0.0071	0.023	0.305	0.760	-0.039	0.053

cylinders:weight	0.0004	0.001	0.411	0.681	-0.001	0.002
cylinders:acceleration	0.2593	0.164	1.582	0.115	-0.063	0.582
cylinders:year	-0.1946	0.092	-2.112	0.035	-0.376	-0.013
cylinders:origin	0.4124	0.492	0.838	0.402	-0.555	1.380
displacement:horsepower	-6.35e-05	0.000	-0.222	0.825	-0.001	0.000
displacement:weight	2.518e-05	1.47e-05	1.717	0.087	-3.66e-06	5.4e-05
displacement:acceleration	-0.0033	0.003	-0.985	0.325	-0.010	0.003
displacement:year	0.0064	0.002	2.793	0.005	0.002	0.011
displacement:origin	0.0245	0.019	1.263	0.207	-0.014	0.063
horsepower:weight	-2.199e-05	2.9e-05	-0.758	0.449	-7.9e-05	3.51e-05
horsepower:acceleration	-0.0077	0.004	-2.118	0.035	-0.015	-0.001
horsepower:year	-0.0070	0.003	-2.016	0.045	-0.014	-0.000
horsepower:origin	-0.0040	0.028	-0.146	0.884	-0.059	0.050
weight:acceleration	0.0002	0.000	0.963	0.336	-0.000	0.001
weight:year	-0.0002	0.000	-1.117	0.265	-0.001	0.000
weight:origin	-0.0005	0.002	-0.286	0.775	-0.004	0.003
acceleration:year	0.0433	0.018	2.448	0.015	0.009	0.078
acceleration:origin	0.4295	0.150	2.854	0.005	0.134	0.725
year:origin	0.1242	0.070	1.764	0.079	-0.014	0.263

Omnibus:	45.617	Durbin-Watson:	1.662
Prob(Omnibus):	0.000	Jarque-Bera (JB):	110.759
Skew:	0.585	Prob(JB):	8.89e-25
Kurtosis:	5.326	Cond. No.	5.69e+07

Notes:

- [1] R² is computed without centering (uncentered) since the model does not contain a constant.
- [2] Standard Errors assume that the covariance matrix of the errors is correctly specified.
- [3] The condition number is large, 5.69e+07. This might indicate that there are strong multicollinearity or other numerical problems.

```
In [ ]: # Lets find only those interaction terms which are statistically significant
        Inter model.pvalues[Inter model.pvalues < 0.05]</pre>
Out[]: displacement
                                    3.235311e-03
        horsepower
                                    2.344125e-02
        acceleration
                                    5.225950e-04
                                    6.936438e-13
        vear
        origin
                                    3.907030e-03
        cylinders:year
                                    3.532847e-02
        displacement:year
                                    5.495075e-03
        horsepower:acceleration
                                    3.484642e-02
        horsepower: year
                                    4.453001e-02
        acceleration: year
                                    1.483186e-02
        acceleration:origin
                                    4.562421e-03
        dtype: float64
```

(f) Try a few different transformations of the variables, such as log(X), \sqrt{X} , X2. Comment on your findings.

```
In []: # Applying transformation for 4 of the columns

auto_3['log(displacement)'] = np.log(auto_3['displacement'])
auto_3['sqrt(weight)'] = np.sqrt(auto_3['weight'])
auto_3['sqrt(horsepower)'] = np.sqrt(auto_3['horsepower'])
auto_3['squared(acceleration)'] = auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['acceleration']*auto_3['ac
```

Out[]: log(displacement) sqrt(weight) sqrt(horsepower) squared(acceleration) 0 18.0 5.726848 59.194594 11.401754 144.00 15.0 5.857933 60.770058 12.845233 132.25 18.0 5.762051 58.617404 12.247449 121.00 16.0 5.717028 58.591808 12.247449 144.00 17.0 5.710427 58.728187 11.832160 110.25

OLS Regression Results

=======================================		=====	=====		======	
=== Dep. Variable: 732		mpg	R-squ	uared:		0.
Model:		0LS	Adj.	R-squared:		0.
730 Method:	Least Squ	iares	F-sta	atistic:		26
4.7 Date:	Sun, 02 Oct	2022	Prob	(F-statistic)	:	2.53e-
109 Time:	23:0	06:58	Log-l	_ikelihood:		-110
<pre>2.9 No. Observations:</pre>		392	AIC:			22
<pre>16. Df Residuals:</pre>		387	BIC:			22
36. Df Model:		4				
Covariance Type:	nonro	bust				
=======================================	coef	st	d err	t	P> t	[0.0
25 0. 975]						
const	76.2582		3.159	24.143	0.000	70.0
48 82.468 log(displacement) 10 -1.204	-3.6068		1.222	-2.951	0.003	-6.0
sqrt(weight) 54 -0.171	-0.3627		0.097	-3.724	0.000	-0.5
sqrt(horsepower) 31 -0.680	-1.3557		0.343	-3.947	0.000	-2.0
squared(acceleration) 12 0.003	-0.0043		0.004	-1.162	0.246	-0.0
=======================================	========	=====	=====	========	=======	=======
Omnibus: 904	43	3.226	Durb	in-Watson:		0.
Prob(Omnibus): 100	6	000.	Jarqı	ue-Bera (JB):		66.
Skew: -15	0	721	Prob	(JB):		4.43e
Kurtosis: +03	2	402	Cond	. No.		4.33e
=======================================		:=====	======		=======	=======

Notes:

[1] Standard Errors assume that the covariance matrix of the errors is corr

ectly specified.

[2] The condition number is large, 4.33e+03. This might indicate that there are strong multicollinearity or other numerical problems.

Observation: Beacuse of transformation, R-squared is decreased. "Displacement" and "acceleration" are having negative coefficients. F-statistics is grater than 1 and p_value less than 0.05 which tells we reject null hypothesis, and there is relationship between the predictors and responses.