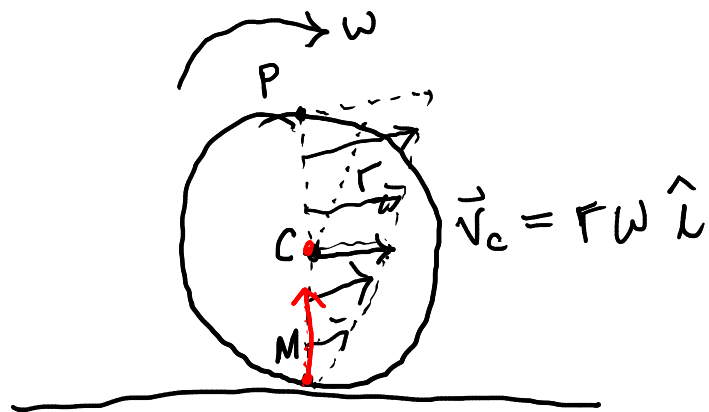


TAM 212

Summary: rolling on a flat surface

velocities



$$\begin{aligned}\vec{v}_M &= 0 \\ \vec{v}_c &= r\omega \hat{l} \\ \vec{v}_p &= 2\vec{v}_c = 2r\omega \hat{l}\end{aligned}$$

constant $\vec{\omega} = -\omega \hat{k}$; $\vec{\alpha} = -\alpha \hat{k} = 0$
rolling is in direction of \vec{v}_c

accelerations

$$\vec{a}_c = \frac{d}{dt} \vec{v}_c = 0$$

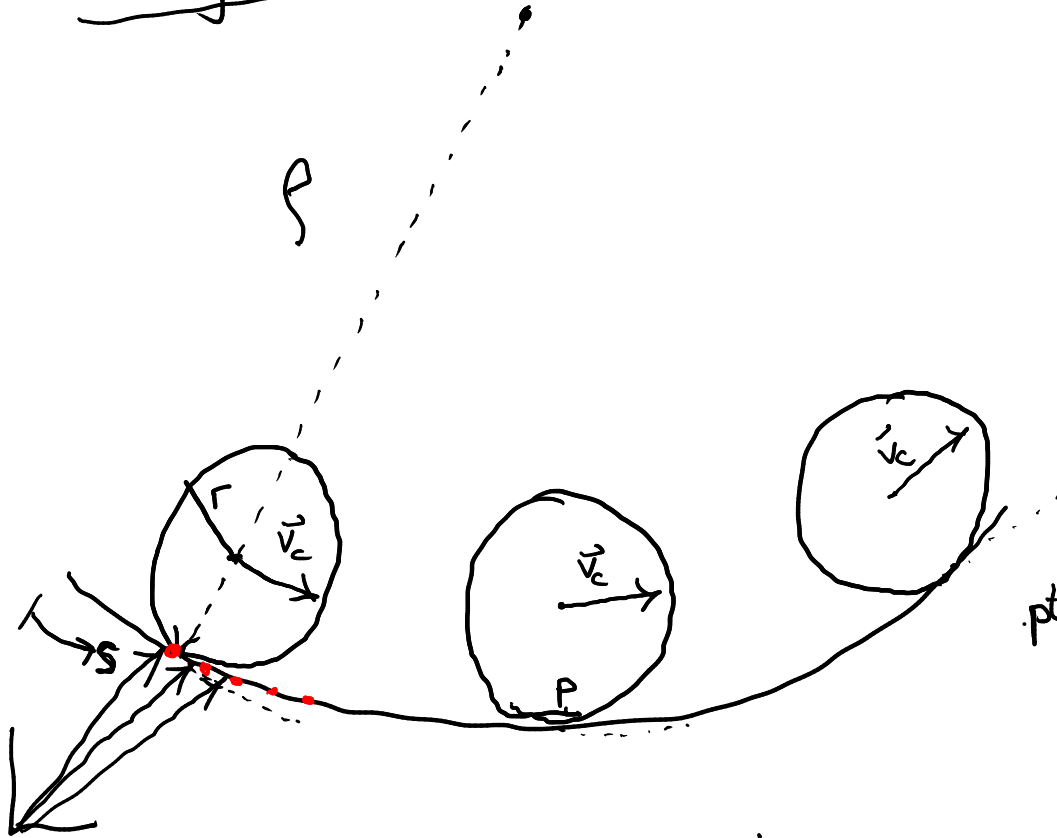
\vec{a}_M = acceleration of the instantaneous center

