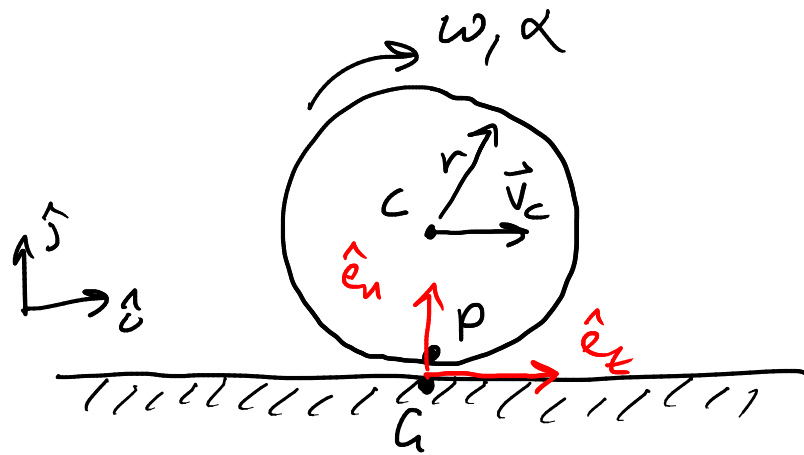


Rolling motion



$$\vec{v}_Q = \vec{v}_P + \vec{\omega} \times \vec{r}_{PQ}$$

$$\vec{v}_C = \cancel{\vec{v}_P} + \vec{\omega} \times \vec{r}_{PC}$$

$$v_C \hat{e}_t = -\omega \hat{k} \times (r \hat{e}_n)$$

$$= r\omega \hat{e}_t$$

$$v_C = r\omega$$

$$v_P = 0$$

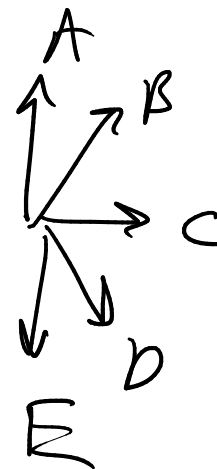
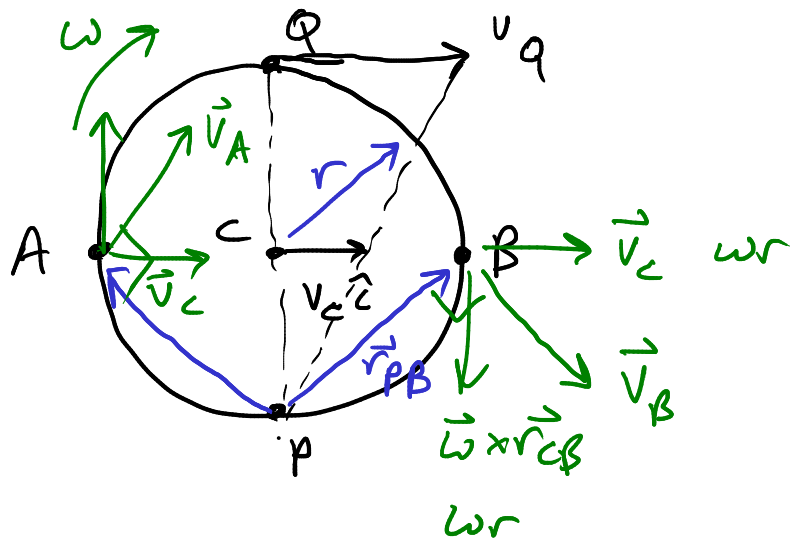
$$\vec{\omega} = -\omega \hat{k}$$

$$\vec{\alpha} = -\alpha \hat{k}$$

rolling vs skidding
= relative motion of P & G.

rolling \Rightarrow no slip between P & G
 $\Rightarrow \vec{v}_P = \vec{v}_G = 0$

\Rightarrow points of contact
have zero relative
velocity.



$$\vec{v}_Q ?$$

$$\vec{v}_B ? = \vec{v}_C + \vec{\omega} \times \vec{r}_{CB}$$

$$= \vec{\omega} \times \vec{r}_{PB}$$

$$\vec{v}_A ?$$

$$\vec{v}_Q = \vec{v}_C + \vec{\omega} \times \vec{r}_{CQ}$$

$$\vec{v}_Q = \vec{v}_P + \vec{\omega} \times \vec{r}_{PQ}$$

