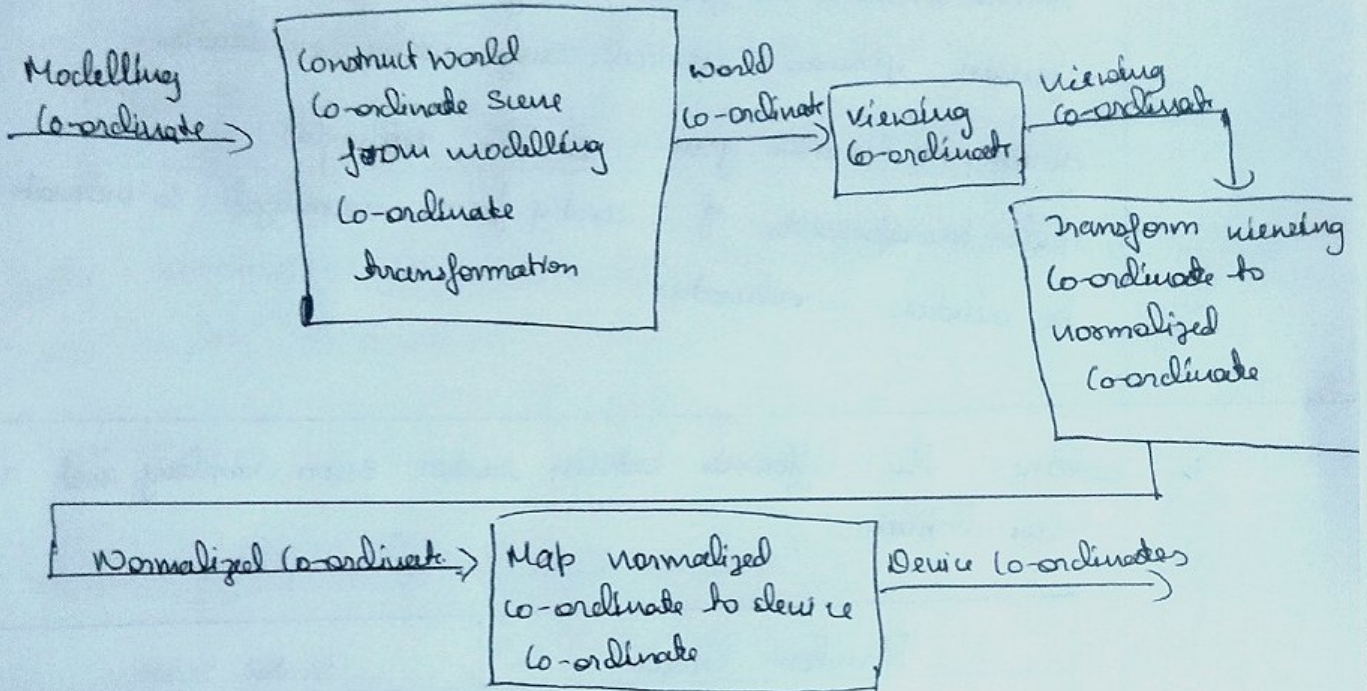


## Assignment

1. Build 2D viewing transformation pipelines and also explain open GL 2D viewing functions



change modelling co-ordinate to world co-ordinate by applying modelling transformation. change world co-ordinate to viewing co-ordinate by determining visible parts. change viewing co-ordinate to normalized co-ordinates and further to device co-ordinate by clipping and determining pixels

### OpenGL 2D viewing functions

gl sets the current matrix mode

gl can assume one of the two values

### GL Modelview

Applies subsequent matrix operations to model view matrix stack.



## GL - PROJECTION

Applies subsequent matrix operation to projection matrix stack

gluortho 2D (xumin, xumax, yumin, yumax);  $\frac{3}{2}$

specifies the viewing window

xumin, xumax: horizontal range, world co-ordinates

yumin, yumax: vertical range, world co-ordinates

gluviewport (xumin, yumin, width, height)

defines transformation of x and y from normalized co-ordinate

to window co-ordinates

4. Outline the differences between raster scan display and random scan displays.

Random Scan	Raster scan
The resolution of Random scan is higher than raster scan	while the resolution of raster scan is lower than random scan
It is costlier than raster scan	cost is lesser
raster scan alteration is easy in comparison of raster scan	any alteration is not easy



