

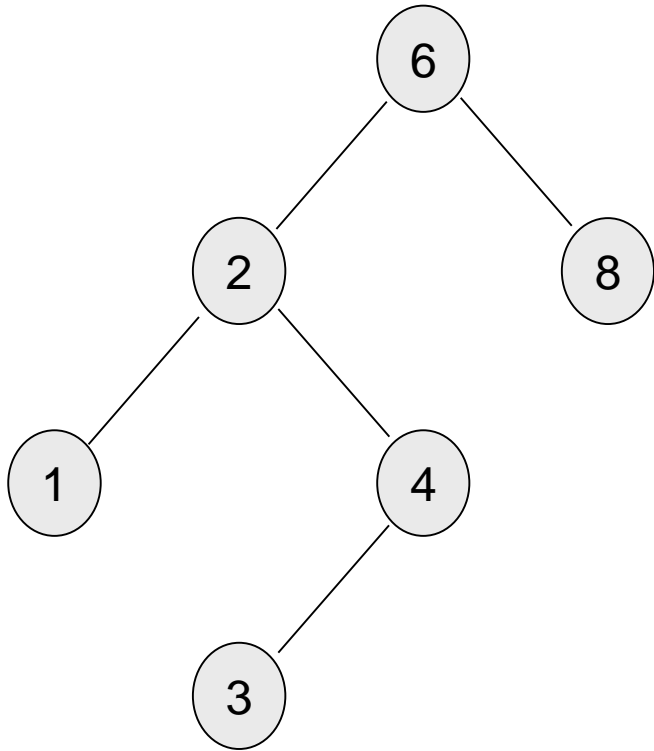
Binary Trees – Issues in Construction

- How can we insert a node in to a binary tree?
 - Need to specify the location as a left or right child of an existing node in the tree
 - What needs to be done if a node is already present at that location?
 - The tree constructed can be of height $n - 1$ (n is number of nodes in the tree)
 - The operations of insertion, search and deletion can be of complexity $O(n)$.
- **Binary search tree** is an alternative to make the searching convenient and also with average time complexity of $O(\log n)$.

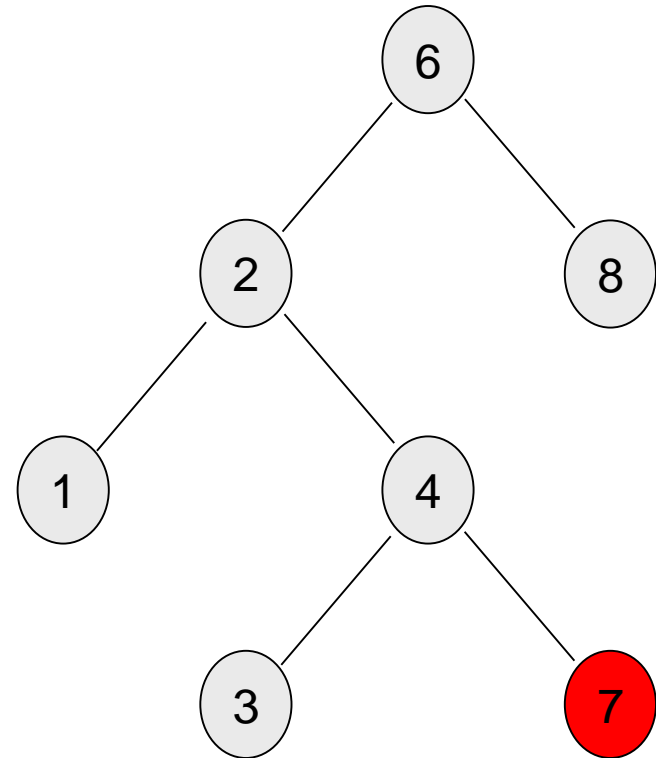
Binary Search Trees

- An important application of binary trees is their use in searching.
- *Binary search tree* is a binary tree in which every node X contains a data value that satisfies the following:
 - a) all data values in its left subtree are smaller than the data value in X
 - b) the data value in X is smaller than all the values in its right subtree.
 - c) the left and right subtrees are also binary search trees.

