MATHEMATICS

Matrices Elementary Transformations

Matrices

Elementary Transformation:

(Recall that R and C symbolically represent the rows and columns of a matrix.)

(a) Interchange of any two rows or any two columns. If we interchange the i^{th} row and the j^{th} row of a matrix then after this interchange the original matrix is transformed to a new matrix.

This transformation is symbolically denoted as $R_i \leftrightarrow R_j$ or R_{ij}

Ex. (1): If
$$A = \begin{bmatrix} 3 & -5 \\ 2 & 6 \end{bmatrix}$$
 then $R_1 \leftrightarrow R_2$ gives $\begin{bmatrix} 2 & 6 \\ 3 & -5 \end{bmatrix}$

Ex. (2): If
$$B = \begin{bmatrix} 1 & 3 & 4 \\ 2 & 5 & 3 \\ 1 & 7 & 8 \end{bmatrix}$$
 then $C_2 \leftrightarrow C_3$ gives $\begin{bmatrix} 1 & 4 & 3 \\ 2 & 3 & 5 \\ 1 & 8 & 7 \end{bmatrix}$

Note that
$$A \neq \begin{bmatrix} 2 & 6 \\ 3 & -5 \end{bmatrix}$$
 and $B \neq \begin{bmatrix} 1 & 4 & 3 \\ 2 & 3 & 5 \\ 1 & 8 & 7 \end{bmatrix}$

But however we write
$$A \sim \begin{bmatrix} 2 & 6 \\ 3 & -5 \end{bmatrix}$$
 and $B \sim \begin{bmatrix} 1 & 4 & 3 \\ 2 & 3 & 5 \\ 1 & 8 & 7 \end{bmatrix}$

Note : The symbol \sim is read as equivalent to.

(b) Multiplication of the elements of any row or column by a non-zero scalar : If k is a non-zero scalar and the row R_i is to be multiplied by constant k then we multiply every element of R_i by the constant k and symbolically the transformation is denoted by $R_i \to kR_i$ or kR_i

Ex. (1): If
$$A = \begin{bmatrix} 4 & 2 & 3 \\ 8 & -6 & 4 \\ 2 & 4 & 9 \end{bmatrix}$$
 then $R_2 \to \frac{1}{2}R_2$ gives $A \sim \begin{bmatrix} 4 & 2 & 3 \\ 4 & -3 & 2 \\ 2 & 4 & 9 \end{bmatrix}$

Similarly, if any column of a matrix is to be multiplied by a constant then we multiply every element of the column by the constant. It is denoted as $C_i \to kC_i$ or kC_i .

Ex. (2): If
$$P = \begin{bmatrix} -1 & 2 & 3 \\ 5 & -6 & 6 \\ 3 & 4 & 9 \end{bmatrix}$$
 then $C_3 \to \frac{1}{3}R_3$ gives $P \sim \begin{bmatrix} -1 & 2 & 1 \\ 5 & -6 & 2 \\ 3 & 4 & 3 \end{bmatrix}$

(c) Adding the scalar multiples of all the elements of any row (or column) to corresponding elements of any other row (column).

If k is a non-zero scalar and the k-multiples of the elements of R_i (or C_i) can be added to the elements of R_j (or C_j) then the transformation is symbolically denoted as $R_i \to R_i + kR_j$ (or $C_i \to C_i + kC_j$)

Ex. (1): If
$$P = \begin{bmatrix} 3 & 2 & 1 \\ -5 & 4 & 2 \end{bmatrix}$$
 then $C_2 \to C_2 - 2C_3$ gives $P \sim \begin{bmatrix} 3 & 0 & 1 \\ -5 & 0 & 2 \end{bmatrix}$

Examples

(I) Apply given elementary transformations on examples (1) and (2)

(1)
$$A = \begin{bmatrix} 3 & -5 \\ 2 & 6 \end{bmatrix}$$
, $R_2 \to R_2 - \frac{2}{3}R_1$ (2) $B = \begin{bmatrix} -2 & 4 \\ 1 & 7 \\ -1 & 3 \end{bmatrix}$, $R_3 \to R_3 + 2R_2$

(3)
$$C = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$$
, Transform C into an lower triangular matrix by using a suitable row transformations.

(4)
$$A = \begin{bmatrix} 1 & -1 & 2 \\ 2 & 1 & 3 \\ 3 & 2 & 4 \end{bmatrix}$$
, Transform A into an upper triangular matrix by using a suitable row transformations.

