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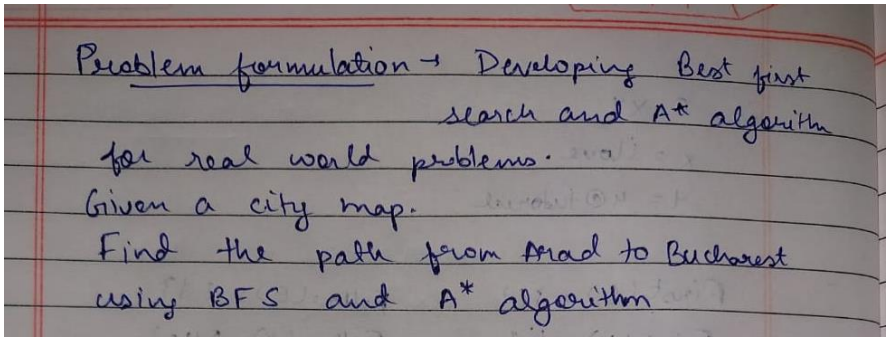
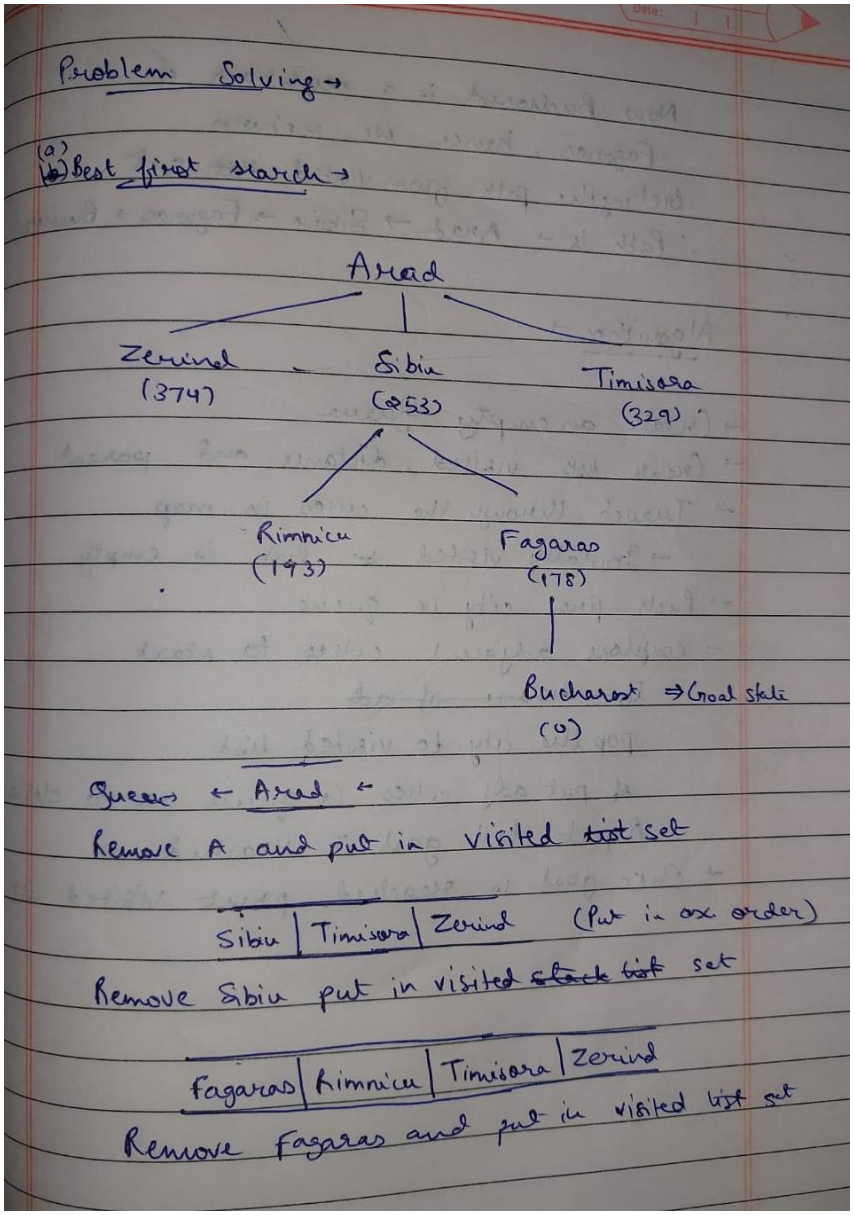
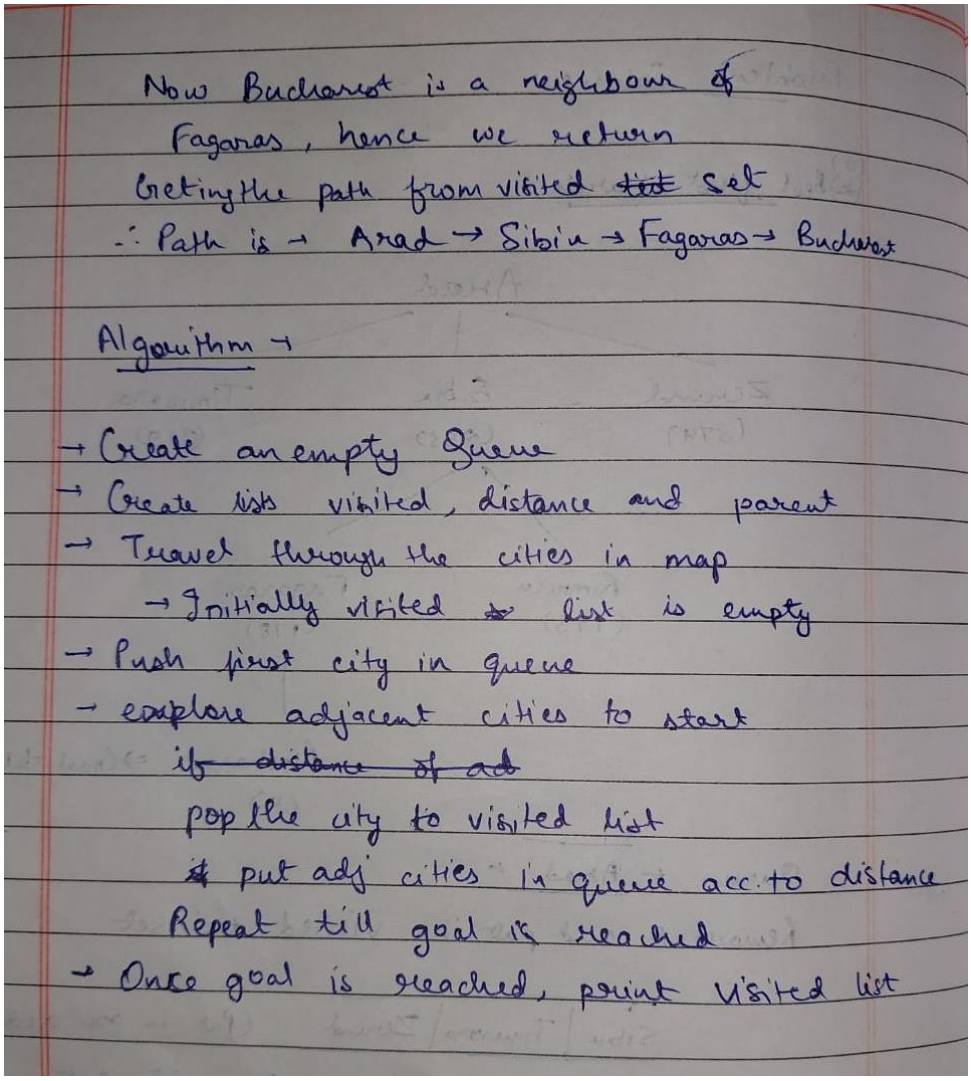
AI LAB 5

