

# **MINOR PROJECT REPORT**

## **“IOT Based Transformer Monitoring”**



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# **ABSTRACT**

Distribution transformers are one of the most important equipment in power network. Because of, the large number of transformers distributed over a wide area in power electric systems, the data acquisition and condition monitoring is a important issue. The main aim of this system is distribution transformer monitoring . Here transformers are damaged due to the oil damage. Oil damage is depends on different parameters and environmental conditions. Now in this system we are concentrating on oil level .In this system oil level measurement action is performed based on the ARDUINO UNO microcontroller. After interfacing the required components user has to develop one application program in embedded-c. Here controller is continuously reading the oil level of transformer and displaying it on mobile screen.

# **INTRODUCTION**

Distribution transformers have a long service life if they are operated under good and rated conditions. However, their life is significantly reduced if they are overloaded, resulting in unexpected failures and loss of supply to a large number of customers thus effecting system reliability. Overloading and ineffective cooling of transformers are the major causes of failure in distribution transformers. Most power companies use Supervisory Control and Data Acquisition (SCADA) system for online monitoring of power transformers but extending the SCADA system for online monitoring of distribution transformers is an expensive proposition. Distribution transformers are currently monitored manually where a person periodically visits a transformer site for maintenance and records parameter of importance. This type of monitoring cannot provide information about occasional overloads and overheating of transformer oil and windings.

All these factors can significantly reduce transformer life. Our system is designed based upon online monitoring of key Operational parameters of distribution transformers can provide useful information about the health of transformers which will help the utilities to Optimally use their transformers and keep the asset in operation for a longer Period. This system will help us to identify problems before any catastrophic Failure, thus resulting in a long life service for transformers. This system is based on embedded system as we are using microcontroller as discussed before. Embedded systems are self-contained programs that are embedded within a piece of hardware. embedded systems are usually set to a specific task Another way to think of an embedded system is as a computer system that is created with optimal efficiency, thereby allowing it to complete specific functions as quickly as possible. It is also has the advantages of significant cost savings, power consumption and greater reliability.

# Hardware and Sensors used

1. **Arduino uno**-The Arduino UNO is an open-source microcontroller board based on the Microchip ATmega328P microcontroller and developed by Arduino.cc. The board is equipped with sets of digital and analog input/output (I/O) pins that may be interfaced to various expansion boards (shields) and other circuits. The board has 14 Digital pins, 6 Analog pins, and programmable with the Arduino Uno (Integrated Development Environment) via a type B USB cable. It can be powered by a USB cable or by an external 9 volt battery, though it accepts voltages between 7 and 20 volts. It is also similar to the Arduino Nano and Leonardo. Layout and production files for some versions of the hardware are also available. "Uno" means one in Italian and was chosen to mark the release of Arduino Software (IDE). Following is the pin diagram of arduino uno.