Example

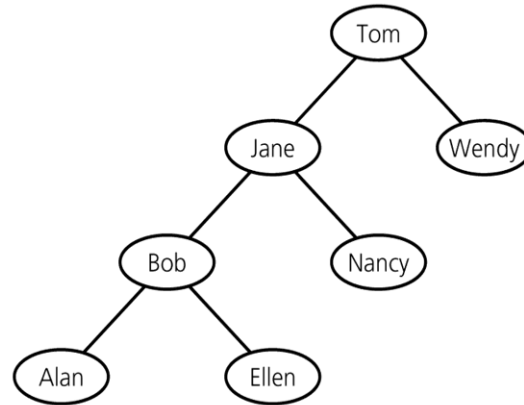


A binary search tree

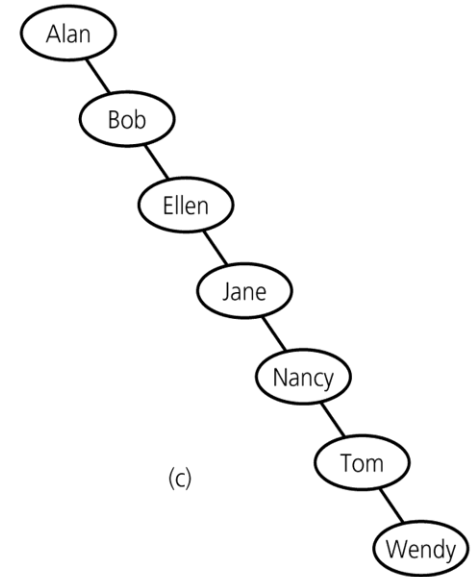


Not a *binary search tree*, but a
binary tree

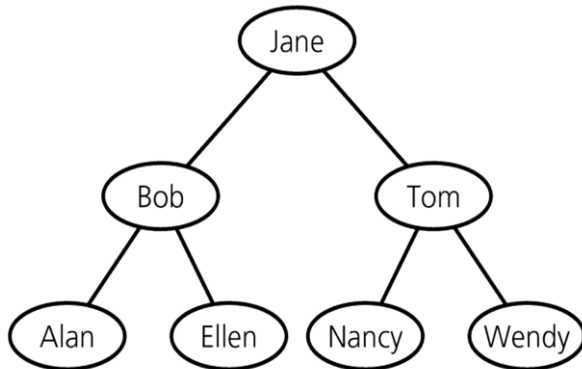
Binary Search Trees – containing same data



(a)



(c)



(b)

Operations on BSTs

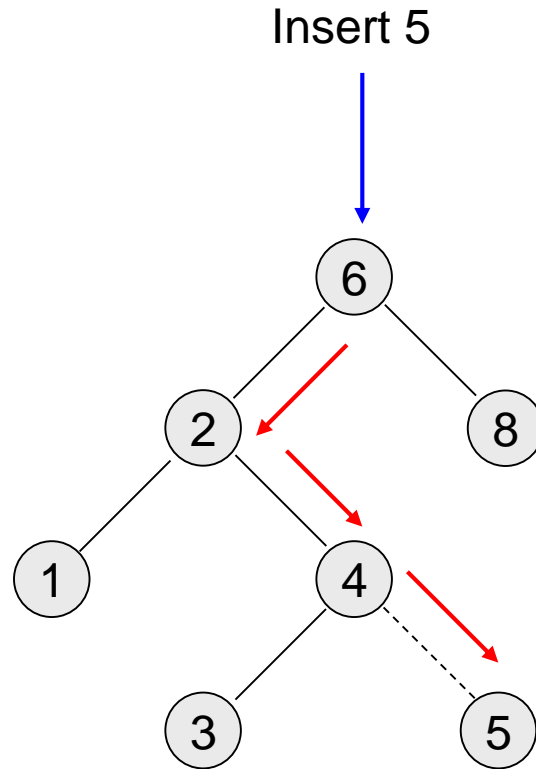
- Most of the operations on binary trees are $O(\log N)$.
 - This is the main motivation for using binary trees rather than using ordinary lists to store items.
- Most of the operations can be implemented using recursion.
 - we generally do not need to worry about running out of stack space, since the average depth of binary search trees is $O(\log N)$.