Aim- (A) Developing Best first search Algorithm for real world problems







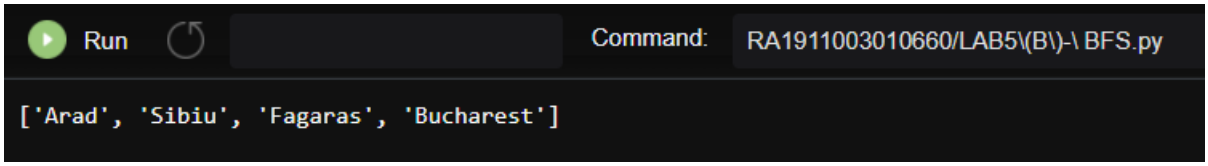
Code-

```
from queue import Queue

romaniaMap = {
    'Arad': ['Sibiu', 'Zerind', 'Timisoara'],
    'Zerind': ['Arad', 'Oradea'],
    'Oradea': ['Zerind', 'Sibiu'],
    'Sibiu': ['Arad', 'Oradea', 'Fagaras', 'Rimnicu'],
    'Timisoara': ['Arad', 'Lugoj'],
    'Lugoj': ['Timisoara', 'Mehadia'],
    'Mehadia': ['Lugoj', 'Drobeta'],
    'Drobeta': ['Mehadia', 'Craiova'],
    'Craiova': ['Drobeta', 'Rimnicu', 'Pitesti'],
    'Rimnicu': ['Sibiu', 'Craiova', 'Pitesti'],
```

