

COLLEGE OF ENGINEERING, PUNE

(An Autonomous Institute of Government of Maharashtra.)

END Semester Examination (MA-15001) LINEAR ALGEBRA

Programme: F.Y.B.Tech.

Branches: All

Max. Marks: 60

While the path N

Duration: 3 hours Wednesday, 28th Nov 2018

Student PRN No.

Instructions:

- 1. All questions are compulsory.
- 2. Figures to the right indicate course outcomes and maximum marks.
- 3. Mobile phones and programmable calculators are strictly prohibited.
- 4. Writing anything on question paper is not allowed.
- 5. Exchange/Sharing of stationery, calculator etc. is not allowed.
- 6. All symbols have their usual meaning. An *inner product space* is a vector space together with an inner product (i.e. a positive definite scalar product) defined on it.
- 7. For every $n \geq 1$, inner product on \mathbb{R}^n will be assumed to be the usual dot product.
- 8. Write all subparts of a question together and label each subpart correctly.

$\mathbf{Q.1}$ (a) Define rank of a matrix.

Reduce the following matrix A to a matrix in row-echelon form. Also find a basis for the column space of A. (CO 3) [4]

$$A = \left(\begin{array}{rrrr} 1 & 2 & 0 & 2 & 1 \\ -1 & -2 & 1 & 1 & 0 \\ 1 & 2 & -3 & -7 & -2 \end{array}\right)$$

- (b) Let S and T be non-empty subsets of \mathbb{R}^4 . Suppose S contains four elements. Identify the errors (if any) in the following statements and write the corrected statements. (CO 2) [3]
 - i. $S \cup S^{\perp \perp}$ might not be a subspace of \mathbb{R}^4 .
 - ii. $T \cap T^{\perp}$ is always a subspace of \mathbb{R}^4 .
 - iii. S is a basis for \mathbb{R}^4 .
- (c) Row equivalent matrices have the same rank. Is the converse true?

 Justify your answer.

 (CO 2) [3]
- (d) Let A be a 6×7 matrix whose rank is 4. Is AX = b consistent for every column vector $b \in \mathbb{R}^6$? Explain. (CO 2) [2]

- (e) Let V be the vector space of functions which have derivatives of all orders. Let $D: V \to V$ be the derivative map and $I: V \to V$ the identity map. Find $\ker(D)$ and $\ker(L)$, where L = D - I. (CO 3) [3]
- **Q.2** (a) Suppose $L: \mathbb{R}^2 \to \mathbb{R}^2$ is a map such that L(1, -1) = (3, 2) and L(-1, 1) = (2, 3). Can you determine L(0, 0)? Why? (CO 3) [2]
 - (b) Let V be the vector space of continuous real valued functions defined on [0,1] with the inner product $\langle f,g\rangle=\int\limits_0^1f(t)g(t)\,dt$ defined on it. Let $f(t)=t^2+t-4$ and g(t)=t-1. Evaluate $\|f-g\|$. (CO 3) [2]
 - (c) Let V be a vector space and $L: V \to V$ a linear map. Then $L^2: V \to V$ is the linear map defined by $L^2(v) = L(L(v))$, for $v \in V$. Show that $\operatorname{Im}(L^2)$ is a subset of $\operatorname{Im}(L)$. Does there exist any such relation between $\ker(L^2)$ and $\ker(L)$? If yes, write that relation. (CO 1) [4]
 - (d) Let V be a finite dimensional vector space and $L: V \to V$ a linear map. Show that L is one-to-one if and only if $\ker(L)$ is zero. (CO 4) [3]
 - (e) Examine whether the following quadratic forms is positive definite. $Q(x_1, x_2, x_3) = 3x_1^2 + 5x_2^2 + 3x_3^2 2x_1x_2 + 2x_1x_3 2x_2x_3$. (CO 3) [4]
- **Q.3** (a) Let $W = \{(x, y, z, w) \in \mathbb{R}^4 | y + z = 0, x = 2w \}.$
 - i. Show that W is a subspace of \mathbb{R}^4 .
 - ii. Find an orthogonal basis B_1 of W.
 - iii. Find a basis B_2 of W^{\perp} .
 - iv. Apply Gram-Schmidt process to the basis $B_1 \cup B_2$ of \mathbb{R}^4 and construct an orthogonal basis of \mathbb{R}^4 . (CO 3) [2+2+3+3]
 - (b) Construct a linear map $T: \mathbb{R}^3 \to \mathbb{R}^2$ which maps (2,0,0) to (2,2) (0,1,0) to (2,3) and (0,0,1) to (3,2). Also find the kernel and and image of T. (CO 3) [5]
- **Q.4** (a) Let $L: \mathbb{R}^n \to \mathbb{R}^n$ be a linear map. Prove that L is one-to-one if and only if it is onto. (CO 5) [3]
 - (b) Transform the quadratic form $Q(x_1, x_2) = x_1^2 + 24x_1x_2 6x_2^2$ to principal axes form or canonical form. What kind of conic section (or pair of straight lines) is represented by the equation Q = 5? (CO 3) [4]
 - (c) Let $A = \begin{pmatrix} 1 & 2 & 0 \\ 1 & 1 & 2 \\ 0 & -1 & 1 \end{pmatrix}$. Show that A has only one (distinct) eigenvalue, say λ with geometric multiplicity 1.

Construct a basis $\{X_1, X_2, X_3\}$ of generalized eigenvectors for A as described below.

Find an eigenvector X_1 corresponding to λ . Find a non-trivial solution X_2 of $(A - \lambda I)X_2 = X_1$. Find a non-trivial solution X_3 of $(A - \lambda I)X_3 = X_2$. [4]

(d) Consider the system of differential equations:

$$\frac{dy_1}{dt} = a y_1 + b y_2$$

$$\frac{dy_2}{dt} = c y_1 + d y_2$$

which can be represented in matrix form: y' = Ay, where $A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$.

Suppose A has two distinct eigenvalues λ_1 and λ_2 with X_1, X_2 as the corresponding eigenvectors. Then the general solution of the above system is given by $y = c_1 e^{\lambda_1 t} X_1 + c_2 e^{\lambda_2 t} X_2$, where c_1, c_2 are arbitrary constants. Find the general solution of the following system. (CO 5) [4]

$$\frac{dy_1}{dt} = 5y_1 + 2y_2$$

$$\frac{dy_2}{dt} = 2y_1 + 5y_2$$