(5)
$$A = \begin{bmatrix} 1 & 2 & 2 \\ 2 & 1 & 2 \\ 2 & 2 & 1 \end{bmatrix}$$
, Transform A into an identity matrix by using a suitable column transformations.

Solutions:

(1) Given:
$$A = \begin{bmatrix} 3 & -5 \\ 2 & 6 \end{bmatrix}$$
, $R_2 \to R_2 - \frac{2}{3}R_1$ $\therefore A \sim \begin{bmatrix} 3 & -5 \\ 2 & 6 \end{bmatrix}$,

(2) Given :
$$B = \begin{bmatrix} -2 & 4 \\ 1 & 2 \\ -1 & 3 \end{bmatrix}$$
, $R_3 \to R_3 + 2R_2$ \therefore $B \sim \begin{bmatrix} -2 & 4 \\ 1 & 7 \\ 1 & 7 \end{bmatrix}$,

(3) Given :
$$C = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$$
, $R_1 \to R_1 - \frac{1}{2}R_2$ \therefore $C \sim \begin{bmatrix} -\frac{1}{2} & 0 \\ 3 & 4 \end{bmatrix}$,

(4) Given :
$$A = \begin{bmatrix} 1 & -1 & 2 \\ 2 & 1 & 3 \\ 3 & 2 & 4 \end{bmatrix}$$

Note: We can apply two transformations simultaneously on two different rows (or columns) at a time but without using the changed row (or column) in the succeeding transformation

$$R_2 \to R_2 - 2R_1 \ , \ R_3 \to R_3 - 3R_1$$

$$A \sim \begin{bmatrix} 1 & -1 & 2 \\ 0 & 3 & -1 \\ 0 & 5 & -2 \end{bmatrix}$$

$$R_3 \to R_3 - \frac{5}{3}R_2$$

$$A \sim \begin{bmatrix} 1 & -1 & 2 \\ 0 & 3 & -1 \\ 0 & 0 & -\frac{1}{3} \end{bmatrix}$$
 which is an upper triangular Matrix

(5) Given:
$$A = \begin{bmatrix} 1 & 2 & 2 \\ 2 & 1 & 2 \\ 2 & 2 & 1 \end{bmatrix}$$

$$C_2 \to C_2 - 2C_1 \ , \ C_3 \to C_3 - 2C_1$$

$$A \sim \begin{bmatrix} 1 & 0 & 0 \\ 2 & -3 & -2 \end{bmatrix}$$

$$A \sim egin{bmatrix} 1 & 0 & 0 \ 2 & -3 & -2 \ 2 & -2 & -3 \end{bmatrix}$$

$$A \sim \begin{bmatrix} 2 & -3 & -2 \\ 2 & -2 & -3 \end{bmatrix}$$

$$C_2 \to C_2 - 2C_3$$

$$A \sim \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & -2 \\ 2 & 4 & -3 \end{bmatrix}$$

$$C_1 \to C_1 - 2C_2 \; , \; C_3 \to C_3 + 2C_2$$

$$A \sim \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -6 & 4 & 5 \end{bmatrix}$$

$$C_3 o rac{1}{5}C_3$$

$$A \sim \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -6 & 4 & 1 \end{bmatrix}$$

$$C_1 \to C_1 + 6C_3 \ , \ C_2 \to C_2 - 4C_3$$

$$A \sim \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$
 which is an Identity Matrix

Elementary transformations on Matrix equations:

Consider the equation AB = X where A, B and X are matrices of same order. In order to apply a sequence of row transformations on the equation AB = X we apply, these operations simultaneously on

on the first matrix A of the product AB on LHS and X on RHS Simillarly, In order to apply a sequence of column transformations on the equation AB = X we apply, these operations simultaneously on the second matrix B of the product AB on LHS and X on RHS Here in the product AB the first matrix A is called Pre Factor and the second matrix B is called Post Factor. Only Row operations are valid on Pre Factor.Only column operations are valid on Post Factor.

valid on Pre Factor. Only column operations are valid on Post Factor. For example, if
$$A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$$
, $B = \begin{bmatrix} 2 & -1 \\ 1 & 3 \end{bmatrix}$ then $AB = \begin{bmatrix} 4 & 5 \\ 10 & 9 \end{bmatrix} = C$