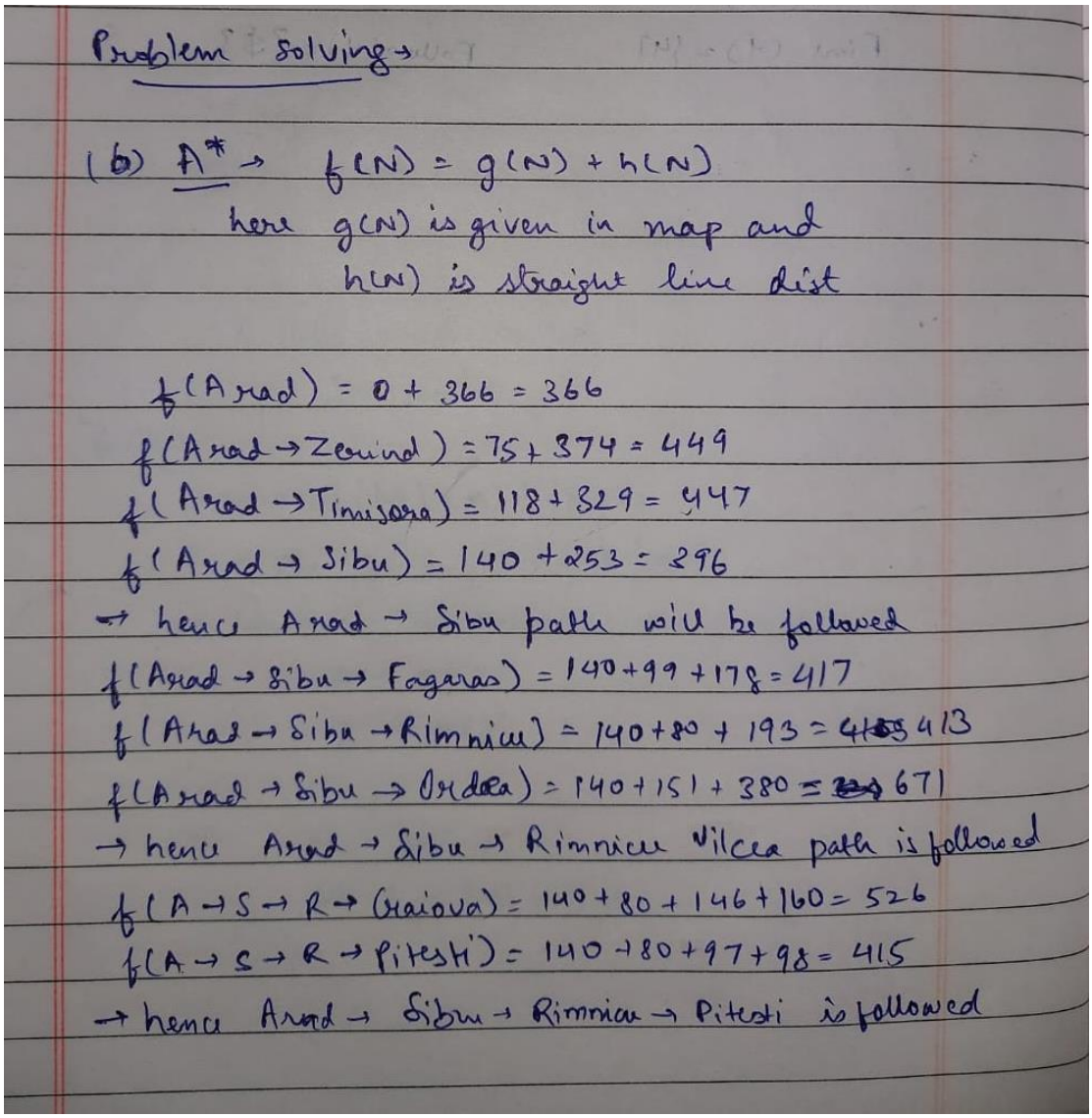
```
    'Fagaras': ['Sibiu', 'Bucharest'],
    'Pitesti': ['Rimnicu', 'Craiova', 'Bucharest'],
    'Bucharest': ['Fagaras', 'Pitesti', 'Giurgiu', 'Urziceni'],
    'Giurgiu': ['Bucharest'],
    'Urziceni': ['Bucharest', 'Vaslui', 'Hirsova'],
    'Hirsova': ['Urziceni', 'Eforie'],
    'Eforie': ['Hirsova'],
    'Vaslui': ['Iasi', 'Urziceni'],
    'Iasi': ['Vaslui', 'Neamt'],
    'Neamt': ['Iasi']
}

def bfs(startingNode, destinationNode):
    # For keeping track of what we have visited
    visited = {}
    # keep track of distance
    distance = {}
    # parent node of specific graph
    parent = {}

    bfs_traversal_output = []
    # BFS is queue based so using 'Queue' from python built-in
    queue = Queue()

    # travelling the cities in map
    for city in romaniaMap.keys():
        # since intially no city is visited so there will be nothing in visited list
        visited[city] = False
        parent[city] = None
        distance[city] = -1

    # starting from 'Arad'
    startingCity = startingNode
```

```
    visited[startingCity] = True
    distance[startingCity] = 0
    queue.put(startingCity)

    while not queue.empty():
        u = queue.get()     # first element of the queue, here it will be 'arad'
        bfs_traversal_output.append(u)

        # explore the adjust cities adj to 'arad'
        for v in romaniaMap[u]:
            if not visited[v]:
                visited[v] = True
                parent[v] = u
                distance[v] = distance[u] + 1
                queue.put(v)

        # reaching our destination city i.e 'bucharest'
    g = destinationNode
    path = []
    while g is not None:
        path.append(g)
        g = parent[g]

    path.reverse()
    # printing the path to our destination city
    print(path)
    # print(distance)
# Starting City & Destination City
bfs('Arad', 'Bucharest')
```

