

## PART A

### Experiment No.02

A.1 Aim: To Implement uninformed search methods using C,python or Java.

A.2 Prerequisite: Data Structure, Searching Techniques

A.3 Outcome:

After successful completion of this experiment students will be able to

- Solve the problems like water jug, tic-tac-toe using uninformed search methods like DFS/BFS.

Tools Required: C /Java

A.4 Theory:

A problem determines the graph and the goal but not which path to select from the frontier. This is the job of a search strategy. A search strategy specifies which paths are selected from the frontier. Different strategies are obtained by modifying how the selection of paths in the frontier is implemented.

The uninformed search strategies that do not take into account the location of the goal.

Intuitively, these algorithms ignore where they are going until they find a goal and report success.

- Depth-First Search
  - Breadth-First Search
  - Lowest-Cost-First Search
- Depth-First Search: The first strategy is depth-first search. In depth-first search, the frontier acts like a last-in first-out stack. The elements are added to the stack one at a time. The one selected and taken off the frontier at any time is the last element that was added.

Algorithm:

DEPTH(AdMax): Depth first search in state space

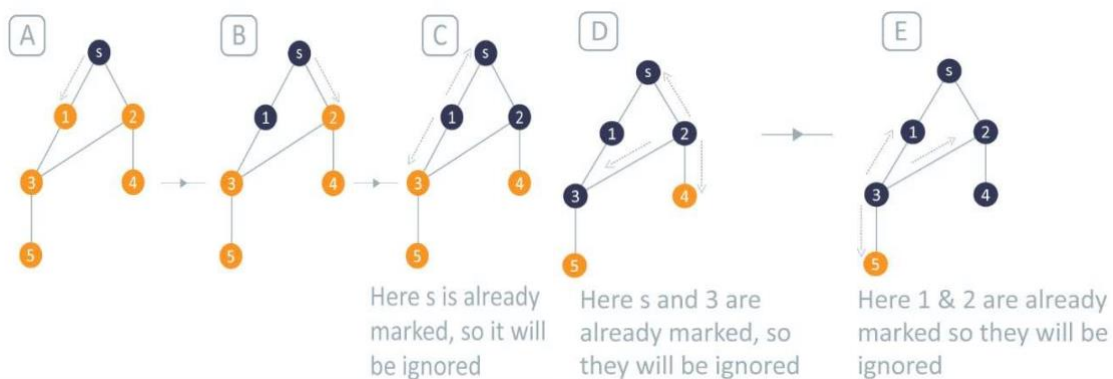


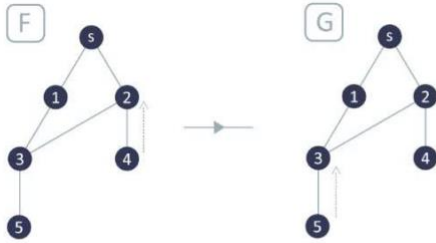
generated in order of the number of arcs in the path. One of the paths with the fewest arcs is selected at each stage.

Algorithm BREADTH: Breadth first search in state space

1. Init lists OPEN  $\{S_i\}$ , CLOSED  $\{\}$
  2. if OPEN =  $\{\}$   
then return FAIL
  3. Remove first node S from OPEN and insert it in CLOSED
  4. Expand node S
    - 4.1. Generate all direct successors  $S_j$  of node S
    - 4.2. for each successor  $S_j$  of S do
      - 4.2.1. Make link  $S_j$  S
      - 4.2.2. if  $S_j$  is final state  
then
        - i. Solution is  $(S_j, S, \dots, S_i)$
        - ii. return SUCCESS
      - 4.2.3. Insert  $S_j$  in OPEN, at the end
  5. repeat from 2
- end.

