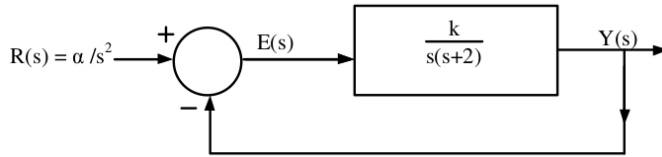


EE23BTECH11024 - G.Karthik Yadav*

GATE 2023 EC 41

1. A Closed loop system is shown in the figure where $k > 0$ and $\alpha > 0$.

The Steady State error due to a ramp input ($R(s) = \alpha s^{-2}$) is given by (GATE 2023 EC 41)



- 1) $\frac{2\alpha}{k}$
- 2) $\frac{\alpha}{k}$
- 3) $\frac{\alpha}{2k}$
- 4) $\frac{\alpha}{4k}$

Solution:

from table Open loop transfer function $G(s)$

Symbol	Parameters	Value
$R(s)$	Laplace transform Ramp input signal $r(t)$	αs^{-2}
$G(s)$	Open Loop transfer function	$\frac{Y(s)}{E(s)} = \frac{k}{s(s+2)}$
$Y(s)$	Laplace transform of the output signal $y(t)$?
$E(s)$	Laplace transform of the error signal $e(t)$	$R(s) - Y(s)$
$E(s)$	Laplace transform of the error signal $e(t)$	$R(s) - Y(s)$
e_s	Steady State Error	?

TABLE I
PARAMETERS

$$G(s) = \frac{Y(s)}{E(s)} \quad (1)$$

$$= \frac{Y(s)}{R(s) - Y(s)} \quad (2)$$

$$Y(s) = \frac{R(s) G(s)}{1 + G(s)} \quad (3)$$

from eq 1 and eq (3)

$$G(s) = \frac{k}{s(s+2)} \quad (4)$$

$$Y(s) = \frac{\alpha k s^{-2}}{k + s(s+2)} \quad (5)$$

$$E(s) = R(s) - Y(s) \quad (6)$$

$$E(s) = \frac{\alpha(s+2)}{s(k + s(s+2))} \quad (7)$$

By Taking Inverse Laplace Transform of eq (4) and eq(5)

$$g(t) = \frac{k(1 - e^{-2t})}{2} u(t) \quad (8)$$

$$y(t) = \alpha t u(t) - \frac{2\alpha}{k} u(t) \quad (9)$$

$$+ \frac{\alpha}{2k\sqrt{1-k}} \left(2\sqrt{1-k} e^{\sqrt{1-k}t-1} + 2\sqrt{1-k} e^{-\sqrt{1-k}t-1} + (2-k) e^{\sqrt{1-k}t-1} - (2-k) e^{-\sqrt{1-k}t-1} \right) u(t)$$

$$e(t) = r(t) - y(t) \quad (10)$$

$$= \alpha t u(t) - y(t) \quad (11)$$

$$e(t) = \frac{2\alpha}{k} u(t) \quad (12)$$

$$- \frac{\alpha}{2k\sqrt{1-k}} \left(2\sqrt{1-k} e^{\sqrt{1-k}t-1} + 2\sqrt{1-k} e^{-\sqrt{1-k}t-1} + (2-k) e^{\sqrt{1-k}t-1} - (2-k) e^{-\sqrt{1-k}t-1} \right) u(t)$$

$$e_s = \lim_{s \rightarrow 0} s E(s) \quad (13)$$

$$= \lim_{s \rightarrow 0} s \frac{R(s)}{1 + G(s)} \quad (14)$$

$$= \lim_{s \rightarrow 0} \frac{\alpha(s+2)}{s(s+2) + k} \quad (15)$$

$$e_s = \frac{2\alpha}{k} \quad (16)$$