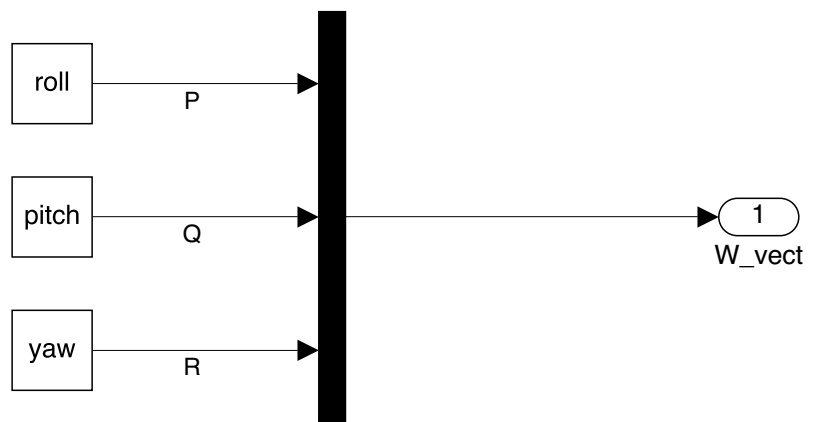





```
function Omega = fcn(W_vect)
```

```
wx = W_vect(1);  
wy = W_vect(2);  
wz = W_vect(3);
```

```
Omega = [0 -wx -wy -wz;  
         wx 0 wz -wy;  
         wy -wz 0 wx;  
         wz wy -wx 0];
```



Sample Times for 'quaternionkinematics'

Color	Annotation	Description	Value
	Cont	Continuous	0
	FiM	Fixed in Minor Step	[0,1]
	Inf	Constant	Inf