Insert operation

Algorithm for inserting X into tree T:

- Proceed down the tree as you would with a find operation.
- if X is found
 - do nothing, (or “update” something)
- else
 - insert X at the last spot on the path traversed.

Example



- What about duplicates?

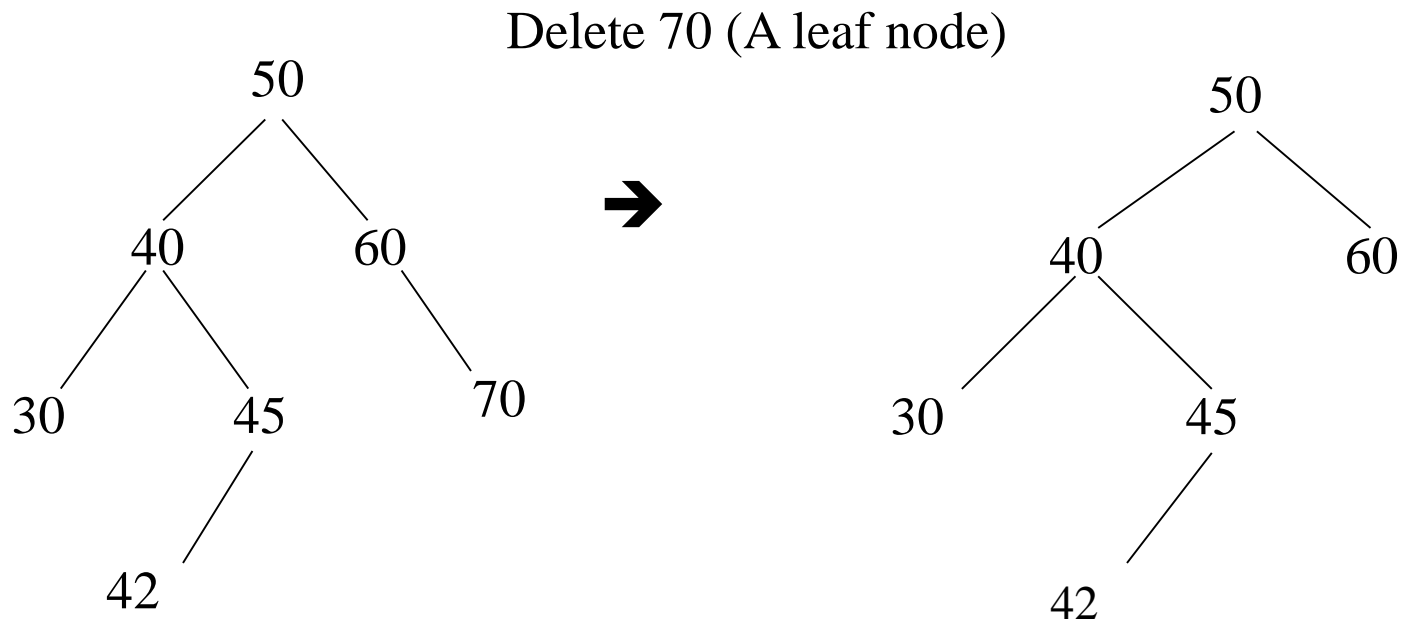
Deletion operation

There are three cases to consider:

1. Deleting a leaf node
 - Replace the link to the deleted node by NULL.
2. Deleting a node with one child:
 - The node can be deleted after its parent adjusts a link to bypass the node.
3. Deleting a node with two children:
 - The deleted value must be replaced by an existing value that is either one of the following:
 - The largest value in the deleted node's left subtree
 - The smallest value in the deleted node's right subtree.