is it (A) zero

(B) non-zero

$$\vec{a}_M = r\omega^2 \hat{j}$$

Rolling on A Curved Surface



$$\vec{\omega} = -\omega \hat{k}$$

$$\vec{\alpha} = -\alpha \hat{k}$$

r = radius of wheel

ρ = radius of curved surface

pt P = point on wheel in contact w/ ground

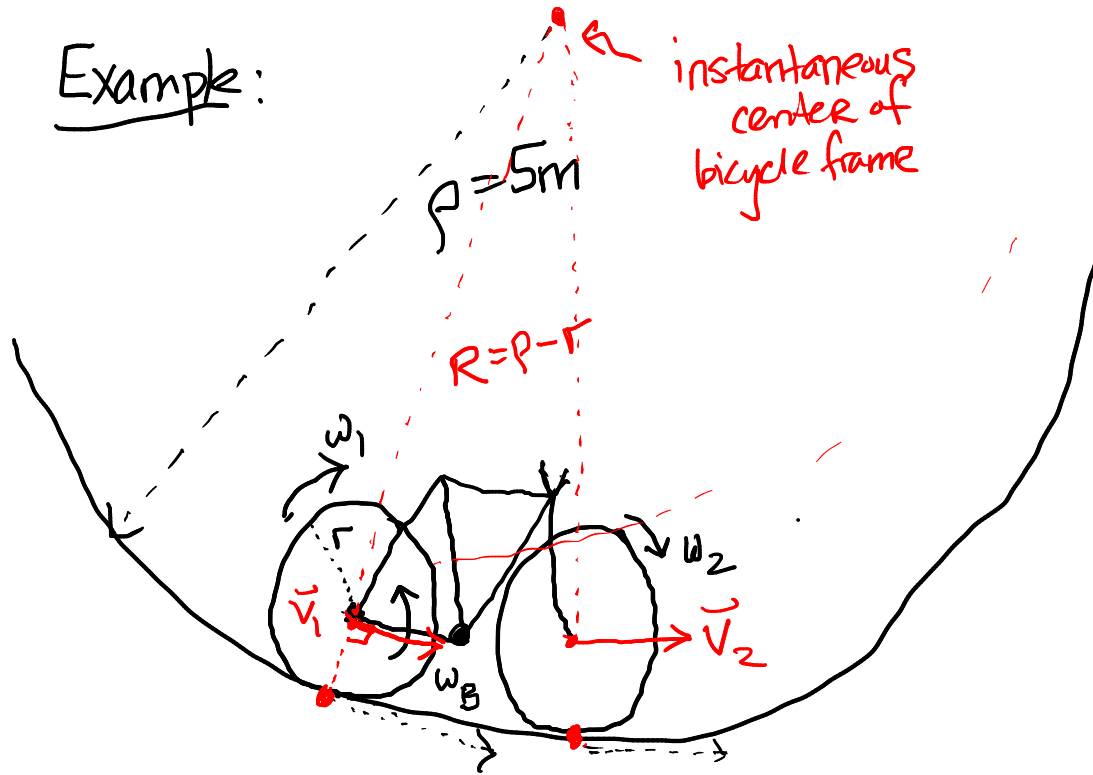
$\vec{r}_M(t)$ = path traced out by instantaneous center M

$$\vec{v}_M(t) = \frac{d\vec{r}_M}{dt} = \dot{s} \hat{e}_t$$

$$\vec{a}_M(t) = \frac{d\vec{v}_M}{dt} = \ddot{s} \hat{e}_t + \frac{(\dot{s})^2}{\rho} \hat{e}_n$$

} Recall tangential / normal coordinates

Example:



velocities

Find: Relationship between $\omega_1, \omega_2, \omega_B$
 $\vec{v}_{C1}, \vec{v}_{C2}, \vec{v}_B$

Bicycle on a Half Pipe

$$\rho = 5\text{m}$$

$$r = 0.5\text{m}$$

$$\omega_B = \frac{v_1}{\rho - r}$$