

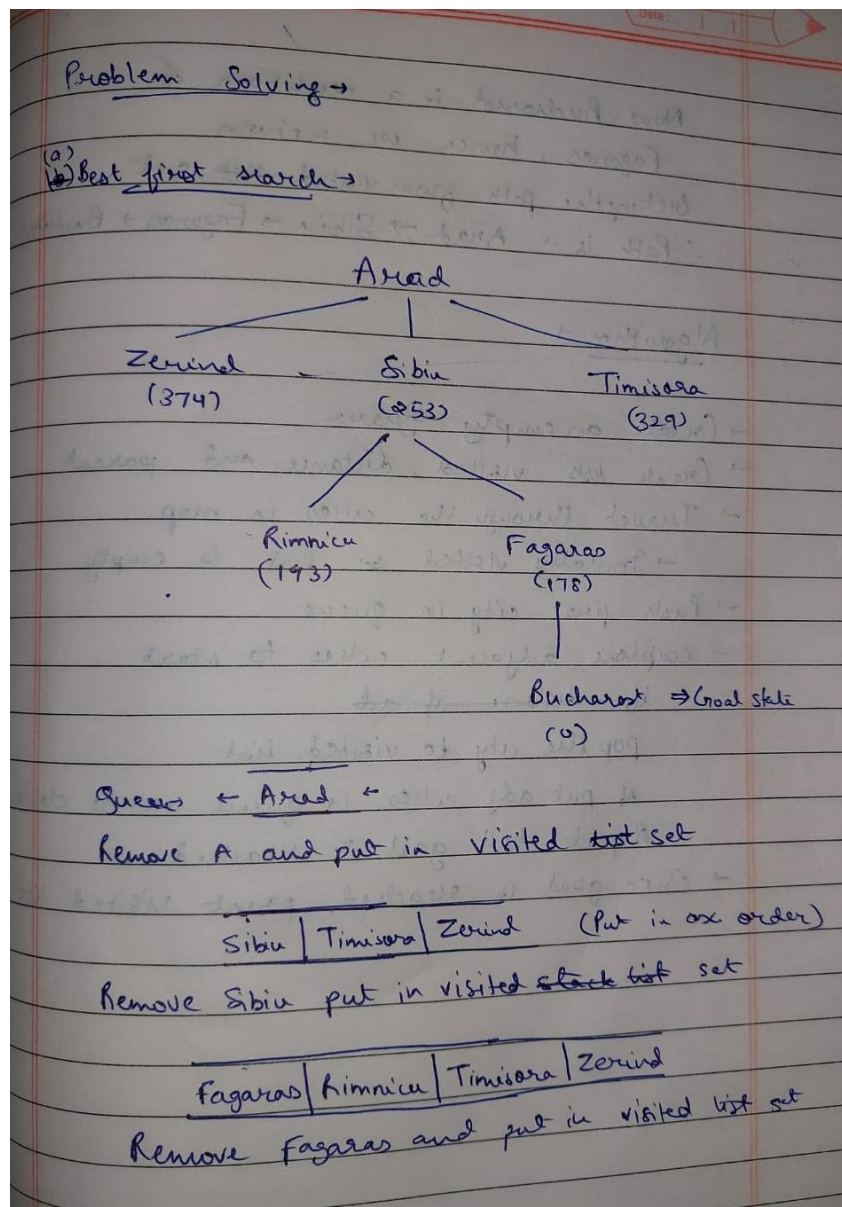
Prajwal Gupta

RA1911003010660

AI LAB 5

Aim- (A) Developing Best first search Algorithm for real world problems

Problem formulation → Developing Best first search and A* algorithm for real world problems.
Given a city map.
Find the path from Arad to Bucharest using BFS and A* algorithm



Now Bucharest is a neighbour of Fagaras, hence we return creating the path from visited ~~list~~ set
∴ Path is → Arad → Sibiu → Fagaras → Bucharest

Algorithm →

- Create an empty Queue
- Create lists visited, distance and parent
- Travel through the cities in map
 - Initially visited ~~to~~ list is empty
- Push first city in queue
- explore adjacent cities to start
 - if distance of adj
 - pop the city to visited list
 - put adj cities in queue acc. to distance
- Repeat till goal is reached
- Once goal is reached, print visited list