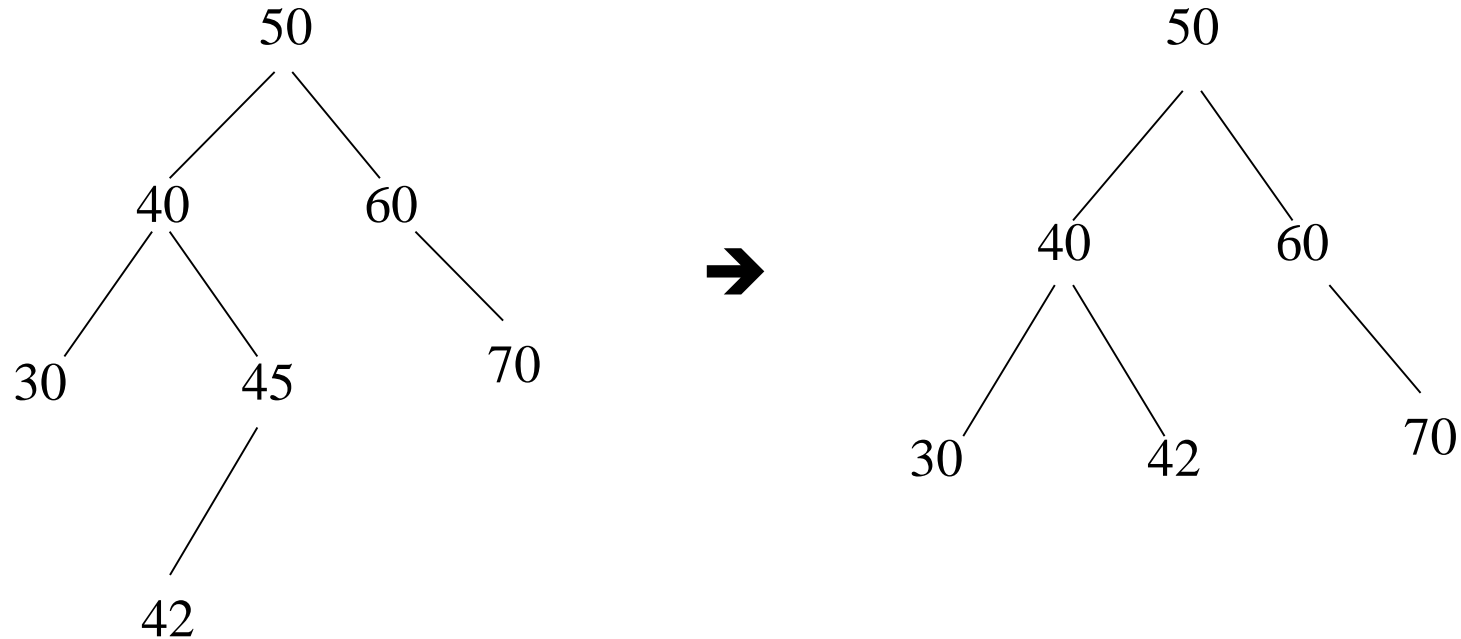
Deletion – Case1: A Leaf Node

To remove the leaf containing the item, we have to set the pointer in its parent to NULL.



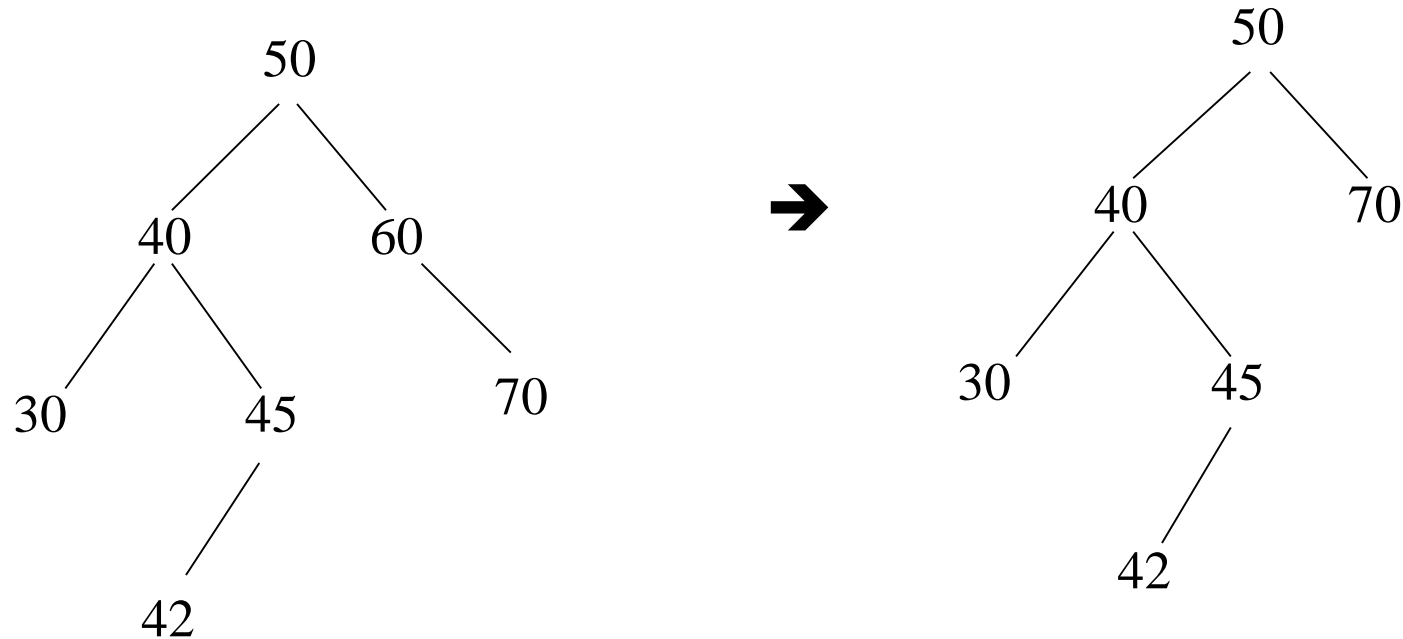
Deletion – Case2: A Node with only a left child