Intersecting is not used	Intersecting is used
It is suitable for applications requiring polygon drawing	It is suitable for creating realistic scenes

3. Apply homogeneous co-ordinates for translation, rotation and scaling via matrix representation

1. Translation  $P = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} + \begin{bmatrix} x_2 \\ y_2 \end{bmatrix}$

rotation  $P' = \begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} \cos \theta & \sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \end{bmatrix}$

Scaling  $P' = \begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} s_x & 0 \\ 0 & s_y \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \end{bmatrix}$

each cartesian co-ordinate  $(x, y)$  with homogeneous co-ordinates  $(x_n, y_n, h)$  where  $x = x_n/h, y = y_n/h$

$$(h^x x, h^y y, h)$$

set  $h=1$

$$(x, y, 1)$$

Homogeneous co-ordinate representation for translation, rotation, scaling and rotation are as follows

$$\begin{bmatrix} x' \\ y' \\ 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & t_x \\ 0 & 1 & t_y \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ 1 \end{bmatrix}$$

$$\begin{bmatrix} x' \\ y' \\ 1 \end{bmatrix} = \begin{bmatrix} s_x & 0 & 0 \\ 0 & s_y & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ 1 \end{bmatrix}$$

$$\begin{bmatrix} x' \\ y' \\ 1 \end{bmatrix} = \begin{bmatrix} \cos \theta & -\sin \theta & 0 \\ \sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ 1 \end{bmatrix}$$

→ explain Bezier curve equation along with properties.

\* For  $N+1$  control-point positions, denoted as  $p_k = (x_k, y_k, z_k)$  with  $k$  varying from 0 to  $n$ . These co-ordinate points are blended to produce position vector  $P(u)$ , which describes the path of an approximating Bezier polynomial function between  $p_0$  and  $p_n$ .

$$P(u) = \sum_{k=0}^n p_k B_{k,n}(u), 0 \leq u \leq 1$$

$$B_{k,n}(u) = C(n, k) u^k (1-u)^{n-k}$$

$$C(n, k) = \frac{n!}{k!(n-k)!}$$

eqn  $P(u)$  represents a set of three parametric equations for the individual curve co-ordinates



$$z_p = z \left( \frac{z_{vp}}{z} \right)$$

$$y_p = y \left( \frac{z_{vp}}{z} \right)$$

→ If the view plane is the  $w$  plane and there are no restrictions on the placement of the projection reference point, then we have

$$z_{vp} = 0$$

$$x_p = x \left( \frac{z_{pnp}}{z_{pnp} - z} \right) - x_{pnp} \left( \frac{z}{z_{pnp} - z} \right)$$

$$y_p = y \left( \frac{z_{pnp}}{z_{pnp} - z} \right) - y_{pnp} \left( \frac{z}{z_{pnp} - z} \right)$$

→ With  $w$  plane as the view plane and the projection reference point on the  $z$  view axis, the perspective equations are

$$x_{pnp} = y_{pnp} = z_{pnp} = 0$$

$$x_p = x \left( \frac{z_{pnp}}{z_{pnp} - z} \right)$$

$$y_p = y \left( \frac{z_{pnp}}{z_{pnp} - z} \right)$$

→ explain open  $gl$  visibility selection function

$glCull (GL\_CULL\_FACE)$



$$x(u) = \sum_{k=0}^n x_k \text{BEZ}_{k,n}(u)$$

$$y(u) = \sum_{k=0}^n y_k \text{BEZ}_{k,n}(u)$$

$$z(u) = \sum_{k=0}^n z_k \text{BEZ}_{k,n}(u)$$

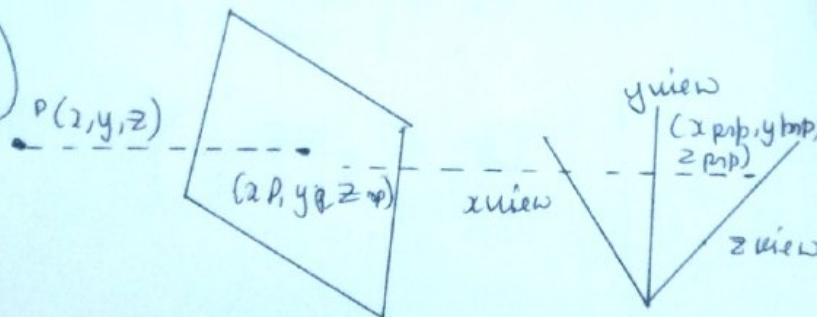
In most cases, a Bezier curve is a polynomial of degree that is one less than designated number of control points. Three points generate a parabola, four points a cubic curve and so forth.