Thus we have $\begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \begin{bmatrix} 2 & -1 \\ 1 & 3 \end{bmatrix} = \begin{bmatrix} 4 & 5 \\ 10 & 9 \end{bmatrix}$

If we apply a row transformation on pre factor i.e. A and on RHS

then the equality of the product of reduced matrices must hold

Now,
$$\begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \begin{bmatrix} 2 & -1 \\ 1 & 3 \end{bmatrix} = \begin{bmatrix} 4 & 5 \\ 10 & 9 \end{bmatrix}$$

Consider $R_2 \to R_2 - 2R_1$

$$\begin{bmatrix} 1 & 2 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 2 & -1 \\ 1 & 3 \end{bmatrix} = \begin{bmatrix} 4 & 5 \\ 2 & -1 \end{bmatrix}$$

LHS =
$$\begin{bmatrix} 1 & 2 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 2 & -1 \\ 1 & 3 \end{bmatrix} = \begin{bmatrix} 1 \times 2 + 2 \times 1 & 1 \times -1 + 2 \times 3 \\ 1 \times 2 + 0 \times 1 & 1 \times -1 + 0 \times 3 \end{bmatrix}$$

$$= \begin{bmatrix} 2+2 & -1+6 \\ 2+0 & -1+0 \end{bmatrix}$$

$$= \begin{bmatrix} 4 & 5 \\ 2 & -1 \end{bmatrix} = \text{RHS}.$$

Inverse of a Matrix

Definition:

If A is a square matrix of order m and if there exists another square matrix B of the same order such that AB = BA = I, where I is the identity matrix of order m, then B is called as the inverse of A and is denoted by A^{-1} , i.e. $B = A^{-1}$. Hence $AA^{-1} = A^{-1}A = I$. By using the same definition we can say that A is the inverse of B and is denoted by B^{-1} , i.e. $A = B^{-1}$. Hence $B^{-1}B = BB^{-1} = I$.

Note:

- (1) Every square matrix A has its corresponding determinant; |A|
- (2) A square matrix A has inverse if and only if $|A| \neq 0$
- (3) A matrix is said to be invertible if its inverse exists.

The inverse of a matrix (if it exists) can be obtained by using two methods. (i) Elementary row or column transformation (ii) Adjoint method

Inverse of a nonsingular matrix by elementary transformation:

Consider the equation $AA^{-1} = I$. Here A is the given matrix of order m and I is the identity matrix of order m. Hence A^{-1} is the only unknown matrix. So to find A^{-1} we have to first convert A to I. This can be done by using a sequence of elementary row transformations on both the sides of the equation. And reduce it to the form $IA^{-1} = B$ so that $A^{-1} = B$.

If we start with the equation $A^{-1}A = I$, then apply a sequence column transformations on the post factor and RHS and reduce the equation to the form $A^{-1}I = B$ so that $A^{-1} = B$.

If A is a non-singular matrix of order 3, say

For reducing the above matrix to $\begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$

the suitable transformations are as follows:

Row Transformations

(1). Reduce a_{11} to '1'

- (2). Reduce a_{21} and a_{31} to '0'
- (3). Reduce a_{22} to '1' using R_2 and R_3
- (4). Reduce a_{12} and a_{32} to '0'
- (5). Reduce a_{33} to '1'
- (6). Reduce a_{13} and a_{23} to '0'

Column Transformations

- (1). Reduce a_{11} to '1'
- (2). Reduce a_{12} and a_{13} to '0'
- (3). Reduce a_{22} to '1' using C_2 and C_3
- (4). Reduce a_{21} and a_{23} to '0'
- (5). Reduce a_{33} to '1'
- (6). Reduce a_{31} and a_{32} to '0'

Examples

(II) Find the inverse of the following matrices by using row transformations (if they exist)

$$\begin{bmatrix} 3 & 5 \\ 2 & 6 \end{bmatrix}, \qquad (2) \begin{bmatrix} 2 & -1 & 1 \\ -1 & 2 & -1 \\ 1 & -1 & 2 \end{bmatrix}, \qquad (3) \begin{bmatrix} \cos \theta & -\sin \theta & 0 \\ \sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix},$$