Delete 45 (A node with only a left child)



Deletion – Case2: A Node with only a right child

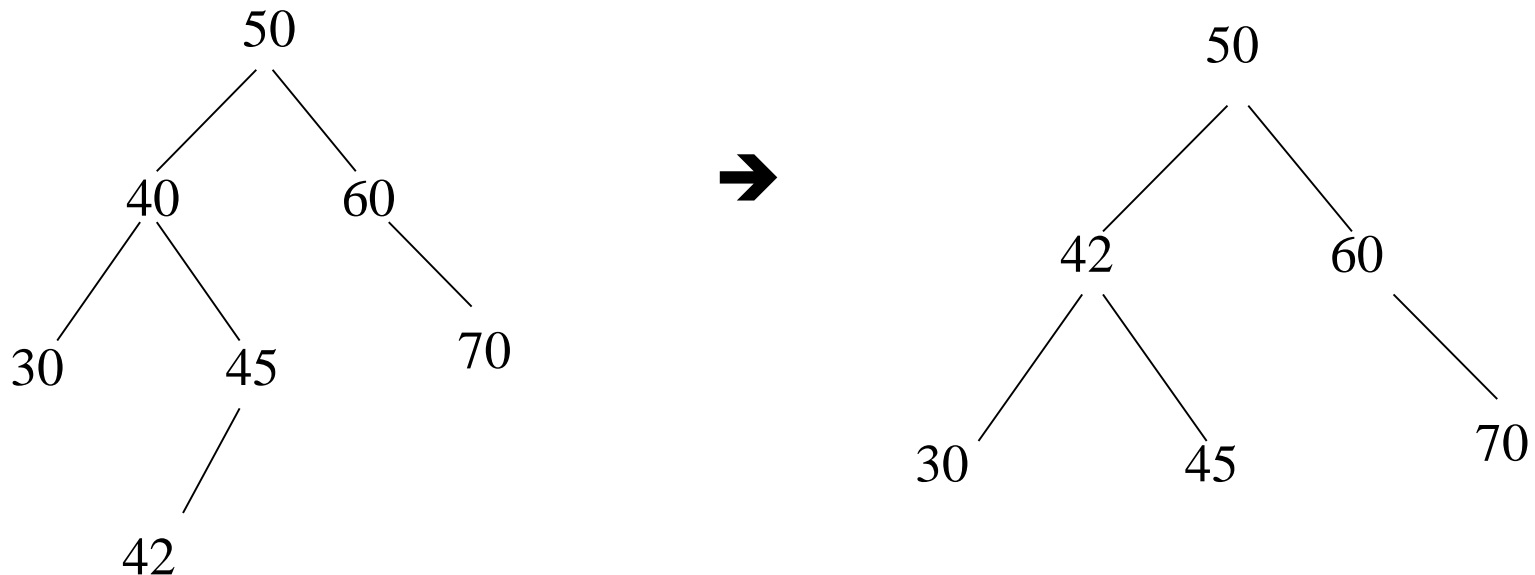
Delete 60 (A node with only a right child)



