generated from a set of control points by forming a set of polynomial function (Berzer Curve) polynomial function These functions are computed from the wordinates of the control points. A berier curve is defined by the defining polygon. It has number of properties that makes them highly & convenient for curve & surface design. It is an approximate splone curve. Proporties of Bezier Curve:

Bezier curve is a prolynomial of degree one
less than the number of control points. Rodratie 10 P2 cabre curve. Bezier curve always passes through the first & last pointsie.

P(0) = Po, P(i) = Pn. The slope of the beginning of the curve is along the line foining the first two control points and the slope at the end of the curve is along the line joining the last 2 points. Bezrer blending function are all positive and sum is always?.

[\langle Bezn,; (u) = 1]

The curve follows the Shape of the defining polygon
The curve Ires enterely within the curvex hall formed by the
four control points. The convex hull property of the Bezier curve ensures that the polynomial smoothly tollows the control polists. Blending Furction: Bezin (u) = "Ci.u' (1-4)"-i $=\frac{n!}{i!(n-i)!} \cdot u^{i}(1-u)^{n-i}$ v For Endividual Coordinates x/u) = { x; Bez; (u) y(a). { fi, Bez;, (u) Z(u)= & 4Z,, Bez,, (u) · Let suppose we are given (n+1) control points positions. then ! P: = (xi, ji, zi) These co-ordinates politicen be blended to produce the following prosition vector p(u) which describes path of an approximation . So, Bezier polynomoul function between Po to Pn is [P(u) = 2 P; Bez, (u)] 05451 where Pin control posts. Bezen - Blandeng function or Bezen furction or Barstern furction. of Bezier Curve for 3 points) [Q(u) = Po Bo, 2(u) + P, B, 2 (u) + P2 B2, 2 (u)] $B_{0,2}(u) = 2 C_0 u^0 (1-u)^{2-0} = (1-u)^2 \rightarrow B_{2,2} = 2 C_2 u^2 (1-u)^{2-2}$ - | B1,2 (u)= 2C, u'(1-4)2-1 2a(ru)

Q(a) = Po (1-u)2 + P, 2u(1-u)+P202 $\chi(u) = (1-u)^2 \chi_0 + 2u(1-u)\chi_1 + u^2 \chi_2$ y(u)= (1-u)2y + 2u(1-u)y, + u2/2 - (Bezier Curve for 4 points) $[Q(u) = P_0 B_{0,3}(u) + P_1 B_{1,3}(u) + P_2 B_{2,3}(u) + P_3 B_{3,3}(u)]$ -> Bo,3(u) = 3Co uo(1-u)3-0=(1-u)3 -> B1,3(u)= 3C, u'(1-u)3-1: (3u(1-u)2 $B_{2,3}(u) = 3C_2 u^2 (1-u)^{3-2} = 3u^2 (1-u)$ $B_{3,3}(u) = 3C_3 u^3(1-u)^{3-3} = u^3$ $[Q(u)=P_0(1-u)^3+3u(1-u)^2P_1+3u^2(1-u)P_2+u^3P_3].$ - Wertvation > · Note: In the figure don't give any value to dotted points, they are done by mistake by me while drawing this figure, so ignore It while you draw this figure of - Using a line parametric equation, lo we will dereve the equation for the Bezier curve. No matter how many control points are there. (Qo= (+u)Po+UP, (Qo post b/w Po (P,) 1, P, (P2) Q1= (1-4)P1+0P2 (Q, " " P2 4 B3) Q2 = (1-u) P2 + UP3 (Q2 " a. & pa,) . C1 = (1-4) Q0+UQ1 ((" , · Q, & Q2) . Cz = (1-4) Q, + U Q2 (C2 11 R: (1-4) C1 + 4 C2 c, & C2) CR " " Now, R(u)=(1-u)C1+UC2 (Replacing value, we get) = (1-4)[(1-4)00+40,]+4[(1-4)00+402] = (1-4)200+(1-4)401+(1-4)400+4202 P.T.O.

 $= (1-u)^{2} [(1-u) P_{0} + v P_{1}] + 2u(1-u) O_{1} + v^{2} O_{2}$ $= (1-u)^{2} [(1-u) P_{0} + v P_{1}] + 2u(1-u) [(1-u) P_{1} + v P_{2}] + u^{2} [(1-u) P_{2} + v P_{3}]$ $= (1-u)^{3} P_{0} + u(1-u)^{2} P_{1} + 2u'(1-u)^{2} P_{1} + 2v^{2} (1-u) P_{2} + u^{2} (1-u) P_{2} + u^{3} P_{3}$ $= [(1-u)^{3} P_{0} + 3v(1-u)^{2} P_{1} + 3v^{2} (1-u) P_{2} + v^{3} P_{3}]$ For Calculating $\chi_{1} y$ wordside. $\chi(u) = (1-u) \chi_{0} + 3u(1-u)^{2} \chi_{1} + 3u^{2} (1-u) \chi_{2} + u^{3} \chi_{3}$ $y(u) = (1-u) \chi_{0} + 3u(1-u)^{2} \chi_{1} + 3u^{2} (1-u) \chi_{2} + u^{3} \chi_{3}$ $y(u) = (1-u) \chi_{0} + 3u(1-u)^{2} \chi_{1} + 3u^{2} (1-u) \chi_{2} + u^{3} \chi_{3}$

[youtube com/watch?v=gr/rC6_LDcy]-, watch this once [[Make It Easy] -, channel]] go YrC6_LDcy