→ write the special cases that we discussed with regards to perspective projection transformation to coordinate

\* if projection reference point is on z view, means  $x_{prp} = y_{prp} = 0$

$$x_p = x \left( \frac{z_{prp} - z_{vp}}{z_{prp} - z} \right)$$

$$y_p = y \left( \frac{z_{prp} - z_{vp}}{z_{prp} - z} \right)$$



z. The projection reference point is fixed at the co-ordinate origin, and

$$(x_{prp}, y_{prp}, z_{prp}) = (0, 0, 0)$$



It is used for turning culling on  
glCullMode (mode)

It specifies what to cull

mode = GL\_BACK to default

glFrontFace (vertex order)

It is for order of vertices

Orientation in changes

vertex order = GL\_CW or GL\_CCW

GL\_CW is for clockwise direction (front)

GL\_CCW is for counterclockwise direction (back)

GL\_CCW is default

create depth buffer by setting GLUT\_DEPTH flag in glutInitDisplayMode  
( ) or the appropriate flag in the

## PI + FLFORMATDESCRIPTOR

enable per-pixel depth testing with glEnable (GL\_DEPTH\_TEST)

clear depth buffer by setting GL\_DEPTH\_BUFFER\_BIT in  
glClear ().

glDepthFunc (condition);

changes the test used

Condition : GL\_LESS [less than visible (default)]

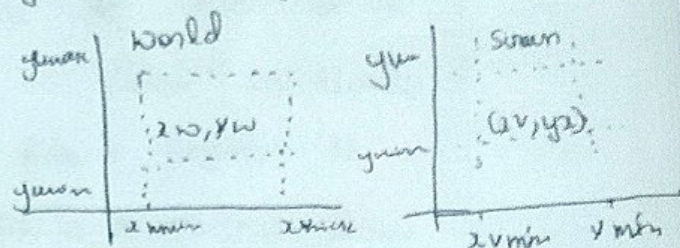
GL\_GREATER [greater than visible]



→ explain normalization transformation for an orthogonal projection

Relative position is sent

$$\frac{x_v - x_{vmin}}{x_{vmax} - x_{vmin}} = \frac{x_w - x_{wmin}}{x_{wmax} - x_{wmin}}$$



$$x_v - x_{vmin} = (x_{vmax} - x_{vmin}) \left( \frac{x_w - x_{wmin}}{x_{wmax} - x_{wmin}} \right)$$

$$x_v - x_{vmin} = (x_w - x_{wmin}) \left( \frac{x_{vmax} - x_{vmin}}{x_{wmax} - x_{wmin}} \right)$$

$$x_v = x_w \left( \frac{x_{vmax} - x_{vmin}}{x_{wmax} - x_{wmin}} \right) + x_{vmin} + \frac{x_{vmin} \cdot x_{wmin} - x_{wmin} \cdot x_{vmax}}{x_{wmax} - x_{wmin}}$$

$$y_v = y_w \left( \frac{y_{vmax} - y_{vmin}}{y_{wmax} - y_{wmin}} \right) + \left( \frac{y_{vmax} \cdot y_{vmin} - y_{wmin} \cdot y_{vmax}}{y_{wmax} - y_{wmin}} \right)$$

$$x_v = x_w s_x + t_x$$

$$\text{where } s_x = \frac{x_{vmax} - x_{vmin}}{x_{wmax} - x_{wmin}}$$

$$t_x = \frac{x_{wmax} \cdot x_{vmin} - x_{wmin} \cdot x_{vmax}}{x_{wmax} - x_{vmin}}$$

similarly

$$y_v = y_w s_y + t_y$$

$$\text{where } s_y = \frac{y_{vmax} - y_{vmin}}{y_{wmax} - y_{wmin}}$$



(5)

$$b_y = \frac{y_{\max} y_{\min} - y_{\min} y_{\max}}{y_{\max} - y_{\min}}$$

$x_v = s_x x_w + t_x$  } can be written as  
 $y_v = s_y y_w + t_y$

$$\text{in window, nonrect} = T.S = \begin{bmatrix} s_x & 0 & t_x \\ 0 & s_y & t_y \\ 0 & 0 & 1 \end{bmatrix}$$