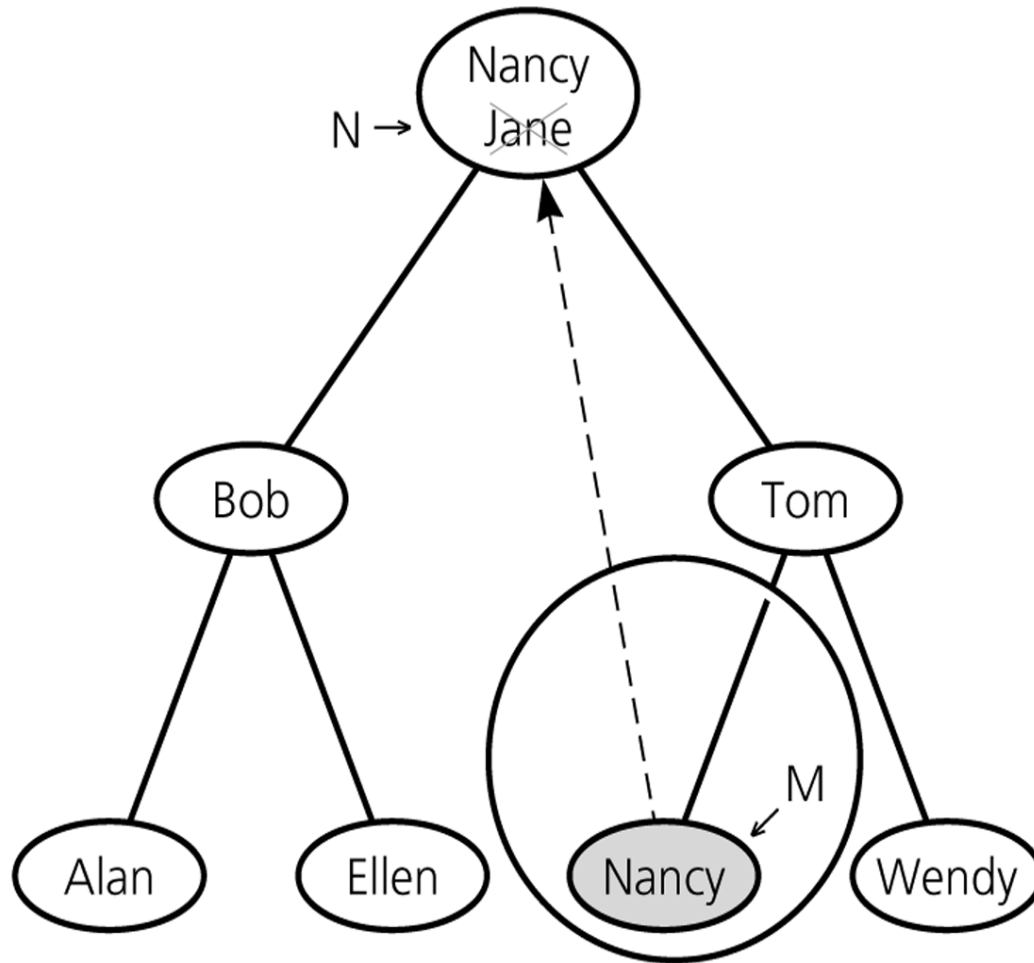
Deletion – Case3: A Node with two children

- Locate the inorder successor of the node.
- Copy the item in this node into the node which contains the item which will be deleted.
- Delete the node of the inorder successor.

Delete 40 (A node with two children)



Deletion – Case3: A Node with two children



Analysis of BST Operations

- The cost of an operation is proportional to the depth of the last accessed node.
- The cost is logarithmic for a well-balanced tree, but it could be as bad as linear for a degenerate tree.
- In the best case we have logarithmic access cost, and in the worst case we have linear access cost.

Order of Operations on BSTs

<u>Operation</u>	<u>Average case</u>	<u>Worst case</u>
Retrieval	$O(\log n)$	$O(n)$
Insertion	$O(\log n)$	$O(n)$
Deletion	$O(\log n)$	$O(n)$
Traversal	$O(n)$	$O(n)$