Code-

```
from queue import Queue
```

```
romaniaMap = {
```

```
    'Arad': ['Sibiu', 'Zerind', 'Timisoara'],
```

```
    'Zerind': ['Arad', 'Oradea'],
```

```
    'Oradea': ['Zerind', 'Sibiu'],
```

```
    'Sibiu': ['Arad', 'Oradea', 'Fagaras', 'Rimnicu'],
```

```
    'Timisoara': ['Arad', 'Lugoj'],
```

```
    'Lugoj': ['Timisoara', 'Mehadia'],
```

```
    'Mehadia': ['Lugoj', 'Drobeta'],
```

```
    'Drobeta': ['Mehadia', 'Craiova'],
```

```
    'Craiova': ['Drobeta', 'Rimnicu', 'Pitesti'],
```

```
    'Rimnicu': ['Sibiu', 'Craiova', 'Pitesti'],
```

```
'Fagaras': ['Sibiu', 'Bucharest'],
'Pitesti': ['Rimnicu', 'Craiova', 'Bucharest'],
'Bucharest': ['Fagaras', 'Pitesti', 'Giurgiu', 'Urziceni'],
'Giurgiu': ['Bucharest'],
'Urziceni': ['Bucharest', 'Vaslui', 'Hirsova'],
'Hirsova': ['Urziceni', 'Eforie'],
'Eforie': ['Hirsova'],
'Vaslui': ['Iasi', 'Urziceni'],
'Iasi': ['Vaslui', 'Neamt'],
'Neamt': ['Iasi']
}
```

```
def bfs(startingNode, destinationNode):
    # For keeping track of what we have visited
    visited = {}
    # keep track of distance
    distance = {}
    # parent node of specific graph
    parent = {}

    bfs_traversal_output = []
    # BFS is queue based so using 'Queue' from python built-in
    queue = Queue()

    # travelling the cities in map
    for city in romaniaMap.keys():
        # since initially no city is visited so there will be nothing in visited list
        visited[city] = False
        parent[city] = None
        distance[city] = -1

    # starting from 'Arad'
    startingCity = startingNode
```

```

visited[startingCity] = True
distance[startingCity] = 0
queue.put(startingCity)

while not queue.empty():
    u = queue.get()    # first element of the queue, here it will be 'arad'
    bfs_traversal_output.append(u)

    # explore the adjacent cities adj to 'arad'
    for v in romaniaMap[u]:
        if not visited[v]:
            visited[v] = True
            parent[v] = u
            distance[v] = distance[u] + 1
            queue.put(v)

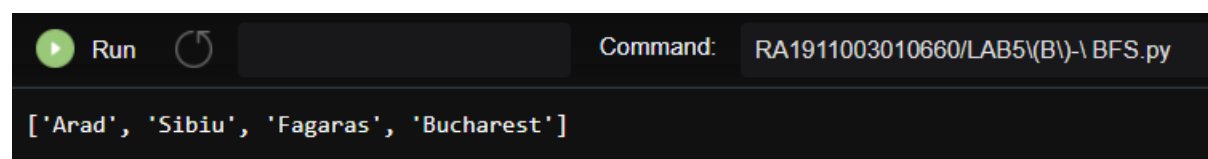
    # reaching our destination city i.e 'bucharest'
    g = destinationNode
    path = []
    while g is not None:
        path.append(g)
        g = parent[g]

    path.reverse()
    # printing the path to our destination city
    print(path)
    # print(distance)

# Starting City & Destination City
bfs('Arad', 'Bucharest')

```

Output-



The screenshot shows a code execution interface with a dark background. At the top, there is a 'Run' button with a green play icon and a circular arrow icon. To the right of the 'Run' button is a text field containing the command 'RA1911003010660/LAB5\B\BFS.py'. Below the 'Run' button, the output of the program is displayed in a monospaced font: ['Arad', 'Sibiu', 'Fagaras', 'Bucharest'].

```

Run Command: RA1911003010660/LAB5\B\BFS.py
['Arad', 'Sibiu', 'Fagaras', 'Bucharest']