Output-



Aim- (B) Developing A* Algorithm for real world problems



Problem solving →

(b) A* → f(N) = g(N) + h(N)

here g(N) is given in map and
h(N) is straight line dist

f(Arad) = 0 + 366 = 366

f(Arad → Zerind) = 75 + 374 = 449

f(Arad → Timisoara) = 118 + 329 = 447

f(Arad → Sibu) = 140 + 253 = 296

→ hence Arad → Sibu path will be followed

f(Arad → Sibu → Fagaras) = 140 + 99 + 178 = 417

f(Arad → Sibu → Rimnicu) = 140 + 80 + 193 = 413

f(Arad → Sibu → Oradea) = 140 + 151 + 380 = 671

→ hence Arad → Sibu → Rimnicu Vilcea path is followed

f(A → S → R → Craiova) = 140 + 80 + 146 + 160 = 526

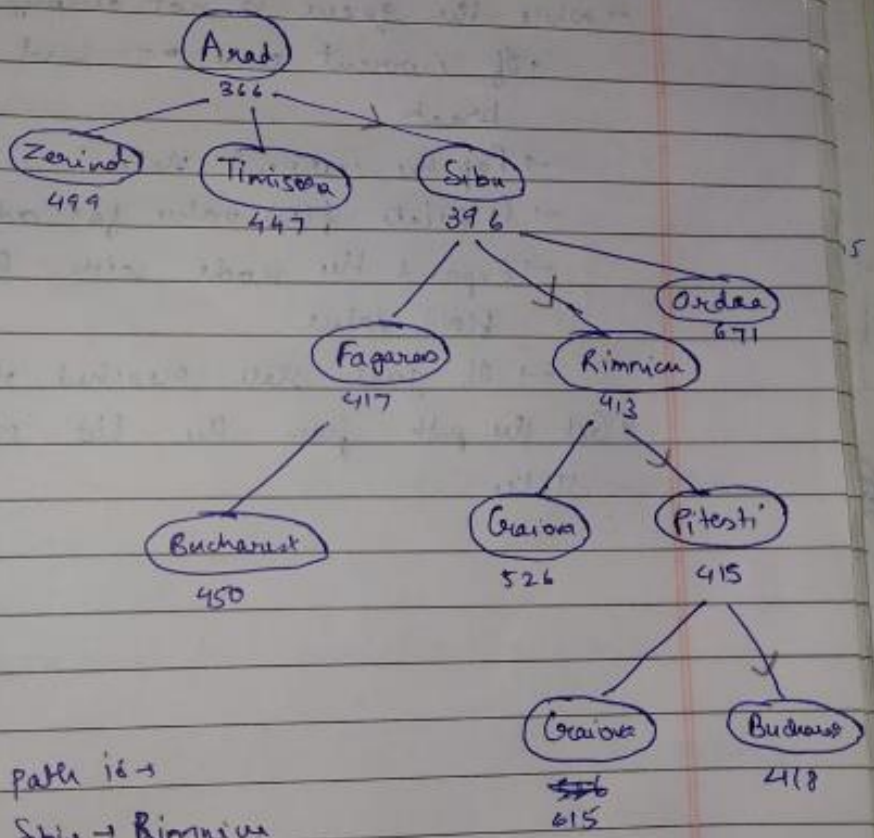
f(A → S → R → Pitesti) = 140 + 80 + 97 + 98 = 415