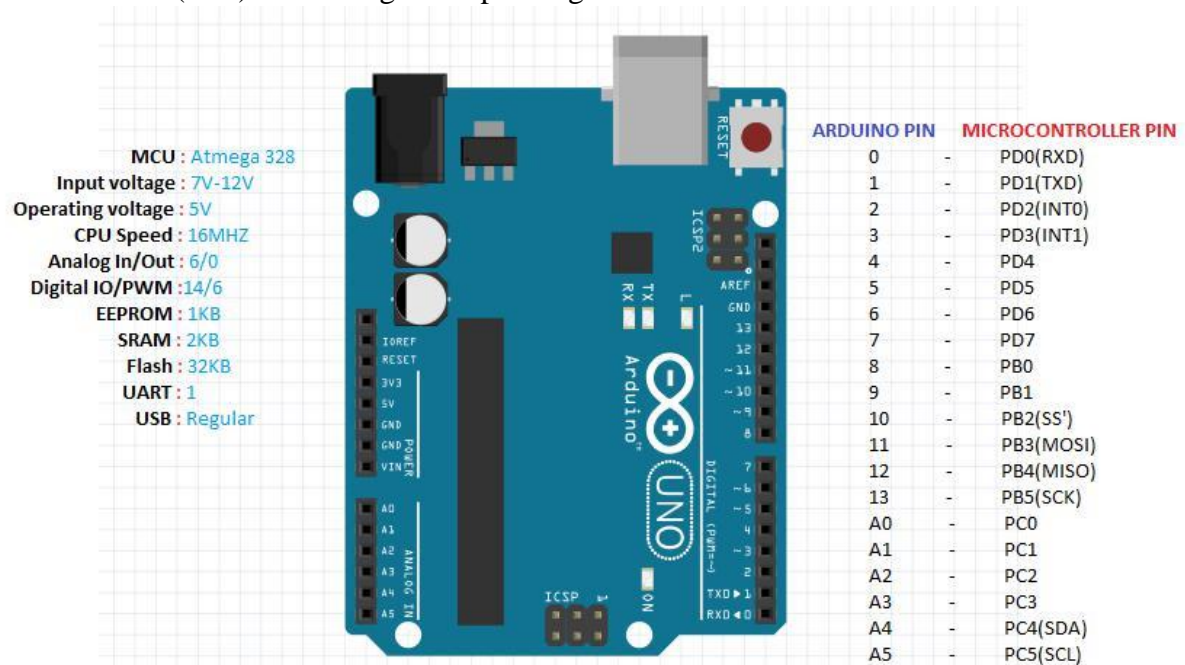


Fig 2.1

2. **Ultrasonic sensor**- As shown above the **HC-SR04 Ultrasonic (US) sensor** is a 4 pin module, whose pin names are Vcc, Trigger, Echo and Ground respectively. This sensor is a very popular sensor used in many applications where measuring distance or sensing objects are required. The module has two eyes like projects in the front which forms the Ultrasonic transmitter and Receiver. The sensor works with the simple high school formula that **Distance = Speed × Time**

The Ultrasonic transmitter transmits an ultrasonic wave, this wave travels in air and when it gets objected by any material it gets reflected back toward the sensor this reflected wave is observed by the Ultrasonic receiver module as shown in the picture below



Fig 2.2

Now, to calculate the distance using the above formulae, we should know the Speed and time. Since we are using the Ultrasonic wave we know the universal speed of US wave at room conditions which is 330m/s. The circuitry inbuilt on the module will calculate the time taken for the US wave to come back and turns on the echo pin high for that same particular amount of time, this way we can also know the time taken. Now simply calculate the distance using a microcontroller or microprocessor.

### 3. Bluetooth module(HC-05)-

#### Introduction

- It is used for many applications like wireless headset, game controllers, wireless mouse, wireless keyboard and many more consumer applications.
- It has range up to <100m which depends upon transmitter and receiver, atmosphere, geographic & urban conditions.
- It is IEEE 802.15.1 standardized protocol, through which one can build wireless Personal Area Network ([PAN](#)). It uses frequency-hopping spread spectrum ([FHSS](#)) radio technology to send data over air.
- It uses serial communication to communicate with devices. It communicates with microcontroller using serial port (USART).

## HC-05 Bluetooth Module

- HC-05 is a Bluetooth module which is designed for wireless communication. This module can be used in a master or slave configuration.

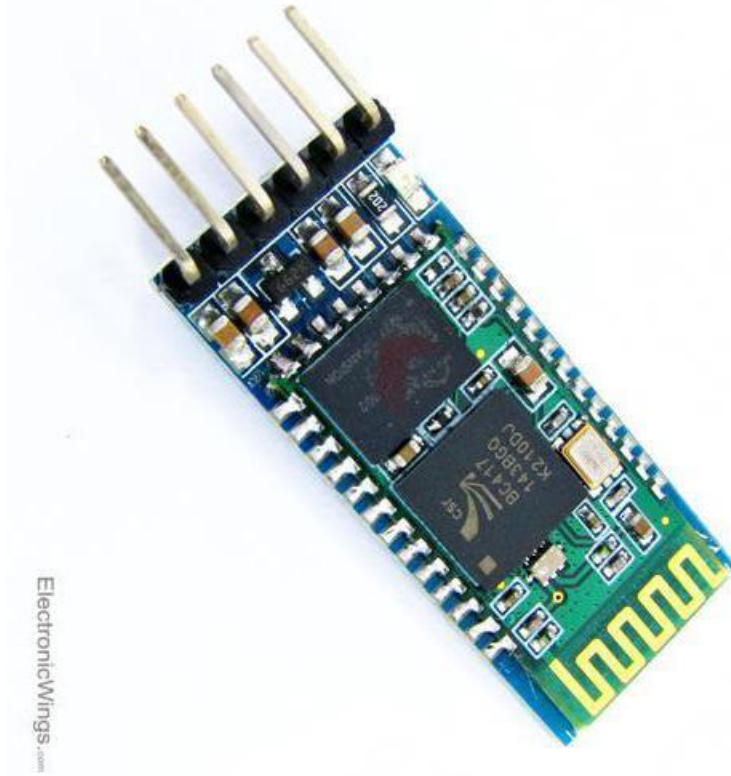


Fig 2.3



## Pin Description



Fig 2.4

Bluetooth serial modules allow all serial enabled devices to communicate with each other using Bluetooth.