```

Aim- (B) Developing A* Algorithm for real world problems

Problem Solving

(b) A* $\rightarrow f(N) = g(N) + h(N)$

here $g(N)$ is given in map and
 $h(N)$ is straight line dist

$$f(\text{Arad}) = 0 + 366 = 366$$

$$f(\text{Arad} \rightarrow \text{Zerind}) = 75 + 374 = 449$$

$$f(\text{Arad} \rightarrow \text{Timisoara}) = 118 + 329 = 447$$

$$f(\text{Arad} \rightarrow \text{Sibu}) = 140 + 253 = 296$$

\rightarrow hence Arad \rightarrow Sibiu path will be followed

$$f(\text{Arad} \rightarrow \text{Sibu} \rightarrow \text{Fagaras}) = 140 + 99 + 178 = 417$$

$$f(\text{Arad} \rightarrow \text{Sibu} \rightarrow \text{Rimnicu}) = 140 + 80 + 193 = 413$$

$$f(\text{Arad} \rightarrow \text{Sibu} \rightarrow \text{Oradea}) = 140 + 151 + 380 = 671$$

\rightarrow hence Arad \rightarrow Sibiu \rightarrow Rimnicu Vilcea path is followed

$$f(A \rightarrow S \rightarrow R \rightarrow \text{Hiriova}) = 140 + 80 + 146 + 160 = 526$$

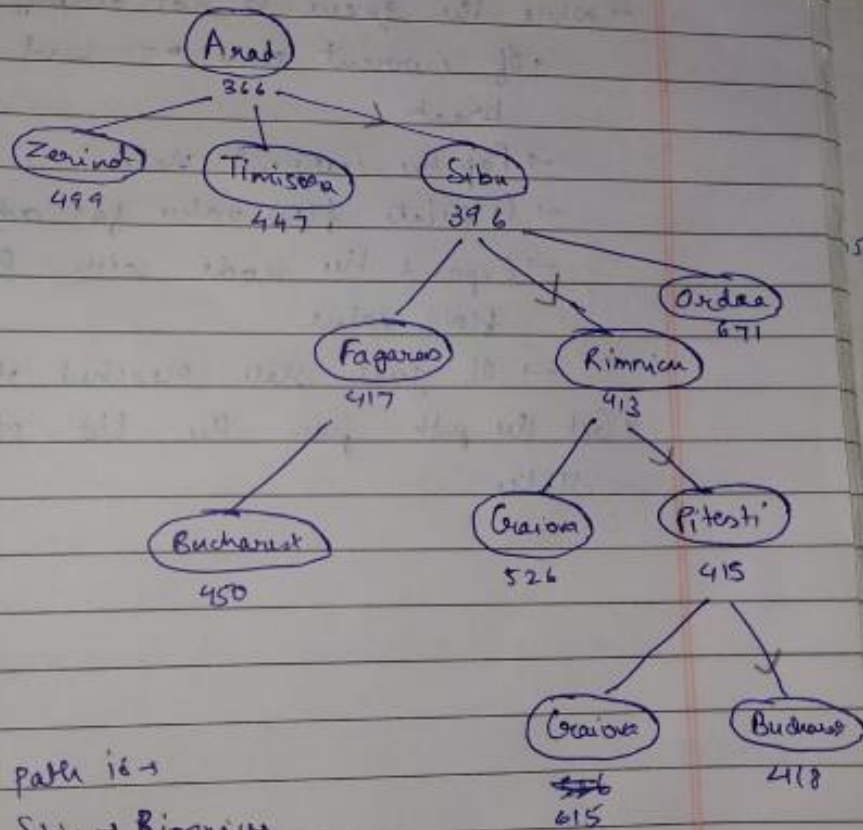
$$f(A \rightarrow S \rightarrow R \rightarrow \text{Pitesti}) = 140 + 80 + 97 + 98 = 415$$

\rightarrow hence Arad \rightarrow Sibiu \rightarrow Rimnicu \rightarrow Pitesti is followed

$$f(A \rightarrow S \rightarrow R \rightarrow P \rightarrow \text{Oradea}) = 140 + 80 + 97 + 138 + 160 = 615$$

$$f(A \rightarrow S \rightarrow R \rightarrow P \rightarrow \text{Bucharest}) = 140 + 80 + 97 + 101 + 0 = 418$$