(III) Find the inverse of the following matrices by using column transformations (if they exist)

$$\begin{bmatrix} 1 & -1 \\ 2 & 3 \end{bmatrix}, \qquad (2) \begin{vmatrix} 1 & 2 & 3 \\ -1 & 1 & 2 \\ 1 & 2 & 4 \end{vmatrix}$$

Solutions

(II). (1) Let,
$$A = \begin{bmatrix} 3 & 5 \\ 2 & 6 \end{bmatrix}$$
, consider $|A| = 18 - 10 = 8 \neq 0$:. A^{-1} exists

We have
$$AA^{-1} = I$$

i.e.
$$\begin{bmatrix} 3 & 5 \\ 2 & 6 \end{bmatrix} A^{-1} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$R_1 \to R_1 - R_2$$

$$\begin{bmatrix} 1 & -1 \\ 2 & 6 \end{bmatrix} A^{-1} = \begin{bmatrix} 1 & -1 \\ 0 & 1 \end{bmatrix}$$

$$R_2 \to R_2 - 2R_1$$

$$\begin{bmatrix} 1 & -1 \\ 0 & 8 \end{bmatrix} A^{-1} = \begin{bmatrix} 1 & -1 \\ -2 & 3 \end{bmatrix} \qquad \therefore A^{-1} = \frac{1}{8} \begin{bmatrix} 6 & -5 \\ -2 & 3 \end{bmatrix}$$

$$R_2 \to \frac{1}{8}R_2$$

$$\begin{bmatrix} 1 & -1 \\ 0 & 1 \end{bmatrix} A^{-1} = \begin{bmatrix} 1 & -1 \\ -\frac{2}{9} & \frac{3}{9} \end{bmatrix}$$

$$R_1 \rightarrow R_1 + R_2$$

$$\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} A^{-1} = \begin{bmatrix} 6/8 & -5/8 \\ -2/8 & 3/8 \end{bmatrix}$$

$$IA^{-1} = \begin{bmatrix} 6/8 & -5/8 \\ -2/8 & 3/8 \end{bmatrix}$$

$$\therefore A^{-1} = \frac{1}{8} \begin{vmatrix} 6 & -5 \\ -2 & 3 \end{vmatrix}$$

(2) Let,
$$A = \begin{bmatrix} 2 & -1 & 1 \\ -1 & 2 & -1 \\ 1 & -1 & 2 \end{bmatrix}$$

consider $|A| = 2(4-1) + 1(-2+1) + 1(1-2) = 6 - 1 - 1 = 4 \neq 0$
 A^{-1} exists

We have
$$AA^{-1} = I$$

$$R_2 \to R_2 + R_1, \ R_3 \to R_3 - R_1$$
i.e.
$$\begin{bmatrix} 2 & -1 & 1 \\ -1 & 2 & -1 \\ 1 & -1 & 2 \end{bmatrix} A^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 & 0 \\ 0 & 3 & -1 \\ 0 & -2 & 2 \end{bmatrix} A^{-1} = \begin{bmatrix} 1 & 1 & 0 \\ 1 & 2 & 0 \\ -1 & -1 & 1 \end{bmatrix}$$

$$R_1 \to R_1 + R_2$$
i.e.
$$\begin{bmatrix} 1 & 1 & 0 \\ -1 & 2 & -1 \\ 1 & -1 & 2 \end{bmatrix} A^{-1} = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & -1 & 2 \end{bmatrix} & \begin{bmatrix} 0 & 0 & 1 \end{bmatrix} & \begin{bmatrix} 0 & -2 & 2 \end{bmatrix} & \begin{bmatrix} -1 & -1 & 1 \end{bmatrix} \\ R_1 \to R_1 + R_2 & R_2 \to R_2 + R_3 & \\ \vdots & \begin{bmatrix} 1 & 1 & 0 \\ -1 & 2 & -1 \\ 1 & -1 & 2 \end{bmatrix} A^{-1} = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} & \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & -2 & 2 \end{bmatrix} A^{-1} = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ -1 & -1 & 1 \end{bmatrix}$$

$$R_1 \to R_1 - R_2, \ R_3 \to R_3 + 2R_2$$

$$\begin{bmatrix} 1\\1\\4 \end{bmatrix} A^{-1} = \begin{bmatrix} 1 & 0 & -1\\0 & 1 & 1\\-1 & 1 & 3 \end{bmatrix}$$