It has 6 pins,

1. **Key/EN:** It is used to bring Bluetooth module in AT commands mode. If Key/EN pin is set to high, then this module will work in command mode. Otherwise by default it is in data mode. The default baud rate of HC-05 in command mode is 38400bps and 9600 in data mode.

HC-05 module has two modes,

1. **Data mode:** Exchange of data between devices.

2. **Command mode:** It uses AT commands which are used to change setting of HC-05. To send these commands to module serial (USART) port is used.

2. **VCC:** Connect 5 V or 3.3 V to this Pin.

3. **GND:** Ground Pin of module.

4. **TXD:** Transmit Serial data (wirelessly received data by Bluetooth module transmitted out serially on TXD pin)

5. **RXD:** Receive data serially (received data will be transmitted wirelessly by Bluetooth module).

6. **State:** It tells whether module is connected or not.

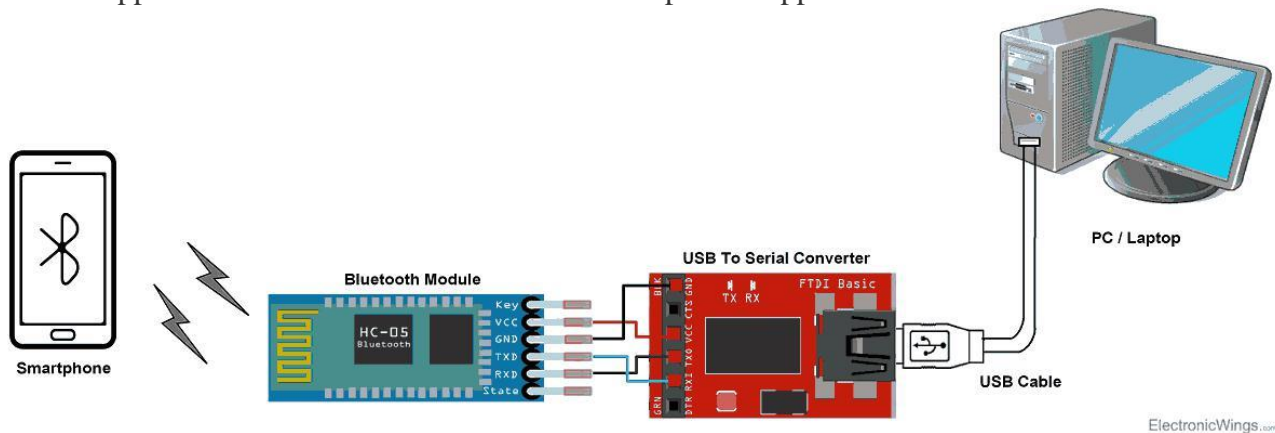
## HC-05 module Information

- HC-05 has red LED which indicates connection status, whether the Bluetooth is connected or not. Before connecting to HC-05 module this red LED blinks continuously in a periodic manner. When it gets connected to any other Bluetooth device, its blinking slows down to two seconds.
- This module works on 3.3 V. We can connect 5V supply voltage as well since the module has on board 5 to 3.3 V regulator.
- As HC-05 Bluetooth module has 3.3 V level for RX/TX and microcontroller can detect 3.3 V level, so, no need to shift transmit level of HC-05 module. But we need to shift the transmit voltage level from microcontroller to RX of HC-05 module.

## Bluetooth communication between Devices

E.g. Send data from Smartphone terminal to HC-05 Bluetooth module and see this data on PC serial terminal and vice versa.

To communicate smartphone with HC-05 Bluetooth module, smartphone requires Bluetooth terminal application for transmitting and receiving data. You can find Bluetooth terminal applications for android and windows in respective app. store.



**Fig 2.5 Bluetooth Module Serial Interface**

So, when we want to communicate through smartphone with HC-05 Bluetooth module, connect this HC-05 module to the PC via serial to USB converter.

Before establishing communication between two Bluetooth devices, 1st we need to pair HC-05 module to smartphone for communication.

**Pair HC-05 and smartphone:**

1. Search for new Bluetooth device from your phone. You will find Bluetooth device with “HC-05” name.
2. Click on connect/pair device option; default pin for HC-05 is 1234 or 0000.

After pairing two Bluetooth devices, open terminal software (e.g. Teraterm, Realterm etc.) in PC, and select the port where we have connected USB to serial module. Also select default baud rate of 9600 bps.

In smart phone, open Bluetooth terminal application and connect to paired device HC-05.