Hence we reached Bucharest through Pitesti;



Hence path is →

Arad → Sibiu → Rimnicu

Bucharest ← Pitesti ←

Algorithm →

- Make a priority queue
- Push the initial state
- While the queue is not empty
 - If current state == end state then break
 - Pop the current state
 - Calculate $f(N)$ value for adjacent states
 - Expand the node with least $f(N)$ value
 - If goal state reached, stop
- Get the path from the list of popped states

Code-

```
import heapq
```

```
class priorityQueue:
```

```
    def __init__(self):
```

```
        self.cities = []
```

```
    def push(self, city, cost):
```

```
        heapq.heappush(self.cities, (cost, city))
```

```
    def pop(self):
```

```
        return heapq.heappop(self.cities)[1]
```

```
    def isEmpty(self):
```

```
        if (self.cities == []):
```

```
            return True
```

```
else:  
    return False
```

```
def check(self):  
    print(self.cities)
```

```
class ctNode:  
    def __init__(self, city, distance):  
        self.city = str(city)  
        self.distance = str(distance)
```

```
romania = {}
```

```
def makedict():  
    file = open("RA1911003010660/LAB5-a.txt", 'r')  
    for string in file:  
        line = string.split(',')  
        ct1 = line[0]  
        ct2 = line[1]  
        dist = int(line[2])  
        romania.setdefault(ct1, []).append(ctNode(ct2, dist))  
        romania.setdefault(ct2, []).append(ctNode(ct1, dist))
```

```
def makehuristikdict():  
    h = {}  
    with open("RA1911003010660/LAB5-b.txt", 'r') as file:  
        for line in file:  
            line = line.strip().split(",")  
            node = line[0].strip()
```



```
sld = int(line[1].strip())  
h[node] = sld  
return h
```

```
def heuristic(node, values):  
    return values[node]
```

```
def astar(start, end):  
    path = {}  
    distance = {}  
    q = priorityQueue()  
    h = makeheuristicdict()  
  
    q.push(start, 0)  
    distance[start] = 0  
    path[start] = None  
    expandedList = []  
  
    while (q.isEmpty() == False):  
        current = q.pop()  
        expandedList.append(current)  
  
        if (current == end):  
            break  
  
        for new in romania[current]:  
            g_cost = distance[current] + int(new.distance)  
  
            # print(new.city, new.distance, "now : " + str(distance[current]), g_cost)  
  
            if (new.city not in distance or g_cost < distance[new.city]):
```

```

distance[new.city] = g_cost
f_cost = g_cost + heuristic(new.city, h)
q.push(new.city, f_cost)
path[new.city] = current

```

```

printoutput(start, end, path, distance, expandedList)

```

```

def printoutput(start, end, path, distance, expandedlist):

```

```

    finalpath = []

```

```

    i = end

```

```

    while (path.get(i) != None):

```

```

        finalpath.append(i)

```

```

        i = path[i]

```

```

    finalpath.append(start)

```

```

    finalpath.reverse()

```

```

    print("Program algoritma Astar on Romania Map")

```

```

    print("\tArad => Bucharest")

```

```

    print("=====")

```

```

    print("Path \t\t: " + str(expandedlist))

```

```

    print("Stops \t\t: " + str(len(expandedlist)))

```

```

    print("=====")

```

```

    print("Path\t: " + str(finalpath))

```

```

    print("Stops \t\t\t: " + str(len(finalpath)))

```

```

    print("Total distance \t\t\t\t\t: " + str(distance[end]))

```

```

def main():

```

```

    src = "Arad"

```

```

    dst = "Bucharest"

```

```

    makedict()

```

```

    astar(src, dst)

```

```

if __name__ == "__main__":

```

```

    main()

```

Output-

```
Run Command: RA1911003010660/LAB5(AI)-\AI\star.py

Program algoritma Astar on Romania Map
  Arad => Bucharest
=====
Path      : ['Arad', 'Sibiu', 'Rimnicu Vilcea', 'Fagaras', 'Pitesti', 'Bucharest']
Stops     : 6
=====
Path      : ['Arad', 'Sibiu', 'Rimnicu Vilcea', 'Pitesti', 'Bucharest']
Stops     : 5
Total distance      : 418
```