Example:





Here 2 is already marked, so it will be ignored

Here 3 is already marked, so it will be ignored

## PART B

(PART B : TO BE COMPLETED BY STUDENTS)

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Grade:	

B.1 Software Code written by student: BFS =>

```
from collections import deque
```

```
# BFS function def
```

```
bfs(graph, start, goal):
```

```
    visited = set() # Set to keep track of visited nodes
```

```
    queue = deque([start]) # Queue for BFS    path = [] # To store the traversal path
```

```
    while queue:
```

```
        node = queue.popleft()
```

```
    if node not in visited:
```

```
        visited.add(node)
```

```
        path.append(node)
```

```
        # Check if goal is found
```

```
    if node == goal:        print("Goal found:", path)        return path
```

```
        # Enqueue all the neighbors of the current node
```

```

        for neighbor in graph[node]:
            if neighbor not in visited:
                queue.append(neighbor)

```

```

    print("Goal not found")
    return None

```

```

# Example usage graph =
{
    '1': ['2', '3'],
    '2': ['1', '4', '5'],
    '3': ['1', '6'],
    '4': ['2'],
    '5': ['2', '6'],
    '6': ['3', '5'] }

```

```

start = '1' goal = '6'
print("Breadth-First Search:")
bfs(graph, start, goal)

```

## DFS

```

# DFS function def dfs(graph, start, goal, visited=None,
path=None):    if visited is None:
                visited = set() # Set to keep track of visited nodes    if
path is None:    path = [] # List to store the path

```

```

    visited.add(start)    path.append(start)

```

```

    # Check if goal is found    if
start == goal:    print("Goal
found:", path)    return path

```

```

    # Recurse for all the neighbors
for neighbor in graph[start]:    if
neighbor not in visited:
    result = dfs(graph, neighbor, goal, visited, path)
if result: # If result is not None, goal is found
return result

```

```

    path.pop() # Backtrack if goal is not found
return None graph = {
    '1': ['2', '3'],
    '2': ['1', '4', '5'],
    '3': ['1', '6'],
    '4': ['2'],

```

```

    '5': ['2', '6'],
    '6': ['3', '5']
}

```

```

start = '1' goal = '6'
print("Depth-First Search:")
dfs(graph, start, goal)

```

## B.2 Input and Output:

BFS:

```

⇒ Breadth-First Search:
Goal found: ['1', '2', '3', '4', '5', '6']
['1', '2', '3', '4', '5', '6']

```

DFS :

```

⇒ Depth-First Search:
Goal found: ['1', '2', '5', '6']
['1', '2', '5', '6']

```

## B.3 Observations and learning:

Uninformed search methods, such as Breadth-First Search (BFS) and DepthFirst Search (DFS), are fundamental techniques used in AI for problem-solving, where the search algorithm explores the solution space without any prior knowledge of the goal

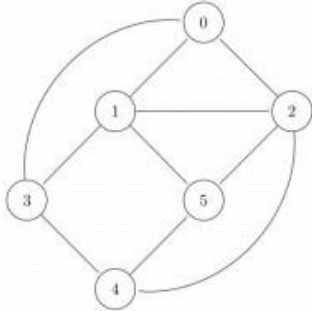
## B.4 Conclusion:

The implementation of uninformed search methods highlights the efficiency and flexibility offered by Python, especially in terms of code simplicity and readability, while C provides more control over memory management and performance optimization

## B.5 Question of Curiosity

(To be answered by student based on the practical performed and learning/observations)

Q1) Which sequence corresponds to that of depth first search for the graph given below. The search starts at vertex 0 and lexicographic ordering is assumed for the edges emanating from each vertex.



- A. 0 1 2 4 3 5
- B. 0 1 2 5 4 3
- C. 0 1 2 3 4 5
- D. 0 1 3 4 2 5

Q2) Given a rooted tree, one desires to find the shortest path from the root to a given node  $v$ . Which algorithm would one use to find this shortest path?

- A. DFS
- B. BFS
- C. Either BFS or DFS

Q3) Consider a graph  $G$ . Let  $T$  be a BFS tree with root  $r$ . Let  $d(u,v)$  denote the length of the shortest path between the nodes  $u$  and  $v$ . If  $v$  is visited before  $u$  in the breadth first search traversal, which of the following statements is true ?

- A.  $d(r,v) > d(r,u)$
- B.  $d(r,v) = d(r,u)$
- C.  $d(r,v) < d(r,u)$
- D. insufficient information to comment on  $d(r,v)$  and  $d(r,u)$

