



# Essential Mathematics for Data Science / Machine Learning

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# Learning Outcomes Live Session - 1



- ☐ Vectors
- ☐ Vector Operations
- ☐ Matrix Algebra



- ❑ Mathematics is an essential part of many engineering and science branches
- ❑ Modern techniques in data science and machine learning are no exceptions
- ❑ “Mathematics is the language with which God has written the universe.” -Galileo Galilei
- ❑ AI is not magic, it is just mathematics .. !!
- ❑ The concepts of Linear Algebra, Calculus, game theory, Optimization and Gradient Descent are frequently used in many DS/ML techniques

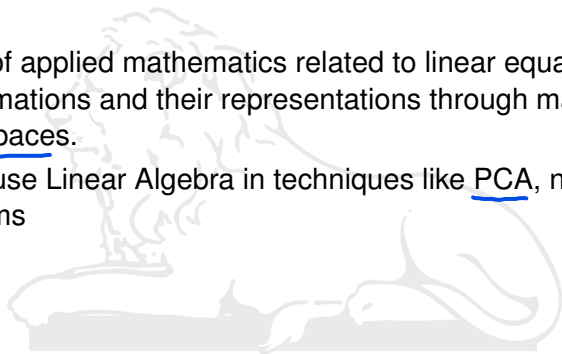


- ☐ Linear Algebra
- ☐ Gradient Calculus
- ☐ Probability and Statistics
- ☐ Optimization

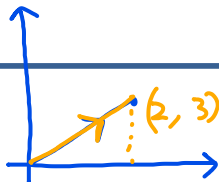




- ❑ branch of applied mathematics related to linear equations, linear transformations and their representations through matrices and vector spaces.
- ❑ We will use Linear Algebra in techniques like PCA, neural network algorithms



# Vector



$$2\hat{i} + 3\hat{j}$$

$$2 + 3\hat{i}$$

$$(2, 3)$$

$$(x_1, x_2)$$

- ❑ a mathematical object that encodes a length and direction
- ❑ A vector is often represented as a 1-dimensional array of numbers, referred to as components and is displayed either in column form or row form
- ❑ Represented geometrically, vectors typically represent coordinates within a n-dimensional space

	Age	Exp.	Income
①	24	2	7.5 L
②	35	14	20 L
③			

# Vectors in $R^n$ /Concept of Vector Space



$R, R^2, R^3,$

(Is  $R^2$  a vector space?)



$S =$  vector space

$s_1, s_2$

$s_1 + s_2 \leftarrow$

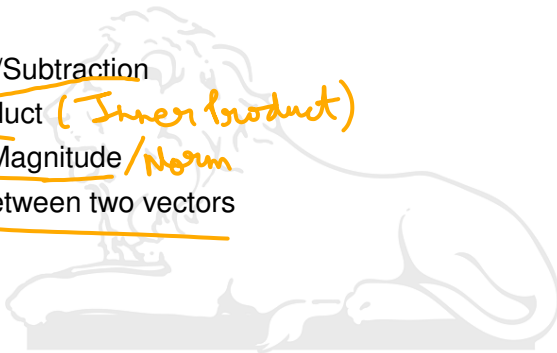
$\alpha s_1, \beta s_2 \leftarrow$

$\alpha s_1 + \beta s_2 \leftarrow$

# Operations with Vectors in $R^n$



- ☐ Addition/Subtraction
- ☐ Dot Product (*Inner product*)
- ☐ Length/Magnitude / *Norm*
- ☐ Angle between two vectors



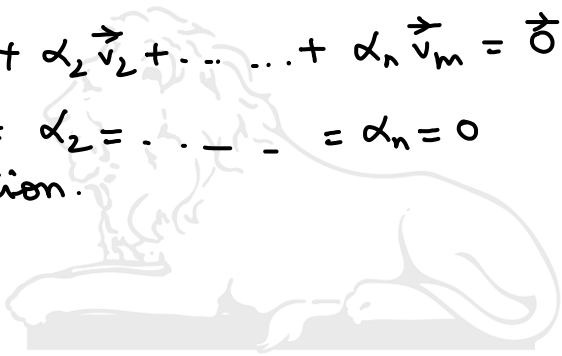


$\mathbb{R}^n$ .

$\vec{v}_1, \vec{v}_2, \dots, \vec{v}_m$  are linearly independent if

$$\alpha_1 \vec{v}_1 + \alpha_2 \vec{v}_2 + \dots + \alpha_n \vec{v}_m = \vec{0}$$

$\Rightarrow \alpha_1 = \alpha_2 = \dots = \alpha_n = 0$  is the only solution.



# Orthogonal Vectors/Orthonormal Vectors



$$\vec{v}_1$$

$$\vec{v}_2 = \frac{\vec{v}_1}{\|\vec{v}_1\|}$$

$\mathbb{R}^2$

$(9, 1)$

$(1, 0)$

$(0, 2)$

$(4, 0)$

$\mathbb{R}^3$

3 vectors which are orthonormal

$(1, 0, 0)$

$(0, 1, 0)$


$(0, 0, 1)$

1 →  
2 →  
⋮  
m →

$$\begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{bmatrix}_{m \times n}$$

$a_{ij}$

$m \times n$



In mathematics, a matrix (plural matrices) is a rectangular array or table of numbers, symbols, or expressions, arranged in rows and columns, which is used to represent a mathematical object or a property of such an object. - Wikipedia

- Matrix Size
- Representing any element of a matrix
- $(1,n)$  and  $(m,1)$  matrices

$$M = \{a_{ij}\}_{m \times n}$$

(Size)  
(Row)

↓  
(Column)

$a_{47}$   
 $a_{12,8}$

# "Matrix as Linear Transformation"

$m \times n$ , " $m = n$ " Square Matrix.



# Eigenvalues and Eigenvectors



Let  $M$  be a  $n \times n$  matrix. A non-zero vector  $X$  is said to be an eigenvector of  $M$  corresponding to eigenvalue  $\lambda$  if

$$M \cdot \underline{X} = \lambda \cdot X$$