→ hence Arad → Sibu → Rimnicu → Pitesti is followed

f(A → S → R → P → Craiova) = 140 + 80 + 97 + 138 + 160 = 615

f(A → S → R → P → Bucharest) = 140 + 80 + 97 + 101 + 0 = 418

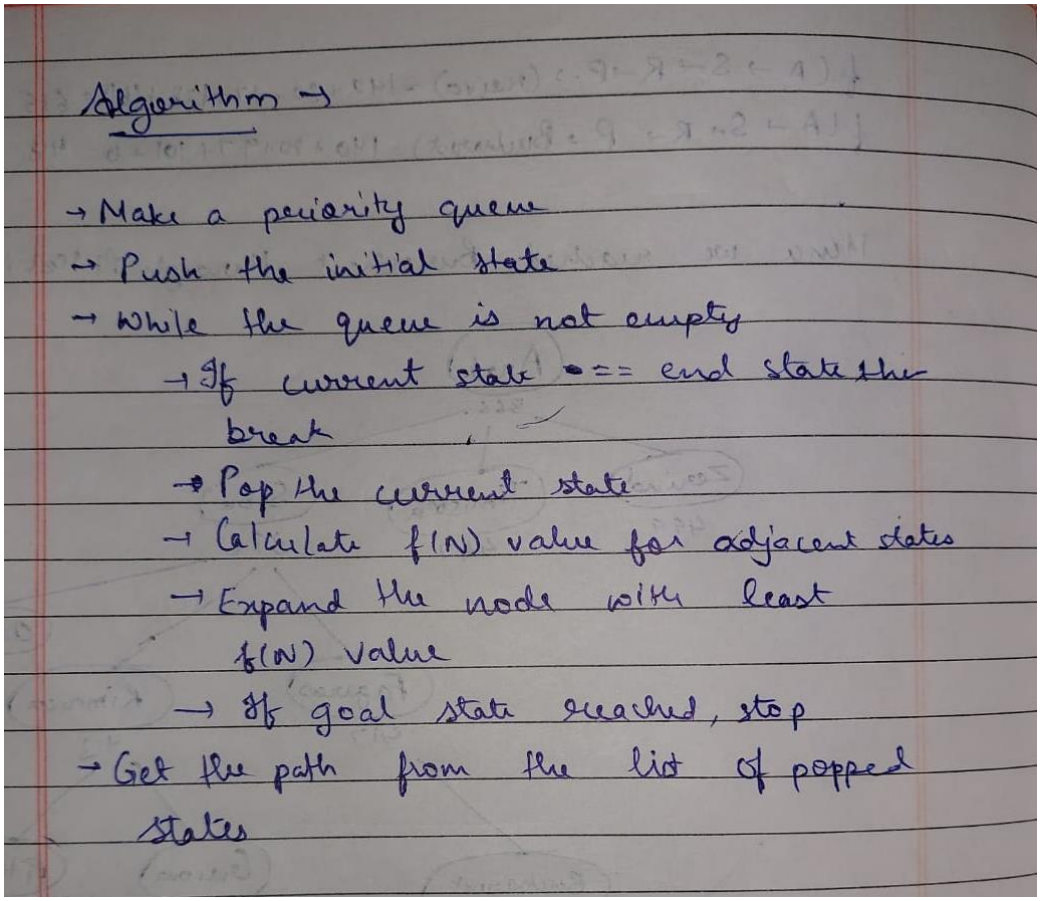
Hence we reached Bucharest through Pitesti