It is simple to communicate, we just have to type in the Bluetooth terminal application of smartphone. Characters will get sent wirelessly to Bluetooth module HC-05. HC-05 will automatically transmit it serially to the PC, which will appear on terminal. Same way we can send data from PC to smartphone.

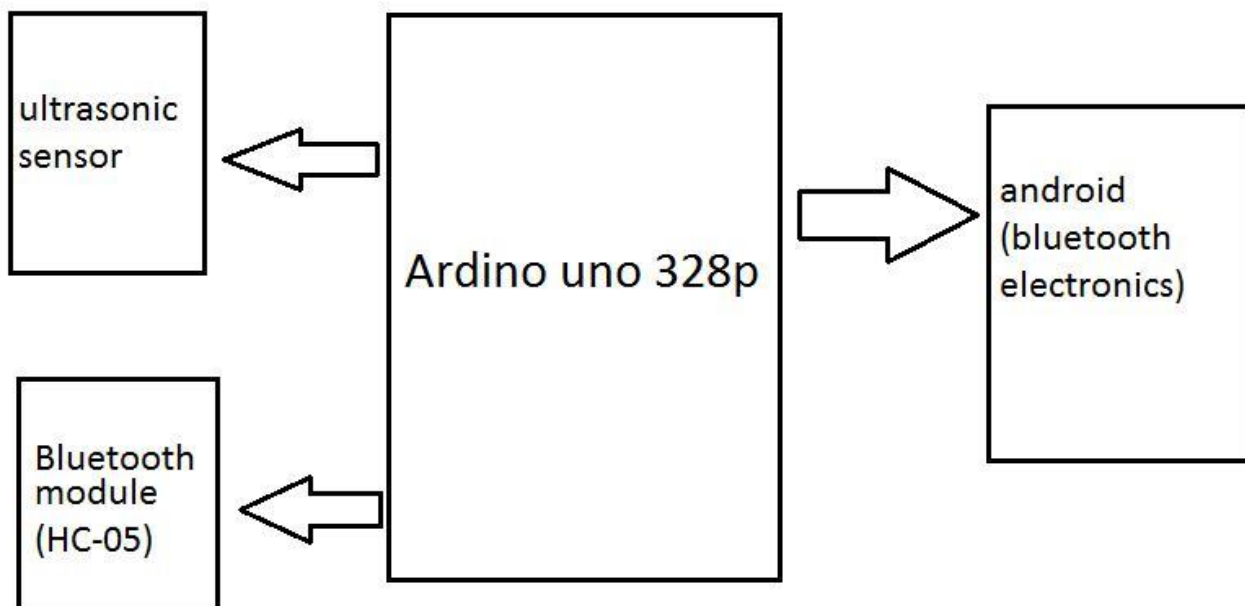


Fig 2.6

## **Code:-**

```
#define trigPin 10
#define echoPin 9

void setup() {

  Serial.begin (9600);
  pinMode(trigPin, OUTPUT);
  pinMode(echoPin, INPUT);
  pinMode(0,INPUT);

}

void loop() {

  long duration, distance,height;
  digitalWrite(trigPin, LOW);
  delayMicroseconds(2);
  digitalWrite(trigPin, HIGH);
  delayMicroseconds(10);
  digitalWrite(trigPin, LOW);
  duration = pulseIn(echoPin, HIGH);
  distance = (duration/2) / 29.1;
  height=100cm;

  Serial.print(height-distance);
  Serial.println(" cm");
  Serial.println(" C");

  delay(50);

}
```

## **ADVANTAGES**

- We Can Sit At Any Place And Access It Using Internet
- We Can Control The System Or The Equipment Using GPRS
- It Is Economical Compared To The SCADA System Used.

## **APPLICATIONS**

- Used to control equipments
- Can also control the system
- In dams

## **CONCLUSION**

The IOT based monitoring of transformer is quite useful as compared to manual monitoring and also it is reliable as it is not possible to monitor always the oil level manually. After receiving of message of any abnormality we can take action immediately to prevent any catastrophic failures of distribution transformers. In a distribution network there are many distribution transformers and associating each transformer with such system, we can easily figure out that which transformer oil level, from the message sent to mobile. We need not have to check all transformers and corresponding phase currents and voltages and thus we can recover the system in less time. The time for receiving messages may vary due to the public GSM network traffic but still then it is effective than manual monitoring.

## **RESULT**

This system would be eliminating the requirement of human power and thus providing efficiency and accuracy. This paper will give accurate details of oil level. It will help to manage sensing the parameters and also record details for level of oil in transformer. This paper will also assure the safety and would not result in any harm to the environment and surroundings.

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