for normalized coordinates,

1 for  $x_{\min}$  and  $y_{\min}$

1 for  $x_{\max}$  and  $y_{\max}$

$$\text{in window, nonrect} = \begin{bmatrix} \frac{2}{x_{\max} - x_{\min}} & 0 & -\frac{x_{\max} + x_{\min}}{x_{\max} - x_{\min}} \\ 0 & \frac{2}{y_{\max} - y_{\min}} & -\frac{y_{\max} + y_{\min}}{y_{\max} - y_{\min}} \\ 0 & 0 & 1 \end{bmatrix}$$

similarly for 3D

$$\text{Hyphe, non} = \begin{bmatrix} \frac{2}{x_{\max} - x_{\min}} & 0 & 0 & -\frac{x_{\max} + x_{\min}}{x_{\max} - x_{\min}} \\ 0 & \frac{2}{y_{\max} - y_{\min}} & 0 & -\frac{y_{\max} + y_{\min}}{y_{\max} - y_{\min}} \\ 0 & 0 & \frac{-2}{z_{\max} - z_{\min}} & -\frac{z_{\max} + z_{\min}}{z_{\max} - z_{\min}} \\ 0 & 0 & 0 & 1 \end{bmatrix}$$



→ Demonstrate openGL function for displaying window management using GLUT

`glutInit (&argc, argv)`

It is used to initialize GLUT library  
glutInit window position (x0, y0)

position of display window on screen

`glutInitWindowSize (dw, dh)`

size of window

dw width is width of display

dh height is height of display

`glutCreateWindow ("string")`

It is used to create display window with name.

`glutDisplayFunc ()`

It sets the display callback for current window  
`glutDisplayFunc ();`

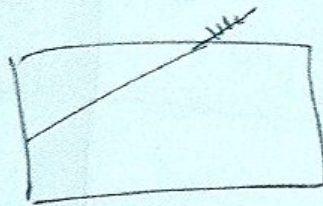
It sets the initial display mode  
`glutInitDisplayMode ()`

It sets the reshape callback for current window  
`glutReshapeFunc ();`

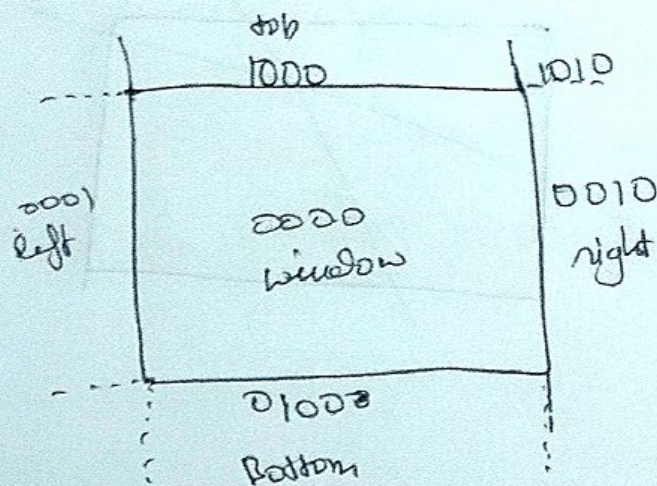
It manages the cursor location of current window



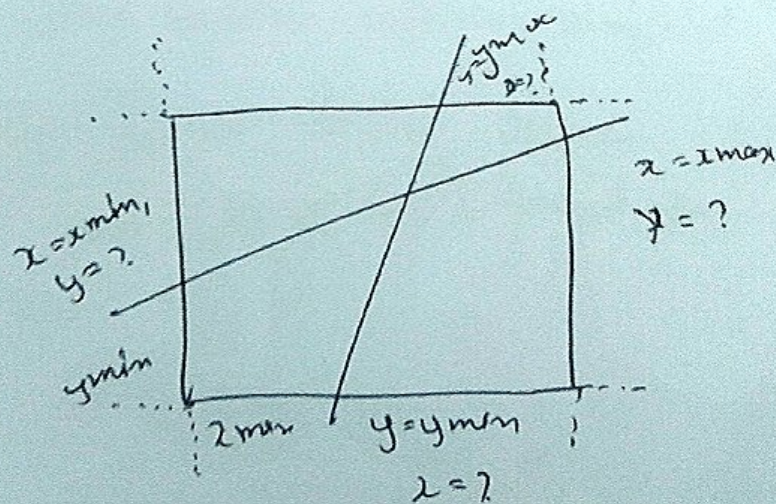
10. Explain Cohen-Sutherland line clipping algorithm
- There will be a rectangular window (clipping window)
  - There will be an object
  - only pencil inside the rectangle must be shown.
  - pencil outside the rectangle should not be shown
- Example



