

# Assignment 1

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(Github link: [https://github.com/PradyumnaG/VR\\_Assignment1](https://github.com/PradyumnaG/VR_Assignment1))

## Overview:

### 1. Coin Detection:

- Detect coins using edge detection.
- Identify number of coins.
- Separate each individual coin.
- Segment coins.

### 2. Image stitching for panorama creation

- Detect Key Point descriptors.
- Identify common Key Point descriptors.
- Stitch the images to produce a final panorama.

## Coin Detection:

### 1. Image Preprocessing:

- Resizing ensures consistent processing for images of varying sizes.
- Grayscale conversion simplifies the image to a single channel.
- Gaussian blur reduces noise, making the thresholding step more effective.
- Adaptive thresholding is used.

## 2. Coin Detection:

- Contours are extracted using `cv2.findContours`.
- Circularity is calculated to determine how close a contour is to a perfect circle.
- Contours with circularity between 0.7 and 1.2 and an area above a minimum threshold are considered valid coins.

## 3. Segmentation and Masking:

- **Outline mode:** Draws the contours of the detected coins on the original image.
- **Mask mode:** Creates a binary mask where the detected coins are filled with a specific color (orange in our case).
- The coins are extracted from the previous step using contours.

## 4. Individual Coin Extraction:

- A circular mask is created for each coin using `cv2.minEnclosingCircle` to determine the center and radius.
- The mask is applied to the original image to isolate the coin.
- The coin is cropped using the bounding box of the circle and saved as a separate file.

## Requirements:

`pip install numpy opencv-python`

## How to run:

Place all your input coin images (name can be anything) in Assignment1/Part1/Input. Run the file using the command:  
`python3 CoinDetectionOrange.py`

## Panorama Creation:

### 1. Feature Detection:

- `cv2.SIFT_create()` initializes the SIFT detector.
- `sift.detectAndCompute()` detects keypoints and computes their descriptors (feature vectors).
- SIFT keypoints are calculated for both the images.

### 2. Feature Matching:

- Matches the descriptors of keypoints from the two images using brute force.
- `cv2.BFMatcher()` initializes the matcher with the L2 norm (Euclidean distance) for comparing descriptors.
- `matcher.match()` finds the best matches between the descriptors of the two images.
- Matches are sorted by distance (quality of match), and only the top matches are used for further processing.

### 3. Image Stitching:

- `cv2.findHomography()` computes the homography matrix using the RANSAC algorithm to handle outliers.
- `cv2.warpPerspective()` warps the first image to align it with the second image using the homography matrix.
- The second image is then overlaid on the warped image to create the final panorama.

## Requirements:

`pip install opencv-python numpy`

## How to run:

Place the input images in Assignment1/Part2/input and replace the input paths in the code.

## Observations and Results:

### Coin Detection:

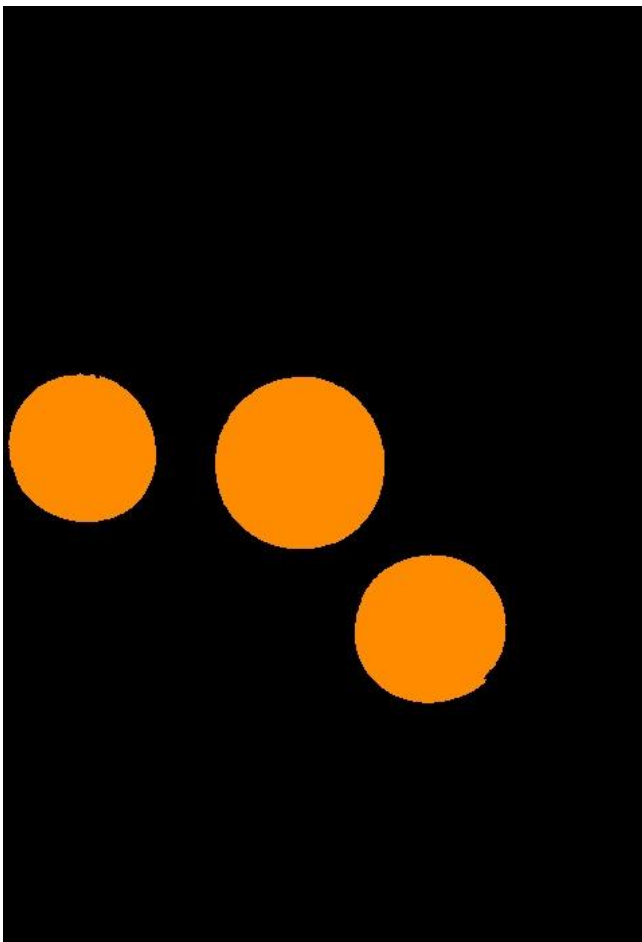
- Successfully detects coin edges using contour edge detection.



- Successfully detects the number of coins and extracts each individual coin.



- Effectively segments all the coins and generates a mask of all the coins.



### Image stitching:

- SIFT keypoints are accurately detected in both the images.



- Keypoints/Features are accurately matched between both the images.



- The final panorama image is successfully generated using RANSAC algorithm and homography.