Hence path is →

Arad → Sibiu → Rimnicu

Bucharest ← Pitesti ↵



Code-

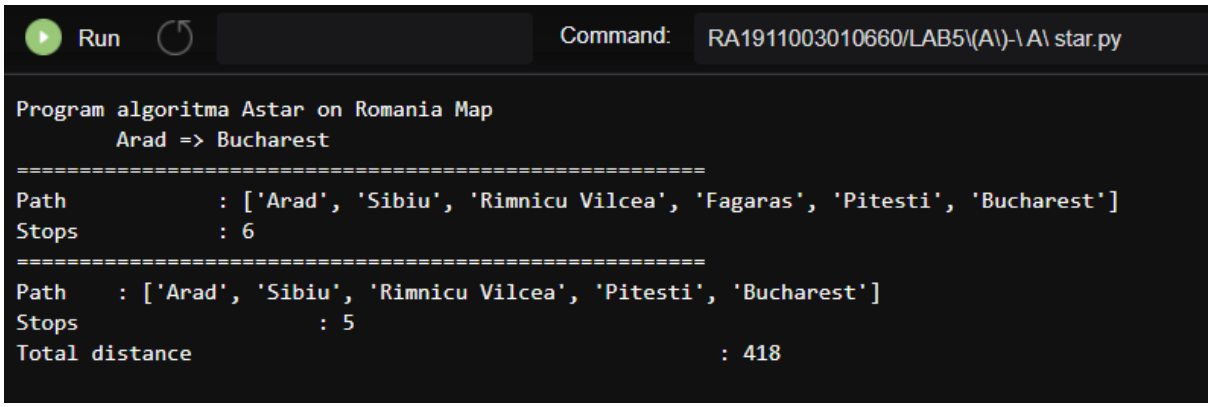
```
import heapq



class priorityQueue:
    def __init__(self):
        self.cities = []

    def push(self, city, cost):
        heapq.heappush(self.cities, (cost, city))

    def pop(self):
        return heapq.heappop(self.cities)[1]

    def isEmpty(self):
        if (self.cities == []):
            return True
```

```
        else:
            return False

    def check(self):
        print(self.cities)


class ctNode:
    def __init__(self, city, distance):
        self.city = str(city)
        self.distance = str(distance)


romania = {}


def makedict():
    file = open("RA1911003010660/LAB5-a.txt", 'r')
    for string in file:
        line = string.split(',')
        ct1 = line[0]
        ct2 = line[1]
        dist = int(line[2])
        romania.setdefault(ct1, []).append(ctNode(ct2, dist))
        romania.setdefault(ct2, []).append(ctNode(ct1, dist))


def makehuristikdict():
    h = {}
    with open("RA1911003010660/LAB5-b.txt", 'r') as file:
        for line in file:
            line = line.strip().split(",")
            node = line[0].strip()
```

```
            sld = int(line[1].strip())
            h[node] = sld
    return h


def heuristic(node, values):
    return values[node]


def astar(start, end):
    path = {}
    distance = {}
    q = priorityQueue()
    h = makehuristikdict()

    q.push(start, 0)
    distance[start] = 0
    path[start] = None
    expandedList = []

    while (q.isEmpty() == False):
        current = q.pop()
        expandedList.append(current)

        if (current == end):
            break

        for new in romania[current]:
            g_cost = distance[current] + int(new.distance)

            # print(new.city, new.distance, "now : " + str(distance[current]), g_cost)

            if (new.city not in distance or g_cost < distance[new.city]):
```

```
                distance[new.city] = g_cost
                f_cost = g_cost + heuristic(new.city, h)
                q.push(new.city, f_cost)
                path[new.city] = current

    printoutput(start, end, path, distance, expandedList)

def printoutput(start, end, path, distance, expandedlist):
    finalpath = []
    i = end

    while (path.get(i) != None):
        finalpath.append(i)
        i = path[i]
    finalpath.append(start)
    finalpath.reverse()
    print("Program algoritma Astar on Romania Map")
    print("\tArad => Bucharest")
    print("=====================================================")
    print("Path \t\t: " + str(expandedlist))
    print("Stops \t\t: " + str(len(expandedlist)))
    print("=====================================================")
    print("Path\t: " + str(finalpath))
    print("Stops \t\t\t: " + str(len(finalpath)))
    print("Total distance \t\t\t\t\t: " + str(distance[end]))

def main():
    src = "Arad"
    dst = "Bucharest"
    makedict()
    astar(src, dst)
if __name__ == "__main__":
    main()
```

Output-


Run
Command:
RA1911003010660/LAB5\(A\)-\ A\ star.py
Program algoritma Astar on Romania Map
Arad => Bucharest
Path : ['Arad', 'Sibiu', 'Rimnicu Vilcea', 'Fagaras', 'Pitesti', 'Bucharest']
Stops : 6
Path : ['Arad', 'Sibiu', 'Rimnicu Vilcea', 'Pitesti', 'Bucharest']
Stops : 5
Total distance : 418