Boundaries



Consider



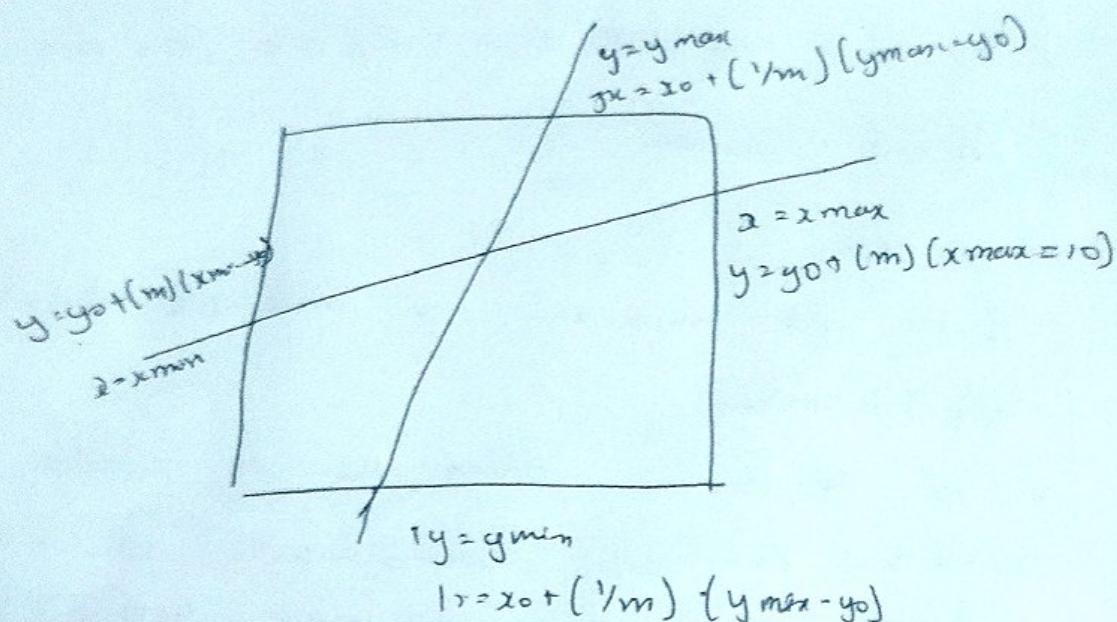


$$m = (y - y_0) / (x - x_0)$$

$$m = (x - x_0) = (y - y_0)$$

$$x = x_0 + (y - y_0) / m$$

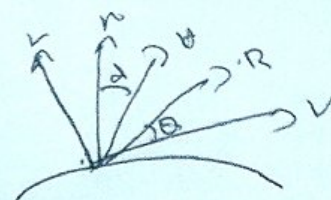
$$y = y_0 + m(x - x_0)$$



Phong model sets the intensity of specular reflection to  $\cos^p$

$n$  = shininess

$$I_{\text{specular}} = \cos^n \theta$$



$I$  = intensity

$\cos^n \theta$  is called specular reflection coefficient

If light direction  $L$  and viewing direction  $V$  are on the same side of the normal  $N$  or if  $L$  is behind the surface, specular effects do not occur



For most opaque materials specular-reflection coefficient is nearly constant is

$$I_{e, \text{specular}} = \begin{cases} k_s \cdot I_p \cdot V \cdot R & , V \cdot R > 0 \text{ and } N \cdot L > 0 \\ 0.0 & , \text{ otherwise} \end{cases}$$

$R$  can be calculated from  $L$  and  $N \cdot R = 2N \cdot L - N \cdot L$

efficient computation

$$\theta = L + V$$

If the light source and the viewer are relatively far from object  $\theta$  is constant

$\theta$  is the direction yielding maximum specular reflection is viewing direction  $V$  if the surface normal  $N$  would coincide with  $\theta$  if  $V$  coplanar with  $R$  and  $L$  (and hence with  $N$  too)  $\theta = \phi/2$ .