$$\begin{bmatrix} 1 \\ 4 \end{bmatrix} A^{-1} = \begin{bmatrix} 0 & 1 & 1 \\ -1 & 1 & 3 \end{bmatrix}$$

$$\begin{bmatrix} 0 & 1 & 1 \\ 0 & 0 & 4 \end{bmatrix} \begin{bmatrix} 11 & -1 & 1 \\ -1 & 1 & 3 \end{bmatrix}$$

$$R_3 \to \frac{1}{4}R_3$$

$$\begin{bmatrix} 1 & 0 & -1 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix} A^{-1} = \begin{bmatrix} 1 & 0 & -1 \\ 0 & 1 & 1 \\ -1/4 & 1/4 & 3/4 \end{bmatrix}$$

$$\begin{bmatrix} 1A^{-1} = \frac{1}{4} \begin{bmatrix} 3 & 1 & -1 \\ 1 & 3 & 1 \\ -1 & 1 & 3 \end{bmatrix}$$

$$\therefore A^{-1} = \frac{1}{4} \begin{bmatrix} 3 & 1 & -1 \\ 1 & 3 & 1 \\ -1 & 1 & 3 \end{bmatrix}$$

$$\therefore A^{-1} = \frac{1}{4} \begin{bmatrix} 3 & 1 & -1 \\ 1 & 3 & 1 \\ -1 & 1 & 3 \end{bmatrix}$$

(2) Let,
$$A = \begin{bmatrix} \cos \theta & -\sin \theta & 0 \\ \sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

 $R_1 \to R_1 + R_3, R_2 \to R_2 - R_3$ $\begin{bmatrix} 1 & 0 & -1 \\ 0 & 1 & 1 \\ 0 & 0 & 4 \end{bmatrix} A^{-1} = \begin{bmatrix} 1 & 0 & -1 \\ 0 & 1 & 1 \\ -1 & 1 & 3 \end{bmatrix} \qquad \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} A^{-1} = \begin{bmatrix} 3/4 & 1/4 & -1/4 \\ 1/4 & 3/4 & 1/4 \\ -1/4 & 1/4 & 3/4 \end{bmatrix}$

$$1A^{-1} = \frac{1}{4} \begin{bmatrix} 1 & 3 & 1 \\ -1 & 1 & 3 \end{bmatrix}$$

$$1\begin{bmatrix} 3 & 1 & -1 \\ 1 & 1 & 3 \end{bmatrix}$$

$$\therefore A^{-1} = \frac{1}{4} \begin{bmatrix} 1 & 3 & 1 \\ -1 & 1 & 3 \end{bmatrix}$$

consider $|A| = \cos \theta (\cos \theta - 0) + \sin \theta (\sin \theta - 0) + 0 = \cos^2 \theta + \sin^2 \theta = 1 \neq 0$

$$\therefore A^{-1} \text{ exists}$$
We have $AA^{-1} = I$

 $R_1 \to \cos \theta R_1 + \sin \theta R_2$

 $R_2 \rightarrow R_2 - \sin \theta R_1$

i.e. $\begin{bmatrix} \cos \theta & -\sin \theta & 0 \\ \sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix} A^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$

 $\begin{vmatrix} 1 & 0 & 0 \\ \sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{vmatrix} A^{-1} = \begin{bmatrix} \cos \theta & \sin \theta & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$

 $\begin{vmatrix} 1 & 0 & 0 \\ 0 & \cos \theta & 0 \\ 0 & 0 & 1 \end{vmatrix} A^{-1} = \begin{bmatrix} \cos \theta & \sin \theta & 0 \\ -\sin \theta \cos \theta & 1 - \sin^2 \theta & 0 \\ 0 & 0 & 1 \end{bmatrix}$

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & \cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix} A^{-1} = \begin{bmatrix} \cos \theta & \sin \theta & 0 \\ -\sin \theta \cos \theta & \cos^2 \theta & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$R_2 \to \frac{1}{\cos \theta} R_2$$

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} A^{-1} = \begin{bmatrix} \cos \theta & \sin \theta & 0 \\ -\sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$IA^{-1} = \begin{bmatrix} \cos \theta & \sin \theta & 0 \\ -\sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix}$$
$$A^{-1} = \begin{bmatrix} \cos \theta & \sin \theta & 0 \\ -\sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

(III). (1) Let,
$$A = \begin{bmatrix} 1 & -1 \\ 2 & 3 \end{bmatrix}$$
,

consider
$$|A| = 3 + 2 = 5 \neq 0$$
 : A^{-1} exists

We have
$$AA^{-1} = I$$

i.e. $\begin{bmatrix} 1 & -1 \\ 2 & 3 \end{bmatrix} A^{-1} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$

$$C_2 \to C_2 + C_1$$

$$\begin{bmatrix} 1 & 0 \\ 2 & 5 \end{bmatrix} A^{-1} = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$$

$$C_2 \to \frac{1}{5}C_2$$

$$\begin{bmatrix} 1 & 0 \\ 2 & 1 \end{bmatrix} A^{-1} = \begin{bmatrix} 1 & 1/5 \\ 0 & 1/5 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} A^{-1} = \begin{bmatrix} 3/5 & 1/5 \\ -2/5 & 1/5 \end{bmatrix}$$
$$IA^{-1} = \begin{bmatrix} 3/5 & 1/5 \\ -2/5 & 1/5 \end{bmatrix}$$

 $C_1 \to C_1 - 2C_2$

$$A^{-1} = \frac{1}{5} \begin{bmatrix} 3 & 1 \\ -2 & 1 \end{bmatrix}$$

(2) Let,
$$A = \begin{bmatrix} 1 & 2 & 3 \\ -1 & 1 & 2 \\ 1 & 2 & 4 \end{bmatrix}$$

$$A^{-1} = \frac{1}{3} \begin{bmatrix} 0 & -2 & 1 \\ 6 & 1 & -5 \\ -3 & 0 & 3 \end{bmatrix}$$

 $C_2 \to 2C_2 - C_3$

Now, $|A| = 1(4-4) - 2(-4-2) + 3(-2-1) = 0 + 12 - 9 = 3 \neq 0$

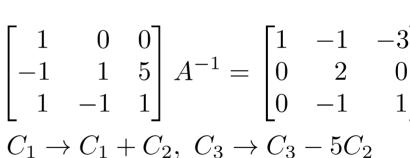
 $\therefore A^{-1}$ exists

We have
$$AA^{-1} = I$$

i.e.
$$\begin{bmatrix} 1 & 2 & 3 \\ -1 & 1 & 2 \\ 1 & 2 & 4 \end{bmatrix} A^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \qquad \begin{bmatrix} 1 & 0 & 0 \\ -1 & 1 & 5 \\ 1 & -1 & 1 \end{bmatrix} A^{-1} = \begin{bmatrix} 1 & -1 & -3 \\ 0 & 2 & 0 \\ 0 & -1 & 1 \end{bmatrix}$$

$$C_2 \to C_2 - 2C_1, \ C_3 \to C_3 - 3C_1$$

$$\begin{bmatrix} 1 & 0 & 0 \\ -1 & 3 & 5 \\ 1 & 0 & 1 \end{bmatrix} A^{-1} = \begin{bmatrix} 1 & -2 & -3 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$



$$\begin{bmatrix} 1 & 0 & 0 \\ -1 & 3 & 5 \\ 1 & 0 & 1 \end{bmatrix} A^{-1} = \begin{bmatrix} 1 & -2 & -3 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -1 & 6 \end{bmatrix} A^{-1} = \begin{bmatrix} 0 & -1 & 2 \\ 2 & 2 & -10 \\ -1 & -1 & 6 \end{bmatrix}$$

$$C_3 \rightarrow \frac{1}{6}C_3$$

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -1 & 1 \end{bmatrix} A^{-1} = \begin{bmatrix} 0 & -1 & 1/3 \\ 2 & 2 & -5/3 \\ -1 & -1 & 1 \end{bmatrix}$$

$$C_2 \rightarrow C_2 + C_3$$

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} A^{-1} = \begin{bmatrix} 0 & -2/3 & 1/3 \\ 2 & 1/3 & -5/3 \\ -1 & 0 & 1 \end{bmatrix}$$

$$IA^{-1} = \begin{bmatrix} 0 & -2/3 & 1/3 \\ 6/3 & 1/3 & -5/3 \\ -3/3 & 0 & 3/3 \end{bmatrix} \quad \therefore \quad A^{-1} = \frac{1}{3} \begin{bmatrix} 0 & -2 & 1 \\ 6 & 1 & -5 \\ -3 & 0 & 3 \end{bmatrix}$$

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THANKYOU

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